

## \* Clock Driven Scheduling:-

It is a periodic task scheduling method, primarily used for hard real-time systems, where all properties of all jobs are known at design time, such that offline scheduling techniques can be used.

When scheduling is clock driven decisions about what job executes when, are made at specific time instants. These instants are chosen before the system begins execution.

Two important clock driven schedulers are:

- 1) Table - driven
- 2) Cyclic schedulers.

## \* General Structure of Cyclic Schedule :-

It describes the frame size, major cycles and its constraints.

### ↳ Frame & Major Cycles :-

The scheduling decision time partitions the time line into intervals called frames. Every frame has length  $f$ , where  $f$  is the frame size.

Every scheduling decisions are made only at the beginning of frame, there is no preemption within each frame. The first job of every task is released at the beginning of some frame.

## 2) Frame Size Constraints :-

These constraints help to decide the frame size.

### (i) Minimum context switching:

frame  
we want the "f" to be sufficiently long so that every job can start and complete its execution within a frame. In this way, no job will be preempted.

$$f \geq \max(e_i)$$

### (ii) Frame size:

To keep the length of the cyclic schedule as short as possible, the frame size f should be chosen so that it divides H (length of hyper period). This condition met, when f divides the  $P_i$  of atleast one task  $T_i$ .

$$\left\lfloor \frac{P_i}{f} \right\rfloor - \frac{P_i}{f} = 0$$

$$\frac{P}{f} = \text{integer}$$

To make it possible for the scheduler to determine whether every job completes by its deadline, the frame size should be sufficiently small and there is atleast one frame between the release time and deadline of every job.

$$2f - \text{GCD}(P_i, f) \leq D_i$$

### (iii) Job Slices:

(2)

Sometimes, the given parameters of some task cannot meet all three frame size constraints simultaneously. In this situation, partition the task that has a large execution time into slices with smaller execution times.

EX

A cyclic scheduler is to be used to run the following set of periodic tasks on a uniprocessor, find out the frame size.

$$T_1 = (1, 4), T_3 = (1, 20) \quad T_j = (c_j, p_j)$$

$$T_2 = (1, 5), T_4 = (2, 20) \quad \& \quad d_j = p_j$$

Sol<sup>n</sup>

Constraint 1:  $F \geq \max(c_i)$

$$F \geq 2$$

constraint 2:

$$H = \text{LCM}(4, 5, 20) = 20$$

$F$  can be  $2, 4, 5, 10, 20$

$$\boxed{\frac{p_j}{f} = \text{integer}}$$

for at least one

constraint 3:  $2f - \text{GCD}(p_i, f) \leq d_i$

for  $f = 2$

$$T_1 \Rightarrow 2 \times 2 - \text{GCD}(4, 2) \leq 4$$

$$4 - 2 = 2 \leq 4 \quad \text{True}$$

$$T_2 \Rightarrow 2 \times 2 - \text{GCD}(5, 2) = 3 \leq 5 \quad \text{True}$$

$$T_3 \Rightarrow 2 \times 2 - \text{GCD}(20, 2) = 2 \leq 20 \quad \text{True}$$

$$T_4 \Rightarrow 2 \times 2 - \text{GCD}(20, 2) = 2 \leq 20 \quad \text{True}$$

True  
for all  
tasks

So frame size ( $f$ ) = 2 Ans.

Ex Consider the following set of periodic real-time tasks to be scheduled by a cyclic scheduler. Determine the frame size for the task set.

$$T_1 = (1, 4)$$

$$T_j = (c_j, p_j, d_j)$$

$$T_2 = (2, 5, ?)$$

$$\text{ & } \cancel{d_j = p_j} \text{ for } T_1 \text{ & } T_2$$

$$T_3 = (5, 20)$$

Sol<sup>n</sup>

Constraint 1:  $f \geq \max(c_i)$

$$f \geq 5$$

Constraint 2:

$$\frac{p_j}{f} = \text{integer for at least one task}$$

$$f \text{ can be } 5, 10, 20.$$

Constraint 3:

$$2f - \text{GCD}(p_j, f) \leq d_i$$

for  $f = 5$

$$T_1 \Rightarrow 2 \times 5 - \text{GCD}(4, 5) \leq 4$$

$$10 - 1 = 9 \leq 4 \text{ false}$$

So we partition the task which has higher execution time.

so split  $T_3$  into two or three tasks.

$$T_{3,1} = (3, 20) \quad ① \quad f \geq 3$$

$$T_{3,2} = (2, 20) \quad ② \quad f \text{ can be } 4, 5, 10, 20$$

$$③ \text{ for } f = 4$$

$$T_1 \Rightarrow 8 - 4 = 4 \leq 4 \text{ true}$$

$$T_2 \Rightarrow 8 - 1 = 7 \leq 7 \text{ true}$$

$$T_{3,1} \Rightarrow 8 - 4 = 4 \leq 4 \text{ true}$$

$$T_{3,2} \Rightarrow 8 - 4 = 4 \leq 4 \text{ true}$$

$$\text{so frame size } (f) = 4 \text{ Ans.}$$

## \* Fixed-Priority Scheduling Algorithm:-

③

It assigns the same priority to all the jobs in each task. Rate monotonic algorithms ~~are~~ and deadline monotonic algorithm are based on fixed priority scheduling algorithm.

### 1) Rate-Monotonic Algorithm (RMA):-

In this algorithm priorities are assigned to task according to their periods. The task which has shorter period has higher priority.

$$\boxed{\text{Period} \downarrow \Rightarrow \text{Priority} \uparrow}$$

Ex  $T_i = (P_i, C_i)$

$$T_1 = (4, 1), T_2 = (5, 2) \text{ & } T_3 = (20, 5)$$

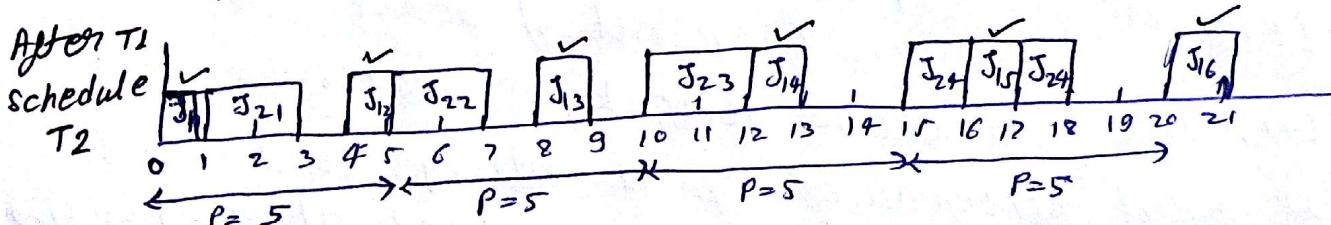
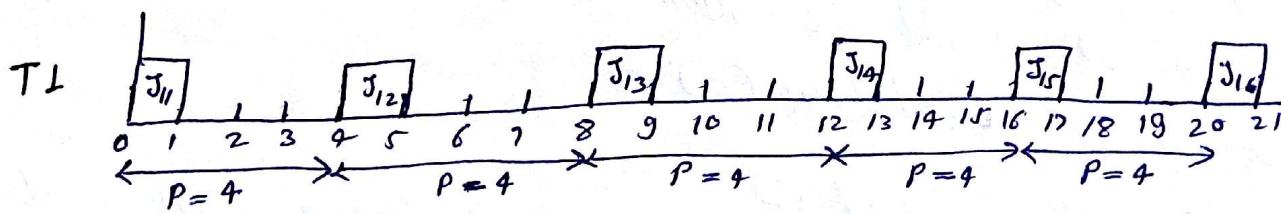
Schedule all tasks on uni-processor using RMA.

Sol<sup>n</sup>

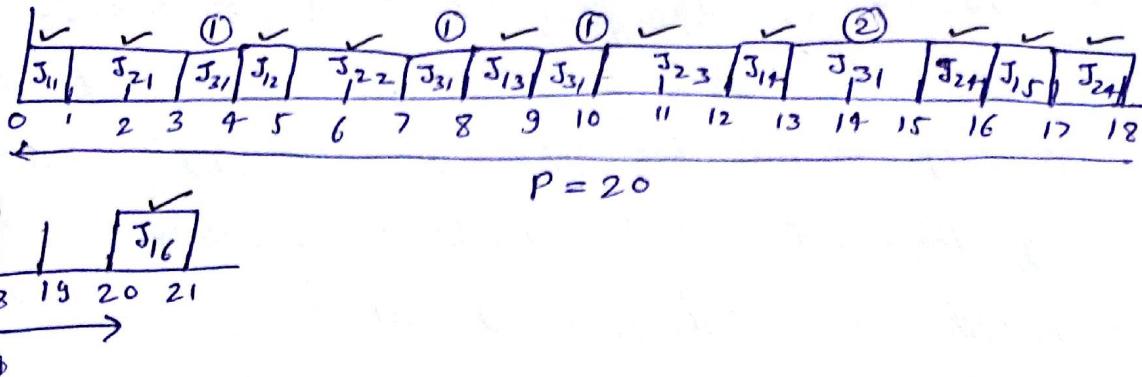
$$\therefore \text{Period} \downarrow \Rightarrow \text{Priority} \uparrow$$

$$\therefore T_1 > T_2 > T_3 \text{ (Priority order)}$$

Task  $T_1$  has highest priority; so it ~~will~~ will schedule first and it can preempt all other task. After  $T_1$ , task  $T_2$  and  $T_3$  schedule according to their priority. All tasks release at time 0.



After  $T_1$  &  $T_2$   
schedule  $T_3$



## \* Schedulability Test for RMA:-

### 1) Necessary Condition :-

A set of periodic real time tasks would not be RMA schedulable unless they satisfy the necessary condition. This condition is necessary but not sufficient.

$$\boxed{\sum_{j=1}^n \frac{C_j}{P_j} \leq 1}, \text{ where } \frac{C_j}{P_j} = U_j \text{ (utilization)}$$

$C_j \rightarrow$  execution time,  $P_j \rightarrow$  period,  $n \rightarrow$  no. of tasks.

### 2) Sufficient condition :-

a) Liu & Layland :- It was obtained by Liu and Layland in 1973.

$$\sum_{j=1}^n U_j \leq n(2^{m-1})$$

If set of task satisfies this sufficient condition, then it would be RMA schedulable and not required to check condition (b).

b) Lehoczky's Test :- When set of tasks fails condition (a), then we check Lehoczky's test. So task set is RMA schedulable if it satisfies condition 1 and in condition 2 either (a) or (b).

$$e_i + \sum_{k=1}^{j-1} \left[ \left\lceil \frac{d_j}{d_k} \right\rceil \times e_k \right] \leq d_i$$

Here  $k = 1$  to  $j-1$  are those task which has higher precedence than  $i$ .

Ex

$$T = (e, p)$$

$$T_1 = (20, 100), T_2 = (30, 150), T_3 = (60, 200)$$

check it satisfy the schedulability of RMA.

Sol<sup>n</sup>

$$1) \quad \sum_{j=1}^n u_j \leq 1$$

$$\sum u_j = \frac{20}{100} + \frac{30}{150} + \frac{60}{200}$$

$$\sum u_j = 0.7 \leq 1$$

so 1<sup>st</sup> condition satisfy.

$$2) (a) \quad \sum_{j=1}^n u_j \leq n(2^{1/n} - 1)$$

$$0.7 \leq 3(2^{1/3} - 1)$$

$$0.7 \leq 0.78$$

II<sup>nd</sup> condition satisfy; so don't require to check condition 2 (b).

so all these tasks are schedulable under RMA.

Ex

$$T_1 = (20, 100)$$

$$T_i = (e_i, p_i)$$

$$T_2 = (30, 150)$$

$$T_3 = (60, 200)$$

$$\& d_i = p_i$$

check it satisfy the schedulability of RMA.

Note

If  $d_i$  is not given, then by default  $d_i = p_i$

$$\text{Soln} \Rightarrow \sum_{j=1}^n u_j \leq 1$$

$$\sum_{j=1}^n u_j = \frac{20}{100} + \frac{30}{150} + \frac{90}{200}$$

$$\sum_{j=1}^n u_j = 0.85 \leq 1 \quad (\text{1st condition satisfy}).$$

$$\Rightarrow (a) \quad \sum_{j=1}^n u_j \leq n(2^{j_m} - 1)$$

$$0.85 \leq 3(2^{1/3} - 1)$$

$$0.85 \neq 0.78 \quad (\text{Not satisfy})$$

so check condition 2(b).

$$(b) \quad c_i + \sum_{k=1}^{j-1} \left\{ \left[ \frac{d_j}{d_k} \right] \times c_k \right\} \leq d_i$$

$$\text{For } T_1 \Rightarrow c_1 \leq d_1$$

$$20 \leq 100$$

$$\text{For } T_2 \Rightarrow c_2 + \left( \frac{d_2}{d_1} \times c_1 \right) \leq d_2$$

$$30 + 30 \leq 150$$

$$60 \leq 150$$

$$\text{For } T_3 \Rightarrow c_3 + \left( \frac{d_3}{d_2} \times c_2 + \frac{d_3}{d_1} \times c_1 \right) \leq d_3$$

$$90 + (40 + 40) \leq 200$$

$$170 \leq 200$$

condition 2(b) satisfy.

so all these tasks are ~~satisfy~~ schedulable under RMA.

## 2) Deadline - Monotonic Algorithm (DMA) :-

(5)

It is also a fixed-priority algorithm. In this algorithm priorities are assigned according to their relative deadlines. Shorter the relative deadline, task has higher priority.

Relative deadline  $\downarrow \Rightarrow$  Priority  $\uparrow$

EX

$$T_i = (\phi_i, P_i, C_i, d_i)$$

$$T_1 = (50, 50, 25, 100)$$

$$T_2 = (0, 62.5, 10, 20)$$

$$T_3 = (0, 125, 25, 50)$$

Schedule tasks on uniprocessor using DMA.

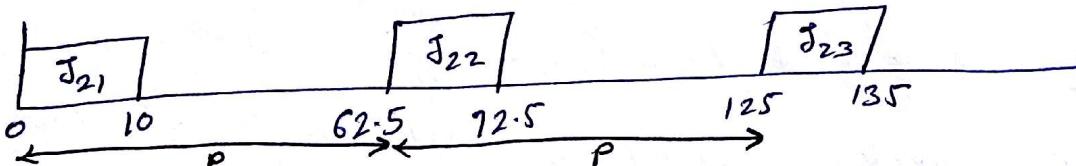
soln

Relative deadline  $\downarrow \Rightarrow$  Priority  $\uparrow$

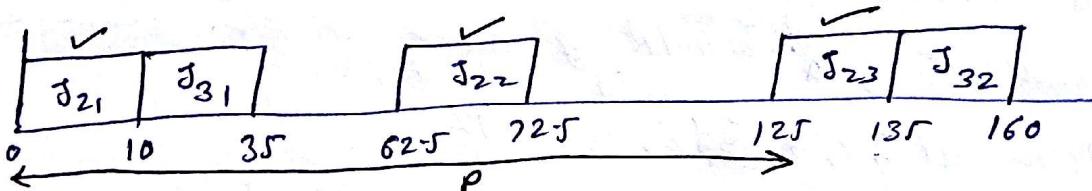
$$\text{so } T_2 > T_3 > T_1 \text{ (Priority Order)}$$

First schedule task T2 then T3 and T1. Here higher priority task can preempt lower priority task.

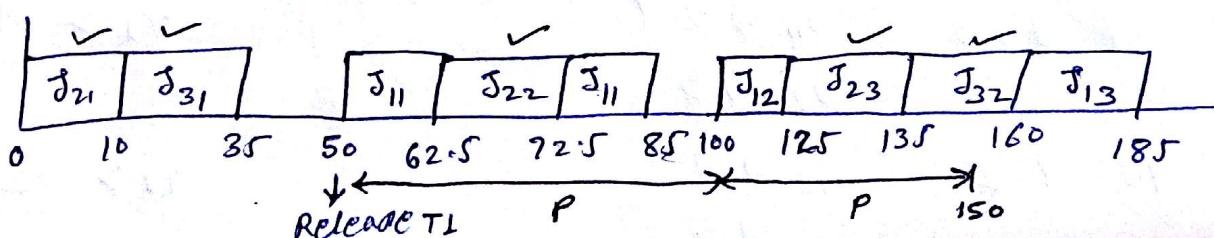
Schedule  
T2



Schedule  
T3



Schedule  
T1



\* Dynamic Priority Scheduling Algorithm:-  
It assigns different priority to the individual job in each task. The priority of the task with respect to other tasks changes as job are released and completed. Dynamic scheduling algorithm are -

- 1) Earliest Deadline First (EDF)
- 2) Least Slack Time (LST)
- 1) Earliest Deadline First (EDF):-

In this algorithm priorities are assigned according to their absolute deadline. A job with lower absolute deadline has higher priority.

Absolute deadline  $\downarrow \Rightarrow$  Priority  $\uparrow$

where Absolute deadline = Release time + Relative deadline

In periodic task, a job release after each period.

Ex

$$T_1 = (P_1, e_1) \text{ & } d_1 = P_1$$

$$T_1 = (2, 0.9) \text{ & } T_2 = (5, 2.3)$$

Sol  
we check priority of each task at the position multiple of ~~period~~ of each task. ~~of all tasks~~

Here at 0, 2, 4, ~~5~~, 6, 8, 10, 12, ...

$$\text{At } t=0 \quad J_{11} \Rightarrow 2 \text{ (Absolute deadline)} \quad T_1 > T_2$$

$$J_{21} \Rightarrow 5$$

$$\text{At } t=2 \quad J_{12} \Rightarrow 4 \quad T_1 > T_2$$

$$J_{21} \Rightarrow 5$$

At  $t=4$

$$\begin{array}{l} J_{13} = 6 \\ J_{21} = 5 \end{array}$$

$T_2 > T_1$

~~At  $t=5$~~

At  $t=5$

$$\begin{array}{l} \cancel{J_{13}} = 6 \\ \cancel{J_{22}} = 10 \end{array}$$

$$\begin{array}{l} J_{13} = 6 \\ J_{22} = 10 \end{array}$$

~~At  $t=5$~~   $T_1 > T_2$

At  $t=6$

$$\begin{array}{l} J_{14} = 8 \\ J_{22} = 10 \end{array}$$

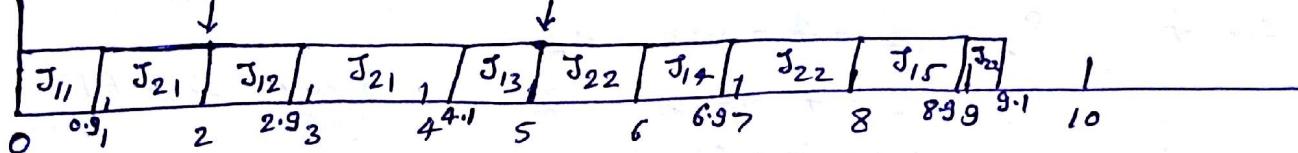
$T_1 > T_2$

At  $t=8$

$$\begin{array}{l} J_{15} = 10 \\ J_{22} = 10 \end{array}$$

$T_1 = T_2$  (Any job can schedule)

Preempt by  $T_1$   $\because J_{13}$  has completed, so start  $J_{22}$  at  $t=5$



## 2) Least Slack Time (LST) :-

In this algorithm priorities are

assigned according to slack time. At time  $t$ , the slack time of each task job is -

$$\text{At time } t \Rightarrow S_i = d_i - t - x_i$$

where  $d_i$  is the absolute deadline of job task  $i$   
 $x_i$  is the remaining execution time of job task  $i$

Task which has lower slack time, assign higher priority.

$$\boxed{\text{Slack Time} \downarrow \Rightarrow \text{Priority} \uparrow}$$

Ex

$$T_j = (P_j, C_j) \text{ & } d_i = P_j$$

$$T_1 = (2, 0.8)$$

$$T_2 = (5, 1.5)$$

$$T_3 = (5.1, 1.5)$$

Schedule task using LST.

