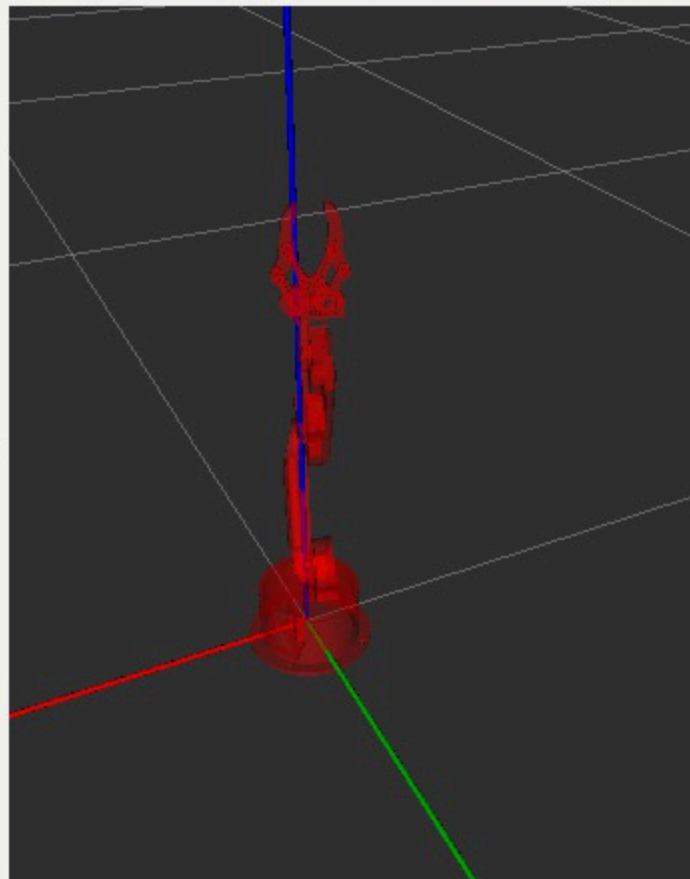


<ul style="list-style-type: none"> Global Options <ul style="list-style-type: none"> Fixed Frame Background Color Frame Rate Default Light Global Status: Ok <ul style="list-style-type: none"> Fixed Frame Grid Axes <ul style="list-style-type: none"> Status: Ok Reference Frame Length Radius RobotModel <ul style="list-style-type: none"> Status: Ok 	<ul style="list-style-type: none"> base 48; 48; 48 30 <input checked="" type="checkbox"/> OK <input checked="" type="checkbox"/> <input checked="" type="checkbox"/> <Fixed Frame> 1 0.0000 <input checked="" type="checkbox"/> <input checked="" type="checkbox"/>
---	---

Rename

ROS Time: 659911427.54 ROS Elapsed: 502.18 Wall Time: 1659911427.57 Wall Elapsed: 502.12 ☐ Experimental

31 fps



Rename

3

Interact Move Camera Select Focus Camera Measure 2D Pose Estimate 2D Nav Goal

Displays

- Global Options
 - Fixed Frame: base
 - Background Color: 48; 48; 48
 - Frame Rate: 30
 - Default Light: ☒
- Global Status: Ok
 - Fixed Frame: OK
- Grid: ☒
- Axes: ☒
 - Status: Ok
 - Reference Frame: <Fixed Frame>
 - Length: 1
 - Radius: 0.0000
- RobotModel: ☒
 - Status: Ok

Add Duplicate Remove Rename

joint_state_publisher

base_joint: 0.79

shoulder: -0.52

elbow: -0.37

wrist: 0.52

Randomize

Center

ϵ

Save Remove Rename

Time

ROS Time: 159911916.10 ROS Elapsed: 990.75 Wall Time: 1659911916.14 Wall Elapsed: 990.75 ☐ Experimental

Reset Left-Click: Rotate. Middle-Click: Move X/Y. Right-Click/Mouse Wheel: Zoom. Shift: More options.

31 fps