

# Non-isomorphic Mappings in Synchronous Derivations

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## 1 Introduction

The formalism of synchronous tree adjoining grammars was introduced as a means for defining mappings between pairs of standard tree adjoining grammars (TAGs). Each mapping defines a (reversible) translation from the strings generated by one TAG in the pair to the other<sup>1</sup>. This mapping was first defined (in [2]) as an iterative rewriting process over derived trees by using links between nodes of the derived trees of a pair of TAGs. However, this definition of synchronous TAGs was modified in [1] and [3] for different reasons. [3] showed that the original definition had two major shortcomings: the rewriting definition could generate strings not in the set of tree adjoining languages (TALs) and the notion of rewriting derived trees was not well-defined in terms of derivation trees. To solve these problems with synchronous TAGs [3] proposes a definition in terms of pairs of isomorphic derivation trees for a pair of TAGs. [1] also redefines synchronous TAGs (for implementational reasons) as a mapping of a derivation tree from a source TAG to a derivation tree in the target TAG. Notably, the approach in [1] considers mappings between derivations that are not isomorphic. This paper looks at the formal nature of non-isomorphic mappings between TAGs.

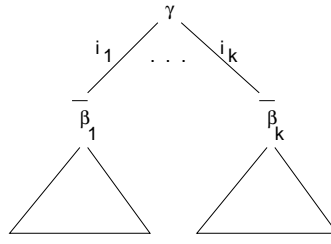
First, we establish some notations and definitions used. Given a TAG, we can represent derivations by *derivation trees* (Definition 1). The adjunction of several trees  $\gamma_1, \dots, \gamma_k$  into a tree  $\gamma$  at distinct addresses  $i_1, \dots, i_k$ , respectively is denoted by  $\gamma[i_1, \gamma_1] \dots [i_k, \gamma_k]$

**Definition 1 (Derivation trees).** Derivation trees have the following inductive definition:

- If  $\gamma$  is an elementary tree with no OA constraints the derivation tree consists of a single node labelled  $\overline{\gamma}$ .
- If  $\gamma_j$  is a derivation tree with root labelled  $\overline{\beta_j}$  for  $1 \leq j \leq k$  then given the derivation

$$\gamma' = \gamma[i_1, \beta_1] \dots [i_k, \beta_k]$$

then following (Fig 1) is also a derivation tree



**Fig. 1.** Definition of derivation tree.

For any TAG we can give a CFG whose tree set is exactly the set of derivation trees for the TAG. [5] defines Generalized Context-Free Grammars (GCFGs) which generates a set of trees that can be interpreted as derivation trees in a TAG.

**Definition 2.** A **GCFG** is written as  $G = (V, S, F, P)$ , where

- $V$  is a set of variables
- $S$  is a distinguished member of  $V$
- $F$  is a finite set of function symbols
- $P$  is a finite set of productions of the form

$$A \rightarrow f(A_1, \dots, A_n)$$

where  $n \geq 0$ ,  $f \in F$ , and  $A, A_1, \dots, A_n \in V$

The set of terms,  $T(G)$  derived from a GCFG,  $G$  is the set of all  $t$  such that  $S \xrightarrow{*} t$  where the *derives* relation is defined as follows.

- $A \xrightarrow{G} f()$  if  $A \rightarrow f()$  is a production.
- $A \xrightarrow{*G} f(t_1, \dots, t_n)$  if  $A \rightarrow f(A_1, \dots, A_n)$  is a production, and  $A_i \xrightarrow{*G} t_i$  for  $1 \leq i \leq n$ .

For each zero arity function  $f \in F$ , we let  $\llbracket f() \rrbracket_{TAG} = \gamma$ , where  $\gamma$  is a complete elementary tree (i.e. with no OA nodes). For each function  $f \in F$  of  $n$  arguments, where  $n \geq 1$ , we let

$$\llbracket f(t_1, \dots, t_n) \rrbracket_{TAG} = \gamma[a_1, \llbracket t_1 \rrbracket_{TAG}] \dots [a_n, \llbracket t_n \rrbracket_{TAG}]$$

$\gamma$  is a tree in which trees  $\llbracket t_1 \rrbracket_{TAG}, \dots, \llbracket t_n \rrbracket_{TAG}$  are adjoined at addresses  $a_1, \dots, a_n$  to produce  $\llbracket f(t_1, \dots, t_n) \rrbracket_{TAG}$ . Note that for any GCFG production,

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<sup>1</sup> A familiarity with TAGs and synchronous TAGs as defined in, for instance, [4] and [2] is assumed.

say  $A \rightarrow f(A_1, A_2)$  we can construct another production  $A \rightarrow f'(A_2, A_1)$  without changing the interpretation of the GCFG. We shall use this fact heavily in later sections.

**Definition 3 (Synchronous TAGs).** A synchronous TAG  $G$  is defined as a set of triples  $\{ \langle L_i, R_i, \cap_i \rangle \}$  where the  $L_i$  and  $R_i$  are elementary trees, both initial and auxiliary and  $\cap_i$  is the set of links between tree addresses in  $L_i$  and  $R_i$ .

Thus,  $G_L = \{L_i\}$  and  $G_R = \{R_i\}$  form the two component TAGs, and in general for a tuple  $\langle x_L, x_R, \dots \rangle$ ,  $x_L$  and  $x_R$  are taken to be its first and second components. Also, the tree associated with a node  $\alpha$  in a derivation tree is referred to as  $\overline{\alpha}$  and the parent of a node  $\alpha$  in a tree is denoted as  $parent(\alpha)$ .

## 2 Isomorphic Synchronous TAG Derivations

For a synchronous TAG  $G$  a derivation is stated as a pair of derivation trees  $D_S = \langle D_L, D_R \rangle$ . Parsing in a synchronous TAG is typically defined as

$$w_L \longrightarrow D_L \longrightarrow D_S \longrightarrow w_R$$

where  $\langle w_L, w_R \rangle \in L(G)$  and using TAG  $G_L$  to parse  $w_L$ . Using the set of links  $\cap$  we obtain  $D_S$  and its right projection  $D_R$  yields the string  $w_R$ . However, as shown in [3] the mapping from  $D_L$  to  $D_S$  is not well defined unless the following conditions hold.

1.  $D_L$  and  $D_R$  are well formed derivation trees relative to  $G_L$  and  $G_R$  respectively.
2.  $D_L$  and  $D_R$  are isomorphic with respect to dominance relations in the trees, i.e. if  $f$  is such an isomorphic map then if  $f(\eta_l) = \eta_r$  then  $f(parent(\eta_l)) = parent(\eta_r)$ .
3. They are also isomorphic with respect to the linking between tree pairs. So, if  $f(\eta_l) = \eta_r$ , then  $\langle \overline{\eta_l}, \overline{\eta_r}, \cap \rangle \in G$  and  $\langle \overline{parent(\eta_l)}, \overline{parent(\eta_r)}, \cap' \rangle \in G$  and  $\langle a, b \rangle \in \cap'$  (the addresses where  $\eta_l$  and  $\eta_r$  adjoined into their parents).

We redefine this notion of a synchronous TAG derivation as a mapping from terms in a GCFG to derivation trees.

**Definition 4 (Isomorphic Synchronous TAGs).** For a synchronous TAG  $G = \langle G_L, G_R, \cap \rangle$  there is a GCFG  $G_L'$  which defines the set of the derivation trees of  $G_L$  (from Definition 2). Then we define  $\llbracket \cdot \rrbracket_{STAG}$  as follows,

1.  $\llbracket f() \rrbracket_{STAG} = \gamma$  where  $\langle \llbracket f() \rrbracket_{TAG}, \gamma, \cap \rangle \in G$
2.  $\llbracket f(t_1, \dots, t_n) \rrbracket_{STAG} = \gamma[b_1, \llbracket t_1 \rrbracket_{STAG}] \dots [b_n, \llbracket t_n \rrbracket_{STAG}]$ , where
  - $\langle \varphi, \gamma, \cap \rangle \in G$
  - $\{a_1 \cap b_1, \dots, a_n \cap b_n\} \subseteq \cap$  and
  - $\llbracket f(t_1, \dots, t_n) \rrbracket_{TAG} = \varphi[a_1, \llbracket t_1 \rrbracket_{TAG}] \dots [a_n, \llbracket t_n \rrbracket_{TAG}]$

3. Let  $\gamma[a, \phi] = \gamma$  and let  $\llbracket f() \rrbracket_{TAG} = \phi$  whenever  $\langle \llbracket f() \rrbracket_{TAG}, \gamma, \rhd \rangle \notin G$

**Theorem 5.** *Synchronous TAGs defined as a pair of isomorphic derivations (Definition 4) generate exactly the set of tree-adjoining languages.*

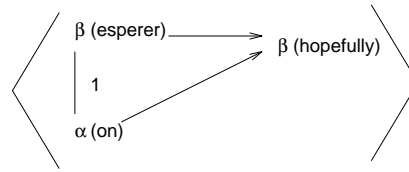
*Proof.* The definition given (Definition 4) always derives a derivation tree which satisfies the isomorphism requirement with respect to dominance relations and linking between nodes. Since the definition given is equivalent to that in [3] the proof in [3][page 8] suffices.

### 3 Non-isomorphic Mappings

There are several examples from the application of synchronous TAGs to areas such as the definition of translations between natural languages and the modelling of natural language semantics for which the isomorphism requirement is found to be too strong a restriction. The following examples are taken from a synchronous TAG mapping between English and French from the implementation by [1]. For more comprehensive arguments about the isomorphism requirement the reader is referred to [3] and [2].

As [2] points out, the English adverbial “hopefully” corresponds to the French phrase “on espère que”. Fig 2 shows the derivation trees and their mapping (which is non-isomorphic). Such a case also occurs in building semantic structures for idioms where a complex syntactic phrase such as “kick the bucket” could be mapped to an atomic formula (“die”) in the semantic representation.

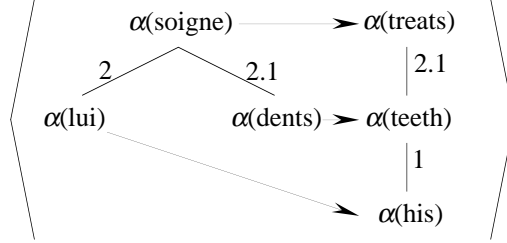
- (1) On espère qu’il ne va pas pleuvoir.  
Hopefully it won’t rain.



**Fig. 2.** Schematic derivation tree pair for example (1). The arrows show the required mapping between the derivations, which is not an isomorphism.

In (2) “de Jean” is substituted into the “dents” tree, whereas in (3) “lui” cliticizes in the tree for “soigne” while in the English sentence both the proper name and the pronoun are part of the object NP of the verb. Again the derivations are not isomorphic as shown by Fig 3.

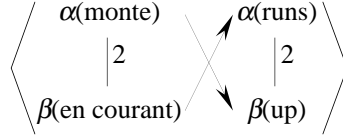
- (2) Le docteur soigne les dents de Jean.  
The doctor treats Jean's teeth.
- (3) Le docteur lui soigne les dents.  
The doctor treats his teeth.



**Fig. 3.** Schematic derivation tree pair for example (3).

In (4) “en courant” adjoins as an adverbial modifier to the verb “monte”. Under the natural mapping, “en courant” would be mapped with “runs” and “monte” with “up”. However such a mapping causes an inversion in the dominance of the node in the derivation tree (see Fig 4).

- (4) Jean monte la rue en courant.  
John runs up the street.



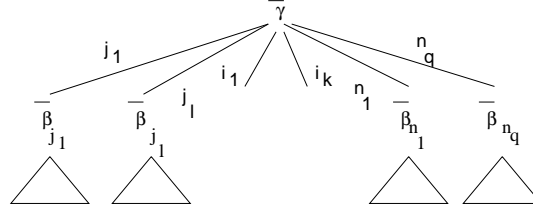
**Fig. 4.** Schematic derivation tree pair for example (4).

### 3.1 Bounded Non-isomorphic Mappings

In the above examples the non-isomorphic maps are bounded, and hence can be handled by allowing bounded subtrees of the derivation tree (or subderivations) to be treated as elementary constituents and stored in the lexicon as a unit. This is the alternative taken in [1] and also mentioned as a solution in [3]. A subderivation is defined as an  $m$ -incomplete derivation tree (see Definition 6).

**Definition 6** (*m*-incomplete derivation tree, [4]). A *m*-incomplete derivation tree is defined by the following conditions:

1. Any derivation tree is a 0-incomplete derivation tree.
2. Let  $\gamma$  an elementary tree. Let  $P$  be the set of addresses of nodes in  $\gamma$  with OA constraints, and let  $Q$  be the set of addresses of nodes in  $\gamma$  not having OA constraints. Let  $\{i_1, \dots, i_k : k \geq 0\} \subseteq P$ ,  $\{n_1, \dots, n_q : q \geq 0\}$  be the rest of the addresses in  $P$  and  $\{j_1, \dots, j_l : l \geq 0\} \subseteq Q$ . Let the auxiliary tree  $\beta_{j_p}$  be adjoinable at the node addressed  $\overline{j_p}$  in  $\gamma$  and  $\Gamma_{j_p}$  be a  $m_{j_p}$ -incomplete derivation tree with root symbol  $\overline{\beta_{j_p}}$  for  $1 \leq p \leq l$ . Similarly, let  $\beta_{n_p}$  be adjoinable at  $n_p$  in  $\gamma$  and  $\Gamma_{n_p}$  be a  $m_{n_p}$ -incomplete derivation tree with root symbol  $\overline{\beta_{n_p}}$  for  $1 \leq p \leq q$ . Then the derivation tree in Fig. 5 is an  $m = (k + m_{j_1} + \dots + m_{j_l} + m_{n_1} + \dots + m_{n_q})$ -incomplete derivation tree.



**Fig. 5.** *m*-incomplete derivation tree.

**Theorem 7.** For every  $\gamma$  derived with  $k$  ( $k \geq 0$ ) adjunctions such that there are  $m$  nodes in  $\gamma$  with OA constraints, there is a *m*-incomplete derivation tree  $\Gamma$  which describes  $\gamma$ .

*Proof.* In [4][page 25].

A synchronous TAG  $G$  is now defined as a set of triples  $\{< L_i, R_i, \curvearrowright_i >\}$  where the  $L_i$  and  $R_i$  are either elementary trees as before, or *m*-incomplete derivation trees. We add the following definition to the earlier definition (Definition 4) to allow the mapping of bounded (potentially) non-isomorphic derivation trees. We denote subderivations with the letters  $\Gamma, \Delta$ , etc.

**Definition 8** (Bounded Non-isomorphic Synchronous Derivations).

The following is added to Definition 4:

4.  $\llbracket f(t_1, \dots, t_m, t_{m+1}, \dots, t_n) \rrbracket_{STAG} =$   
 $\Delta[b_{m+1}, \llbracket t_{m+1} \rrbracket_{STAG}], \dots, [b_n, \llbracket t_n \rrbracket_{STAG}], [c_p, \llbracket t_p \rrbracket_{STAG}], \dots, [c_k, \llbracket t_k \rrbracket_{STAG}]$   
 where,

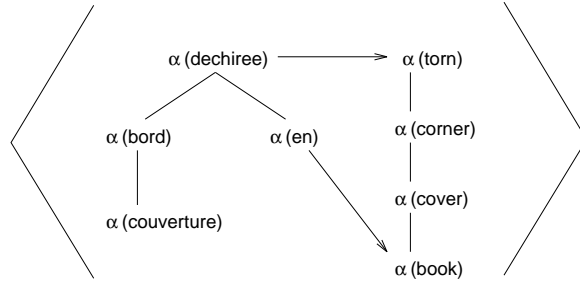
- $A_i \xRightarrow{G} f_i(t_{i_1}, \dots, t_{i_n}), 1 \leq i \leq m$  and  $m \geq 0$
- $\llbracket f(f_1(), \dots, f_m()) \rrbracket_{TAG} = \Gamma$
- $\langle \Gamma, \Delta, \neg \rangle \in G$ , and
- for each  $i, 1 \leq i \leq m, \llbracket f_i(t_{i_1}, \dots, t_{i_n}) \rrbracket_{TAG} = \gamma[c_{i_1}, \llbracket t_{i_1} \rrbracket_{TAG}] \dots [c_{i_n}, \llbracket t_{i_n} \rrbracket_{TAG}]$  and let  $\{c_p, \dots, c_k\} = \{c_{i_1}, \dots, c_{i_n}\} \cap \neg$  and let  $t_p \dots t_k$  be the associated terms.

Note that the above definition is only for subderivations of height at most one. For a more general version of the above definition all we have to do is substitute for  $A_i \xRightarrow{G} f_i(\dots)$  the statement  $A_i \xRightarrow{G^*} f_{i_1}(\dots(f_{i_n}(\dots)))$  and then check all subsets of the set of leftmost (or rightmost) derivations to check for  $\Gamma$  as above.

### 3.2 Unbounded Non-isomorphic Mappings

Although most of the examples discussed earlier seem to require only cases of bounded non-isomorphic mappings, there are cases when an unbounded distance can occur between subderivations to be transferred. For example:

- (5) Le bord de la couverture de ce livre est déchirée.  
 Le bord de la couverture en est déchirée.  
 The corner of the cover of the book is torn out.



**Fig. 6.** Schematic derivation tree pair for example (5).

For (5) Fig 6 shows an instance of an unbounded non-isomorphic map between the derivation trees for French and English. To handle such cases we now define an unbounded mapping in a synchronous TAG which is nevertheless restricted enough to preserve the formal properties defined in previous sections.

Unbounded subderivations are stored in the lexicon as a pair  $\langle P_L, P_R \rangle$  where both  $P_L$  and  $P_R$  are a finite set of GCFG productions. Let  $\Phi =$

$\{A_1, \dots, A_n\}$  be the set of lhs's of the productions in  $P_L$ . Then  $P_L$  is defined as the finite set of productions of the form:

- $A_i \rightarrow f_i(\alpha_i)$ , or
- $A_i \rightarrow f_i(A_p, \dots, A_q, \alpha_i)$ , where  $1 \leq i \leq n$ , and  $\{A_p, \dots, A_q\} \subseteq \Phi$  and each  $\alpha_i$  is any sequence of labels, possibly empty.

$P_R$  is then defined as:

- $A_i \rightarrow f_i(X, \alpha_i)$
- where,  $X$  is a sequence of labels, say  $A_p, \dots, A_q$  such that  $\{A_p, \dots, A_q\} \subseteq \Phi \cup \Phi'$  where  $\Phi'$  is the finite set of lhs's of new productions added to  $P_R$ .

Such a definition allows the introduction of a bounded number of productions into  $P_R$  and also allows the removal of productions. Now, given  $D_L$  to obtain  $D_S = \langle D_L, D_R \rangle$  take the GCFG  $G$  that corresponds to  $D_L$  and for each pair  $\langle P_L, P_R \rangle$  find productions of  $P_L$  in  $P_{D_L}$  (renaming labels as necessary) and replace them with productions in  $P_R$ .  $\llbracket \rrbracket_{STAG}$  can now be applied as before to obtain  $D_R$ . Note that this definition doesn't make clear that  $P_R$  will give us a well-formed TAG derivation tree. This requires a proof or further stipulation.

*Example 1.* For the unbounded example in (5) define  $P_L = \{S \rightarrow f(A_2, \alpha), A_2 \rightarrow f_2(\beta), A_3 \rightarrow f_3(\delta)\}$  and  $P_R = \{S \rightarrow f(\alpha), A_2 \rightarrow f_2(\beta), A_3 \rightarrow f_3(A_2, \delta)\}$ . Then for the following set of GCFG productions for the French example in Fig 6

- $\alpha(\text{déchirée}) : S \rightarrow f(A_1, A_2)$
- $\alpha(\text{bord}) : A_1 \rightarrow f_1(A_3)$
- $\alpha(\text{couverture}) : A_3 \rightarrow f_3()$
- $\alpha(\text{en}) : A_2 \rightarrow f_2()$

conversion of the productions above that are matched by  $P_L$  to the productions in  $P_R$  gives us the English derivation tree in Fig 6.

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