

Linearization at the Transmitter

Consider x_i which is the i^{th} element of \mathbf{x}

$$x_i = \mathbf{w}_i^H \mathbf{s}, \quad \sigma_{x_i}^2 = E[|x_i|^2] = \sigma_s^2 \mathbf{w}_i^H \mathbf{w}_i$$

where \mathbf{w}_i^H is the i^{th} row of \mathbf{W}

$$\therefore x_i \sim \mathcal{N}(0, \sigma_{x_i}^2)$$

$$\text{Let } t_i = Q_{Tx}(x_i)$$

where Q_{Tx} is as in (1)

$$\text{then } t_i = g_i^{Tx} x_i + d_i^{Tx}$$

according to bussgang decomposition, where g_i^{Tx} , d_i^{Tx} are the bussgang gain & uncorrelated non-gaussian distortion, respectively

$$\begin{aligned} g_i^{Tx} &= E[Q'_{Tx}(x_i)] = \frac{1}{\sigma_{x_i}} E[2\delta(x_i)] = \frac{1}{\sigma_{x_i}} \frac{2}{\sqrt{2\pi}} p(0) \\ &= \frac{2}{\sqrt{2\pi}} \frac{1}{\sigma_{x_i}} = \frac{2}{\sqrt{2\pi}} \sigma_{x_i}^{-1/2} \end{aligned}$$

where $p(x_i)$ is the pdf of x_i

Extending this :

$$\begin{aligned} t_1 &= g_1^{Tx} x_1 + d_1^{Tx} \\ t_2 &= g_2^{Tx} x_2 + d_2^{Tx} \\ &\vdots \\ t_N &= g_N^{Tx} x_N + d_N^{Tx} \end{aligned}, \quad \mathbf{t} = \begin{bmatrix} t_1 \\ t_2 \\ \vdots \\ t_N \end{bmatrix}$$

then

$$\mathbf{t} = \begin{bmatrix} g_1^{Tx} & 0 & \dots & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} + \begin{bmatrix} d_1^{Tx} \\ \vdots \\ d_N^{Tx} \end{bmatrix}$$

$$\begin{bmatrix} 0 & g_1^{Tx} & & \\ \vdots & & \ddots & \\ 0 & 0 & \dots & g_N^{Tx} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} + \begin{bmatrix} d_1 \\ \vdots \\ d_N \end{bmatrix}$$

$$t = G_{Tx} x + d_{Tx}$$

$$G_{Tx} \begin{bmatrix} g_1^{Tx} \\ g_2^{Tx} \\ \vdots \\ g_N^{Tx} \end{bmatrix} = \sqrt{\frac{2n_{Tx}}{\pi}} \begin{bmatrix} \sigma_{x_1}^2 & & \\ 0 & \sigma_{x_2}^2 & \\ & \ddots & \\ 0 & & \sigma_{x_N}^2 \end{bmatrix}^{-1/2} =$$

$$= \sqrt{\frac{2n_{Tx}}{\pi}} \text{diag}^{-1/2} \left(\begin{bmatrix} \sigma_{x_1}^2 & E[x_1^* x_2] & \dots & E[x_1^* x_N] \\ E[x_2^* x_1] & \sigma_{x_2}^2 & & \\ \vdots & & \ddots & \\ E[x_N^* x_1] & & & \sigma_{x_N}^2 \end{bmatrix} \right) = \sqrt{\frac{2n_{Tx}}{\pi}} \text{diag}^{-1/2} (C_x)$$

$$G_{Tx} = \sqrt{\frac{2n_{Tx}}{\pi}} \text{diag}^{-1/2} (C_x)$$

where $C_x = E[x x^H] = W W^H$ as in (9)

* Deriving $C_t = E[t t^H]$

From G. Jacovitti and R. 2002:

$$C_t[k, m] = E[t_k t_m^*] =$$

$$\begin{aligned} E \left[Q_{Tx}(x_k) Q_{Tx}^*(x_m) \right] &= \frac{2}{\pi} n_{Tx} \left(\arcsin[\text{Re}[p_{x_k x_m}]] + j \arcsin[\text{Im}[p_{x_k x_m}]] \right) \\ &= C_t^R[k, m] + j C_t^I[k, m] \end{aligned}$$

where $x_{ik} \sim N(0, \sigma_{x_{ik}}^2)$, $C_t[l_k m]$ is the element of C_t corresponding

to row l_k and column m and $\rho_{x_{ik} x_m} = \frac{E[x_{ik} x_m^*]}{\sqrt{E[|x_{ik}|^2]} \sqrt{E[|x_m|^2]}}$

$$= \frac{1}{\sqrt{E[|x_{ik}|^2]} \sqrt{E[|x_m|^2]}} (\operatorname{Re}[E[x_{ik} x_m^*]] + j \operatorname{Im}[E[x_{ik} x_m^*]]) = \operatorname{Re}[\rho] + j \operatorname{Im}[\rho]$$

Accordingly $C_t = C_t^R + j C_t^I$ where

$$C_t^R = \operatorname{Re}[C_t] \quad \text{and} \quad C_t^I = \operatorname{Im}[C_t]$$

From the above we can present C_t^R as:

$$C_t^R = \operatorname{Re}[C_t] = \frac{2}{\pi} n_{Tx} \arcsin \left(\operatorname{Re} \begin{bmatrix} \frac{E[x_1 x_1^*]}{E[|x_1|^2]} & \dots & \frac{E[x_1 x_N^*]}{\sqrt{E[|x_1|^2]} \sqrt{E[|x_N|^2]}} \\ \vdots & \frac{E[x_2 x_2^*]}{E[|x_2|^2]} & \vdots \\ \frac{E[x_N x_N^*]}{\sqrt{E[|x_N|^2]} \sqrt{E[|x_1|^2]}} & \dots & \frac{E[x_N x_N^*]}{E[|x_N|^2]} \end{bmatrix} \right)$$

$= \frac{2}{\pi} n_{Tx} \arcsin(A)$, where A is presented below:

$$A = \begin{bmatrix} (E[|x_1|^2])^{-1/2} & 0 & \dots & 0 \\ 0 & (E[|x_2|^2])^{-1/2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & (E[|x_N|^2])^{-1/2} \end{bmatrix} \begin{bmatrix} \operatorname{Re}[E[x_1 x_1^*]] & \operatorname{Re}[E[x_1 x_N^*]] \\ \operatorname{Re}[E[x_2 x_2^*]] & \vdots \\ \vdots & \vdots \\ \operatorname{Re}[E[x_N x_N^*]] & \operatorname{Re}[E[x_N x_1^*]] \end{bmatrix} \begin{bmatrix} E[|x_1|^2] & 0 & \dots & 0 \\ 0 & E[|x_2|^2] & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & E[|x_N|^2] \end{bmatrix}^{-1/2}$$

$$\text{diag}(C_x)^{-1/2}$$

$$\text{Re}[C_x]$$

$$\text{diag}(C_x)^{-1/2}$$

$$\therefore C_t^R = \frac{2n_{rx}}{\pi} \arcsin \left[\text{diag}(C_x)^{-1/2} \text{Re}[C_x] \text{diag}(C_x)^{-1/2} \right]$$

C_t^I can be derived similarly resulting in:

$$C_t^I = \frac{2}{\pi} n_{rx} \arcsin \left[\text{diag}(C_x)^{-1/2} \text{Im}[C_x] \text{diag}(C_x)^{-1/2} \right]$$

and $C_t = C_t^R + j C_t^I$ as in (14)

Linearization at the Receiver

The linearization at the receiver is similar to that of the T_x when y is approximated to be gaussian for large N according to the CLT.

Tractable Approximation of the MSE

$$\begin{aligned} E &= \frac{1}{K} E[\|s - V^H r\|^2] = \frac{1}{K} E[(s - V^H r)^H (s - V^H r)] = \\ &= \frac{1}{K} E[s^H s - s^H V^H r - r^H V s + r^H V V^H r] = \\ &= \frac{1}{K} E[s^H s - 2 \text{Re}[s^H V^H r] + r^H V V^H r] = \frac{1}{K} \text{tr}(E[ss^H]) + \frac{1}{K} \text{tr}(V^H E[r r^H] V) \\ &- \frac{2}{K} \text{tr}(V^H E[r s^H]) \end{aligned}$$

$$= 1 + \frac{1}{K} \text{tr}(V^H C_r V) - \frac{2}{K} \text{tr}(V^H E[r s^H])$$

$$E[r s^H] = E[(G_{R \times} (\Gamma_P H (G_{Tx} W s + d_{Tx}) + z) + d_{Rx}) s^H]$$

$$= \Gamma_P G_{R \times} H G_{Tx} W E[s s^H]$$

$$\xi = 1 + \frac{1}{K} \text{tr}(V^H C_r V) - \frac{2}{K} \Gamma_P \text{tr}(\text{Re}[G_{R \times} H G_{Tx} W])$$

$$\nabla \xi_V = \frac{2}{K} V^H C_r - \frac{\Gamma_P}{K} \nabla_V [\text{tr}[V^H G_{R \times} H G_{Tx} W + (G_{R \times} H G_{Tx} W)^H V]]$$

$$\nabla \xi_V = \frac{2}{K} V^H - \frac{2 \Gamma_P}{K} (G_{R \times} H G_{Tx} W)^H$$

$$\nabla \xi_V = 0 \Rightarrow \hat{V} = \Gamma_P (G_{R \times} H G_{Tx} W) C_r^{-1}$$

Channel Model

Discrete physical channel model [15]:

$$H = \sum_{k=1}^L \beta_R a_R(\phi_R, \theta_{R,1k}, \theta_{R,1k}) a_T^H(\phi_T, \theta_{T,1k}, \theta_{T,1k})$$

$$= A_R(\phi_R, \theta_R) H_P A_T^H(\phi_T, \theta_T)$$

$$\mathbf{P} = \text{diag} (P_1, \dots, P_L)$$

For a $JN \times JN$ ($JM \times JM$) planar array with half-wavelength spaced antennas placed with broadsides facing each other,

The steering vector is given as :

$$\mathbf{a}_x(\theta_x, \theta_y) = \begin{bmatrix} 1, e^{j\pi(\sin\theta_x \cos\theta_y + \sin\theta_x \sin\theta_y)} \\ e^{j\pi(\sin\theta_x \cos\theta_y + (JN-1)\sin\theta_x \sin\theta_y)} \\ \dots \\ e^{j\pi((JN-1)\sin\theta_x \cos\theta_y + (JN-1)\sin\theta_x \sin\theta_y)} \end{bmatrix}$$

where x can be Tx or Rx & $M=N$.

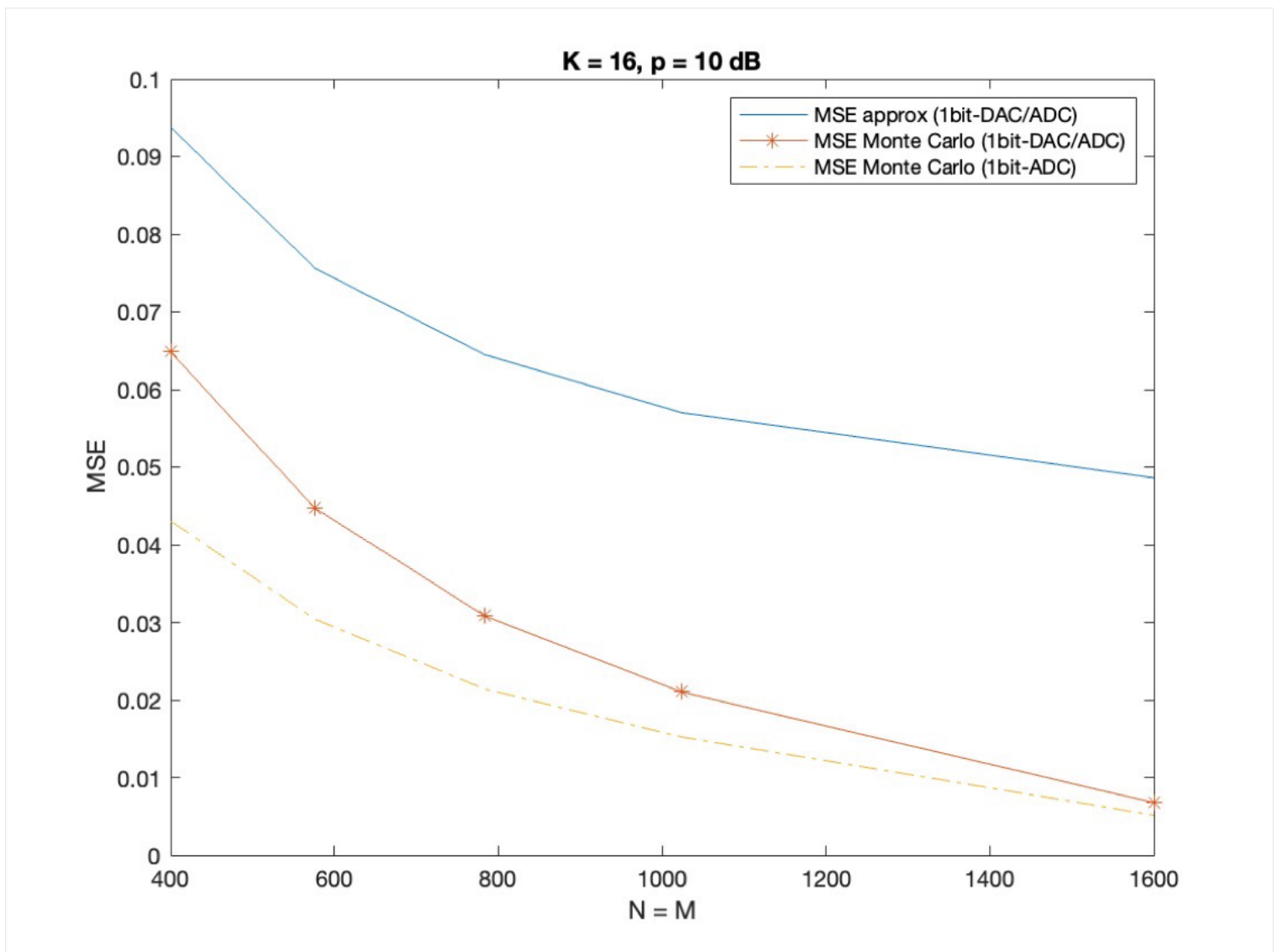
Simulation Results

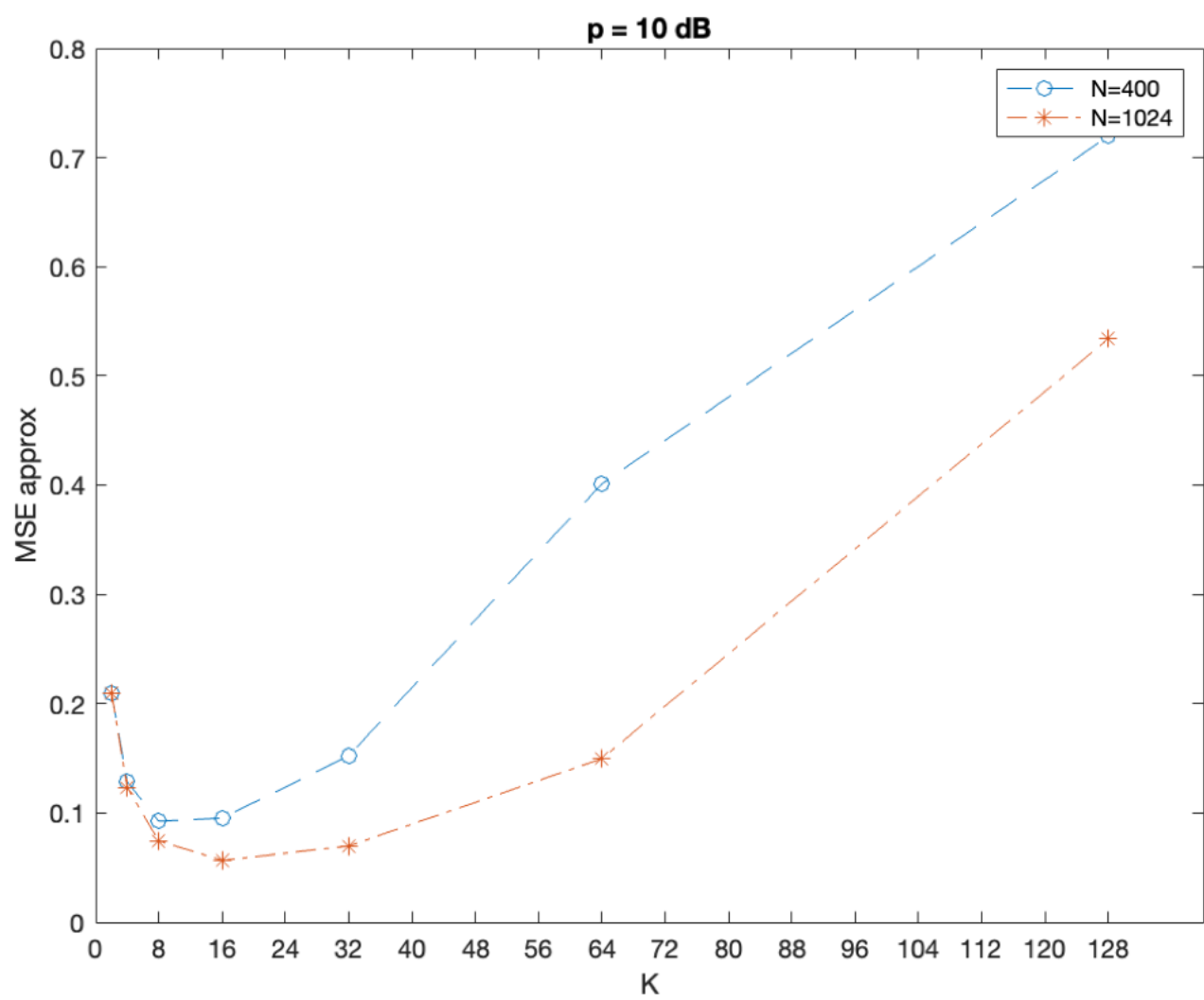
The system is simulated to generate Figure (2), (4), and (5).

For Figure (2), I only simulate 10^2 independent channel realizations. Also for Monte Carlo simulations I simulated $2 \cdot 10^3$ as with 10^3 , the sample autocorrelation C_{rr} is badly conditioned yielding problems with C_{rr}^{-1} .

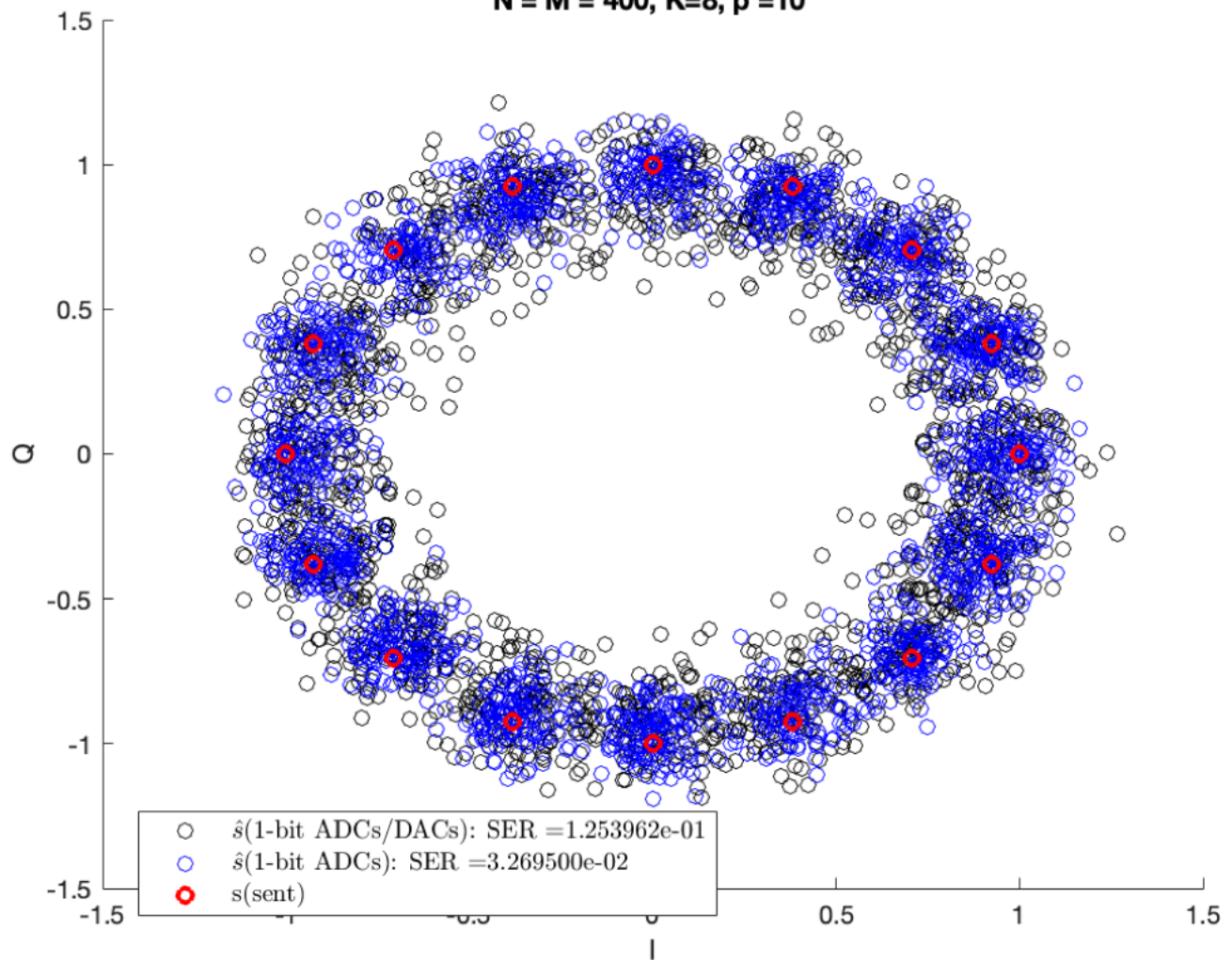
For Figure (4), I only generate two curves corresponding to $N=400, 1024$.

While the numbers of my simulation don't exactly match those in the paper. The curves and constellations are similar in behavior. The code is attached.

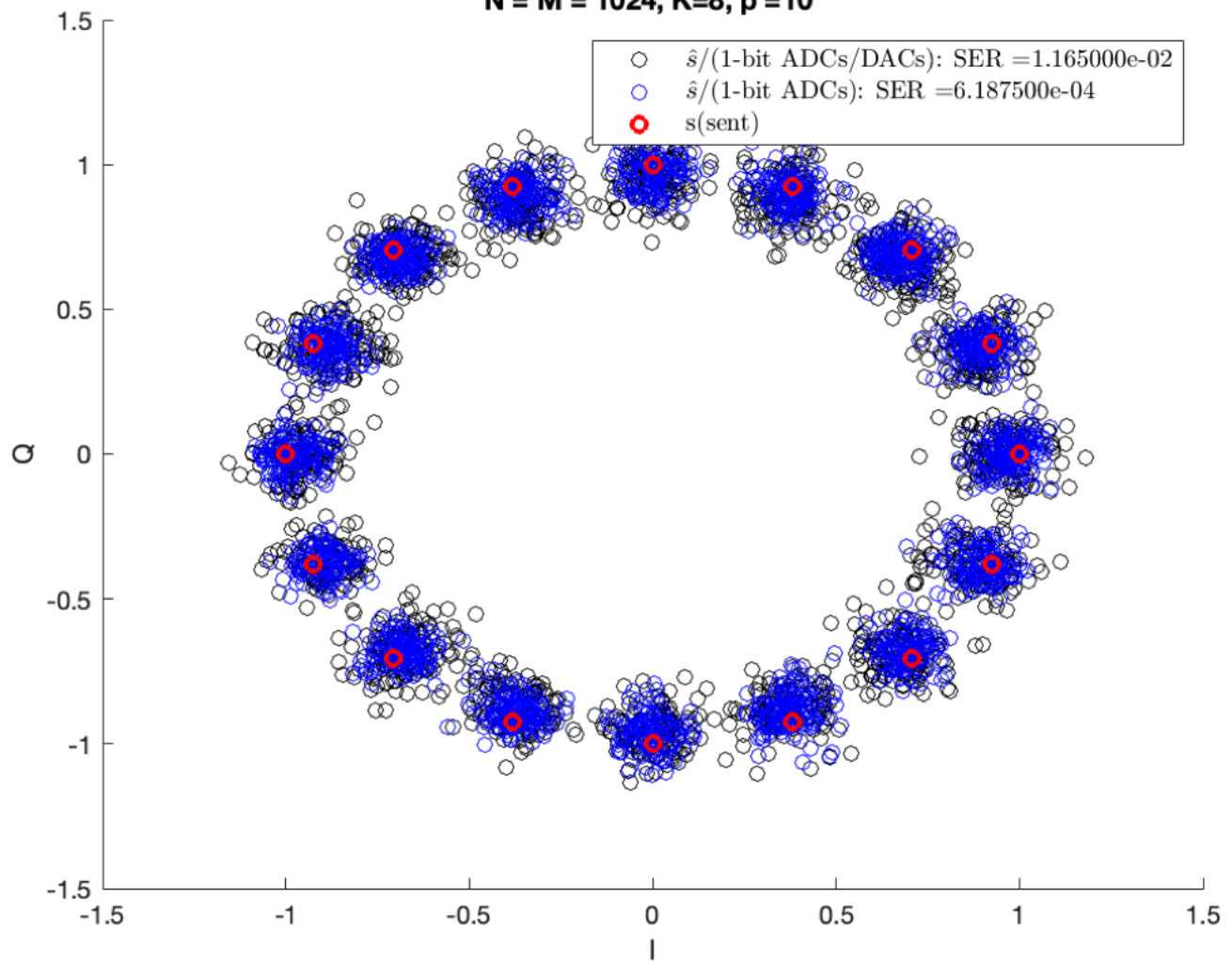




$N = M = 400, K=8, p=10$



N = M = 1024, K=8, p=10



$N = M = 1600, K=8, p=10$

