A process maintains and represents the execution of a program; an application can contain one or more processes. A process has many components that it gets broken down into to be stored and interacted with. The <a href="Microsoft docs">Microsoft docs</a> break down these other components, "Each process provides the resources needed to execute a program. A process has a virtual address space, executable code, open handles to system objects, a security context, a unique process identifier, environment variables, a priority class, minimum and maximum working set sizes, and at least one thread of execution." This information may seem intimidating, but this room aims to make this concept a little less complex.

As previously mentioned, processes are created from the execution of an application. Processes are core to how Windows functions, most functionality of Windows can be encompassed as an application and has a corresponding process. Below are a few examples of default applications that start processes.

- MsMpEng (Microsoft Defender)
- wininit (keyboard and mouse)
- Isass (credential storage)

Attackers can target processes to evade detections and hide malware as legitimate processes. Below is a small list of potential attack vectors attackers could employ against processes,

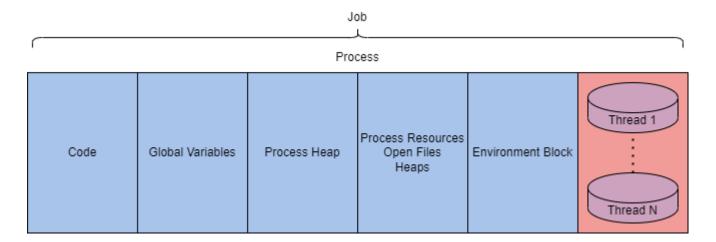
- Process Injection (<u>T1055</u>)
- Process Hollowing (T1055.012)
- Process Masquerading (<u>T1055.013</u>)

Processes have many components; they can be split into key characteristics that we can use to describe processes at a high level. The table below describes each critical component of processes and their purpose.

Process Component	Purpose
Private Virtual Address Space	Virtual memory addresses that the process is allocated.
Executable Program	Defines code and data stored in the virtual address space.
Open Handles	Defines handles to system resources accessible to the process.
Security Context	The access token defines the user, security groups, privileges, and other security information.
Process ID	Unique numerical identifier of the process.
Threads	Section of a process scheduled for execution.

We can also explain a process at a lower level as it resides in the virtual address space. The table and diagram below depict what a process looks like in memory.

Component	Purpose
Code	Code to be executed by the process.
Global Variables	Stored variables.
Process Heap	Defines the heap where data is stored.
Process Resources	Defines further resources of the process.
Environment Block	Data structure to define process information.



This information is excellent to have when we get deeper into exploiting and abusing the underlying technologies, but they are still very abstract. We can make the process tangible by observing them in the *Windows Task Manager*. The task manager can report on many components and information about a process. Below is a table with a brief list of essential process details.

Value/Component	Purpose	Example
Name	Define the name of the process, typically inherited from the application	conhost.exe
PID	Unique numerical value to identify the process	7408
Status	Determines how the process is running (running, suspended, etc.)	Running
User name	User that initiated the process. Can denote privilege of the process	SYSTEM

These are what you would interact with the most as an end-user or manipulate as an attacker.

There are multiple utilities available that make observing processes easier; including <u>Process</u> <u>Hacker 2, Process Explorer</u>, and <u>Procmon</u>.

Processes are at the core of most internal Windows components. The following tasks will extend the information about processes and how they're used in Windows.



A thread is an executable unit employed by a process and scheduled based on device factors.

Device factors can vary based on CPU and memory specifications, priority and logical factors, and others.

We can simplify the definition of a thread: "controlling the execution of a process."

Since threads control execution, this is a commonly targeted component. Thread abuse can be used on its own to aid in code execution, or it is more widely used to chain with other API calls as part of other techniques.

Threads share the same details and resources as their parent process, such as code, global variables, etc. Threads also have their unique values and data, outlined in the table below.

Component	Purpose
Stack	All data relevant and specific to the thread (exceptions, procedure calls, etc.)
Thread Local Storage	Pointers for allocating storage to a unique data environment
Stack Argument	Unique value assigned to each thread
Context Structure	Holds machine register values maintained by the kernel

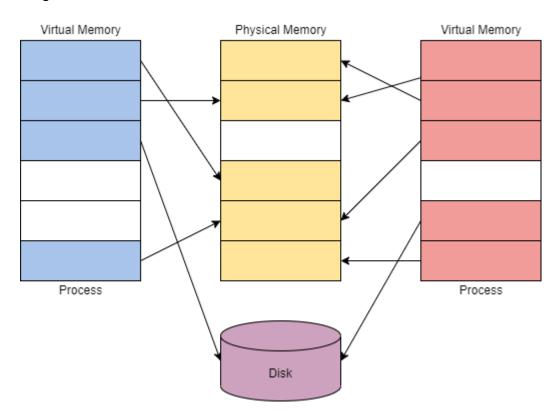
Threads may seem like bare-bones and simple components, but their function is critical to processes.

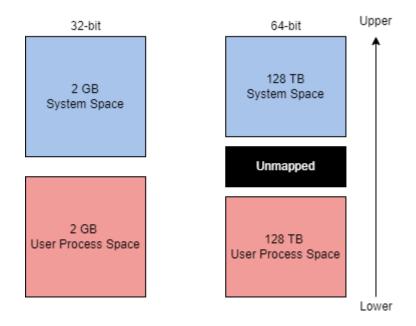
Open the provided file: "Logfile.PML" in Procmon and answer the questions below.		
No answer needed	✓ Correct Answer	
What is the thread ID of the first thread created by notepad.exe?		
5908	✓ Correct Answer	♀ Hint
What is the stack argument of the previous thread?		
6584	✓ Correct Answer	♀ Hint

Virtual memory is a critical component of how Windows internals work and interact with each other. Virtual memory allows other internal components to interact with memory as if it was physical memory without the risk of collisions between applications. The concept of modes and collisions is explained further in task 8.

Virtual memory provides each process with a <u>private virtual address space</u>. A memory manager is used to translate virtual addresses to physical addresses. By having a private virtual address space and not directly writing to physical memory, processes have less risk of causing damage.

The memory manager will also use *pages* or *transfers* to handle memory. Applications may use more virtual memory than physical memory allocated; the memory manager will transfer or page virtual memory to the disk to solve this problem. You can visualize this concept in the diagram below.





The theoretical maximum virtual address space is 4 GB on a 32-bit x86 system.

This address space is split in half, the lower half (0x00000000 - 0x7FFFFFFF) is allocated to processes as mentioned above. The upper half (0x80000000 - 0xFFFFFFFFF) is allocated to OS memory utilization. Administrators can alter this allocation layout for applications that require a larger address space through settings (increaseUserVA) or the AWE (Address Windowing Extensions).

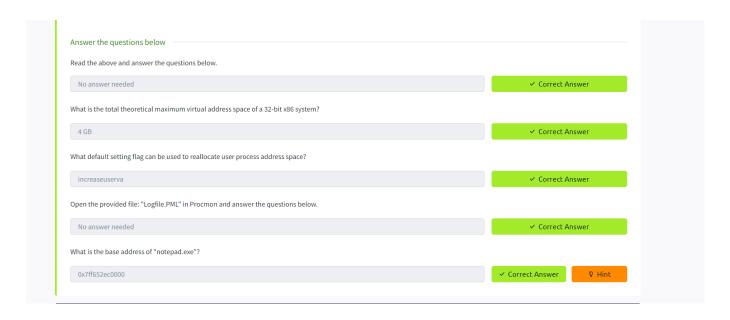
The theoretical maximum virtual address space is 256 TB on a 64-bit modern system.

The exact address layout ratio from the 32-bit system is allocated to the 64-bit system.

Most issues that require settings or AWE are resolved with the increased theoretical maximum.

You can visualize both of the address space allocation layouts to the right.

Although this concept does not directly translate to Windows internals or concepts, it is crucial to understand. If understood correctly, it can be leveraged to aid in abusing Windows internals.



The <u>Microsoft docs</u> describe a DLL as "a library that contains code and data that can be used by more than one program at the same time."

DLLs are used as one of the core functionalities behind application execution in Windows. From the <u>Windows documentation</u>, "The use of DLLs helps promote modularization of code, code reuse, efficient memory usage, and reduced disk space. So, the operating system and the programs load faster, run faster, and take less disk space on the computer."

When a DLL is loaded as a function in a program, the DLL is assigned as a dependency. Since a program is dependent on a DLL, attackers can target the DLLs rather than the applications to control some aspect of execution or functionality.

```
    DLL Hijacking (<u>T1574.001</u>)
    DLL Side-Loading (<u>T1574.002</u>)
    DLL Injection (<u>T1055.001</u>)
```

DLLs are created no different than any other project/application; they only require slight syntax modification to work. Below is an example of a DLL from the *Visual C++ Win32 Dynamic-Link Library project*.

```
#include "stdafx.h"
#define EXPORTING_DLL
#include "sampleDLL.h"
BOOL APIENTRY DllMain( HANDLE hModule, DWORD ul_reason_for_call, LPVOID
lpReserved
)
{
    return TRUE;
}
```

```
void HelloWorld()
{
    MessageBox( NULL, TEXT("Hello World"), TEXT("In a DLL"), MB_OK);
}
```

Below is the header file for the DLL; it will define what functions are imported and exported. We will discuss the header file's importance (or lack of) in the next section of this task.

```
#ifndef INDLL_H
    #define INDLL_H
    #ifdef EXPORTING_DLL
        extern __declspec(dllexport) void HelloWorld();
#else
        extern __declspec(dllimport) void HelloWorld();
#endif
#endif
```

The DLL has been created, but that still leaves the question of how are they used in an application?

DLLs can be loaded in a program using load-time dynamic linking or run-time dynamic linking.

When loaded using *load-time dynamic linking*, explicit calls to the DLL functions are made from the application. You can only achieve this type of linking by providing a header (.h) and import library (.lib) file. Below is an example of calling an exported DLL function from an application.

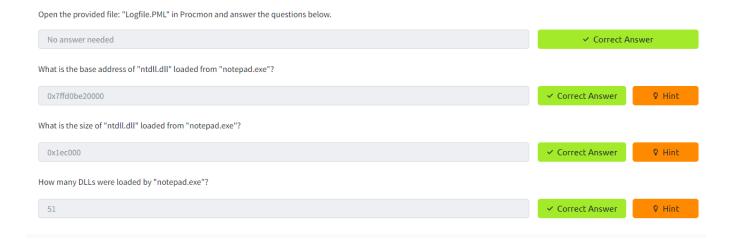
```
#include "stdafx.h"
#include "sampleDLL.h"
int APIENTRY WinMain(HINSTANCE hInstance, HINSTANCE hPrevInstance, LPSTR
lpCmdLine, int nCmdShow)
{
    HelloWorld();
    return 0;
}
```

When loaded using *run-time dynamic linking*, a separate function

(LoadLibrary or LoadLibraryEx) is used to load the DLL at run time. Once loaded, you need to use GetProcAddress to identify the exported DLL function to call. Below is an example of loading and importing a DLL function in an application.

```
typedef VOID (*DLLPROC) (LPTSTR);
```

In malicious code, threat actors will often use run-time dynamic linking more than load-time dynamic linking. This is because a malicious program may need to transfer files between memory regions, and transferring a single DLL is more manageable than importing using other file requirements.



Executables and applications are a large portion of how Windows internals operate at a higher level. The PE (**P**ortable **E**xecutable) format defines the information about the executable and stored data. The PE format also defines the structure of how data components are stored.

The PE (**P**ortable **E**xecutable) format is an overarching structure for executable and object files. The PE (**P**ortable **E**xecutable) and COFF (**C**ommon **O**bject **F**ile **F**ormat) files make up the PE format.

PE data is most commonly seen in the hex dump of an executable file. Below we will break down a hex dump of calc.exe into the sections of PE data.

The structure of PE data is broken up into seven components,

## The **DOS Header** defines the type of file

The MZ DOS header defines the file format as .exe. The DOS header can be seen in the hex dump section below.

The **DOS Stub** is a program run by default at the beginning of a file that prints a compatibility message. This does not affect any functionality of the file for most users.

The DOS stub prints the message This program cannot be run in DOS mode. The DOS stub can be seen in the hex dump section below.

```
00000040 0E 1F BA 0E 00 B4 09 CD 21 B8 01 4C CD 21 54 68 ..º..´.ĺ!¸.Lĺ!Th 00000050 69 73 20 70 72 6F 67 72 61 6D 20 63 61 6E 6E 6F is program canno 00000060 74 20 62 65 20 72 75 6E 20 69 6E 20 44 4F 53 20 t be run in DOS 00000070 6D 6F 64 65 2E 0D 0D 0A 24 00 00 00 00 00 00 mode....$......
```

The **PE File Header** provides PE header information of the binary. Defines the format of the file, contains the signature and image file header, and other information headers.

The PE file header is the section with the least human-readable output. You can identify the start of the PE file header from the PE stub in the hex dump section below.

The **Image Optional Header** has a deceiving name and is an important part of the **PE File Header** 

The **Data Dictionaries** are part of the image optional header. They point to the image data directory structure.

The **Section Table** will define the available sections and information in the image. As previously discussed, sections store the contents of the file, such as code, imports, and data. You can identify each section definition from the table in the hex dump section below.

Now that the headers have defined the format and function of the file, the sections can define the contents and data of the file.

Section	Purpose
.text	Contains executable code and entry point
.data	Contains initialized data (strings, variables, etc.)
.rdata or .idata	Contains imports (Windows API) and DLLs.
.reloc	Contains relocation information
.rsrc	Contains application resources (images, etc.)
.debug	Contains debug information

Read the above and answer the questions below.	
No answer needed	✓ Correct Answer
What PE component prints the message "This program cannot be run in DOS mode"?	
DOS Stub	✓ Correct Answer
Open "notepad.exe" in Detect It Easy and answer the questions below.	
No answer needed	✓ Correct Answer
What is the entry point reported by DiE?	
00000014001acd0	✓ Correct Answer
What is the value of "NumberOfSections"?	
0006	✓ Correct Answer
What is the virtual address of ".data"?	
00024000	✓ Correct Answer
What string is located at the offset "0001f99c"?	
Microsoft.Notepad	✓ Correct Answer

Interacting with Windows internals may seem daunting, but it has been dramatically simplified. The most accessible and researched option to interact with Windows Internals is to interface through Windows API calls. The Windows API provides native functionality to interact with the Windows operating system. The API contains the Win32 API and, less commonly, the Win64 API.

We will only provide a brief overview of using a few specific API calls relevant to Windows internals in this room. Check out the <u>Windows API room</u> for more information about the Windows API.

Most Windows internals components require interacting with physical hardware and memory.

The Windows kernel will control all programs and processes and bridge all software and hardware interactions. This is especially important since many Windows internals require interaction with memory in some form.

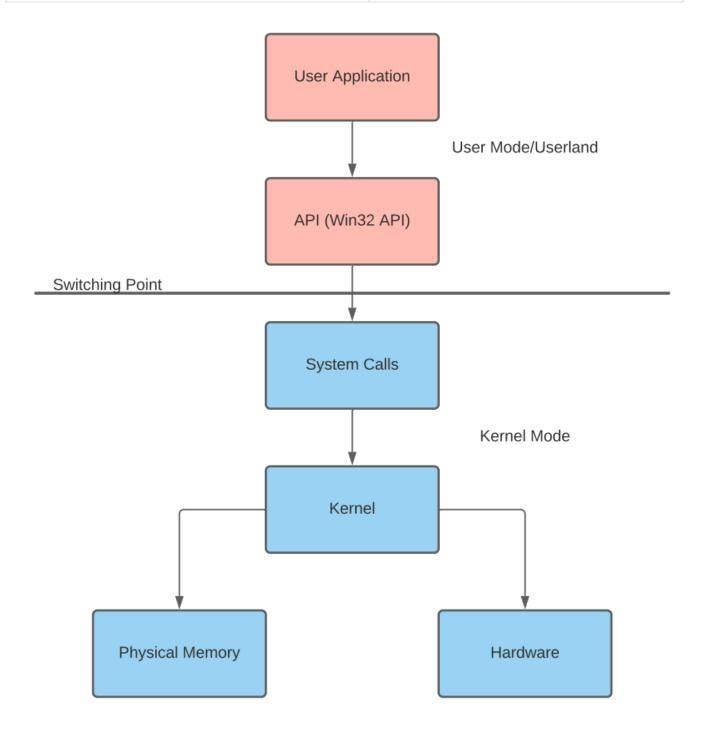
An application by default normally cannot interact with the kernel or modify physical hardware and requires an interface. This problem is solved through the use of processor modes and access levels.

A Windows processor has a *user* and *kernel* mode. The processor will switch between these modes depending on access and requested mode.

The switch between user mode and kernel mode is often facilitated by system and API calls. In documentation, this point is sometimes referred to as the "Switching Point."

User mode	Kernel Mode

No direct hardware access	Direct hardware access
Creates a process in a private virtual address space	Ran in a single shared virtual address space
Access to "owned memory locations"	Access to entire physical memory



Applications started in user mode or "*userland*" will stay in that mode until a system call is made or interfaced through an API. When a system call is made, the application will switch modes. Pictured right is a flow chart describing this process.

When looking at how languages interact with the Win32 API, this process can become further warped; the application will go through the language runtime before going through the API. The most common example is C# executing through the CLR before interacting with the Win32 API and making system calls.

We will inject a message box into our local process to demonstrate a proof-of-concept to interact with memory.

The steps to write a message box to memory are outlined below,

- 1. Allocate local process memory for the message box.
- 2. Write/copy the message box to allocated memory.
- 3. Execute the message box from local process memory.

At step one, we can use OpenProcess to obtain the handle of the specified process.

At step two, we can use VirtualAllocEx to allocate a region of memory with the payload buffer.

At step three, we can use WriteProcessMemory to write the payload to the allocated region of memory.

```
WriteProcessMemory(
    hProcess, // Opened target process
    remoteBuffer, // Allocated memory region
    payload, // Data to write
    sizeof payload, // byte size of data
```

```
NULL
);
```

At step four, we can use CreateRemoteThread to execute our payload from memory.

```
remoteThread = CreateRemoteThread(
    hProcess, // Opened target process
    NULL,
    0, // Default size of the stack
    (LPTHREAD_START_ROUTINE)remoteBuffer, // Pointer to the starting
address of the thread
    NULL,
    0, // Ran immediately after creation
    NULL
);
```

