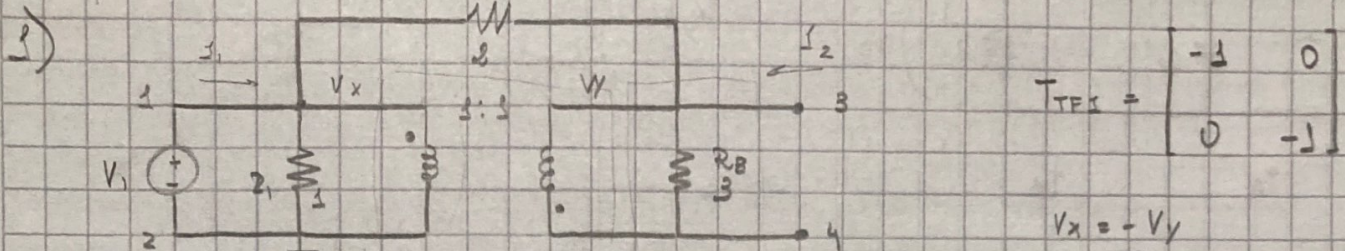


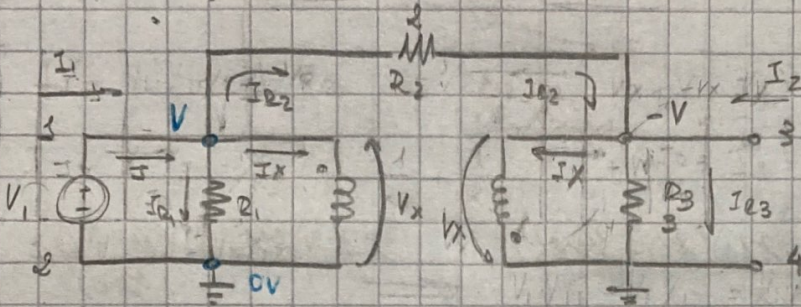
TS6



$$T_{FE1} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$V_x = -V_y$$

$$I_x = I_y$$



$$I_1 = I_{R1} + I_x + I_{R2} = \frac{V_1}{R_1} + I_x + \frac{2V}{R_2}$$

$$I_x + I_{R2} = I_{R3} + I_x$$

$$I_x = I_{R2} - I_{R3} = \frac{2V}{R_2} + \frac{V}{R_3}$$

$$I_1 = \frac{V}{R_1} + \frac{V}{R_3} + \frac{2V}{R_2} - \frac{2V}{R_2} = V \left(\frac{1}{R_1} + \frac{1}{R_3} + \frac{2}{R_2} \right)$$

$$\mathcal{L}_{11} = \frac{V_1}{I_1} \Big|_{I_2=0} = \left(\frac{1}{R_1} + \frac{1}{R_3} + \frac{2}{R_2} \right)^{-1} = \frac{3}{10} = 0,3 \Omega$$

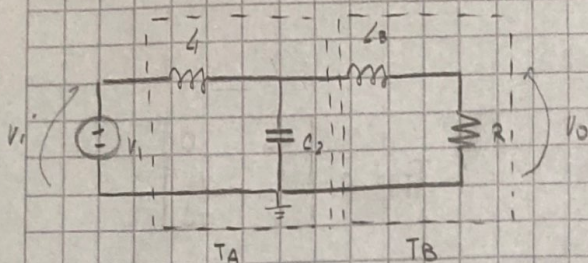
$$\mathcal{L}_{12} = \mathcal{L}_{21} = \frac{V_1}{I_2} \Big|_{I_1=0} = \frac{V_2}{I_1} \Big|_{I_2=0} = \frac{-V_1}{I_1} \Big|_{I_2=0} = -0,3 \Omega$$

$$V_2 = V_{R3} = -V_1$$

$$\mathcal{L}_{22} = \frac{V_2}{I_2} \Big|_{I_1=0} = \frac{-V_1}{I_2} \Big|_{I_1=0} = -\mathcal{L}_{12} = 0,3 \Omega$$

Ej #8

$L_1 = 1,5 \quad L_2 = 4/3 \quad L_3 = 0,5 \quad R = 1$



$$T_A = \begin{bmatrix} s^2 L_1 C_2 + 1 & s L_1 \\ s C_2 & 1 \end{bmatrix}$$

$$A = \frac{V_1}{V_2} \Big|_{I_2=0} \quad B = \frac{V_1}{-I_2} \Big|_{V_2=0}$$

$$T_B = \begin{bmatrix} \frac{s L_3}{R} + 1 & s L_3 \\ \frac{s}{R} & 1 \end{bmatrix}$$

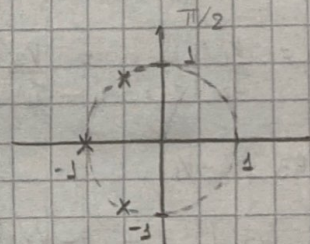
$$C = \frac{I_1}{V_2} \Big|_{I_2=0} \quad D = \frac{I_1}{-I_2} \Big|_{V_2=0}$$

$$T_A, T_B = T_{tot} = \begin{bmatrix} \frac{(4/C_2 + (R + s L_3)(s L_1 + 1/s C_2))}{R/s C_2} & \frac{s L_1 + s L_3 + \frac{s L_1 + s L_3}{1/s C_2}}{1/s C_2} \\ \frac{R + 1/s C_2 + s L_3}{R + s C_2} & \frac{s L_3 + 1/s C_2}{1/s C_2} \end{bmatrix}$$

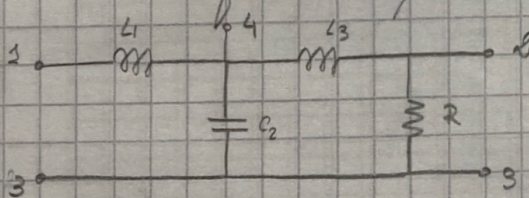
con Python

$$H(s) = \frac{1}{A} = \frac{1}{1,5s + (0,5s + 1)(2s^2 + 1)} = \frac{1}{s^3 + 2s^2 + 2s + 1}$$

$$H(s) = \frac{1}{(s+1)(s+e^{j2/3\pi})(s+e^{-j2/3\pi})}$$



b) Para la referencia para obtener la MAT



$$Y = \begin{bmatrix} 1/s L_1 & 0 & 0 & -1/s L_1 \\ 0 & 1/s L_3 + 1/R & -1/R & -1/s L_3 \\ 0 & -1/R & 1/R + s C_2 & -s C_2 \\ -1/s L_1 & -1/s L_3 & -s C_2 & \frac{1}{s L_1} + \frac{1}{s L_3} + s C_2 \end{bmatrix}$$

$$c) A_{mu}^{id} = A_{13}^{23} = \text{sgn}(2-3) \cdot \text{sgn}(1-3) \frac{y_{13}}{y_{23}} \frac{-23}{-23}$$

(con Python)

$$A_{13}^{23} = \frac{R_1}{s^3 L_1 L_3 + s^2 R C_2 L_1 + s(L_1 + L_3) + R_1} = \frac{1}{s^3 + 2s^2 + 2s + 1}$$