# 6 PIPE, Message Queue and Shared Memory

#### 6.1 Aim

Implement programs for Inter Process Communication using PIPE, Message Queue and Shared Memory

## 6.2 Theory

#### 6.2.1 PIPE

#### • Ordinary PIPE

PIPE is a method for interprocess communication. One end of the pipe is used for writing data and the other end of the pipe is used for reading data. The communication is unidirectional and the pipe is terminated when the process exits.

#### • Named PIPE

In named PIPE, a file is used for storing data from one process which is to be read by another process. Since a file is used, a named PIPE can exist beyond the lifetime of a process. The communication in a named PIPE is bidirectional.

#### 6.2.2 Message Queue

Message queue is a method for interprocess communication in which a linked list stored in the kernel is used by processes to transfer data between processes. Each message queue will have a unique key which is used to identify the queue. So only processes which have these unique key will be able to use the message queue. Bidirectional communication is possible in message queue.

#### 6.2.3 Shared Memory

In interprocess communication using shared memory, a memory space is shared between processes for communication. The shared memory space resides in the address space of the process that creates the shared memory space. Processes which wish to use this memory space must attach the shared memory to its address space. One process can write to the memory location and the other process can read from the memory location.

## 6.3 Algorithm

```
Algorithm 1 Ordinary PIPE

procedure MAIN PROCEDURE

if pipe(p) < 0 then

Throw error and exit

end if

if (pid = fork()) > 0 then

Write the messages to the pipe and wait for child process to terminate

else

read the messages from the pipe,print the messages and exit

end if

end procedure
```

## Algorithm 2 Named Pipe Writer

```
procedure Main
   mkfifo(path,0666)
                                        ▷ Creates the pipe if it does not exist
   while true do
       fd1 = open(path, WRONLY)
                                         ▷ Open the pipe in write only mode
       fgets(str2, 80, stdin)
       write(fd1, str2, strlen(str2)+1)
                                                > write the data into the pipe
       close(fd1)
                                                     \triangleright close the file descriptor
       fd1 = open(path,RDONLY)
                                          ▷ Open the pipe in read only mode
       read(fd1, str1, 80) ▷ read the data from the pipe and print the data
       printf("Reader: % s \n", str1)
       close(fd1)
                                                     \triangleright close the file descriptor
   end while
end procedure
```

### Algorithm 3 Named Pipe Reader

```
procedure MAIN
   mkfifo(path,0666)
                                       ▷ Creates the pipe if it does not exist
   while true do
       fd1 = open(path,RDONLY)
                                         ▷ Open the pipe in read only mode
      read(fd1, str1, 80) \triangleright read the data from the pipe and print the data
      printf("Writer: %s \n", str1)
       close(fd1)
                                                    ▷ close the file descriptor
      fd1 = open(path, WRONLY)
                                         ▷ Open the pipe in write only mode
       fgets(str2, 80, stdin)
       write(fd1, str2, strlen(str2)+1)
                                               > write the data into the pipe
       close(fd1)
                                                    ▷ close the file descriptor
   end while
end procedure
```

## Algorithm 4 Message Queue Writer

```
procedure Main  \begin{array}{l} key = & ftok("progfile",65) \quad \triangleright \mbox{Creates a unique key for the message queue} \\ msgid = & msgget(key,0666|IPC\_CREAT) \quad \triangleright \mbox{Creates the message queue if} \\ it does not exist with key \\ message.mesg\_type = 1 \\ printf("Enter the data to be written ") \\ scanf("%s",message.mesg\_text) \\ msgsnd(msgid,\&\ message,sizeof(message),0) \quad \triangleright \mbox{Sends data to the message} \\ queue \\ printf("Data send is % s \n",message.mesg\_text) \\ end procedure \\ \end{array}
```

### Algorithm 5 Message Queue Reader

```
 \begin{array}{l} \textbf{procedure Main} \\ key = ftok("progfile",65) \quad \rhd \ Creates \ a \ unique \ key \ for \ the \ message \ queue \\ msgid = msgget(key,0666 \mid IPC\_CREAT) \rhd \ Creates \ the \ message \ queue \ if \\ it \ does not \ exist \\ msgrcv(msgid,\&message,sizeof(message),1,0) \quad \rhd \ Read \ message \ from \ the \\ queue \\ printf("The \ data \ recieved \ is \ \%s \ n",message.mesg\_text) \\ msgctl(msgid,IPC\_RMID,NULL) \qquad \rhd \ Destroys \ the \ queue \\ \textbf{end \ procedure} \\ \end{array}
```

## Algorithm 6 Shared Memory Writer

#### procedure Main

```
\mbox{key\_t key} = \mbox{ftok("shmfile",65)} \qquad \rhd \mbox{Create a unique key for the shared} \\ \mbox{memory}
```

int shmid = shmget(key,1024,0666 | IPC\_CREAT)  $\,\,\triangleright$  Create the shared memory location if it does not exist

char \* str = (char \*)shmat(shmid,(void \*)0,0)  $\,\triangleright$  Attach a variable to the shared memory

```
printf("Enter the data to be written ")
```

```
scanf("%s",str) 

▷ Write data to the memory location printf("The data written to the shared memory is %s",str)
```

shmdt(str) > Destroys the variable attached to the shared memory end procedure

## Algorithm 7 Shared Memory Reader

## procedure Main

```
\mbox{key\_t key} = \mbox{ftok}("\mbox{shmfile",65}) \qquad \rhd \mbox{Create a unique key for the shared} \\ \mbox{memory}
```

int shmid = shmget(key,1024,0666 | IPC\_CREAT)  $\,\,\triangleright$  Create the shared memory location if it does not exist

char \* str = (char \*)shmat(shmid,(void \*)0,0)  $\,\triangleright$  Attach a variable to the shared memory

printf("The data read from shared memory is %s \n",str)  $\quad \triangleright$  Print data from shared memory

```
shmdt(str) 

▷ Destroy the variable attached to the shared memory shmctl(shmid,IPC_RMID,NULL) 

▷ Destroy the shared memory end procedure
```

#### 6.4 Code

#### PIPE

```
#include < stdio.h>
   #include < unistd.h>
3 #include < stdlib.h>
_{4} #include < sys / wait.h>
   #define MSGSIZE 16
    \frac{\text{char msg}[][\text{MSGSIZE}]}{\text{msg}[][\text{MSGSIZE}]} = \{ \text{"hello}, \text{ world } \#1 \text{","hello}, \text{ world } \#2 \text{","hello}, \} 
         world #3"};
   int main()
9 {
      char inbuf[MSGSIZE];
10
11
      int p[2], i, pid;
12
      if (pipe(p) < 0)
13
         exit(1);
14
     if((pid = fork()) > 0){
```

```
for (i = 0; i < 3; i++){
16
         printf("Writing message %s to pipe ...\n", msg[i], i);
17
         write(p[1], msg[i], MSGSIZE);
18
19
       wait (NULL);
20
21
22
     else{
       for (i = 0; i < 3; i++) {
23
         read(p[0], inbuf, MSGSIZE);
24
         printf("The parent says % s\n", inbuf);
25
26
       printf("Finished reading");
27
       exit (2);
28
29
     return 0;
30
31 }
```

### Named Pipe Writer Process

```
1 #include <stdio.h>
2 #include <string.h>
3 #include <fcntl.h>
4 #include <sys/stat.h>
5 #include <sys/types.h>
6 #include <unistd.h>
8 int main()
9 {
10
       char * myfifo = "/tmp/myfifo";
11
       mkfifo(myfifo, 0666);
12
13
       char arr1[80], arr2[80];
       while (1)
14
       {
            fd = open(myfifo, O_WRONLY);
16
            fgets(arr2, 80, stdin);
17
            write (fd, arr2, strlen(arr2)+1);
18
            close (fd);
19
20
            fd = open(myfifo, O_RDONLY);
21
            read(fd, arr1, sizeof(arr1));
printf("User2: %s\n", arr1);
22
23
            close (fd);
24
25
       return 0;
26
27 }
```

## Named Pipe Reader Process

```
#include <stdio.h>
#include <string.h>
#include <fcntl.h>
#include <sys/stat.h>
```

```
5 #include <sys/types.h>
6 #include <unistd.h>
7 int main()
8 {
          int fd1;
9
           \begin{array}{l} \textbf{char} * \texttt{myfifo} = \texttt{"/tmp/myfifo";} \\ \texttt{mkfifo} (\texttt{myfifo} , \ 0666); \\ \end{array} 
10
11
12
          char str1[80], str2[80];
13
          while (1)
14
15
                 {\rm fd1} \, = \, {\rm open} \, (\, {\rm myfifo} \, , \! O\_RDONLY) \, ;
16
                 \operatorname{read}(\operatorname{fd1}, \operatorname{str1}, 80);
17
                 printf("User1: %s \n", str1);
                 close (fd1);
19
                 fd1 = open (myfifo,O WRONLY);
20
21
                 fgets(str2, 80, stdin);
                 write (fd1, str2, strlen(str2)+1);
22
23
                 close (fd1);
24
25
          return 0;
26 }
```

#### Message Queue Writer Process

```
1 #include < stdio.h>
2 #include < sys/ipc.h>
_3 #include < sys / msg.h>
  struct mesg_buffer{
      long mesg_type;
6
       char mesg_text[100];
  } message;
8
10
  int main(){
11
       key_t key;
12
       int msgid;
13
       key = ftok("progfile",65);
14
       msgid = msgget(key,0666|IPC_CREAT);
15
       message.mesg_type = 1;
printf("Enter the data to be written ");
16
17
       scanf("%s", message.mesg_text);
18
19
       msgsnd(msgid,\&message,sizeof(message),0);
20
       printf("Data send is %s \n", message.mesg_text);
21
22
       return 0;
23
24 }
```

## Message Queue Reader Process

```
1 #include < stdio.h>
```

```
2 #include < sys/ipc.h>
3 \#include < sys/msg.h >
  struct mesg_buffer{
      long mesg_type;
       char mesg_text[100];
8 } message;
10 int main(){
      key_t key;
11
       int msgid;
12
       key = ftok("progfile",65);
13
       msgid = msgget (key,0666 | IPC CREAT);
14
       msgrcv(msgid,&message, sizeof(message),1,0);
15
       printf("The data recieved is %s \n", message.mesg_text);
16
       msgctl(msgid,IPC RMID,NULL);
17
18
       return 0;
19
```

#### **Shared Memory Writer Process**

```
1 #include < stdio.h>
2 #include < sys / ipc . h>
_3 #include < sys/shm.h>
5 int main(){
         key_t key = ftok("shmfile",65);
6
         int shmid = shmget(key,1024,0666 | IPC_CREAT);
         \begin{array}{lll} \mathbf{char} \ * \ \mathbf{str} &= (\mathbf{char} \ *) \, \mathbf{shmat} \, (\mathbf{shmid} \, , (\mathbf{void} \ *) \, \mathbf{0} \, , \mathbf{0}) \, ; \end{array}
9
10
         printf("Enter the data to be written ");
         scanf("%s", str);
11
         printf("The data written to the shared memory is %s", str);
12
13
         shmdt(str);
14
         return 0;
15
16 }
```

#### **Shared Memory Reader Process**

```
#include < stdio.h>
#include < sys/ipc.h>
#include < sys/shm.h>

int main() {
    key_t key = ftok("shmfile",65);
    int shmid = shmget(key,1024,0666|IPC_CREAT);
    char * str = (char *)shmat(shmid,(void *)0,0);
    printf("The data read from shared memory is %s \n",str);
    shmdt(str);
    shmctl(shmid,IPC_RMID,NULL);
```

```
13 return 0;
14 }
```

# 6.5 Output

• Ordinary PIPE

```
Writing message hello, world #1 to pipe ...
Writing message hello, world #2 to pipe ...
Writing message hello, world #3 to pipe ...
The parent says hello, world #1
The parent says hello, world #2
The parent says hello, world #3
```

• Named PIPE Writer

helloworld

User2: helloworld1

helloworld2

User2: helloworld3

• Named PIPE Reader

User1: helloworld helloworld1

User1: helloworld2

helloworld3

• Message Queue Writer

Enter the data to be written helloworld1 Data send is helloworld1

• Message Queue Reader

The data recieved is helloworld1

• Shared Memory Writer

Enter the data to be written helloworld123
The data written to the shared memory is helloworld123

#### • Shared Memory Reader

The data read from shared memory is helloworld123

### 6.6 Result

#### • Ordinary PIPE

Ordinary PIPE was implemented in C++. The program creates a child reader process using fork while the parent acts as th writer process. The parent writes data to the pipe which is read by the child process.

### • Named PIPE

Named PIPE was implemented in C++. There are two programs, a reader program and a writer program. The reader and writer program creates the named PIPE if it does not exist. The writer PIPE takes user input and writes it to the queue. It then reads the data written by reader program from PIPE and prints the data. The reader process first reads the data from Named PIPE and displays it. It then takes user input and then writes to the named PIPE.

#### • Message Queue

Message Queue was implemented in C++. There are two programs, a reader program and a writer program. The reader and writer program creates a message queue if it does not exist. The writer program takes a user input and writes it to the message queue. The reader program reads the data from the message queue and prints it. The reader program then closes the message queue

## • Shared Memory

Shared Memory was implemented in C++. There are two programs, a reader program and writer program. The reader program and writer program creates a shared memory if it does not exist. The writer program attaches a variable to the shared memory location. It then takes a user input to this variable. This is saved in shared memory. The reader program attaches a variable to the shared memory and prints the variable.