

# Integrating Factor Technique: Deep Mathematical Analysis

ODE 1 - Prof. Adi Ditkowski

Lesson 15

## 1 The Mathematical Foundation

The integrating factor technique is more than a computational tool - it represents a fundamental principle in the theory of linear differential equations. This lesson explores the deep mathematical structure underlying this method.

### 1.1 The Fundamental Question

Given a linear first-order ODE:

$$\frac{dy}{dt} + p(t)y = g(t) \quad (1)$$

We seek a function  $\mu(t)$  such that multiplication transforms the equation into:

$$\frac{d}{dt}[\mu(t)y] = \mu(t)g(t) \quad (2)$$

**Theorem 1** (Existence and Uniqueness of Integrating Factor). *For any continuous function  $p(t)$  on an interval  $I$ , there exists a unique (up to scalar multiplication) integrating factor  $\mu(t) > 0$  given by:*

$$\mu(t) = \exp\left(\int_{t_0}^t p(s)ds\right) \quad (3)$$

where  $t_0 \in I$  is arbitrary.

*Proof.* Requiring  $\mu(t)y' + \mu(t)p(t)y = \frac{d}{dt}[\mu(t)y] = \mu'(t)y + \mu(t)y'$  yields:

$$\mu'(t)y + \mu(t)y' = \mu(t)y' + \mu(t)p(t)y \quad (4)$$

$$\mu'(t) = \mu(t)p(t) \quad (5)$$

$$\frac{d\mu}{dt} = p(t)\mu \quad (6)$$

This is a separable equation with solution:

$$\mu(t) = C \exp\left(\int p(t)dt\right) \quad (7)$$

Since any non-zero constant  $C$  yields a valid integrating factor, we choose  $C = 1$  for simplicity. The uniqueness (up to scalar multiplication) follows from the uniqueness of solutions to the initial value problem  $\mu' = p(t)\mu$ ,  $\mu(t_0) = \mu_0$ .  $\square$

## 2 Connection to Exact Differential Equations

The integrating factor transforms a non-exact equation into an exact one. This reveals the deep connection between linear equations and exact equations.

**Proposition 1** (Exactness After Multiplication). *The equation  $\mu(t)[y' + p(t)y - g(t)] = 0$  can be written as:*

$$M(t, y)dt + N(t, y)dy = 0 \quad (8)$$

where  $M = \mu(t)[p(t)y - g(t)]$  and  $N = \mu(t)$ . This equation is exact, meaning:

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial t} \quad (9)$$

*Proof.* Computing the partial derivatives:

$$\frac{\partial M}{\partial y} = \mu(t)p(t) \quad (10)$$

$$\frac{\partial N}{\partial t} = \mu'(t) = \mu(t)p(t) \quad (11)$$

The equality follows from the defining property of  $\mu(t)$ .  $\square$

## 3 Alternative Forms and Generalizations

### 3.1 Non-Standard Form Integrating Factors

Consider the general first-order linear equation:

$$a_1(t)y' + a_0(t)y = g(t) \quad (12)$$

**Method 1** (Direct Integrating Factor). *Instead of converting to standard form, find  $\mu(t)$  such that:*

$$\frac{d}{dt}[\mu(t)a_1(t)y] = \mu(t)g(t) \quad (13)$$

*This requires:*

$$\mu(t)a_1(t)y' + [\mu'(t)a_1(t) + \mu(t)a_1'(t)]y = \mu(t)a_1(t)y' + \mu(t)a_0(t)y \quad (14)$$

*Leading to:*

$$\mu'(t) = \mu(t) \left[ \frac{a_0(t) - a_1'(t)}{a_1(t)} \right] \quad (15)$$

### 3.2 Integrating Factors Depending on $y$

While not applicable to linear equations, for completeness we note that some equations admit integrating factors  $\mu(y)$ :

**Theorem 2** (Integrating Factor  $\mu(y)$ ). *For the equation  $M(t, y)dt + N(t, y)dy = 0$ , an integrating factor  $\mu(y)$  exists if and only if:*

$$\frac{1}{M} \left( \frac{\partial M}{\partial y} - \frac{\partial N}{\partial t} \right) = h(y) \quad (16)$$

*is a function of  $y$  alone. Then  $\mu(y) = \exp \left( \int h(y) dy \right)$ .*

## 4 The Operator Perspective

**Definition 1** (Linear Differential Operator). *Define the operator  $L : C^1(I) \rightarrow C(I)$  by:*

$$L[y] = y' + p(t)y \quad (17)$$

The integrating factor  $\mu(t)$  transforms  $L$  into the operator  $\mu L$ , which can be written as:

$$\mu L[y] = \frac{d}{dt}[\mu y] \quad (18)$$

This is a composition of multiplication by  $\mu$  followed by differentiation.

### 4.1 The Adjoint Connection

**Theorem 3** (Adjoint Operator and Integrating Factor). *The adjoint operator  $L^*$  defined by:*

$$L^*[v] = -v' + p(t)v \quad (19)$$

*has the property that  $\mu(t)$  satisfies  $L^*[\mu] = 0$ , making it a solution to the homogeneous adjoint equation.*

## 5 Discontinuous Coefficients

When  $p(t)$  has discontinuities, the integrating factor may have different forms on different intervals.

**Example 1** (Jump Discontinuity). *Consider:*

$$y' + p(t)y = 1, \quad p(t) = \begin{cases} 1 & t < 0 \\ 2 & t \geq 0 \end{cases} \quad (20)$$

*The integrating factor is:*

$$\mu(t) = \begin{cases} e^t & t < 0 \\ e^{2t} & t \geq 0 \end{cases} \quad (21)$$

*Note that  $\mu(t)$  has a jump discontinuity at  $t = 0$ , with  $\mu(0^-) = 1$  and  $\mu(0^+) = 1$ .*

## 6 Special Integration Techniques

### 6.1 Pattern Recognition

Key patterns for  $\int p(t)dt$ :

$$p(t) = \frac{f'(t)}{f(t)} \Rightarrow \int p(t)dt = \ln |f(t)| \quad (22)$$

$$p(t) = \tan(t) \Rightarrow \int p(t)dt = -\ln |\cos(t)| \quad (23)$$

$$p(t) = \cot(t) \Rightarrow \int p(t)dt = \ln |\sin(t)| \quad (24)$$

$$p(t) = \frac{n}{t} \Rightarrow \int p(t)dt = n \ln |t| \quad (25)$$

### 6.2 Reduction Formulas

For repeated integration by parts situations:

**Lemma 1** (Reduction Formula for  $\int t^n e^{at} dt$ ).

$$\int t^n e^{at} dt = \frac{t^n e^{at}}{a} - \frac{n}{a} \int t^{n-1} e^{at} dt \quad (26)$$

## 7 The Fundamental Solution Connection

**Theorem 4** (Reciprocal Relationship). *If  $y_h(t)$  is a non-zero solution to the homogeneous equation  $y' + p(t)y = 0$ , then:*

$$\mu(t) = \frac{1}{y_h(t)} \quad (27)$$

*is an integrating factor for the non-homogeneous equation.*

*Proof.* Since  $y'_h + p(t)y_h = 0$ , we have  $y'_h/y_h = -p(t)$ . Therefore:

$$y_h = C e^{-\int p(t)dt} \Rightarrow \frac{1}{y_h} = \frac{1}{C} e^{\int p(t)dt} \quad (28)$$

which is indeed an integrating factor (the constant  $1/C$  can be absorbed).  $\square$

## 8 Numerical Stability Considerations

Prof. Ditkowski may ask about the numerical implications of the integrating factor method.

**Proposition 2** (Growth of Integrating Factor). *If  $p(t) > 0$  on  $[a, b]$ , then  $\mu(t)$  grows exponentially. If  $p(t) < 0$ , then  $\mu(t)$  decays exponentially. This affects numerical stability:*

- *Growing  $\mu$ : May cause overflow but preserves relative accuracy*
- *Decaying  $\mu$ : May cause underflow and loss of significant digits*

## 9 Historical Development

The integrating factor method was developed by Leonhard Euler in the 18th century. The key insight was recognizing that certain non-exact equations could be made exact through multiplication by an appropriate function.

Euler's contribution: Transform difficult problems into solvable ones through clever multiplication - a recurring theme in mathematics.

## 10 Extension to Systems

For the system  $\mathbf{x}' = A(t)\mathbf{x} + \mathbf{g}(t)$ , the integrating factor becomes the matrix exponential or fundamental matrix:

$$\Phi(t) = \exp\left(\int_0^t A(s)ds\right) \quad (29)$$

when  $A(t)$  commutes with its integral. Otherwise, we need the Peano-Baker series.

## 11 Summary: The Complete Picture

The integrating factor method connects to multiple areas of mathematics:

- Creates exact differential equations
- Relates to operator theory and adjoint operators
- Connected to fundamental solutions via reciprocal relationship
- Has numerical stability implications
- Generalizes to matrix systems