

Direct Integration: The Foundation of ODE Solutions

ODE 1 - Prof. Adi Ditkowski

Lesson 11

1 Introduction

Definition 1 (Directly Integrable ODE). *An ODE is **directly integrable** if it can be written in the form:*

$$\frac{d^n y}{dx^n} = f(x)$$

where $f(x)$ is a function of x only (not involving y or its derivatives).

Direct integration is the simplest solution method, requiring only antiderivatives. Yet it forms the foundation for all other ODE techniques!

2 First-Order Direct Integration

2.1 General Method

Method 1 (Solving $y' = f(x)$). 1. Recognize the form: $\frac{dy}{dx} = f(x)$

2. Integrate both sides: $y = \int f(x) dx + C$

3. If initial condition $y(x_0) = y_0$ is given, determine C

4. Verify the solution by differentiation

Example 1 (Basic Direct Integration). Solve: $\frac{dy}{dx} = 3x^2 - 2x + 1$ with $y(0) = 5$

Solution:

$$y = \int (3x^2 - 2x + 1) dx \tag{1}$$

$$= x^3 - x^2 + x + C \tag{2}$$

Using $y(0) = 5$:

$$5 = 0^3 - 0^2 + 0 + C \implies C = 5$$

Therefore: $y = x^3 - x^2 + x + 5$

2.2 Definite Integral Form

Theorem 1 (IVP Solution via Definite Integral). *The solution to $\frac{dy}{dx} = f(x)$ with $y(x_0) = y_0$ is:*

$$y(x) = y_0 + \int_{x_0}^x f(t) dt$$

The definite integral form automatically incorporates the initial condition - no need to find C separately!

3 Higher-Order Direct Integration

3.1 General Pattern

Theorem 2 (n-th Order Direct Integration). *For $\frac{d^n y}{dx^n} = f(x)$, the general solution contains n arbitrary constants:*

$$y(x) = \int^{(n)} f(x) dx + C_1 x^{n-1} + C_2 x^{n-2} + \cdots + C_{n-1} x + C_n$$

where $\int^{(n)}$ denotes n -fold integration.

Example 2 (Second-Order). *Solve: $y'' = \cos(x)$ with $y(0) = 1$, $y'(0) = 0$*

First integration:

$$y' = \int \cos(x) dx = \sin(x) + C_1$$

Using $y'(0) = 0$: $0 = \sin(0) + C_1 \implies C_1 = 0$

Second integration:

$$y = \int \sin(x) dx = -\cos(x) + C_2$$

Using $y(0) = 1$: $1 = -\cos(0) + C_2 = -1 + C_2 \implies C_2 = 2$

Solution: $y = -\cos(x) + 2$

4 Special Cases and Common Integrals

4.1 Important Antiderivatives for ODEs

$f(x)$	$\int f(x) dx$	Domain Note
$x^n \ (n \neq -1)$	$\frac{x^{n+1}}{n+1} + C$	All x
$\frac{1}{x}$	$\ln x + C$	$x \neq 0$
e^{ax}	$\frac{1}{a}e^{ax} + C$	All x
$\sin(ax)$	$-\frac{1}{a}\cos(ax) + C$	All x
$\cos(ax)$	$\frac{1}{a}\sin(ax) + C$	All x
$\frac{1}{x^2+a^2}$	$\frac{1}{a}\arctan\left(\frac{x}{a}\right) + C$	All x
$\frac{1}{\sqrt{a^2-x^2}}$	$\arcsin\left(\frac{x}{a}\right) + C$	$ x < a$

Always include absolute values in $\ln |x|$ and check domain restrictions!

4.2 The Zero Derivative Case

Theorem 3 (Polynomial Solutions). *If $\frac{d^n y}{dx^n} = 0$, then y is a polynomial of degree at most $n - 1$:*

$$y(x) = C_1 x^{n-1} + C_2 x^{n-2} + \cdots + C_{n-1} x + C_n$$

5 Solution Verification

Method 2 (Verification Checklist). 1. Differentiate your solution n times

2. Substitute into the original ODE
3. Verify the equation holds identically
4. Check initial conditions (if given)
5. Verify domain of validity

Prof. Ditkowski awards partial credit for solution verification even if your answer is incorrect. Always show this step!

6 Common Errors to Avoid

Critical mistakes that lose points:

- Forgetting $+C$ in indefinite integrals
- Missing absolute values: $\int \frac{1}{x} dx = \ln |x| + C$
- Wrong number of constants for higher-order equations
- Not checking domain restrictions
- Arithmetic errors in determining constants

7 Physical Applications

Example 3 (Free Fall Motion). *For an object in free fall: $\frac{d^2 y}{dt^2} = -g$ where y is height, t is time, g is gravitational acceleration.*

Solution:

$$v = \frac{dy}{dt} = -gt + v_0 \quad (\text{velocity}) \quad (3)$$

$$y = -\frac{1}{2}gt^2 + v_0t + y_0 \quad (\text{position}) \quad (4)$$

The constants v_0 and y_0 represent initial velocity and position.