

E4 Project : MALIS

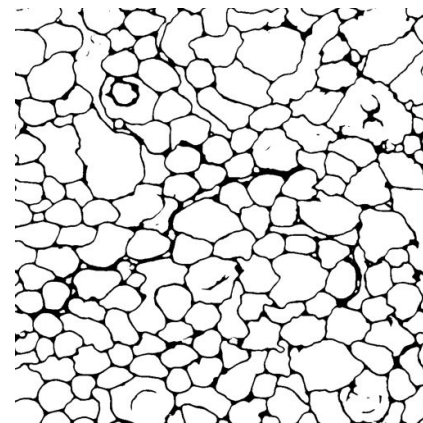
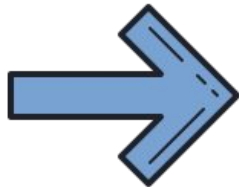
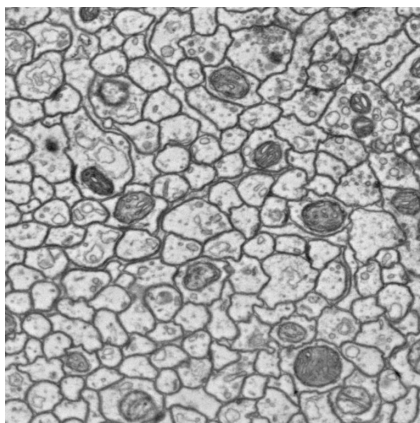
Work available at : *github.com/garridoq/malis-project*

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Tiphany LAMY-VERDIN
Raphaël LAPERTOT
Josselin LEFEVRE
Annie LIM

Introduction

Drosophila connectome segmentation



⇒ **Brain architecture**

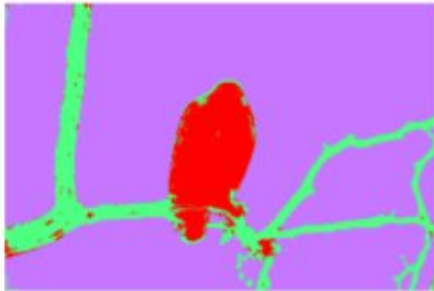
Image segmentation



Original image



Boundary detection



Semantic segmentation



Object detection

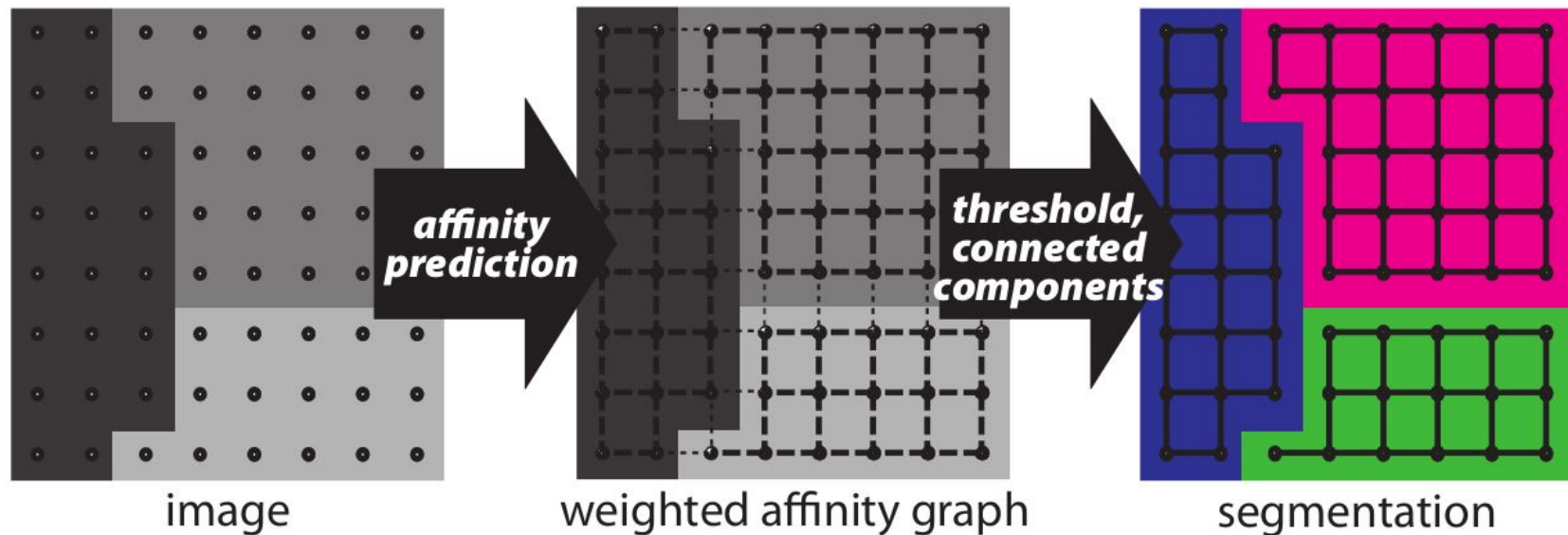
Summary

- Method's presentation
- Our implementation
- Results
- Project organization

Method's presentation

S. Turaga *et al.*, "Maximin affinity learning of image segmentation," 2009

segmentation algorithm



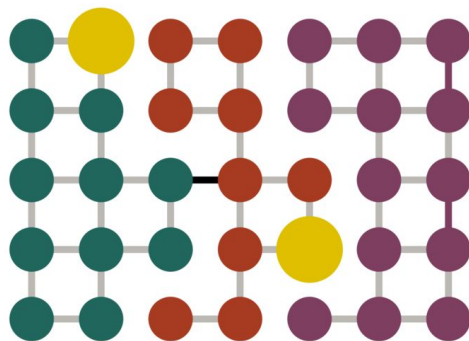
How to predict affinity ?

Various methods :

- Distance between pixels
- Any kind of classifier that is smooth
- Neural Networks

Rand Index

$$1 - RI(\hat{S}, S) = \binom{N}{2}^{-1} \sum_{i < j} |\delta(s_i, s_j) - \delta(\hat{s}_i, \hat{s}_j)|$$



Belong to
same object?

Predicted	Truth
Yes	No

Computing the Maximin affinity

- Maximin path : $P_{ij}^* = \arg \max_{P \in \mathcal{P}_{ij}} \min_{\langle k,l \rangle \in P} A_{kl}$
- Maximin affinity : $A_{ij}^* = \max_{P \in \mathcal{P}_{ij}} \min_{\langle k,l \rangle \in P} A_{kl}$

Property : Any path in a MST is a Maximin path

Computing the Maximin affinity

First paper approach :

Process:

- Pick a single pair of random pixels i, j
- Find the maximin affinity between them



Data from the MST is not used fully

Computing the Maximin affinity

Second paper approach : Constrained MALIS

We want to compute a loss over all pairs of points, which gives us :

$$L(s, a) = \sum_{u, v \in F} l(\delta(u, v), a(\text{mm}(u, v))).$$

This can be reduced to a quasilinear computation :

$$w_P(e) = |\{(u, v) \in F^2 \mid \delta(u, v) = 1, e = \text{mm}(u, v)\}|.$$

$$w_N(e) = |\{(u, v) \in F^2 \mid \delta(u, v) = 0, e = \text{mm}(u, v)\}|$$

$$L(s, a) = \sum_{e \in \text{MST}(G)} w_P(e)l(1, a(e)) + w_N(e)l(0, a(e))$$

Constrained Malis loss

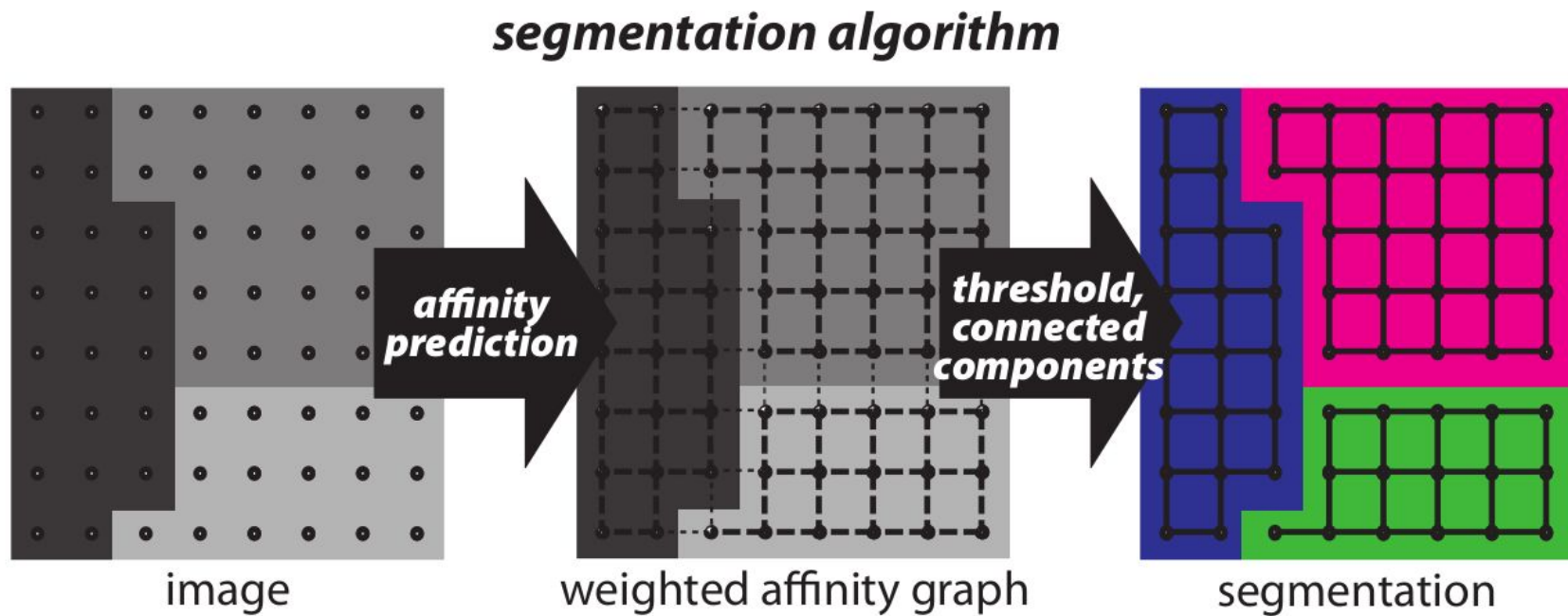
Computing w_p and w_n :

Adding an edge e to our MST merges two trees T_1 and T_2

$$\text{Then } w_p = \sum_{i \in \{1, \dots, k\}} |V_{T_1}^i| |V_{T_2}^i|$$

$$w_n = \sum_{i \neq j \in \{1, \dots, k\}} |V_{T_1}^i| |V_{T_2}^j| = |V_{T_1}| |V_{T_2}| - w_p$$

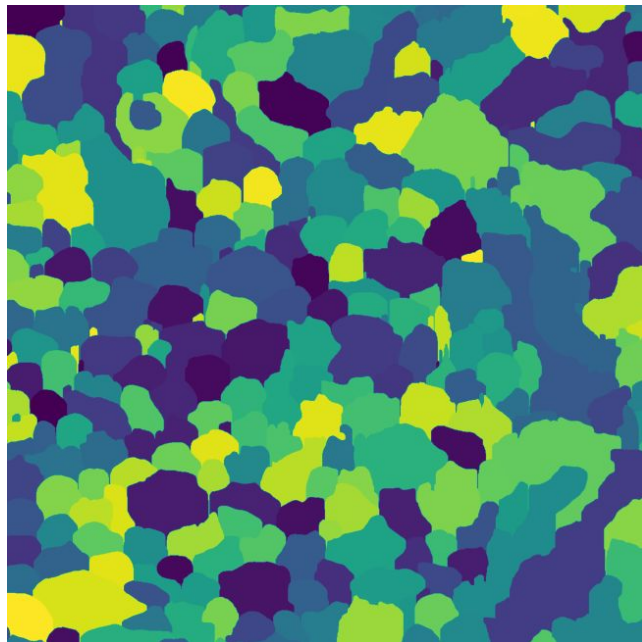
MALIS' method



Additional post processing

Examples

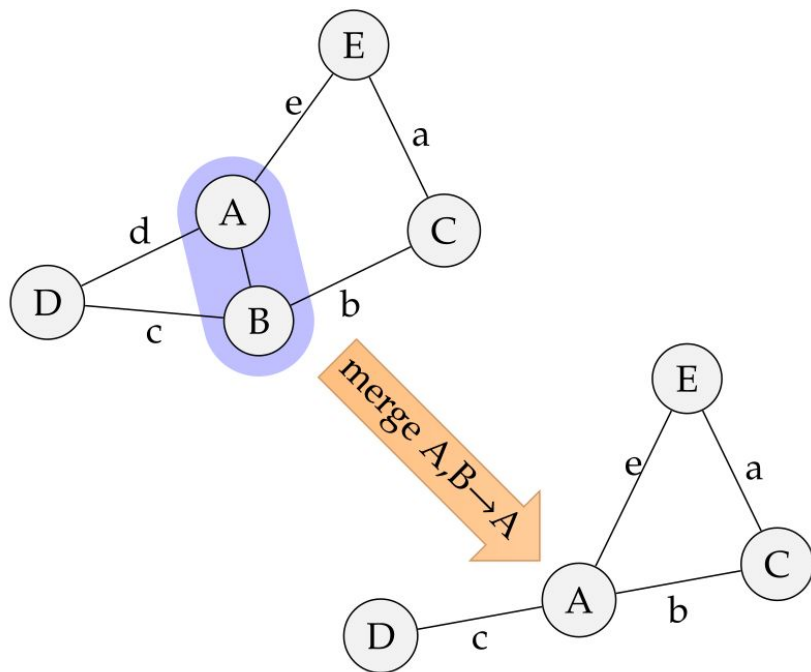
- Watershed
- Watershed + deletion of small regions
- Mumford Shah + cut
- **Watershed + agglomeration (as used in the improved version of MALIS)**



Result of a watershed

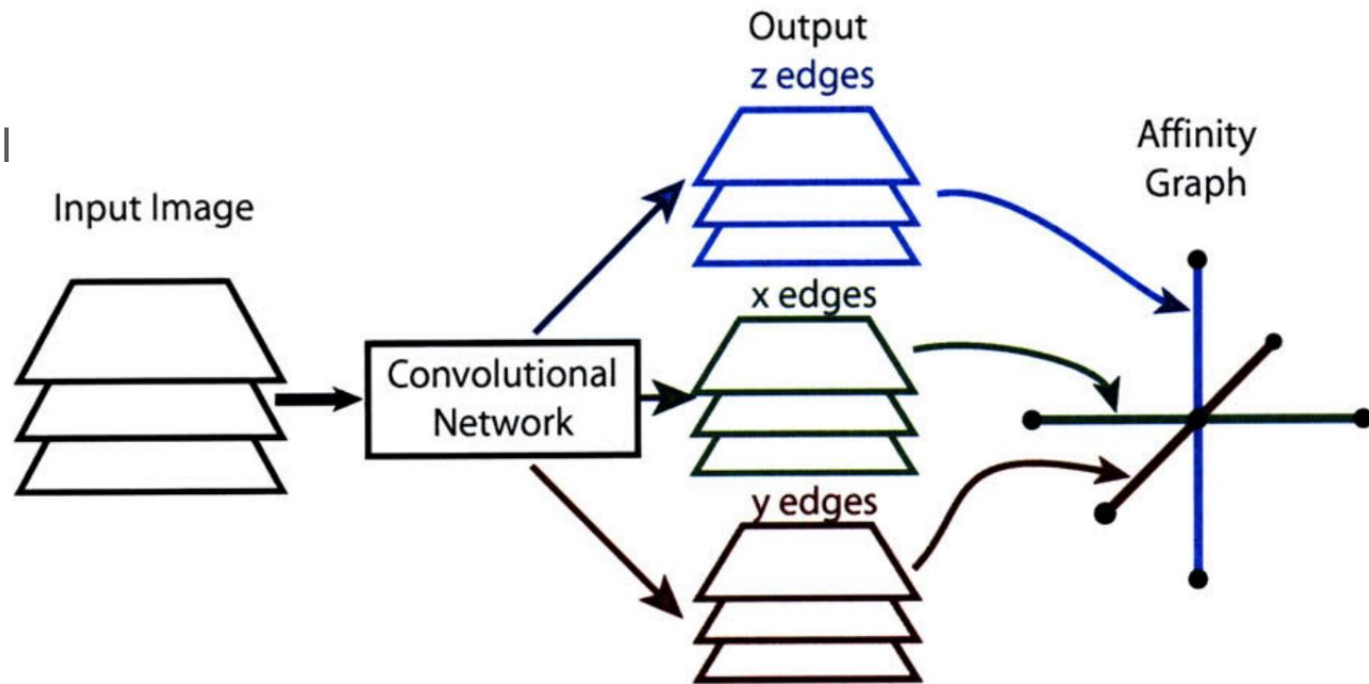
Agglomeration of objects

- Compute a Region Adjacency Graph
- Edge values are the affinity between both objects
- Merge object with smallest edge value between them



Our implementation

- Pytorch for the neural network
- Higraph to compute the loss

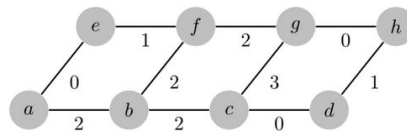


Using a MST and a BPT

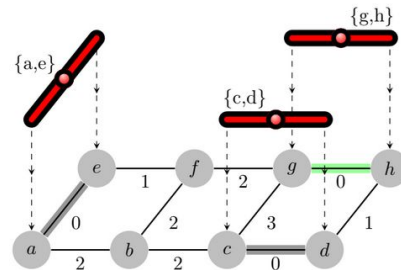
The BPT contains all the data for computing

$$w_p = \sum_{i \in \{1, \dots, k\}} |V_{T_1}^i| |V_{T_2}^i|$$

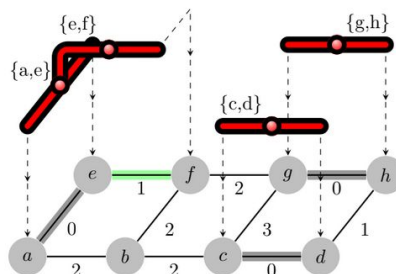
and w_n



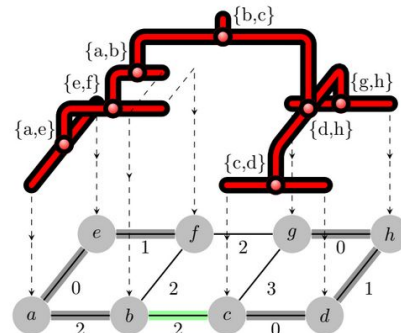
(a) Edge-weighted graph



(b) First nodes of Q_{BT}



(c) Adding a node to Q_{BT}



(d) Final Q_{BT}

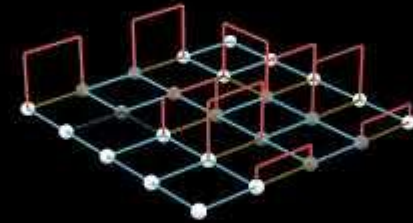
Visualizing the construction of the MST & BPT

Light blue : Low affinity

Dark blue : High affinity

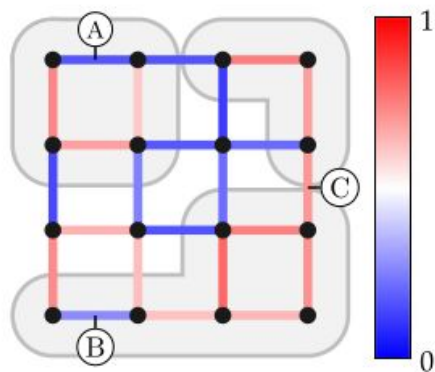
Yellow : Maximum Spanning Tree

Red : Binary Partition Tree

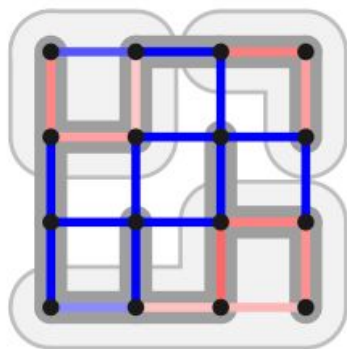


Two pass loss

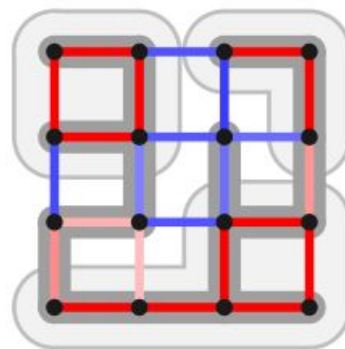
$$L(s, a) = \sum_{e \in \text{MST}(G)} w_P(e)l(1, a(e)) + w_N(e)l(0, a(e))$$



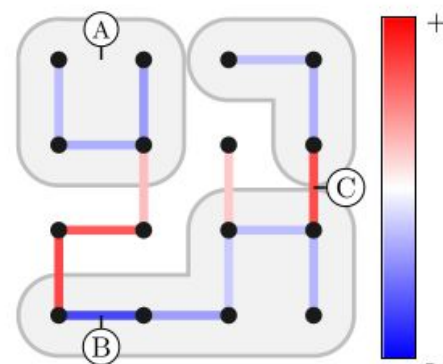
(a) Predicted affinities.



(b) Positive pass.

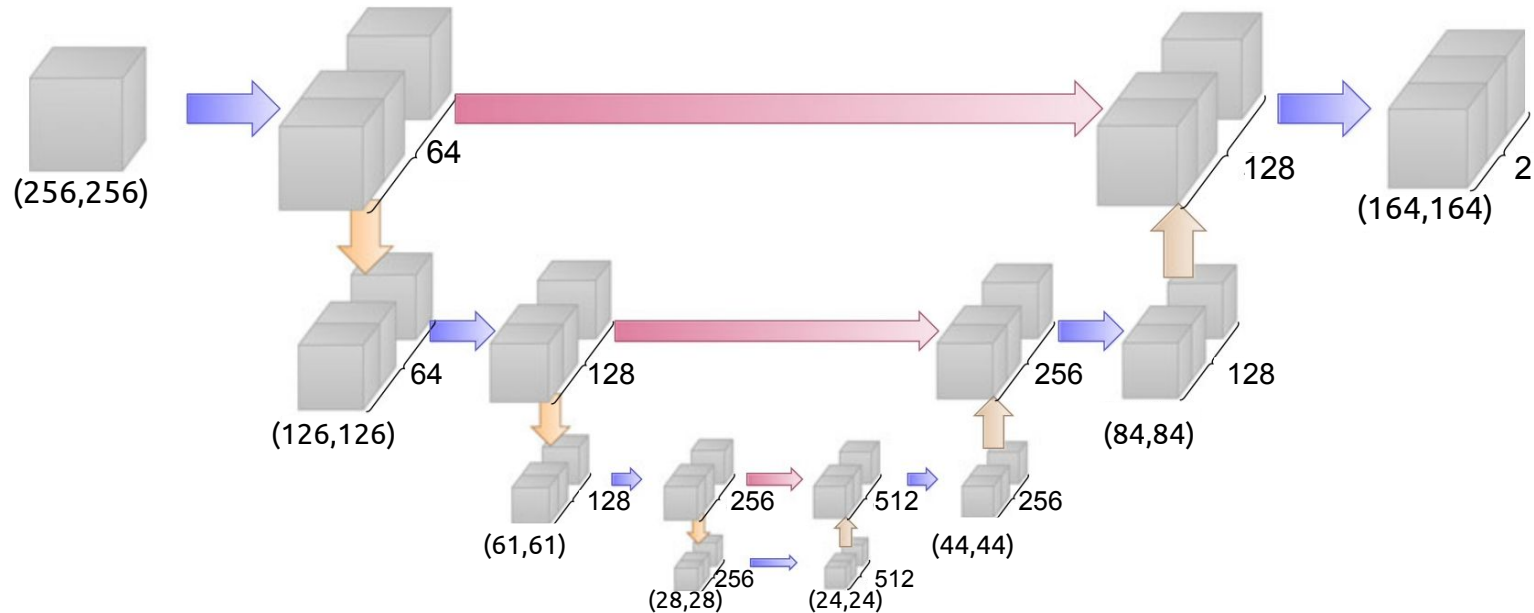


(c) Negative pass.



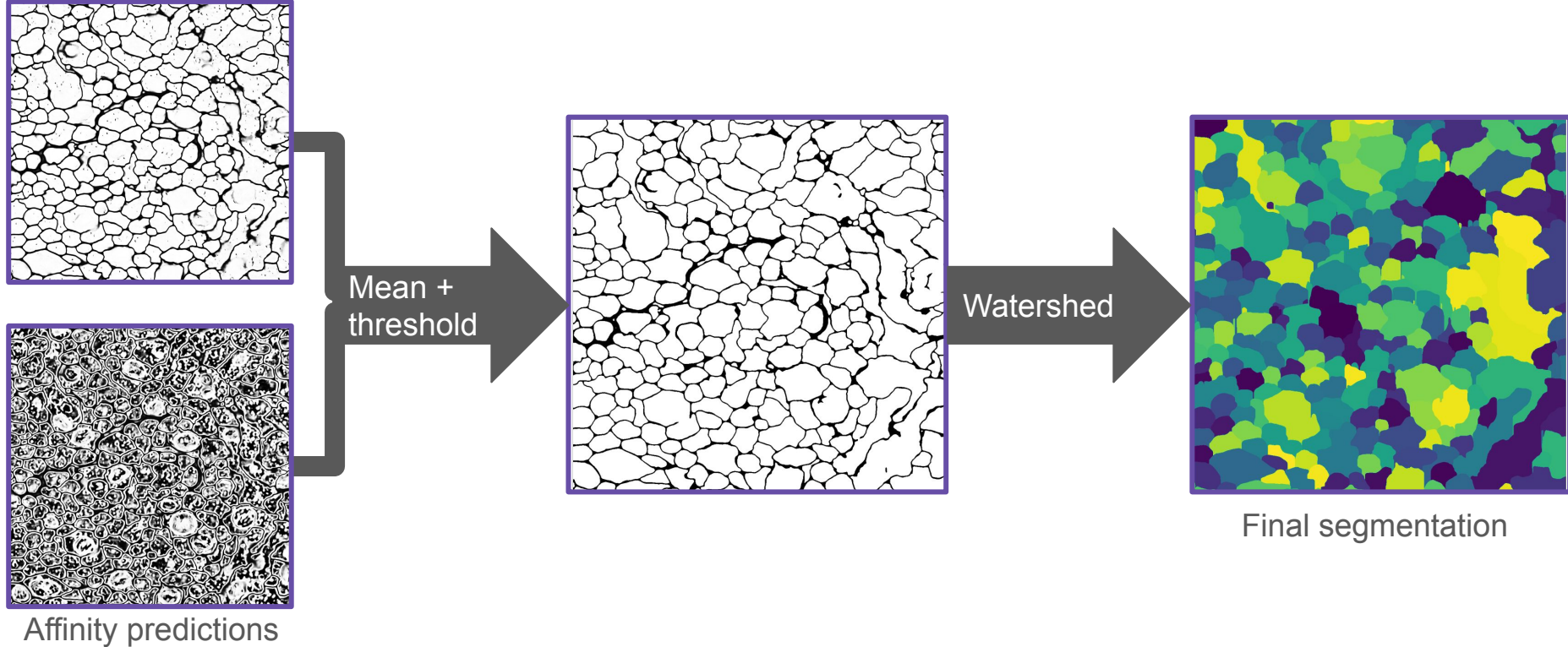
(d) Gradient of loss.

Results: U-net architecture



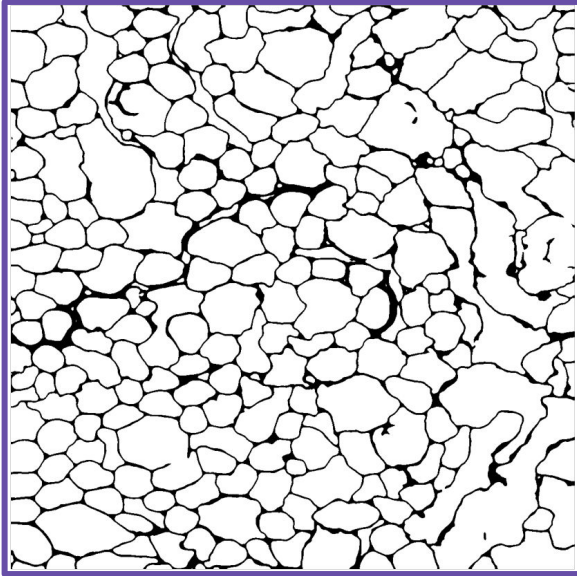
Architecture used for the experiments

Results: Post processing used

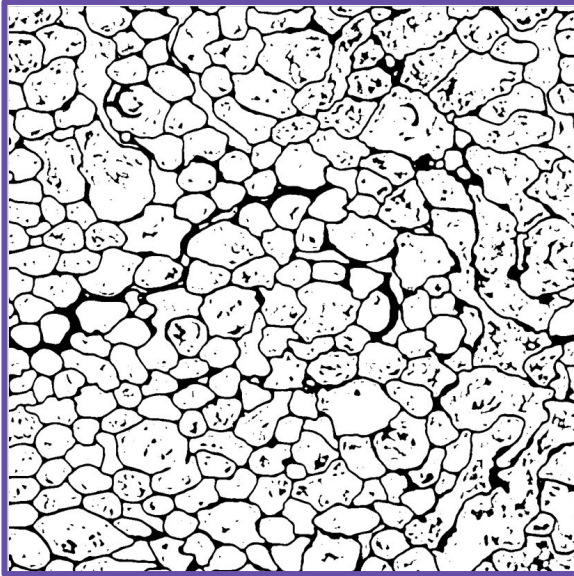


Results: Post processing used

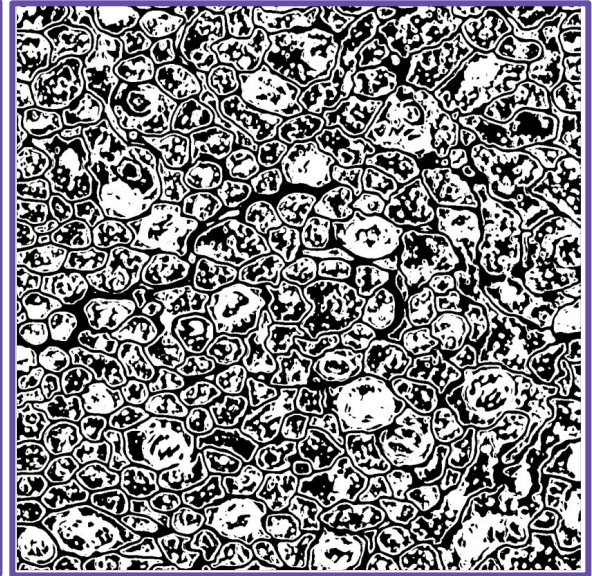
Influence of threshold value



$\theta = 0.25$



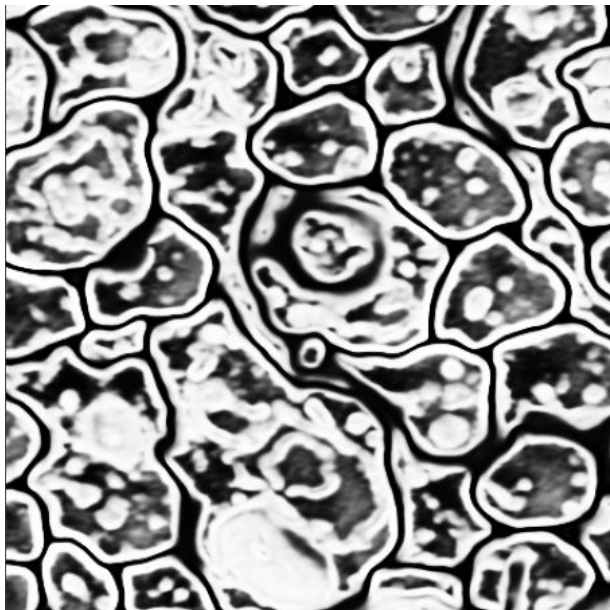
$\theta = 0.5$



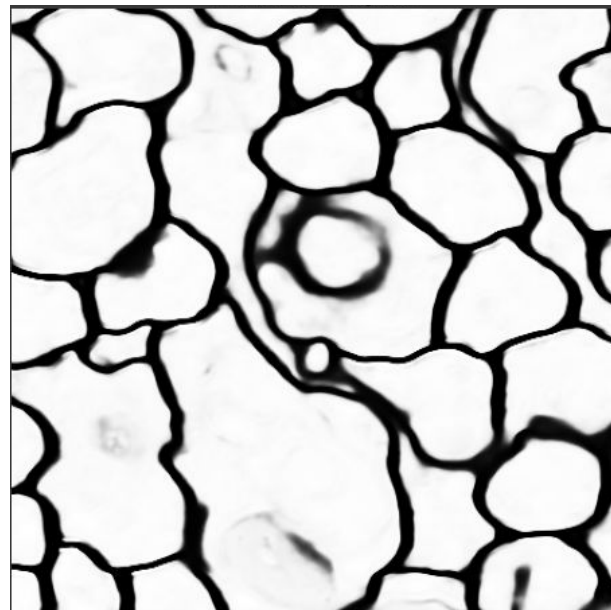
$\theta = 0.75$

Discrepancies between affinities

Prediction difference between X and Y axis:

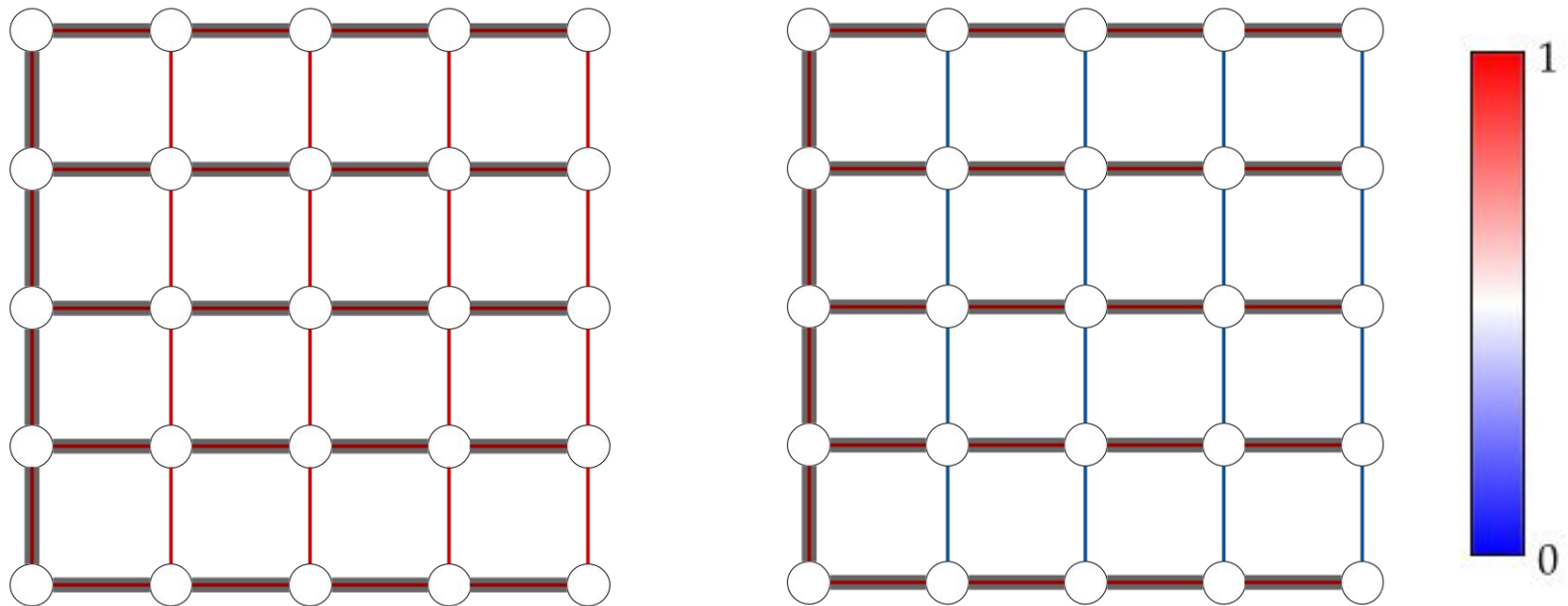


Affinity along the x axis



Affinity along the y axis

Graphs with the same MALIS loss



Both are valid, and give the same loss, but the left one is more desirable

Results: CREMI dataset

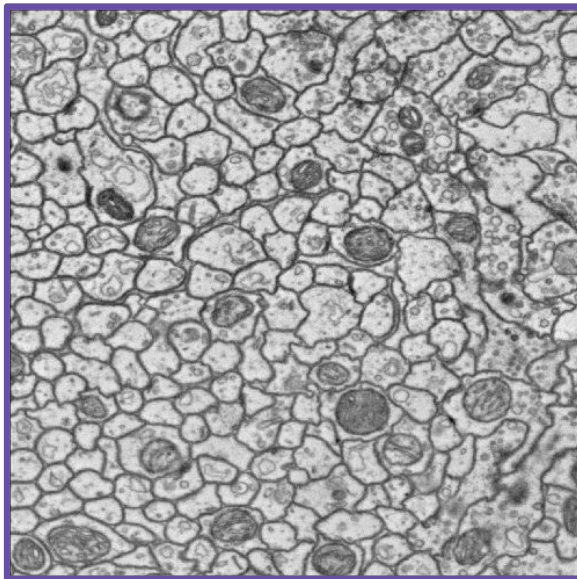
Dataset presentation :

Image size :
1250x1250x125

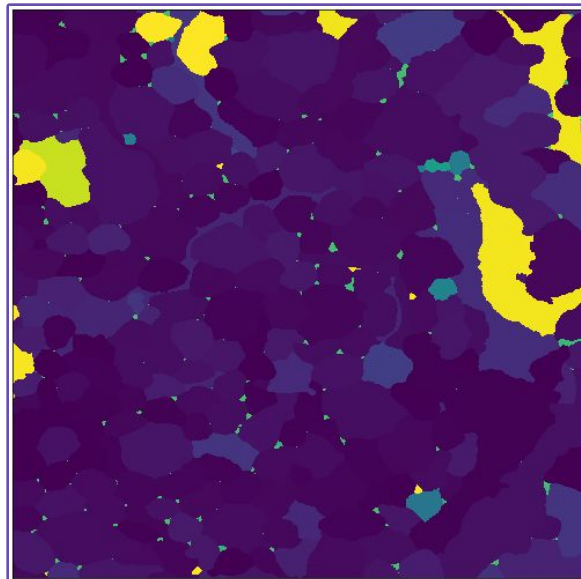
Number of images used : 1

Split train/test : 100/25

Evaluation using a
python 2 library



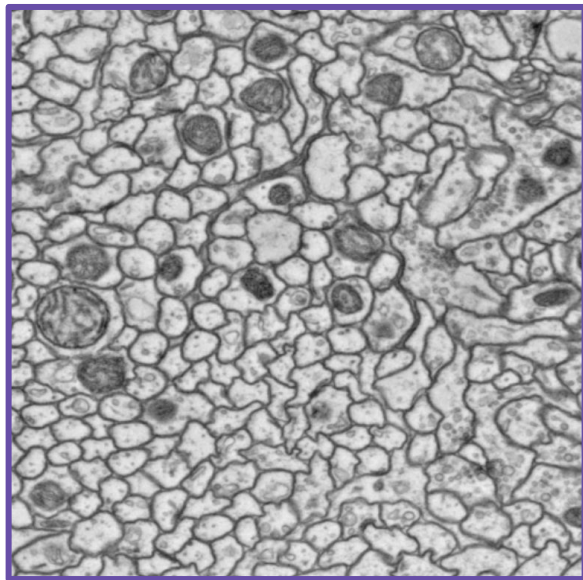
Original image



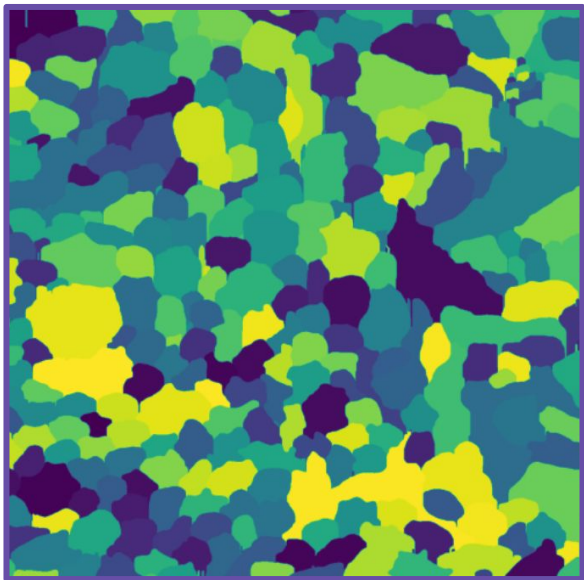
Groundtruth

Results: CREMI dataset

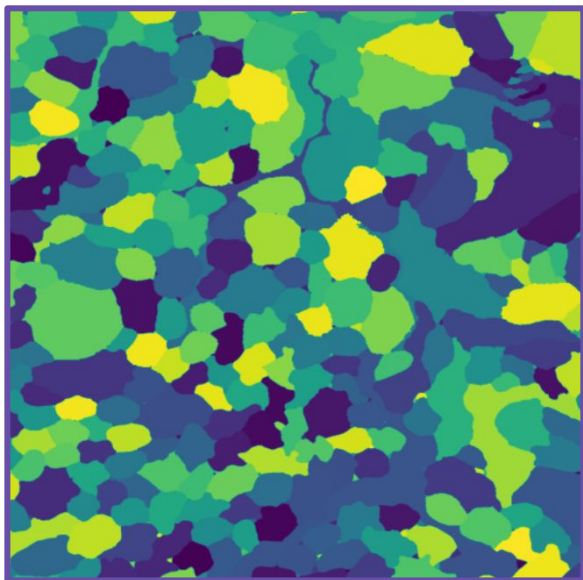
Example results : CREMI volume A (Test set)



Original image



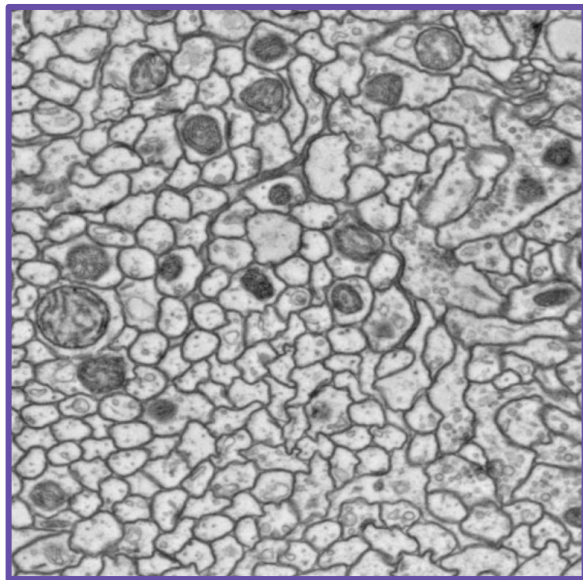
Our segmentation



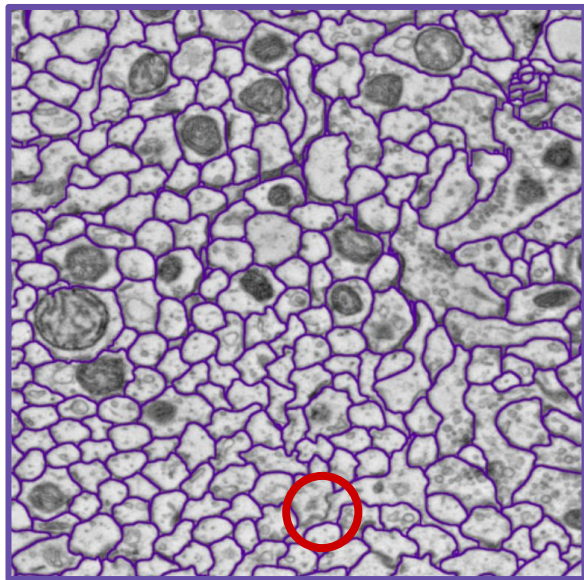
Groundtruth

Results: CREMI dataset

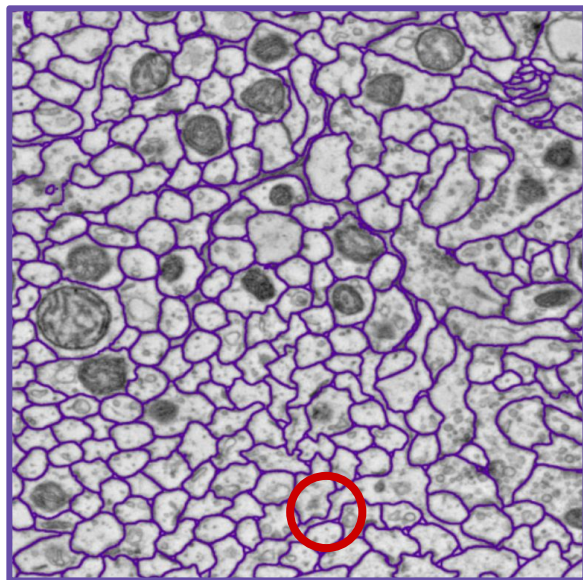
Example results : CREMI volume A (Test set)



Original image



Our segmentation



Groundtruth

Results: Metrics used

Rand index :

$$R(X, Y) = \binom{N}{2}^{-1} \sum_{i < j} |\delta(X_i, X_j) - \delta(Y_i, Y_j)|$$

VOI merge and split :

$$VOI(X, Y) = \underbrace{H(X|Y)}_{\text{VOI split}} + \underbrace{H(Y|X)}_{\text{VOI merge}}$$

CREMI score :

$$CREMI = \sqrt{VOI(X, Y) \times (1 - R(X, Y))}$$

Results: CREMI dataset Training set

Numerical results

	Rand index	VOI merge (lower is better)	VOI split (lower is better)	CREMI score (lower is better)
FCN + MALIS	0.61	1.25	1.03	0.94
U-Net	0.58	0.91	0.52	0.78
U-Net MALA	0.83	0.46	0.54	0.42

Results: CREMI dataset Test set

Numerical results

	Rand index	VOI merge (lower is better)	VOI split (lower is better)	CREMI score (lower is better)
FCN + MALIS	0.53	1.57	1.38	1.18
U-Net	0.52	1.07	0.47	0.87
U-Net MALA	0.80	0.50	0.57	0.46
<i>SOTA (in 3D)</i>	<i>0.89</i>	<i>0.115</i>	<i>0.339</i>	<i>0.221</i>

Project organization

- Meetings (Hangouts)
- Weekly reports
- Trello
- Jupyter notebooks
- Social networks



Difficulties encountered

- Scientific papers
- Basic knowledge
- Higma
- PyTorch
- Quarantine



Conclusion

Work available at : *github.com/garridoq/malis-project*