

2015-2

$$P_0 \quad r$$

$$P(t) = P_0 \cdot (1+r)^t \quad t \text{ esb ev wos.}$$

$$P(t^*) = 3P_0 \Rightarrow P_0 \cdot (1+r)^{t^*} = 3P_0$$

$$\Rightarrow (1+r)^{t^*} = 3 \Rightarrow \ln((1+r)^{t^*}) = \ln(3)$$

$$t^* \cdot \ln(1+r) = \ln(3) \Rightarrow t^* = \frac{\ln(3)}{\ln(1+r)} = \frac{\ln(3)}{\ln(1.02)} \Rightarrow t^* = 55,48$$

2016-1

$$\frac{dx}{dt} = 3x(t) - 2y(t)$$

$$\vec{x}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

$$\frac{dy}{dt} = 2x(t) - 2y(t)$$

$$\Rightarrow \begin{bmatrix} \dot{x}(t) \\ \dot{y}(t) \end{bmatrix} = \begin{bmatrix} 3 & -2 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} \quad A = \begin{bmatrix} 3 & -2 \\ 2 & -2 \end{bmatrix}$$

$$\vec{x}'(t) = A\vec{x}(t)$$

$$\vec{x}(t) = e^{\lambda t} \cdot \vec{v} \Rightarrow \vec{x}'(t) = e^{\lambda t} \cdot \lambda \cdot \vec{v}$$

$$(e^{\lambda t})' \cdot \vec{v} = A \cdot (e^{\lambda t}) \cdot \vec{v} \Rightarrow A \cdot \vec{v} = \lambda \vec{v}$$

$$\textcircled{i} \quad \det(A - \lambda I) = 0$$

$$A = \begin{bmatrix} 3 & -2 \\ 2 & -2 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} 3-\lambda & -2 \\ 2 & -2-\lambda \end{bmatrix}$$

$$\det(A - \lambda I) = (3-\lambda)(-2-\lambda) - \underbrace{(-2) \cdot 2}_{-4} = (\lambda-3)(\lambda+2) + 4$$

$$= \lambda^2 - \lambda - 6 + 4 = \boxed{\lambda^2 - \lambda - 2 = 0}$$

$$\begin{aligned} a &= 1 \\ b &= -1 \\ c &= -2 \end{aligned}$$

$$\lambda_{1,2} = \frac{1 \pm \sqrt{1 - 4 \cdot (-2)}}{2} = \frac{1 \pm \sqrt{1+8}}{2}$$

$$= \frac{1 \pm \sqrt{9}}{2} = \frac{1 \pm 3}{2} \Rightarrow \boxed{\lambda_1 = 2} \quad \boxed{\lambda_2 = -1}$$

Mum

$\boxed{N=2}$	$(A - \lambda I) \cdot \vec{v} = 0$
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$$A - 2I = \begin{bmatrix} 3-2 & -2 \\ 2 & -2-2 \end{bmatrix}$$

$A - \lambda I$

$$\det(A - \lambda I) = 0$$

$$= \begin{bmatrix} 1-2 \\ 2-4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 \\ 2 & -4 \end{bmatrix} \cdot \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0 \Rightarrow v_1 - 2v_2 = 0 \Rightarrow \boxed{v_1 = 2v_2}$$

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 2v_2 \\ v_2 \end{pmatrix} = v_2 \begin{pmatrix} 2 \\ 1 \end{pmatrix} \quad \boxed{\vec{v}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}}$$

$$\boxed{\lambda_2 = -1} \quad A - \lambda_2 I = A + I = \begin{bmatrix} 3 & -2 \\ 2 & -2 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 4 & -2 \\ 2 & -1 \end{bmatrix}$$

$$A+I = \begin{bmatrix} 4 & -2 \\ 2 & -1 \end{bmatrix}$$

$\vec{v}$

$$(A+I) \cdot \vec{v} = 0$$

$$\begin{pmatrix} 4 & -2 \\ 2 & -1 \end{pmatrix} \cdot \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0 \quad 4v_1 - 2v_2 = 0$$

$\Rightarrow 2v_1 = v_2$

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} v_1 \\ 2v_1 \end{pmatrix} = v_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad \vec{v}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\boxed{M=2}$$

$$\boxed{\vec{V}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}}$$

$$\boxed{\lambda_2 = -1} \quad \boxed{\vec{V}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}}$$

$$\vec{x}(t) = G_1 \cdot e^{2t} \cdot \begin{pmatrix} 2 \\ 1 \end{pmatrix} + G_2 \cdot e^{-t} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} G_1 \cdot e^{2t} \cdot 2 \\ G_1 \cdot e^{2t} \end{pmatrix} + \begin{pmatrix} G_2 \cdot e^{-t} \\ 2G_2 \cdot e^{-t} \end{pmatrix} = \boxed{\begin{pmatrix} 2G_1 \cdot e^{2t} + G_2 \cdot e^{-t} \\ G_1 \cdot e^{2t} + 2G_2 \cdot e^{-t} \end{pmatrix}}$$

$$\vec{X}(0) = \begin{pmatrix} 2C_1 + C_2 \\ C_1 + 2C_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 5 \end{pmatrix}$$

$$X(0) = 1$$

$$Y(0) = 5$$

$$2C_1 + C_2 = 1 \Rightarrow \boxed{C_2 = 1 - 2C_1} \quad (\Rightarrow) \quad C_2 = 1 - 2(-1)$$

$$= 1 + 2$$

$$C_1 + 2C_2 = 5 \Rightarrow C_1 + 2 \cdot [1 - 2C_1] = 5 \quad = 3$$

$$\begin{aligned} &\Rightarrow C_1 + 2 - 4C_1 = 5 \Rightarrow -3C_1 + 2 = 5 \Rightarrow 2 - 5 = 3C_1 \\ &\Rightarrow 3C_1 = -3 \Rightarrow \boxed{C_1 = -1} \quad \boxed{C_2 = 3} \end{aligned}$$

$$|G_1 = -1|$$

$$|G_2 = 3|$$

$$\vec{X}(t) = \begin{pmatrix} 2G_1 e^{2t} + G_2 \cdot e^{-t} \\ G_1 \cdot e^{2t} + 2G_2 \cdot e^{-t} \end{pmatrix} = \begin{pmatrix} -2 \cdot e^{2t} + 3e^{-t} \\ -e^{2t} + 6e^{-t} \end{pmatrix}$$

$$\vec{X}(t) = \begin{pmatrix} -2e^{2t} + 3e^{-t} \\ -e^{2t} + 6e^{-t} \end{pmatrix} \rightarrow \text{Alternativus a)}$$

2016-2

$$y'' - 2y' + 2y = 0$$

$$y(x) = e^{rx} \Rightarrow$$

$$y'(x) = r \cdot e^{rx}$$

$$y''(x) = r^2 e^{rx}$$

$$\Rightarrow r^2 \cdot e^{rx} - 2 \cdot r \cdot e^{rx} + 2 \cdot e^{rx} = 0$$

$$\Rightarrow (r^2 - 2r + 2) \cdot \underline{e^{rx}} = 0 \Rightarrow r^2 - 2r + 2 = 0$$

$$r^2 - 2r + 2 = 0$$

$$\boxed{a=1} \quad \boxed{b=-2} \quad \boxed{c=2}$$

$$r_{1,2} = \frac{2 \pm \sqrt{4 - 4 \cdot 2}}{2} = \frac{2 \pm \sqrt{4 - 8}}{2} = \frac{2 \pm \sqrt{-4}}{2}$$

$$= \frac{2 \pm 2\sqrt{-1}}{2} = 1 \pm i\sqrt{1} = 1 \pm i \quad \left| \begin{array}{l} a+bi \\ a-bi \end{array} \right.$$

$y_1(x) = e^{ax} \cdot \cos(bx)$   
 $y_2(x) = e^{ax} \cdot \sin(bx)$

$$y_1(x) = e^x \cdot \cos(x)$$

$$y_2(x) = e^x \cdot \sin(x)$$

$$Y(\omega) = G_1 \cdot Y_1(\omega) + G_2 \cdot Y_2(\omega)$$

$$G_1 = G_2 = 1$$

$$= G_1 \cdot e^x \cdot \cos(\omega) + G_2 \cdot e^x \cdot \sin(\omega)$$

$$\boxed{Y(\omega) = G_1 \cdot e^x \cdot \cos(\omega) + G_2 \cdot e^x \cdot \sin(\omega)} \quad (1)$$

$$Y'(x) = G_1 \cdot \left[ \underbrace{(e^x)^1}_{e^x} \cdot \cos(\omega) + e^x \cdot (\cos(\omega))' \right] \\ + G_2 \cdot \left[ \underbrace{(e^x)^1}_{e^x} \cdot \sin(\omega) + e^x \cdot (\sin(\omega))' \right]$$

$$y(x) = C_1 \cdot [e^x \cdot \cos(x) - e^x \cdot \sin(x)] + C_2 \cdot [e^x \cdot \sin(x) + e^x \cdot \cos(x)] \quad (2)$$

$$y(0) = 1 \Rightarrow y(0) = C_1 = 1 \Rightarrow C_1 = 1$$

$$y'(0) = 2 \Rightarrow y'(0) = C_1 + C_2 = 2 \Rightarrow 1 + C_2 = 2$$

$$\Rightarrow C_2 = 2 - 1 = 1 \Rightarrow C_2 = 1$$

$$y(x) = e^x \cdot [\cos(\omega x) + \sin(\omega x)]$$

Akkordlösung

2017 - 1

$$dp - r \cdot p \left(1 - \frac{p}{K}\right) dt = 0$$

$$dp = r \cdot p \left(1 - \frac{p}{K}\right) dt$$

$$\frac{dp}{p \left(1 - \frac{p}{K}\right)} = r \cdot dt \Rightarrow \frac{K \cdot dp}{(p(K-p))} = r dt$$

$$p \left(1 - \frac{p}{K}\right) = \frac{p}{K} \cdot K \left(1 - \frac{p}{K}\right) = \frac{p}{K} \cdot (K-p) = \frac{p(K-p)}{K}$$

$$\frac{dp}{\rho(k-\rho)} = \frac{r}{k} dt$$

$$\int \left[ \frac{dp}{\rho(k-\rho)} \right] = \int \frac{r}{k} dt$$

$$\frac{r \cdot t + C}{k}$$

$$\Rightarrow \int \frac{dp}{\rho(k-\rho)} = \frac{r \cdot t + C}{k} \quad (*)$$

$$\frac{1}{\rho(\kappa-\rho)} = \frac{A}{\rho} + \frac{B}{(\kappa-\rho)}$$

•  $\rho(\kappa-\rho)$

$$1 = A \cdot (\kappa - \rho) + B \cdot \rho \quad \left. \right\} = A \cdot \kappa - A \cdot \rho + B \rho \\ = A \cdot \kappa + (B - A) \cdot \rho$$

$$A \cdot \kappa + (B - A) \cdot \rho = 1 \Rightarrow \begin{array}{l} B - A = 0 \\ A \cdot \kappa = 1 \end{array} \Rightarrow \boxed{\begin{array}{l} B = A \\ A = \frac{1}{\kappa} \end{array}} \quad \boxed{B = \frac{1}{\kappa}}$$

$$\frac{1}{\rho(k-\rho)} = \frac{1}{k} \cdot \left[ \frac{1}{\rho} + \frac{1}{k-\rho} \right] \quad / \int d\rho$$

$$\int \frac{d\rho}{\rho(k-\rho)} = \frac{1}{k} \cdot \left[ \int \frac{d\rho}{\rho} + \int \frac{d\rho}{(k-\rho)} \right]$$

$w = k-\rho$   
 $dw = -d\rho$   
 $\int -\frac{dw}{w} = -\int \frac{dw}{w}$

$$\frac{1}{k} \cdot \left[ \ln(|\rho|) - \ln(|k-\rho|) \right] + C_2 = -\frac{\ln|w|}{w} = -\ln|k-\rho|$$

$$\frac{1}{k} \left[ \ln |\rho| - \ln |k-\rho| \right] + G_2 = \frac{r \cdot t}{k} + C/k$$

$$\ln \left| \frac{\rho}{k-\rho} \right| + G_2 \cdot k = r \cdot t + C \cdot k$$

$$\ln \left| \frac{\rho}{k-\rho} \right| = r \cdot t + \underbrace{C - k - G_2 \cdot k}_{C_3}$$

$$\ln \left| \frac{\rho}{\kappa - \rho} \right| = r \cdot t + C_3$$

$A > 0$

$$\Rightarrow e^{r \cdot t + C_3} = \left| \frac{\rho}{\kappa - \rho} \right| \Rightarrow e^{r \cdot t} \cdot e^{C_3} = \left| \frac{\rho}{\kappa - \rho} \right|$$

$$e^{rt} \cdot A = \left| \frac{\rho}{\kappa - \rho} \right| \Rightarrow \frac{\rho}{\kappa - \rho} = \underbrace{(\pm A)}_{B=1} e^{rt}$$

$$\frac{P}{K-P} = B \cdot e^{rt} \Rightarrow P = B \cdot e^{rt} \cdot K - P \cdot B \cdot e^{rt}$$

$$P + P \cdot B \cdot e^{rt} = B \cdot e^{rt} \cdot K$$

$$P(1 + B \cdot e^{rt}) = B \cdot e^{rt} \cdot K$$

$$P(t) = \frac{B \cdot e^{rt} \cdot K}{1 + B \cdot e^{rt}} = \frac{B \cdot K}{e^{-rt} + B}$$

$$\rho(t) = \frac{B \cdot K}{e^{-r \cdot t} + B}$$

$$\rho(0) = \rho_0$$

$$\rho(0) = \frac{B \cdot K}{1 + B} = \rho_0 \Rightarrow BK = \rho_0 + D \cdot \rho_0$$

$$\Rightarrow B(K - \rho_0) = \rho_0 \Rightarrow B = \frac{\rho_0}{K - \rho_0}$$

$$P(t) = \frac{\frac{P_0}{(k-P_0)} \cdot k \cdot (k-P_0)}{e^{-rt} + \left(\frac{P_0}{k-P_0}\right) \cdot (k-P_0)}$$

Alternative 6)

$$= \frac{\frac{P_0 \cdot k}{(k-P_0) \cdot e^{-rt} + P_0}}{1} = P(t)$$

2017-2

$$\frac{dx}{dt} = 3x(t) - 5y(t)$$

$$\frac{dy}{dt} = x(t) - y(t)$$

$$\begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix} = \begin{pmatrix} 3 & -5 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$
$$\vec{x}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$
$$A = \begin{bmatrix} 3 & -5 \\ 1 & -1 \end{bmatrix} \Rightarrow \vec{x}'(t) = A \cdot \vec{x}(t)$$

$$\boxed{\vec{x}(t) = e^{\lambda t} \cdot \vec{v}} \Rightarrow \boxed{\vec{x}'(t) = \lambda \cdot e^{\lambda t} \cdot \vec{v}}$$

$$\cancel{\lambda \cdot e^{\lambda t} \cdot \vec{v}} = A \cdot \cancel{e^{\lambda t} \cdot \vec{v}} \Rightarrow \boxed{A \vec{v} = \lambda \vec{v}}$$

$$A - \lambda I = \begin{pmatrix} 3-\lambda & -5 \\ 1 & -1-\lambda \end{pmatrix}$$

$$\det(A - \lambda I) = (3-\lambda)(-1-\lambda) - (-5) \cdot 1 = (\lambda-3)(\lambda+1) + 5$$

$$= \lambda^2 - 2\lambda - 3 + 5 = \lambda^2 - 2\lambda + 2$$

$$\det(A - \lambda I) = \boxed{\lambda^2 - 2\lambda + 2 = 0}$$

$$\boxed{\begin{array}{l} a = 1 \\ b = -2 \\ c = 2 \end{array}}$$

$$\lambda_{1,2} = \frac{2 \pm \sqrt{4 - 4 \cdot 2}}{2} = \frac{2 \pm \sqrt{4 - 8}}{2} = \frac{2 \pm \sqrt{-4}}{2}$$

$$= \frac{2 \pm 2\sqrt{-1}}{2} = 1 \pm i\sqrt{1} = 1 \pm i$$

$$\boxed{\begin{array}{l} \lambda_1 = 1+i \\ \lambda_2 = 1-i \end{array}}$$

$$\boxed{\lambda_1 = 1+i}$$

$$A - \lambda I = A - (1+i)I = \begin{pmatrix} 3 - (1+i) & -5 \\ 1 & -1 - (1+i) \end{pmatrix}$$

$$= \begin{pmatrix} 2-i & -5 \\ 1 & -2-i \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0$$

$$(2-i)v_1 - 5v_2 = 0 \Rightarrow (2-i)v_1 = 5v_2 \Rightarrow \boxed{v_2 = \frac{(2-i)}{5}v_1}$$

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} v_1 \\ \frac{(2-\delta)}{5} \cdot v_1 \end{pmatrix} = \begin{pmatrix} 1 \\ \frac{(2-\delta)}{5} \end{pmatrix} \cdot v_1 =$$

$$\boxed{\vec{v} = \begin{pmatrix} 5 \\ 2-i \end{pmatrix}}$$

$$\boxed{\Delta = 1-i}$$

$$A - (1-i) \cdot I = \begin{pmatrix} 3-(1-i) & -5 \\ 1 & -1-(1-i) \end{pmatrix}$$

$$= \begin{pmatrix} 2+i & -5 \\ 1 & -2+i \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0$$

$$(2+i) \cdot v_1 - 5v_2 = 0 \Rightarrow (2+i)v_1 = 5v_2 \Rightarrow \boxed{v_2 = \frac{(2+i)v_1}{5}}$$

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} v_1 \\ \frac{(z+i)v_1}{5} \end{pmatrix} = v_1 \cdot \begin{pmatrix} 1 \\ \frac{(z+i)}{5} \end{pmatrix} =$$

$$\boxed{\vec{v}_2 = \begin{pmatrix} 5 \\ z+i \end{pmatrix}}$$

$$\boxed{\lambda_1 = 1+i} \quad \boxed{\vec{v}_1 = \begin{pmatrix} 5 \\ 2-i \end{pmatrix}} \quad \boxed{\lambda_2 = 1-i} \quad \boxed{\vec{v}_2 = \begin{pmatrix} 5 \\ 2+i \end{pmatrix}}$$

$$\boxed{\vec{x}(0) = \begin{pmatrix} 3 \\ 1 \end{pmatrix}} \quad e^t \cdot e^{it} = e^t \cdot [\cos(t) + i \cdot \sin(t)]$$

$$\vec{x}(t) = C_1 \cdot e^{(1+i)t} \begin{pmatrix} 5 \\ 2-i \end{pmatrix} + C_2 \cdot e^{(1-i)t} \begin{pmatrix} 5 \\ 2+i \end{pmatrix}$$

$$= C_1 \cdot [e^t \cdot (\cos(t) + i \cdot \sin(t))] \begin{pmatrix} 5 \\ 2-i \end{pmatrix}$$

$$+ C_2 \cdot [e^t \cdot (\cos(t) - i \cdot \sin(t))] \cdot \begin{pmatrix} 5 \\ 2+i \end{pmatrix}$$

$$\begin{aligned} e^{(1-i)t} &= e^t \cdot e^{-it} \\ &= e^t \cdot [\cos(-t) + i \cdot \sin(-t)] \\ &= e^t \cdot [\cos(t) - i \cdot \sin(t)] \end{aligned}$$

$$= G_1 \cdot \left[ e^{t \cdot \cos(t)} + i \cdot e^{t \cdot \sin(t)} \right] \cdot \left( \frac{5}{z - \sigma} \right) \\ + (G_2 \cdot \left[ t e^{t \cdot \cos(t)} - \sigma \cdot e^{t \cdot \sin(t)} \right] \cdot \left( \frac{5}{z + \sigma} \right))$$

$$= \left( \frac{(G_1 \cdot e^{t \cdot \cos(t)} \cdot 5 + G_1 \cdot \sigma \cdot e^{t \cdot \sin(t)} \cdot 5)}{(z - \sigma)} \right. \\ \left. + \frac{(G_2 \cdot t e^{t \cdot \cos(t)} + (z - \sigma) \cdot (G_1 \cdot e^{t \cdot \sin(t)} \cdot i)) \cdot 5}{(z + \sigma)} \right)$$

$$+ \left( \begin{array}{l} C_2 \cdot e^t \cdot \cos(t) \cdot 5 - i \cdot e^t \cdot \sin(t) \cdot (z \cdot 5) \\ G \cdot e^t \cdot \cos(t) (z+i) - (z \cdot e^t \cdot i \cdot \sin(t)) (z+i) \end{array} \right)$$

$$= \left( \begin{array}{l} 5C_1 \cdot e^t \cdot \cos(t) + 5G_1 \cdot i \cdot e^t \cdot \sin(t) + 5G_2 \cdot e^t \cdot \cos(t) \\ - 5C_2 \cdot i \cdot e^t \cdot \sin(t) \\ (z-i)(G_1 e^t \cdot \cos(t) + (z-i) \cdot G_1 \cdot e^t \sin(t) \cdot i) \\ + (z \cdot e^t \cdot \cos(t)) \cdot (z+i) - G_2 \cdot e^t \cdot i \cdot \sin(t) \cdot (z+i) \end{array} \right)$$

$$\vec{x}(0) = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$$\vec{x}(0) = \begin{pmatrix} 5c_1 + 5c_2 \\ (2-i) \cdot c_1 + c_2(2+i) \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$$① \boxed{c_1 + c_2 = \frac{3}{5}}$$
$$② \boxed{(2-i) \cdot c_1 + (2+i) \cdot c_2 = 1}$$
$$\boxed{c_1 = \frac{3}{5} - c_2}$$

$$(2-i) \cdot \left( \frac{3}{5} - c_2 \right) + (2+i) \cdot (c_2) = 1$$

$$\Rightarrow \cancel{\frac{6}{5}} - \cancel{2c_2} - \cancel{i \cdot \frac{3}{5}} + \cancel{i \cdot c_2} + \cancel{2c_2} + \cancel{i \cdot c_2} = 1$$

$$2i \cdot c_2 + \frac{3}{5} \cdot (2-i) = 1$$

$$\underline{2i \cdot c_2 = 1 - \frac{3}{5}(2-i)} = \frac{5}{5} - \frac{(6-3i)}{5} = \underline{\underline{\frac{3i-1}{5}}}$$

$$2i \cdot G_2 = \left(\frac{3i-1}{5}\right) \Rightarrow G_2 = \left(\frac{3i-1}{5}\right) \cdot \frac{1}{2i}$$

$$= \frac{1}{10} \cdot \left( \underbrace{\frac{3i-1}{i}}_{\text{Factor out } i} \right) = \frac{1}{10} \cdot \left( \frac{3i^2 - i}{i^2} \right) = \frac{1}{10} \left( \frac{-3-i}{-1} \right)$$

$$= \frac{1}{10} \cdot (3+i) \quad \boxed{G_2 = \left( \frac{3+i}{10} \right)} \quad \boxed{G_1 = \left( \frac{3-i}{10} \right)}$$

$$G = \frac{3}{5} - G_2 = \frac{3}{5} - \left( \frac{3+i}{10} \right) = \frac{6}{10} - \frac{(3+i)}{10} = \frac{6-3-i}{10} = \boxed{\frac{3-i}{10}}$$

$$\vec{X}(t) = \begin{pmatrix} 5C_1 \cdot e^t \cdot \cos(t) + 5(C_1 \cdot i \cdot e^t \cdot \sin(t)) \\ + 5C_2 \cdot e^t \cdot \cos(t) - 5(C_2 \cdot i \cdot e^t \cdot \sin(t)) \\ \hline (2-i) \cdot (C_1 \cdot e^t \cdot \cos(t) + (2-i) \cdot (C_1 \cdot e^t \cdot \sin(t)) \cdot i \\ + (C_2 \cdot e^t \cdot \cos(t))(2+i) - C_2 e^t \cdot i \sin(t)(2+i) \end{pmatrix}$$

$$C_1 = \frac{3-i}{10}$$

$$C_2 = \frac{3+i}{10}$$

$$\begin{aligned} & \frac{5 \cdot (3-i)}{10} \cdot e^t \cdot \cos(t) + 5 \cdot \left(\frac{3-i}{10}\right) \cdot i \cdot e^t \cdot \sin(t) \\ & + 5 \cdot \left(\frac{3+i}{10}\right) \cdot e^t \cdot \cos(t) - 5 \cdot \left(\frac{3+i}{10}\right) \cdot i \cdot e^t \cdot \sin(t) \end{aligned}$$

$$= \frac{(3-i)}{2} \cdot e^t \cdot \cos(t) + \frac{(3-i)}{2} \cdot i \cdot e^t \cdot \sin(t)$$

$\frac{3i - i^2}{2} = \frac{3i - (-1)}{2} = \frac{3i+1}{2}$   
 $\frac{(3i+1)}{2} - \frac{(3i-1)}{2}$

$$+ \left( \frac{3+i}{2} \right) \cdot e^t \cdot \cos(t) - \frac{(3+i)}{2} \cdot i \cdot e^t \cdot \sin(t) = \frac{2}{2} = 1$$

$\frac{(3-i) + (3+i)}{2} = \frac{6}{2} = 3$

$\frac{3i + i^2}{2} = \frac{3i - 1}{2}$

$$= \left[ \frac{(3-i)}{2} \cdot e^t \cdot \cos(t) + \left( \frac{3i+1}{2} \right) \cdot e^t \cdot \sin(t) \right] = 3 \cdot e^t \cdot \cos(t) + e^t \cdot \sin(t)$$

$$+ \left( \frac{3+i}{2} \right) \cdot e^t \cdot \cos(t) - \frac{(3i-1)}{2} \cdot e^t \cdot \sin(t)$$

$$\vec{x}(t) = \begin{pmatrix} 3e^t \cdot \cos(t) + e^t \cdot \sin(t) \\ e^t \cdot \sin(t) + e^t \cdot \cos(t) \end{pmatrix}$$

→ Alternative b)

$$= (2-i) C_1 e^{t \cdot \cos(t)} + (2-i) \cdot (C_1 \cdot e^{t \cdot \cos(t)} \cdot i)$$

$$C_1 = \frac{3-i}{10}$$

$$+ (5 \cdot e^{t \cdot \cos(t)} (2+i) - C_2 \cdot e^{t \cdot i \cdot \sin(t)} (2+i)) \quad C_2 = \frac{3+i}{10}$$

$$= \left( \frac{(2-i)(3-i)}{10} \right) e^{t \cdot \cos(t)} + \left( \frac{(2-i) \cdot (3-i) \cdot i}{10} \right) \cdot e^{t \cdot \sin(t)}$$

$$+ \left( \frac{(3+i) \cdot (2+i)}{10} \right) \cdot e^{t \cdot \cos(t)} - \left( \frac{(3+i) \cdot i \cdot (2+i)}{10} \right) \cdot e^{t \cdot \sin(t)}$$

$$\frac{(2-i)(2-i)}{10} + \frac{(3+i)(2+i)}{10} = \frac{6-2i-3i+t^2}{10} + \frac{6+3i+2i+t^2}{10} = \frac{12}{10} = \frac{10}{10} - 1$$

$$= \left( e^t \cdot \cos(t) + e^t \cdot \sin(t) \right)$$

$$\frac{(2-i)(3-i) \cdot i}{10} - \frac{(3+i)(2+10) \cdot i}{10}$$

$$= \frac{[6-2i-3i+i^2] \cdot i}{10} - \frac{[6+3i+2i+i^2] \cdot i}{10}$$

$$= \frac{1}{10} \cdot i \cdot \left[ \cancel{\frac{10-i}{10}} - \cancel{\frac{6-3i-2i-i^2}{10}} \right] - \frac{1 \cdot i}{10} \cdot (10i) = 1$$

2018-1

a) Si  $m=2, n=1, \rho=1, q=1, t=0$

$$\left( \frac{d^2y}{dx^2} \right) \left( \frac{dy}{dx} \right) + y = 0$$

~~$\times$~~  No tres  
ni numeros  
de segundo orden  ~~$\times$~~

b) Si:  $m=1, n=1, p=0, q=1, t=0$

$$\left(\frac{dy}{dx}\right) + 1 = x$$

L'ordre  
No homogene  
Diverg. Ordre

c) Se  $m=1, n=2, p=1, q=1, \epsilon=1$

$$\left(\frac{dy}{dx}\right) \cdot \left(\frac{dy}{dx}\right) + x \cdot y = 2x$$

No horogos  
No best  
De orden uno

X

d)  $m=2, n=1, p=1, q=1, \epsilon=0$

$$\left(\frac{d^2y}{dx^2}\right) \cdot \left(\frac{dy}{dx}\right) + 0 \cdot y = x$$

No best  
No horogos  
Segundo orden  
(oportunamente constante)

✓  
Alternativa  
d)

2018 - 2

$$\frac{dp}{dt} = c \cdot r \cdot \left(1 - \left(\frac{p(t)}{\kappa}\right) - \left(\frac{p(t)}{\kappa}\right)^2\right)$$

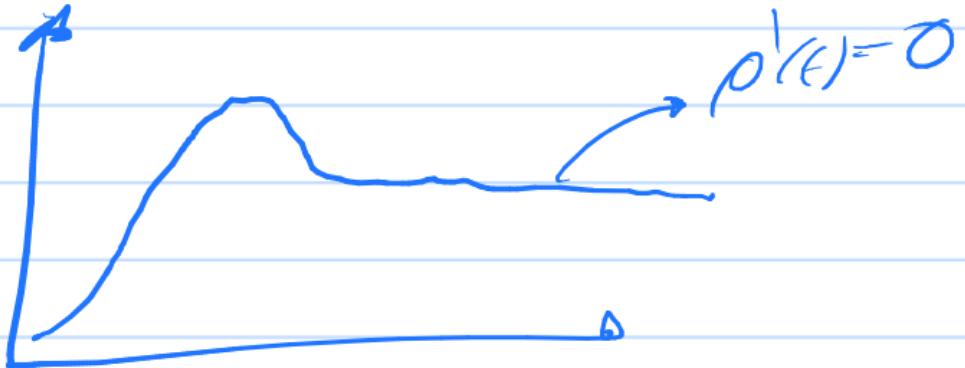
$p(t)$

$\curvearrowright$

$$\frac{dp}{dt} = c \cdot r \cdot \left(1 - \left[\frac{p(t)}{\kappa}\right] - \left[\frac{p(t)}{\kappa}\right]^2\right) \quad \left| \begin{array}{l} \text{lim} \\ \rightarrow \infty \end{array} \right.$$

$$\left| \begin{array}{l} \text{lim} \\ \rightarrow \infty \end{array} \right. p(t) = \cancel{(c \cdot r)} \left(1 - \left[\cancel{\frac{\text{lim}}{\infty} p(t)}\right] - \left[\cancel{\frac{\text{lim}}{\infty} p(t)}\right]^2\right)$$

$\circ$   $\left| \begin{array}{l} \text{lim} \\ \rightarrow \infty \end{array} \right. p(t) = P_{TER}$



$$\mu = \frac{\rho_{tem}}{k}$$

$$0 = 1 - \left( \frac{\rho_{tern}}{k} \right) - \left( \frac{\rho_{tem}}{\omega} \right)^2$$

$$\begin{aligned}\omega &= 1 \\ b &= 1 \\ c &= -1\end{aligned}$$

$$0 = 1 - \mu - \mu^2 \rightarrow \mu^2 + \mu - 1 = 0$$

$$\mu_{1,2} = \frac{-1 \pm \sqrt{1+4(-1)}}{2} = \frac{-1 \pm \sqrt{5}}{2}$$

$$\mu_{1,2} = -\frac{1 \pm \sqrt{5}}{2}$$

$$\mu_1 = -\frac{1-\sqrt{5}}{2} < 0$$

$$\mu_2 = \frac{\sqrt{5}-1}{2} \quad \checkmark \quad \mu_2 = \frac{\rho_{\text{term}}}{K} \quad \Rightarrow \quad \frac{\rho_{\text{term}}}{K} = \left( \frac{\sqrt{5}-1}{2} \right)$$

$$\rho_{\text{term}} = \left( \frac{\sqrt{5}-1}{2} \right) \cdot K$$

Alternativ b)

2019-1

$$\frac{dA}{dt} = k \cdot A^2 \Rightarrow dA \cdot A^{-2} = k \cdot dt$$

$$\int A^{-2} dA = \int k dt + C \Rightarrow \left( \frac{A^{-1}}{-1} \right) = k \cdot t + C$$

$$\Rightarrow -\frac{1}{A} = kt + C \Rightarrow -\frac{1}{(kt+C)} = A(t)$$

$$A(0) = 100 \Rightarrow -\frac{1}{C} = 100 \Rightarrow C = -\frac{1}{100}$$

$$A(1) = -\frac{1}{(k+c)} = 50$$

$$\Rightarrow \left(\frac{1}{k+c}\right) = -50 \Rightarrow k+c = -\frac{1}{50}$$

$$k - \frac{1}{100} = -\frac{1}{50} \Rightarrow k = -\frac{1}{50} + \frac{1}{100} = -\frac{2}{100} + \frac{1}{100}$$

$$\boxed{k = -\frac{1}{100}}$$

$$A(t) = -\frac{1}{(k \cdot L \cdot C)} = -\frac{1}{\left(-\frac{1}{100} \cdot t - \frac{1}{100}\right)}$$

$$= \frac{1}{\left(\frac{t+1}{100}\right)} = \frac{100}{t+1}$$

$$A(t) = \frac{100}{t+1}$$

$$A(4) = \frac{100}{4+1} = \frac{100}{5} = 20 \text{ [go]} \quad \boxed{\text{Alternative 9}}$$

2019-2

$$\frac{dT}{dt} = k \cdot (A - t)$$

$$u = A - t \quad du = -dt$$

$$\int -\frac{du}{u} = -\ln|u| = -\ln|A-t|$$

$$\Rightarrow \frac{dT}{A-t} = k \cdot dt \Rightarrow \int \frac{dT}{A-t} = kt + C_1$$

$$\Rightarrow -\ln|A-t| = kt + C \Rightarrow \ln|A-t| = -kt - C$$

$$e^{-kt} \cdot e^{-C} = |A-t| \xrightarrow{\text{BXO}} D \cdot e^{-k \cdot t} = |A-t| \quad ?$$

$$\Rightarrow A-t = \underbrace{\pm B \cdot e^{-k \cdot t}}_{C=\pm B} + f_0 = A - C = 2A$$

$$C = \pm B$$

$$\Rightarrow \frac{A-2A}{C=-A} = C$$

$$\Rightarrow A-t = C \cdot e^{-k \cdot t}$$

$$\boxed{A-C \cdot e^{-kt} = t}$$

$$\boxed{H(t) = A - C \cdot e^{-kt}} \quad \Rightarrow H(t) = A - (-4)e^{-kt} \\ = A + 4e^{-kt}$$

$$= A \cdot (1 + e^{-k \cdot t})$$

$$H(t) = A \cdot (1 + e^{-k \cdot t})$$

$$+_{(t^*)} = 1,5 \cdot A \Rightarrow +_{(t^*)} = \frac{3}{2} \cdot A$$

$$\Rightarrow A \cdot (1 + e^{-k \cdot t^*}) = \frac{3A}{2}, \quad \frac{3}{2} - 1 = \frac{3}{2} - \frac{2}{2} = \frac{1}{2}$$

$$1 + e^{-k \cdot t^*} = \frac{3}{2} \Rightarrow e^{-k \cdot t^*} = \frac{3}{2} - 1 = \frac{1}{2}$$

$$e^{-kt^*} = \left( + \frac{1}{2} \right) \quad / \ln(\cdot)$$

$$\ln(e^{-kt^*}) = \ln\left(\frac{1}{2}\right)$$

$$-kt^* = -\ln(2) \Rightarrow kt^* = \ln(2)$$

$t^* = \frac{\ln(2)}{k}$

A denotes  $\delta$