學號: R06522709 系級: 機械碩三 姓名: 鄭呈毅

請實做以下兩種不同 feature 的模型,回答第 (1) ~ (2) 題:抽全部 9 小時內的污染源 feature 當作一次項(加 bias)抽全部 9 小時內 pm2.5 的一次項當作 feature(加 bias) 備註:

- a. NR 請皆設為 0, 其他的非數值(特殊字元)可以自己判斷
- b. 所有 advanced 的 gradient descent 技術(如: adam, adagrad 等) 都是可以用的
- c. 第 1-2 題請都以題目給訂的兩種 model 來回答
- d. 同學可以先把 model 訓練好, kaggle 死線之後便可以無限上傳。
- e. 根據助教時間的公式表示, (1) 代表 p = 9x18+1 而(2) 代表 p = 9*1+1
- 1. (1%)記錄誤差值 (RMSE)(根據 kaggle public+private 分數), 討論兩種 feature 的影響 a.抽全部 9 小時內的污染源 feature 當作一次項(加 bias):

Private score=5.51 Public score = 5.65 b.抽全部 9 小時內 pm2.5 的一次項當作 feature(加 bias) privatecore=6.67 public score =6.66

如果以 9 小時內的所有汙染源資訊來 train model 的話 RMSE 會比只取 pm2.5 作為 feature 的結果還要小上很多,我想這是因為 pm2.5 本來就是我們想要預測的目標,而雖然前段時間的 pm2.5 必定與下一個時刻的 pm2.5 有一定的關係,但是顯然 pm2.5 也會受到其他 feature 的影響,因此在只考慮 pm2.5 本身的情況下,預測結果並非最好。此外我在 train 只取 pm2.5 作為 feature 的 model 時,有出現 model 發散的情形,iteration 為 1000 時則 kaggle 上顯示的 RMSE 為 55,甚至超過全部預測 0 所得到的 RMSE,但是如果 iteration 為 50 的話 RMSE 只有 6,因 為我是採用 TA 手把手所提供的 model,理論上來說 gradient descent 不應該出現這種情況才對,後來發現似乎是對這個 feature 來說 learning rate 0.001 太大,導致 model 發散,後來把 learning rate 調成 0.00001 之後就沒有這個問題了。

2. (1%)解釋什麼樣的 data preprocessing 可以 improve 你的 training/testing accuracy, ex. 你怎麼挑掉你覺得不適合的 data points。請提供數據(RMSE)以佐證你的想法。

a.不挑掉任何 data point:

private score=5.94 public score = 6.54 b.同 TA 手把手 code 挑掉 pm2.5<=2 or >=100: private score=5.64 public score = 5.81

如同 TA 在手把手時段所傳授的,如果資料點本身就不合理,就不應該餵進 model 裡面,最明顯的就是 pm2.5 當中會出現負值,這是一定不合理的;pm2.5>65 就會對所有人的身體健康造成危害,而在台灣 pm2.5>80 已是非常嚴重的情況,所以若 pm2.5>100 已是 outlier,應該要予以剔除。另外在所有 feature 當中,rainfall 高頻率出現 NAN 的情形,一開始我認為這個 feature 紀錄狀況並不完整,應該不具參考價值,所以就將它剔除,但訓練結果不佳,我想這可能是因為降兩本身就會大幅影響 PM2.5 產生,像是兩季的 pm2.5 比起旱季的 pm2.5 少上很多,因此雖然該 feature 紀錄狀況不完整,但是一但有紀錄,則該資訊會大幅影響預測的正確性,因此仍然需要將此 feeature 餵進 model 中。

3.(3%) Refer to math problem

$$\begin{aligned}
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& \left[-(a) \right] \leq \left\{ (1, 1, 2), (2, 3, 4), (3, 3, 5), (4, 4, 1) (5, 5, 6) \right\} \\
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We want to minimize J(0) > let To(J(0)) =0.

$$\int_{\frac{1}{2}\theta_{1}} J(\theta) = \int_{-2\pi}^{\pi} \int_{t=1}^{\pi} \left[y^{t\theta} - (x_{1}\theta_{1} + x_{2}\theta_{2} + ... x_{1}\theta_{1}) \right]^{2}$$

$$\int_{\frac{1}{2}\theta_{1}} J(\theta) = \int_{-2\pi}^{\pi} \int_{t=1}^{\pi} \left[y^{t\theta} - (x_{1}\theta_{1} + x_{2}\theta_{2} + ... x_{1}\theta_{1}) \right]^{2}$$

$$\int_{\frac{1}{2}\theta_{1}} J(\theta) = \int_{-2\pi}^{\pi} \int_{t=1}^{\pi} \left[y^{t} - (x_{1}\theta_{1} + x_{2}\theta_{2} + ... x_{1}\theta_{1}) \right] \left(x_{1}^{t\theta} \right) \left(x_{1}^{$$

$$|-(c)| J(e) = \frac{1}{2\pi} \sum_{t=1}^{N} \left[y_{t} - w_{t}^{(t)} \right]^{2} + \frac{2}{2} (w_{t}^{(t)})^{2}$$

$$= \frac{2}{3} (w_{t}^{(t)} + w_{t}^{(t)} + w_{t}^{(t)} + w_{t}^{(t)}) + w_{t}^{(t)}$$

$$\Rightarrow \frac{3}{3} e_{t}^{(t)} J(e_{t}^{(t)}) = \frac{1}{4} \sum_{t=1}^{N} \left[y_{t}^{(t)} - (x_{t}^{(t)})^{T} w \right] (-x_{t}^{(t)}) + \lambda w_{t}^{(t)}$$

$$\Rightarrow etting partial defination t_{0} o.
$$\Rightarrow \frac{1}{11} \sum_{t=1}^{N} x_{t}^{(t)} \left(x_{t}^{(t)} \right)^{T} w + \lambda w = \frac{1}{4} \sum_{t=1}^{N} x_{t}^{(t)} y_{t}^{(t)}.$$

$$\Rightarrow \frac{1}{11} x_{t}^{T} x_{t} + \lambda w_{t}^{(t)} = \frac{1}{4} x_{t}^{T} y_{t}^{(t)}.$$

$$\Rightarrow w_{t}^{(t)} \left[x_{t}^{(t)} + \lambda w_{t}^{(t)} \right] = \frac{1}{4} x_{t}^{T} x_{t}^{(t)}.$$

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$$\Rightarrow w_{t}^{(t)} \left[x_{t}^{(t)} + \lambda w_{t}^{(t)} + \lambda w_{t}^{(t)} + \lambda w_{t}^{(t)} \right] + \frac{1}{4} x_{t}^{T} y_{t}^{(t)}.$$

$$\Rightarrow w_{t}^{(t)$$$$

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3-(a)
$$e_{k} = \frac{1}{N} \sum_{i=1}^{N} (g_{k}(x_{i}) - y_{i})^{2}, k = 0, 1 ... k$$

$$S_{k} = \frac{1}{N} \sum_{i=1}^{N} (g_{k}(x_{i}))^{2}, \quad e_{0} = \frac{1}{N} \sum_{i=1}^{N} y_{i}^{2} \quad (g_{0} = involved)$$
 $e_{N} = \frac{1}{N} \sum_{i=1}^{N} g_{k}(x_{i}) y_{i} \quad \text{in terms} \quad N, \ e_{k}, S_{k}.$

$$e_{N} = \frac{1}{N} \sum_{i=1}^{N} (g_{k}(x_{i}))^{2} - 2g_{k}(x_{i}) y_{i} + y_{i}^{2}$$

$$= \frac{1}{N} \sum_{i=1}^{N} (g_{k}(x_{i}))^{2} - 2\frac{1}{N} \sum_{i=1}^{N} g_{k}(x_{i}) y_{i} + \frac{1}{N} \sum_{i=1}^{N} y_{i}^{2}$$

$$= S_{k} - 2\frac{1}{N} g_{k}(x_{i}) y_{i} + e_{0}$$

$$\Rightarrow \sum_{i=1}^{N} g_{k}(x_{i}) y_{i} = (S_{k} + e_{0} - e_{k}) \times \frac{N}{2}$$

$$\frac{\partial}{\partial x} \left(+ \cos t \left(\frac{\xi}{\xi_{-1}} d_{\xi} g_{k} \right) \right) = \frac{\lambda}{N} \underbrace{\frac{\xi}{\xi_{-1}}}_{\xi_{-1}} \left(d_{\xi} g_{k}(X_{1}) - y_{-1} \right) g_{k}(X_{1})}_{\xi_{-1}} = 0$$

$$\frac{\partial}{\partial x} \left(d_{\xi} g_{k}(X_{1}) - y_{-1} g_{k}(X_{1}) \right) - y_{-1} g_{k}(X_{1})}_{\xi_{-1}} = 0$$

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$$\frac{\partial}{\partial x} \left(d_{\xi} g_{k}(X_{1}) \right) - y_{-1} g_{k}(X_{1}) \right) - y_{-1} g_{k}(X_{1})$$

$$\frac{\partial}{\partial x} \left(d_{\xi} g_{k}(X_{1}) \right) - y_{-1} g_{k}(X_{1}) \right) - y_{-1} g_{k}($$