

2015-2

$\rho_0$        $r$

$$\rho(t) = \rho_0 \cdot (1+r)^t$$

$t$  est en ANS.

$$\rho(t^*) = 3\rho_0 \Rightarrow \cancel{\rho_0} \cdot (1+r)^{t^*} = 3\cancel{\rho_0}$$

$$\Rightarrow (1+r)^{t^*} = 3 \Rightarrow \ln((1+r)^{t^*}) = \ln(3)$$

$$t^* \cdot \ln(1+r) = \ln(3) \Rightarrow t^* = \frac{\ln(3)}{\ln(1+r)} = \frac{\ln(3)}{\ln(1.02)} \Rightarrow t^* = 55,48$$

2016-1

$$\frac{dx}{dt} = 3x(t) - 2y(t)$$

$$\frac{dy}{dt} = 2x(t) - 2y(t)$$

$$\vec{x}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

$$\Rightarrow \begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 3 & -2 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & -2 \\ 2 & -2 \end{bmatrix}$$

$$\vec{x}'(t) = A \vec{x}(t)$$

$$\vec{x}(t) = e^{\lambda t} \cdot \vec{v}$$

$$\vec{x}'(t) = e^{\lambda t} \cdot \lambda \cdot \vec{v}$$

$$e^{\lambda t} \cdot \lambda \cdot \vec{v} = A \cdot e^{\lambda t} \cdot \vec{v} \Rightarrow A \cdot \vec{v} = \lambda \vec{v}$$

$$(i) \det(A - \lambda I) = 0$$

$$A = \begin{bmatrix} 3 & -2 \\ 2 & -2 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} 3 - \lambda & -2 \\ 2 & -2 - \lambda \end{bmatrix}$$

$$\det(A - \lambda I) = (3 - \lambda)(-2 - \lambda) - \underbrace{(-2) \cdot 2}_{-4} = (\lambda - 3)(\lambda + 2) + 4$$

$$= \lambda^2 - \lambda - 6 + 4 = \boxed{\lambda^2 - \lambda - 2 = 0}$$

$$\begin{aligned} a &= 1 \\ b &= -1 \\ c &= -2 \end{aligned}$$

$$\lambda_{1,2} = \frac{1 \pm \sqrt{1 - 4 \cdot (-2)}}{2} = \frac{1 \pm \sqrt{1 + 8}}{2}$$

$$= \frac{1 \pm \sqrt{9}}{2} = \frac{1 \pm 3}{2} \Rightarrow \boxed{\lambda_1 = 2} \quad \boxed{\lambda_2 = -1}$$

*nur*

$$\boxed{\lambda = 2} \quad (A - \lambda I) \cdot \vec{v} = 0$$

$$\det(A - \lambda I) = 0$$

$$A - \lambda I$$

$$A - 2I = \begin{bmatrix} 3-2 & -2 \\ 2 & -2-2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & -2 \\ 2 & -4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 \\ 2 & -4 \end{bmatrix} \cdot \underbrace{\begin{bmatrix} v_1 \\ v_2 \end{bmatrix}}_{\vec{v}} = 0 \Rightarrow v_1 - 2v_2 = 0 \Rightarrow \boxed{v_1 = 2v_2}$$

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 2v_2 \\ v_2 \end{pmatrix} = v_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\boxed{\vec{v}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}}$$

$$\boxed{\lambda_2 = -1}$$

$$A - \lambda I = A + I = \begin{bmatrix} 3 & -2 \\ 2 & -2 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 4 & -2 \\ 2 & -1 \end{bmatrix}$$

$$A+I = \begin{bmatrix} 4 & -2 \\ 2 & -1 \end{bmatrix}$$

 $\vec{v}$ 

$$(A+I) \cdot \vec{v} = 0 \quad \begin{pmatrix} 4 & -2 \\ 2 & -1 \end{pmatrix} \cdot \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0 \quad \begin{aligned} 4v_1 - 2v_2 &= 0 \\ \Rightarrow 2v_1 &= v_2 \end{aligned}$$

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} v_1 \\ 2v_1 \end{pmatrix} = v_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad \vec{v}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\boxed{\lambda_1 = 2}$$

$$\boxed{\vec{v}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}}$$

$$\boxed{\lambda_2 = -1}$$

$$\boxed{\vec{v}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}}$$

$$\vec{x}(t) = C_1 \cdot e^{2t} \cdot \begin{pmatrix} 2 \\ 1 \end{pmatrix} + C_2 \cdot e^{-t} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} C_1 \cdot e^{2t} \cdot 2 \\ C_1 \cdot e^{2t} \end{pmatrix} + \begin{pmatrix} C_2 \cdot e^{-t} \\ 2C_2 \cdot e^{-t} \end{pmatrix} = \begin{pmatrix} 2C_1 \cdot e^{2t} + C_2 \cdot e^{-t} \\ C_1 \cdot e^{2t} + 2C_2 \cdot e^{-t} \end{pmatrix}$$

$$\vec{X}(0) = \begin{pmatrix} 2C_1 + C_2 \\ C_1 + 2C_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 5 \end{pmatrix}$$

$$\begin{aligned} X(0) &= 1 \\ Y(0) &= 5 \end{aligned}$$

$$2C_1 + C_2 = 1 \Rightarrow \boxed{C_2 = 1 - 2C_1} \quad (\rightarrow) \quad C_2 = 1 - 2(-1)$$

$$C_1 + 2C_2 = 5 \Rightarrow C_1 + 2 \cdot [1 - 2C_1] = 5 \quad \begin{matrix} = 1+2 \\ = 3 \end{matrix}$$

$$\rightarrow C_1 + 2 - 4C_1 = 5 \Rightarrow -3C_1 + 2 = 5 \Rightarrow 2 - 5 = 3C_1$$

$$\rightarrow 3C_1 = -3 \Rightarrow \boxed{C_1 = -1} \quad \boxed{C_2 = 3}$$



$$C_1 = -1 \quad C_2 = 3$$

$$\vec{x}(t) = \begin{pmatrix} 2C_1 e^{2t} + C_2 \cdot e^{-t} \\ C_1 \cdot e^{2t} + 2C_2 \cdot e^{-t} \end{pmatrix} = \begin{pmatrix} -2 \cdot e^{2t} + 3e^{-t} \\ -e^{2t} + 6e^{-t} \end{pmatrix}$$

$$\vec{x}(t) = \begin{pmatrix} -2e^{2t} + 3e^{-t} \\ -e^{2t} + 6e^{-t} \end{pmatrix} \Rightarrow \text{Alternativ a)}$$

2016-2

$$y'' - 2y' + 2y = 0$$

$$y(x) = e^{rx} \Rightarrow y'(x) = r \cdot e^{rx} \Rightarrow y''(x) = r^2 \cdot e^{rx}$$

$$\Rightarrow r^2 \cdot e^{rx} - 2 \cdot r \cdot e^{rx} + 2 \cdot e^{rx} = 0$$

$$\Rightarrow (r^2 - 2r + 2) \cdot \underline{e^{rx}} = 0 \Rightarrow r^2 - 2r + 2 = 0$$

$$r^2 - 2r + 2 = 0$$

$$[a=1] \quad [b=-2] \quad [c=2]$$

$$r_{1,2} = \frac{2 \pm \sqrt{4 - 4 \cdot 2}}{2} = \frac{2 \pm \sqrt{4 - 8}}{2} = \frac{2 \pm \sqrt{-4}}{2}$$

$$= \frac{2 \pm 2\sqrt{-1}}{2} = 1 \pm \sqrt{-1} = 1 \pm i \quad \left\{ \begin{array}{l} a+bi \\ \end{array} \right. \quad \begin{array}{l} y_1(x) = e^{a \cdot x} \cdot \cos(bx) \\ y_2(x) = e^{a \cdot x} \cdot \sin(bx) \end{array}$$

$$y_1(x) = e^x \cdot \cos(x)$$

$$y_2(x) = e^x \cdot \sin(x)$$

$$Y(x) = C_1 \cdot Y_1(x) + C_2 \cdot Y_2(x)$$

$$C_1 = C_2 = 1$$

$$= C_1 \cdot e^x \cdot \cos(x) + C_2 \cdot e^x \cdot \sin(x)$$

$$Y(x) = C_1 \cdot e^x \cdot \cos(x) + C_2 \cdot e^x \cdot \sin(x) \quad (1)$$

$$Y'(x) = C_1 \cdot \left[ \overbrace{(e^x)' \cdot \cos(x)}^{e^x} + e^x \cdot \overbrace{(\cos(x))'}^{-\sin(x)} \right] + C_2 \cdot \left[ \overbrace{(e^x)' \cdot \sin(x)}^{e^x} + e^x \cdot \overbrace{(\sin(x))'}_{\cos(x)} \right]$$

$$y' = C_1 \cdot [e^x \cdot \cos(x) - e^x \cdot \sin(x)] + C_2 \cdot [e^x \cdot \sin(x) + e^x \cdot \cos(x)] \quad (2)$$

$$y(0) = 1 \Rightarrow y(0) = C_1 = 1 \Rightarrow \boxed{C_1 = 1}$$

$$y'(0) = 2 \Rightarrow y'(0) = C_1 + C_2 = 2 \Rightarrow 1 + C_2 = 2$$

$$\Rightarrow C_2 = 2 - 1 = 1 \Rightarrow \boxed{C_2 = 1}$$

$$y(x) = e^x \cdot [\cos(x) + \sin(x)] \rightarrow \text{Alternative c)}$$

2017 - 1

$$dp - r \cdot p \left(1 - \frac{p}{K}\right) dt = 0$$

$$dp = r \cdot p \left(1 - \frac{p}{K}\right) dt$$

$$\frac{dp}{p \left(1 - \frac{p}{K}\right)} = r \cdot dt \Rightarrow \frac{k \cdot dp}{\left(\frac{p(k-p)}{k}\right)} = r dt$$

$$p \left(1 - \frac{p}{K}\right) = \frac{p}{K} \cdot K \left(1 - \frac{p}{K}\right) = \frac{p}{K} \cdot (K - p) = \frac{p(K-p)}{K}$$

$$\frac{dp}{p(k-p)} = \frac{r}{k} dt$$

$$\int \frac{dp}{p(k-p)} = \int \frac{r}{k} dt$$

$$\frac{r \cdot t}{k} + C$$

$$\Rightarrow \int \frac{dp}{p(k-p)} = \frac{r \cdot t}{k} + C \quad (*)$$



$$\frac{1}{\rho(k-\rho)} = \frac{A}{\rho} + \frac{B}{(k-\rho)} \quad / \cdot \rho(k-\rho)$$

$$1 = A \cdot (k-\rho) + B \cdot \rho \quad \begin{cases} = A \cdot k - A \cdot \rho + B \cdot \rho \\ = A \cdot k + (B-A) \cdot \rho \end{cases}$$

$$A \cdot k + (B-A) \cdot \rho = 1 \Rightarrow B-A=0 \Rightarrow \boxed{B=A}$$

$$A \cdot k = 1 \Rightarrow \boxed{A = \frac{1}{k}} \quad \boxed{B = \frac{1}{k}}$$

$$\frac{1}{p(k-p)} = \frac{1}{k} \cdot \left[ \frac{1}{p} + \frac{1}{k-p} \right] \quad / \int dp$$

$$\int \frac{dp}{p(k-p)} = \frac{1}{k} \cdot \left[ \int \frac{dp}{p} + \int \frac{dp}{(k-p)} \right]$$

$u = k-p$   
 $du = -dp$

$$\int -\frac{du}{u} = -\int \frac{du}{u}$$

$$\frac{1}{k} \cdot \left[ \ln(|p|) - \ln(|k-p|) \right] + C_2 = -\ln|u| = -\ln|k-p|$$

$$\frac{1}{k} \cdot \underbrace{\left[ \ln |\rho| - \ln |k-\rho| \right]} + G_2 = \frac{r}{k} \cdot t + C/k$$

$$\ln \left| \frac{\rho}{k-\rho} \right| + G_2 \cdot k = r \cdot t + C \cdot k$$

$$\ln \left| \frac{\rho}{k-\rho} \right| = r \cdot t + \underbrace{C \cdot k - G_2 \cdot k}_{C_3}$$

$$\ln \left| \frac{\rho}{\kappa - \rho} \right| = r \cdot t + C_3$$

$$\Rightarrow e^{r \cdot t + C_3} = \left| \frac{\rho}{\kappa - \rho} \right| \Rightarrow e^{r \cdot t} \cdot \overbrace{e^{C_3}}^{A > 0} = \left| \frac{\rho}{\kappa - \rho} \right|$$

$$e^{rt} \cdot A = \left| \frac{\rho}{\kappa - \rho} \right| \Rightarrow \frac{\rho}{\kappa - \rho} = \underbrace{\pm A}_{B^-} e^{r \cdot t}$$

$$\frac{\rho}{k - \rho} = B \cdot e^{rt} \Rightarrow \rho = B \cdot e^{r \cdot t} \cdot k - \rho \cdot B \cdot e^{rt}$$

$$\rho + \rho \cdot B \cdot e^{rt} = B \cdot e^{rt} \cdot k$$

$$\rho(1 + B \cdot e^{rt}) = B \cdot e^{rt} \cdot k$$

$$\rho(t) = \frac{B \cdot \cancel{e^{rt} \cdot k}}{1 + B \cdot \cancel{e^{rt}}} = \frac{B \cdot k}{e^{-rt} + B}$$

$$\rho(t) = \frac{B \cdot K}{e^{-r \cdot t} + B}$$

$$\rho(0) = \rho_0$$

$$\rho(0) = \frac{B \cdot K}{1 + B} = \rho_0 \Rightarrow BK = \rho_0 + B \cdot \rho_0$$

$$\Rightarrow B(K - \rho_0) = \rho_0 \Rightarrow B = \frac{\rho_0}{K - \rho_0}$$

$$P(t) = \frac{\frac{P_0}{(K-P_0)} \cdot K \cdot (K-P_0)}{e^{-rt} + \left( \frac{P_0}{K-P_0} \right) \cdot (K-P_0)} \quad \boxed{\text{Alternative 6)}$$

$$= \frac{P_0 \cdot K}{(K-P_0) \cdot e^{-rt} + P_0} = P(t)$$

2017-2

$$\frac{dx}{dt} = 3x(t) - 5y(t)$$

$$\frac{dy}{dt} = x(t) - y(t)$$

$$\begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix} = \begin{pmatrix} 3 & -5 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

$$\vec{x}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

$$A = \begin{bmatrix} 3 & -5 \\ 1 & -1 \end{bmatrix}$$



$$\vec{x}'(t) = A \cdot \vec{x}(t)$$



$$\vec{x}(t) = e^{\lambda t} \cdot \vec{v} \Rightarrow \vec{x}'(t) = \lambda \cdot e^{\lambda t} \cdot \vec{v}$$

$$\cancel{\lambda \cdot e^{\lambda t} \cdot \vec{v}} = A \cdot \cancel{e^{\lambda t} \cdot \vec{v}} \Rightarrow A\vec{v} = \lambda \cdot \vec{v}$$

$$A - \lambda I = \begin{pmatrix} 3 - \lambda & -5 \\ 1 & -1 - \lambda \end{pmatrix}$$

$$\det(A - \lambda I) = (3 - \lambda)(-1 - \lambda) - (-5) \cdot 1 = (\lambda - 3)(\lambda + 1) + 5$$

$$= \lambda^2 - 2\lambda - 3 + 5 = \lambda^2 - 2\lambda + 2$$

$$\det(A - \lambda I) = \lambda^2 - 2\lambda + 2 = 0$$

$$\begin{aligned} a &= 1 \\ b &= -2 \\ c &= 2 \end{aligned}$$

$$\lambda_{1,2} = \frac{2 \pm \sqrt{4 - 4 \cdot 2}}{2} = \frac{2 \pm \sqrt{4 - 8}}{2} = \frac{2 \pm \sqrt{-4}}{2}$$

$$= \frac{2 \pm 2 \cdot \sqrt{-1}}{2} = 1 \pm i$$

$$\begin{aligned} \lambda_1 &= 1 + i \\ \lambda_2 &= 1 - i \end{aligned}$$

$$\boxed{\lambda_1 = 1 + i}$$

$$A - \lambda I = A - (1 + i) = \begin{pmatrix} 3 - (1 + i) & -5 \\ 1 & -4 - (1 + i) \end{pmatrix}$$

$$= \begin{pmatrix} 2 - i & -5 \\ 1 & -2 - i \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0$$

$$(2 - i)v_1 - 5v_2 = 0 \Rightarrow (2 - i)v_1 = 5v_2 \Rightarrow \boxed{v_2 = \frac{(2 - i) \cdot v_1}{5}}$$

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} v_1 \\ \frac{(2-i) \cdot v_1}{5} \end{pmatrix} = \begin{pmatrix} 1 \\ \frac{(2-i)}{5} \end{pmatrix} \cdot v_1 =$$

$$\vec{v}_1 = \begin{pmatrix} 5 \\ 2-i \end{pmatrix}$$

$$\boxed{v_2 = 1 - i}$$

$$A - (1-i) \cdot I = \begin{pmatrix} 3 - (1-i) & -5 \\ 1 & -1 - (1-i) \end{pmatrix}$$

$$= \begin{pmatrix} 2+i & -5 \\ 1 & -2+i \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0$$

$$(2+i) \cdot v_1 - 5v_2 = 0 \Rightarrow (2+i)v_1 = 5v_2 \Rightarrow \boxed{v_2 = \frac{(2+i)v_1}{5}}$$

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} v_1 \\ \frac{(2+i)}{5} v_1 \end{pmatrix} = v_1 \cdot \begin{pmatrix} 1 \\ \frac{(2+i)}{5} \end{pmatrix} =$$

$$\boxed{\vec{v}_2 = \begin{pmatrix} 5 \\ 2+i \end{pmatrix}}$$

$$\lambda_1 = 1 + i$$

$$\vec{V}_1 = \begin{pmatrix} 5 \\ 2 - i \end{pmatrix}$$

$$\lambda_2 = 1 - i$$

$$\vec{V}_2 = \begin{pmatrix} 5 \\ 2 + i \end{pmatrix}$$

$$\vec{x}(0) = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$$e^t \cdot e^{it} = e^t \cdot [\cos(t) + i \sin(t)]$$

$$\vec{x}(t) = C_1 \cdot e^{(1+i)t} \begin{pmatrix} 5 \\ 2-i \end{pmatrix} + C_2 \cdot e^{(1-i)t} \begin{pmatrix} 5 \\ 2+i \end{pmatrix}$$

$$= C_1 \cdot [e^t \cdot (\cos(t) + i \sin(t))] \begin{pmatrix} 5 \\ 2-i \end{pmatrix}$$

$$+ C_2 \cdot [e^t \cdot (\cos(t) - i \sin(t))] \begin{pmatrix} 5 \\ 2+i \end{pmatrix}$$

$$e^{(1-i)t} = e^t \cdot e^{-it}$$

$$= e^t [\cos(-t) + i \sin(-t)]$$

$$= e^t [\cos(t) - i \sin(t)]$$

$$= C_1 \cdot [e^{t \cdot \cos(t)} + i \cdot e^{t \cdot \sin(t)}] \cdot \begin{pmatrix} 5 \\ 2-i \end{pmatrix} \\ + C_2 \cdot [e^{t \cdot \cos(t)} - i \cdot e^{t \cdot \sin(t)}] \cdot \begin{pmatrix} 5 \\ 2+i \end{pmatrix}$$


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$$= \begin{pmatrix} C_1 \cdot e^{t \cdot \cos(t)} \cdot 5 + C_1 \cdot i \cdot e^{t \cdot \sin(t)} \cdot 5 \\ (2-i) \cdot C_1 \cdot e^{t \cdot \cos(t)} + (2-i) \cdot C_1 \cdot e^{t \cdot \sin(t)} \cdot i \end{pmatrix}$$



$$+ \left( C_2 \cdot e^t \cdot \cos(t) \cdot 5 - i \cdot e^t \cdot \sin(t) \cdot (C_2 \cdot 5) \right. \\ \left. C_1 \cdot e^t \cdot \cos(t) (2+i) - C_2 \cdot e^t \cdot i \cdot \sin(t) (2+i) \right)$$

$$= \left( \begin{aligned} & \underbrace{5C_1 \cdot e^t \cdot \cos(t)}_1 + \underbrace{5C_1 \cdot i \cdot e^t \cdot \sin(t)}_0 + \underbrace{5C_2 \cdot e^t \cdot \cos(t)}_1 \\ & - \underbrace{5C_2 \cdot i \cdot e^t \cdot \sin(t)}_1 \\ & \underbrace{(2-i)(1e^t \cdot \cos(t))}_1 + \underbrace{(2-i) \cdot C_1 \cdot e^t \sin(t) \cdot i}_0 \\ & + \underbrace{C_2 \cdot e^t \cdot \cos(t) \cdot (2+i)}_1 - \underbrace{C_2 \cdot e^t \cdot i \cdot \sin(t) \cdot (2+i)}_0 \end{aligned} \right)$$

$$\vec{x}(0) = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$$\vec{x}(0) = \begin{pmatrix} 5c_1 + 5c_2 \\ (2-i) \cdot c_1 + c_2(2+i) \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$$\textcircled{i} \quad \boxed{c_1 + c_2 = \frac{3}{5}}$$

$$\boxed{c_1 = \frac{3}{5} - c_2}$$

$$\textcircled{ii} \quad \boxed{(2-i) \cdot (1 + (2+i) \cdot c_2) = 1}$$

$$(2-i) \cdot \left( \frac{3}{5} - C_2 \right) + (2+i) \cdot C_2 = 1$$

$$\Rightarrow \frac{6}{5} - \cancel{2C_2} - \frac{i \cdot 3}{5} + \cancel{i \cdot C_2} + \cancel{2C_2} + \cancel{i \cdot C_2} = 1$$

$$2i \cdot C_2 + \frac{3}{5} \cdot (2-i) = 1$$

$$\underline{2i \cdot C_2} = 1 - \frac{3}{5}(2-i) = \frac{5}{5} - \frac{(6-3i)}{5} = \underline{\underline{\frac{3i-1}{5}}}$$

$$2i \cdot C_2 = \left( \frac{3i-1}{5} \right) \Rightarrow C_2 = \left( \frac{3i-1}{5} \right) \cdot \frac{1}{2i}$$

$$= \frac{1}{10} \cdot \left( \frac{3i-1}{i} \right) = \frac{1}{10} \cdot \left( \frac{3i^2 - i}{i^2} \right) = \frac{1}{10} \left( \frac{-3-i}{-1} \right)$$

$$= \frac{1}{10} \cdot (3+i)$$

$$C_2 = \left( \frac{3+i}{10} \right) \quad C_1 = \left( \frac{3-i}{10} \right)$$

$$C_1 = \frac{3}{5} - C_2 = \frac{3}{5} - \left( \frac{3+i}{10} \right) = \frac{6}{10} - \frac{(3+i)}{10} = \frac{6-3-i}{10} = \left( \frac{3-i}{10} \right)$$

$$\vec{x}(t) = \begin{pmatrix} 5C_1 \cdot e^t \cdot \cos(t) + 5C_1 \cdot i \cdot e^t \cdot \sin(t) \\ + 5C_2 \cdot e^t \cdot \cos(t) - 5C_2 \cdot i \cdot e^t \cdot \sin(t) \\ \vdots \\ (2-i) \cdot C_1 \cdot e^t \cdot \cos(t) + (2-i) \cdot C_1 \cdot e^t \cdot \sin(t) \cdot i \\ + C_2 \cdot e^t \cdot \cos(t) (2+i) - C_2 \cdot e^t \cdot i \sin(t) (2+i) \end{pmatrix}$$

$$C_1 = \frac{3-i}{10}$$

$$C_2 = \frac{3+i}{10}$$

$$\frac{5 \cdot (3-i)}{10} \cdot e^t \cdot \cos(t) + 5 \cdot \left(\frac{3-i}{10}\right) \cdot i \cdot e^t \cdot \sin(t)$$

$$+ 5 \cdot \left(\frac{3+i}{10}\right) \cdot e^t \cdot \cos(t) - 5 \cdot \left(\frac{3+i}{10}\right) \cdot i \cdot e^t \cdot \sin(t)$$

$$= \frac{(3-i)}{2} \cdot e^t \cdot \cos(t) + \frac{(3-i)}{2} \cdot i \cdot e^t \cdot \sin(t) \quad \begin{matrix} 3i - i^2 = 3i - (-1) = \frac{3i+1}{2} \\ \frac{(3i+1)}{2} - \frac{(3i-1)}{2} \end{matrix}$$

$$+ \frac{(3+i)}{2} \cdot e^t \cdot \cos(t) - \frac{(3+i)}{2} \cdot i \cdot e^t \cdot \sin(t) \quad \begin{matrix} \frac{(3-i)}{2} + \frac{(3+i)}{2} = \frac{6}{2} = 3 \\ 3i + i^2 = 3i - 1 \end{matrix} = \frac{2}{2} = 1$$

$$= \left\{ \frac{(3-i)}{2} \cdot e^t \cdot \cos(t) + \frac{(3+i)}{2} \cdot e^t \cdot \sin(t) \right\} + \left\{ \frac{(3+i)}{2} \cdot e^t \cdot \cos(t) - \frac{(3-i)}{2} \cdot e^t \cdot \sin(t) \right\} = 3 \cdot e^t \cdot \cos(t) + e^t \cdot \sin(t)$$

$$\vec{x}(t) = \begin{pmatrix} 3e^t \cdot \cos(t) + e^t \cdot \sin(t) \\ e^t \cdot \sin(t) + e^t \cdot \cos(t) \end{pmatrix}$$

$\Rightarrow$

Alternative b)

$$C_1 = \frac{3-i}{10}$$

$$C_2 = \frac{3+i}{10}$$

$$= (2-i) C_1 e^t \cos(t) + (2-i) \cdot C_1 \cdot e^t \sin(t) \cdot i \\ + C_2 \cdot e^t \cos(t) (2+i) - C_2 \cdot e^t \cdot i \sin(t) (2+i)$$

$$= \left( \frac{(2-i)(3-i)}{10} \right) e^t \cos(t) + \left( \frac{(2-i) \cdot (3-i) \cdot i}{10} \right) \cdot e^t \sin(t)$$

$$+ \left( \frac{(3+i) \cdot (2+i)}{10} \right) \cdot e^t \cos(t) - \left( \frac{(3+i) \cdot i \cdot (2+i)}{10} \right) \cdot e^t \sin(t)$$

$$\frac{(2-i)(2-i)}{10} + \frac{(3+i)(2+i)}{10} =$$

$$\frac{6 - 2i - 3i + i^2}{10}$$

$$+ \frac{6 + 3i + 2i + i^2}{10} = \frac{10}{10} = 1$$



$$= (e^t \cdot \cos(t) + e^t \cdot \sin(t))$$

$$\frac{(2-i)(3-i) \cdot i}{10} - \frac{(3+i) \cdot (2-i) \cdot i}{10}$$

$$= \frac{[6 - 2i - 3i + i^2] \cdot i}{10} - \frac{[6 + 3i + 2i + i^2] \cdot i}{10}$$

$$= \frac{1}{10} \cdot i \cdot \left[ \frac{\cancel{6} - 2\cancel{i} - 3\cancel{i} + \cancel{i^2}}{\cancel{10}} - \frac{\cancel{6} - 3\cancel{i} - 2\cancel{i} - \cancel{i^2}}{\cancel{10}} \right] - \frac{1 \cdot i}{\cancel{10}} \quad (\cancel{10i})$$

$= 1$

2013-1

a) Si  $m=2, n=1, p=1, q=1, t=0$

$$\left(\frac{d^2 y}{dx^2}\right)\left(\frac{dy}{dx}\right) + y = 0$$

No lineal  
No homogénea  
De segundo orden

X

b)  $\Sigma: m=1, n=1, p=0, q=1, t=0$

$$\left(\frac{dy}{dx}\right) + 1 = \underline{\underline{x}}$$

Lives!  
No horogers  
Down Order

c) Si  $m=1, n=2, p=1, q=1, t=1$

$$\left(\frac{dy}{dx}\right) \cdot \left(\frac{dy}{dx}\right) + x \cdot y = \underline{\underline{2x}}$$

No homogéneo  
No lineal  
De orden dos

X

d)  $m=2, n=1, p=1, q=1, t=0$

$$\left(\frac{d^2y}{dx^2}\right) \cdot \left(\frac{dx}{dx}\right) + y = \underline{\underline{x}}$$

No lineal  
No homogéneo  
Segundo orden  
(coeficientes constantes)

✓ Alternativa  
2)

2018-2

$$\frac{d\rho}{dt} = c \cdot r \cdot \left( 1 - \left( \frac{\rho(t)}{K} \right) - \left( \frac{\rho(t)}{K} \right)^2 \right)$$

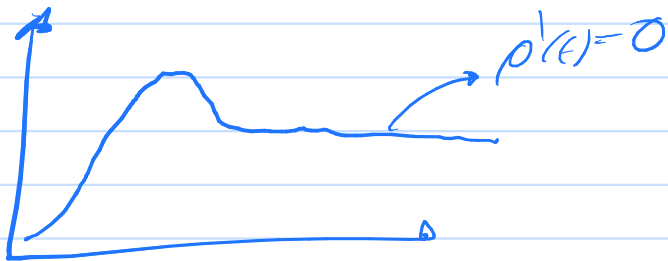
$\rho'(t)$

$\rho(t)$

$$\frac{d\rho}{dt} = c \cdot r \cdot \left( 1 - \left[ \frac{\rho(t)}{K} \right] - \left[ \frac{\rho(t)}{K} \right]^2 \right) \quad \text{for } t \rightarrow \infty$$

$$\lim_{t \rightarrow \infty} \rho'(t) = 0 = c \cdot r \cdot \left( 1 - \left[ \lim_{t \rightarrow \infty} \frac{\rho(t)}{K} \right] - \left[ \lim_{t \rightarrow \infty} \frac{\rho(t)}{K} \right]^2 \right)$$

$\lim_{t \rightarrow \infty} \rho(t) = \rho_{\text{ter}}$



$$u = \frac{\rho_{tern}}{K}$$

$$0 = 1 - \left( \frac{\rho_{tern}}{K} \right) - \left( \frac{\rho_{tern}}{K} \right)^2 \quad \begin{array}{l} a=1 \\ b=1 \\ c=-1 \end{array}$$

$$0 = 1 - u - u^2 \rightarrow u^2 + u - 1 = 0$$

$$u_{1,2} = \frac{-1 \pm \sqrt{1 - 4(-1)}}{2} = \frac{-1 \pm \sqrt{5}}{2}$$

$$\mu_{1,2} = -\frac{1 \pm \sqrt{5}}{2}$$

$$\mu_1 = -\frac{1 - \sqrt{5}}{2} < 0$$

$$\mu_2 = \frac{\sqrt{5} - 1}{2} \checkmark \quad \mu_2 = \frac{\rho_{\text{term}}}{K} \Rightarrow \frac{\rho_{\text{term}}}{K} = \left( \frac{\sqrt{5} - 1}{2} \right)$$

$$\rho_{\text{term}} = \left( \frac{\sqrt{5} - 1}{2} \right) \cdot K$$

Alternative b)

2019-1

$$\frac{dA}{dt} = k \cdot A^2 \Rightarrow dA \cdot A^{-2} = k \cdot dt$$

$$\int A^{-2} dA = \int k dt + C \Rightarrow \left( \frac{A^{-1}}{-1} \right) = k \cdot t + C$$

$$\Rightarrow -\frac{1}{A} = kt + C \Rightarrow -\frac{1}{(kt+C)} = A(t)$$

$$A(0) = 100 \Rightarrow -\frac{1}{C} = 100 \Rightarrow C = -\frac{1}{100}$$



$$A(1) = -\frac{1}{(k+c)} = 50$$

$$\Rightarrow \left(\frac{1}{k+c}\right) = -50 \Rightarrow k+c = -\frac{1}{50}$$

$$k - \frac{1}{100} = -\frac{1}{50} \Rightarrow k = -\frac{1}{50} + \frac{1}{100} = -\frac{2}{100} + \frac{1}{100}$$

$$\boxed{k = -\frac{1}{100}}$$

$$= -\frac{1}{100}$$

$$A(t) = - \frac{1}{(k \cdot t + C)} = - \frac{1}{\left(-\frac{1}{100} \cdot t - \frac{1}{100}\right)}$$

$$= \frac{1}{\left(\frac{t+1}{100}\right)} = \frac{100}{t+1}$$

$$A(t) = \frac{100}{t+1}$$

$$A(4) = \frac{100}{4+1} = \frac{100}{5} = 20 \text{ [95]}$$

Alternative c)

2019-2

$$\frac{dT}{dt} = k \cdot (A - T)$$

$$u = A - T \quad du = -dT$$

$$\int -\frac{du}{u} = -\ln|u| = -\ln|A - T|$$

$$\Rightarrow \frac{dT}{A - T} = k \cdot dt \Rightarrow \int \frac{dT}{A - T} = k \cdot t + C_1$$

$$\Rightarrow -\ln|A - T| = kt + C_1 \Rightarrow \ln|A - T| = -kt - C_1$$

$$e^{-kt} \cdot e^{-C_1} = |A - T| \Rightarrow \overset{B}{\overbrace{e^{-C_1}}} \cdot e^{-kt} = |A - T| \quad \text{BDO}$$

$$\Rightarrow A - t = \underbrace{\pm B}_{C = \pm B} \cdot e^{-k \cdot t}$$

$$\downarrow$$

$$\Rightarrow A - t = C \cdot e^{-k \cdot t}$$

$$t(0) = A - C = 2A$$

$$\Rightarrow \underbrace{A - 2A = C}_{C = -A}$$

$$\boxed{A - C \cdot e^{-k \cdot t} = t}$$

$$\boxed{t(t) = A - C \cdot e^{-k \cdot t}} \Rightarrow t(t) = A - (-A) e^{-k \cdot t} = A + A \cdot e^{-k \cdot t}$$

$$= A \cdot (1 + e^{-\kappa t})$$

$$f(t) = A \cdot (1 + e^{-\kappa t})$$

$$f(t^0) = 1,5 \cdot A \Rightarrow f(t^0) = \frac{3}{2} \cdot A$$

$$\Rightarrow A \cdot (1 + e^{-\kappa \cdot t^0}) = \frac{3A}{2} \quad \frac{3}{2} - 1 = \frac{3}{2} - \frac{2}{2} = \frac{1}{2}$$

$$1 + e^{-\kappa \cdot t^0} = \frac{3}{2} \Rightarrow e^{-\kappa t^0} = \frac{3}{2} - 1 = \frac{1}{2}$$

$$e^{-kt^*} = \left(1 - \frac{1}{2}\right) \quad / \ln()$$

$$\ln(e^{-kt^*}) = \ln\left(\frac{1}{2}\right)$$

$$-kt^* = -\ln(2) \Rightarrow kt^* = \ln(2)$$

$$\boxed{t^* = \frac{\ln(2)}{k}} \Rightarrow \boxed{\text{Alternative } \phi)}$$