

# Lesson 50: Practice Problems - Numerical Methods

ODE 1 - Prof. Adi Ditkowski

## Part A: Euler's Method (6 problems)

1. Apply Euler's method with  $h = 0.1$  to solve:

$$y' = x - y, \quad y(0) = 1$$

Find  $y(0.3)$  (show all steps).

2. Use Euler's method with  $h = 0.25$  for:

$$y' = y + e$$

$$y(0) = 0$$

Compute approximations at

$$x = 0.25, 0.5, 0.75, 1.$$

3. For the IVP  $y' = -2y$ ,  $y(0) = 1$ :

- (a) Find the exact solution
- (b) Apply Euler with  $h = 0.5$  to find  $y(1)$
- (c) Compare with the exact value

4. Determine the maximum stable step size for Euler's method applied to:

$$y' = -10y$$

5. Use Euler's method with  $h = 0.2$  for the system:

$$x' = y, \quad y' = -x, \quad x(0) = 1, \quad y(0) = 0$$

Find  $(x(0.4), y(0.4))$ .

6. Backward Euler for  $y' = -100y$ ,  $y(0) = 1$ . Show that with  $h = 0.1$ :

$$y_1 = y_0 \overline{1+100h}$$

## Part B: Runge-Kutta Methods (6 problems)

1. Apply the improved Euler method (Heun) with  $h = 0.5$  to:

$$y' = xy, \quad y(0) = 1$$

Find  $y(1)$ .

2. Use the midpoint method (RK2) with  $h = 0.25$  for:

$$y' = \sin(x) + y, \quad y(0) = 0$$

Compute  $y(0.5)$ .

3. Apply RK4 with  $h = 0.5$  to solve:

$$y' = x$$

$$y^2 + y^2, \quad y(0) = 0$$

*Find*

$y(0.5)$  (show all  $k_i$  values).

4. For  $y' = -y + x + 1$ ,  $y(0) = 1$ :

(a) Apply one step of RK4 with  $h = 1$

(b) Find the exact solution and compare

5. Use RK4 with  $h = 0.2$  for the system:

$$\begin{cases} x' = x - y \\ y' = x + y \end{cases}, \quad x(0) = 1, \quad y(0) = 0$$

Find  $(x(0.2), y(0.2))$ .

6. Compare Euler and RK4 for  $y' = y$ ,  $y(0) = 1$  with  $h = 0.5$ . Find  $y(0.5)$  using both methods and the exact solution.

## Part C: Error Analysis (5 problems)

7. For  $y' = y$ ,  $y(0) = 1$  on  $[0, 1]$ :

(a) If we want global error  $< 10^{-4}$  using Euler, estimate required  $h$

(b) Repeat for RK4

(c) How many steps does each method need?

8. The local truncation error for Euler is  $h^2 \frac{y''(\xi)}{2}$ . For  $y' = x^2$ ,  $y(0) = 0$ :  
Find the exact local error at  $x = h$

Verify it's  $O(h^2)$

Given that RK4 has local error  $O(h^5)$ , if halving the step size reduces the error by factor  $F$ , what is  $F$ ?

For  $y' = -1000y + 1000$ ,  $y(0) = 2$ :

- (a) Find the exact solution
- (b) Is this equation stiff? Why?
- (c) What happens if you use Euler with  $h = 0.01$ ?

Richardson extrapolation: If  $y_h$  is the Euler approximation with step  $h$  and  $y_{h/2}$  with step  $h/2$ , show that:

$$y_{\text{improved}} = 2y_{h/2} - y_h$$

$h$

has error

$O(h^2)$ .

## Part D: Stability Analysis (5 problems)

- 4. For the test equation  $y' = \lambda y$  with  $\lambda = -5$ :
  - (a) Find the stability condition for Euler
  - (b) Find the stability condition for RK4
  - (c) Which method allows larger steps?
- 5. Show that backward Euler is unconditionally stable for  $y' = \lambda y$  with  $\text{Re}(\lambda) < 0$ .
- 6. For the system:

$$\mathbf{y}' = \begin{pmatrix} -1 & 10 \\ 0 & -100 \end{pmatrix} \mathbf{y}$$

- (a) Find the eigenvalues
  - (b) What step size does Euler need for stability?
  - (c) Is this system stiff?
- 7. The stability function for RK4 is:

$$R(z) = 1 + z + \frac{z^2}{2} + \frac{z^3}{6} + \frac{z^4}{24}$$

Find  $R(-2)$  and determine if  $h\lambda = -2$  is stable.

Compare stability regions: sketch the stability boundary in the complex  $h\lambda$  plane for:

- (a) Euler's method
- (b) Backward Euler

## Part E: Implementation Considerations (3 problems)

3. Write pseudocode for adaptive step size control using error estimation.
4. For solving to tolerance  $\epsilon = 10^{-6}$  on  $[0, 10]$ :
  - (a) Estimate steps needed for Euler
  - (b) Estimate steps needed for RK4
  - (c) Which is more efficient?
5. Higher-order ODEs: Convert  $y'' + 2y' + y = e^x, y(0) = 1, y'(0) = 0$  to a system and show first Euler step with  $h = 0.1$ .

## Part F: Exam-Style Problems (5 problems)

3. [10 points] Consider  $y' = x + y, y(0) = 1$ .
  - 3 pts Apply two steps of Euler's method with  $h = 0.5$
  - 4 pts Apply one step of RK4 with  $h = 1$3 pts The exact solution is  $y = 2e^x - x - 1$ . Compare errors.
4. [8 points] For the pendulum equation (small angle):
$$\theta'' + \theta = 0, \quad \theta(0) = 0.1, \quad \theta'(0) = 0$$
  - 2 pts Convert to a first-order system
  - 4 pts Apply one step of RK4 with  $h = 0.1$
  - 2 pts Is the total energy conserved numerically?
5. [9 points] Stability analysis for  $y' = -50y$ :
  - 2 pts Find maximum stable  $h$  for Euler
  - 2 pts Find maximum stable  $h$  for RK4 (given stability limit  $|h\lambda| < 2.78$ )
  - 2 pts If you need to solve on  $[0, 10]$ , how many steps for each?
  - 3 pts Which method is more efficient and why?
6. [10 points] Method comparison:
  - 3 pts Explain why RK4 is more accurate than Euler
  - 3 pts When would you prefer implicit over explicit methods?
  - 2 pts What is the trade-off in choosing step size?
  - 2 pts How do adaptive methods work?

7. [12 points] *Prof. Ditkowski Special* The chemical reaction  $A \rightarrow B \rightarrow C$  has rate equations:

$$\begin{cases} A' = -100A \\ B' = 100A - B \\ C' = B \end{cases}$$

with  $A(0) = 1$ ,  $B(0) = C(0) = 0$ .

3 pts Is this system stiff? Explain.

3 pts Apply one Euler step with  $h = 0.001$

3 pts What happens with  $h = 0.1$ ?

3 pts Suggest an appropriate numerical method

## Solutions and Hints

### Selected Solutions:

**Problem 1:** -  $y_1 = 1 + 0.1(0 - 1) = 0.9$  -  $y_2 = 0.9 + 0.1(0.1 - 0.9) = 0.82$  -  $y_3 = 0.82 + 0.1(0.2 - 0.82) = 0.758$

**Problem 4:** For stability:  $|1 - 10h| < 1$ , so  $h < 0.2$

**Problem 9:** RK4 for  $y' = x^2 + y^2$ :  $-k_1 = 0$  -  $k_2 = 0.5(0.25)^2 = 0.03125$  -  $k_3 = 0.5[(0.25)^2 + (0.0156)^2] \approx 0.0312$  -  $k_4 = 0.5[(0.5)^2 + (0.0312)^2] \approx 0.125$  -  $y_1 \approx 0.031$

**Problem 13:** For Euler:  $h \sim \sqrt{10^{-4}} = 0.01$ , need 100 steps For RK4:  $h \sim (10^{-4})^{1/4} \approx 0.1$ , need 10 steps

**Problem 18:** Eigenvalues:  $-1, -100$ . Need  $h < 2/100 = 0.02$  for stability. Yes, stiff!

**Key Insights:** - RK4 typically 10-100× more efficient than Euler - Stiffness determined by eigenvalue ratio - Implicit method trades computation per step for stability - Energy conservation tests numerical accuracy