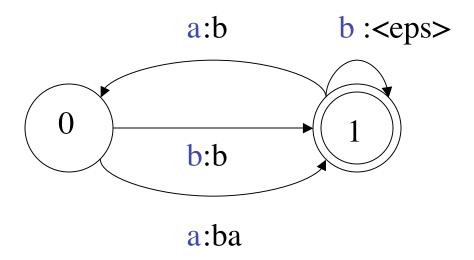
CMPT 825 Natural Language Processing

Anoop Sarkar

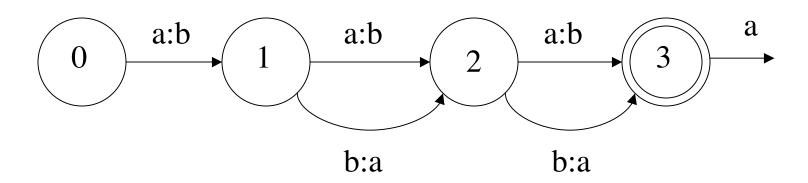
http://www.cs.sfu.ca/~anoop

Sequential transducers

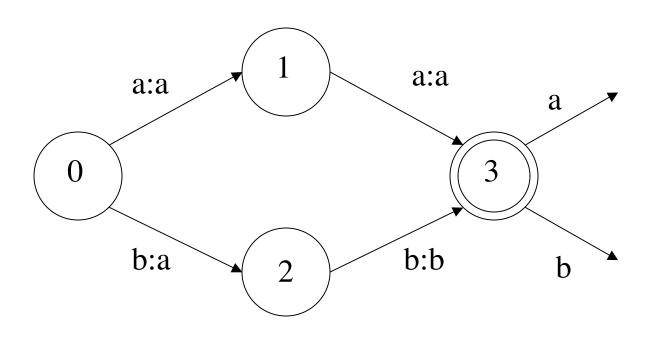


- determinization
- minimization

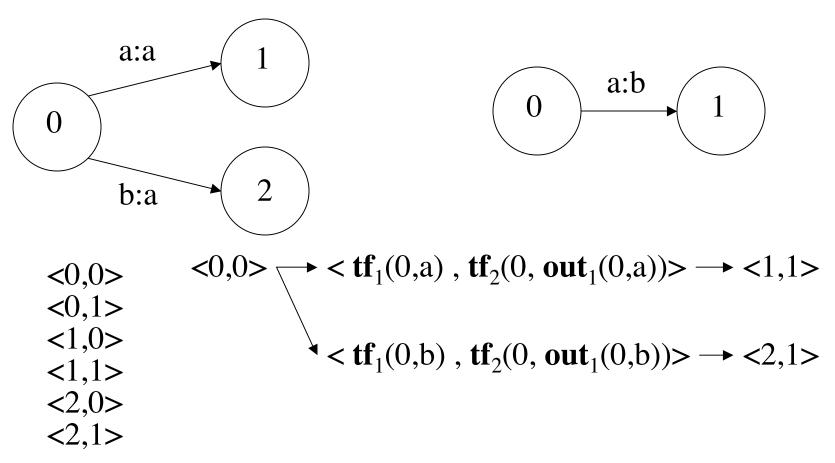
Subsequential transducers



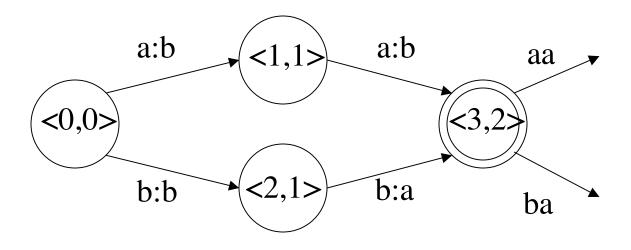
p-subsequential Transducers



Composition: T₁ o T₂

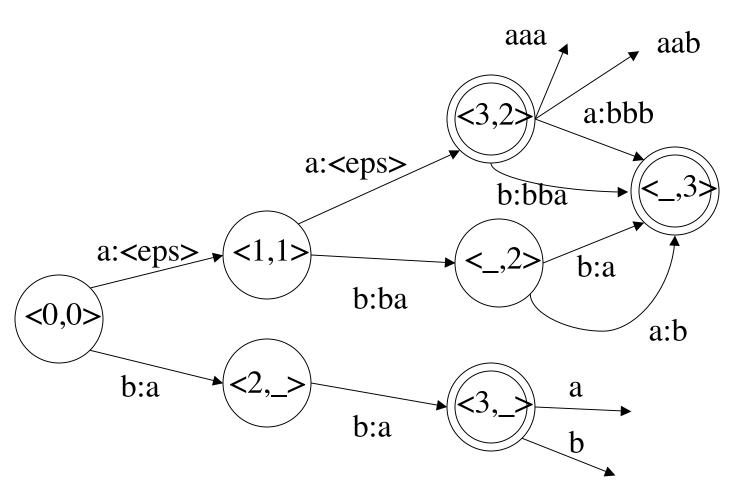


Composition: T_1 o T_2



$$<0,0> \longrightarrow <\mathbf{tf}_1(0,\mathbf{a})\;,\;\mathbf{tf}_2(0,\mathbf{out}_1(0,\mathbf{a}))> \longrightarrow <1,1> \\ <\mathbf{tf}_1(0,\mathbf{b})\;,\;\mathbf{tf}_2(0,\mathbf{out}_1(0,\mathbf{b}))> \longrightarrow <2,1>$$

Union: $T_1 + T_2$



Arbitrary Transducers

- We've seen algorithms over subsequential transducers: but what about arbitrary transducers?
- There exist transducers with no sequential equivalent. e.g. a^{|w|} if |w| is even; else b^{|w|}
- If f is a transducer, then there is a left sequential l and a right sequential r such that $f = l \cdot r$
- It is decidable if a transducer is sequential
- See details in Mohri 1997.

Slides on Minimization taken from the presentation made by Jason Eisner at the following conference talk

Simpler & More General Minimization for Weighted Finite-State Automata

Jason Eisner

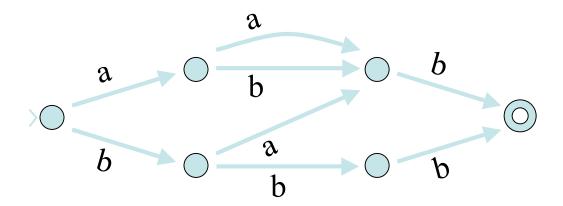
Johns Hopkins University

May 28, 2003 — HLT-NAACL

Input: A DFA (deterministic finite-state automaton)

Output: An equiv. DFA with as few states as possible

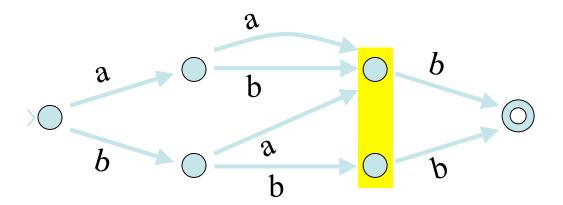
Complexity: O(larcsl log lstatesl) (Hopcroft 1971)



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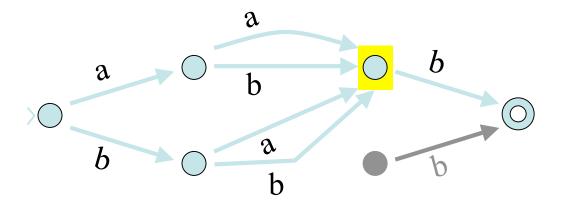
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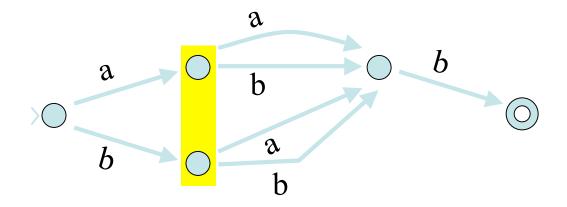
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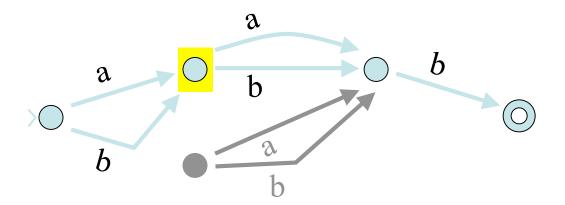
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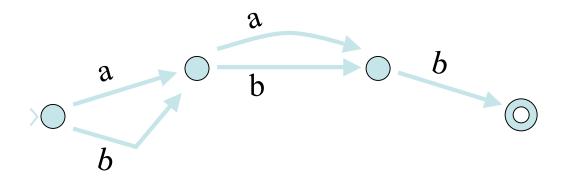
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Complexity: O(larcsl log lstatesl) (Hopcroft 1971)



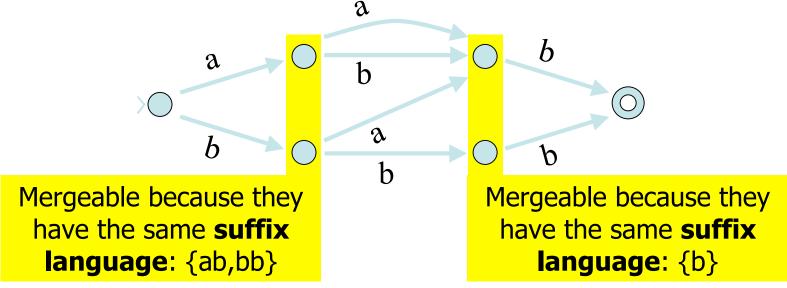
Can't always work backward from final state like this. A bit more complicated because of cycles.

Input: A DFA (deterministic finite-state automaton)

Output: An equiv. DFA with as few states as possible

Complexity: O(larcsl log lstatesl) (Hopcroft 1971)

Here's what you **should** worry about:



An equivalence relation on states ... merge the equivalence classes

Input: A DFA (<u>deterministic</u> finite-state automaton)

Output: An equiv. DFA with as few states as possible

Complexity: O(larcsl log lstatesl) (Hoperoft 1971)

Q: Why minimize # states, rather than # arcs?

A: Minimizing # states also minimizes # arcs!

Q: What if the input is an NDFA (nondeterministic)?

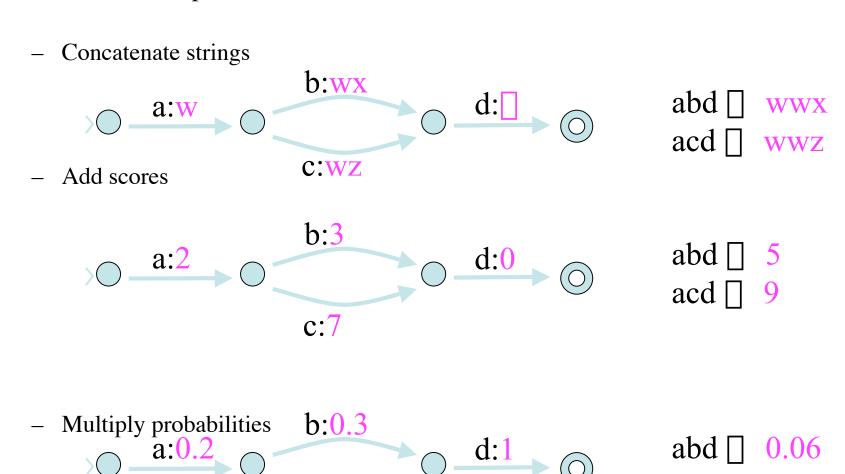
A: Determinize it first. (could yield exponential blowup (3))

Q: How about minimizing an NDFA to an NDFA?

A: Yes, could be exponentially smaller ⊕, but problem is PSPACE-complete so we don't try. ⊗

Real-World NLP: Automata With Weights or Outputs

• Finite-state computation of functions



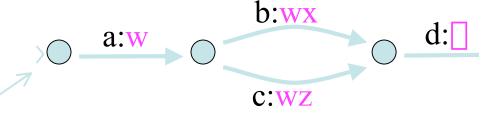
acd \square

Weight Algebras

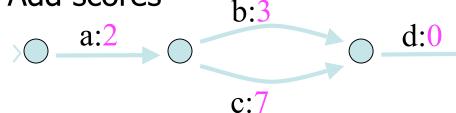
- Specify a weight algebra (K,)
- Define DFAs over (K,)
- Arcs have weights in set K
- A path's weight is also in K: multiply its arc weights with
- Examples:
 - (strings, concatenation)
 - (scores, addition)
 - (probabilities, multiplication)
 - (score vectors, addition)
 - (real weights, multiplication)
 - (objective func & gradient, product-rule multiplication)
 - (bit vectors, conjunction)

Finite-state computation of fu

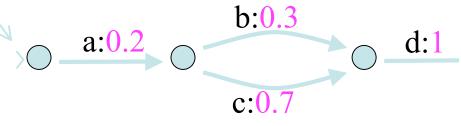
Concatenate strings



Add scores



Multiply probabilities

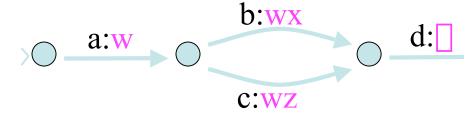


Weight Algebras

- Specify a weight algebra (K,)
- Define DFAs over (K,)
- Arcs have weights in set K
- A path's weight is also in K: multiply its arc weights with
- Q: Semiring is $(K, \oplus,)$. Why not talk about \oplus too?
- A: Minimization is about DFAs.
- At most one path per input.
- So no need to \oplus the weights of multiple accepting paths.

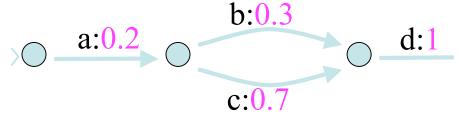
Finite-state computation of fu

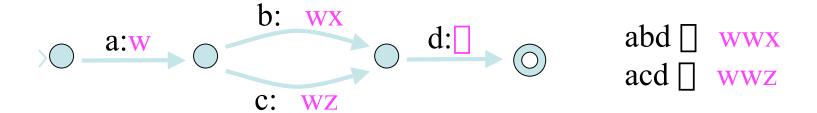
Concatenate strings

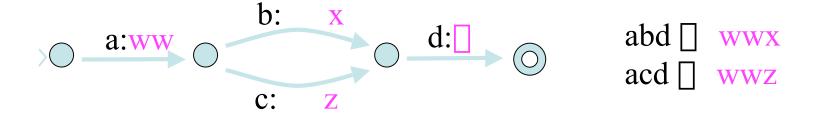


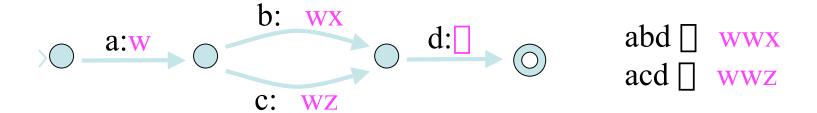
• Add scores
b:3
c:7

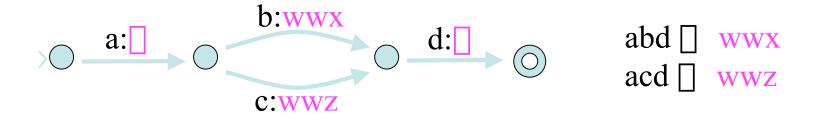
Multiply probabilities

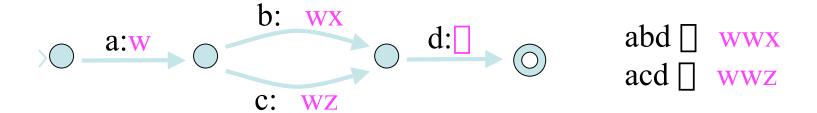


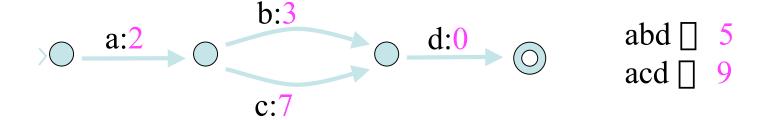


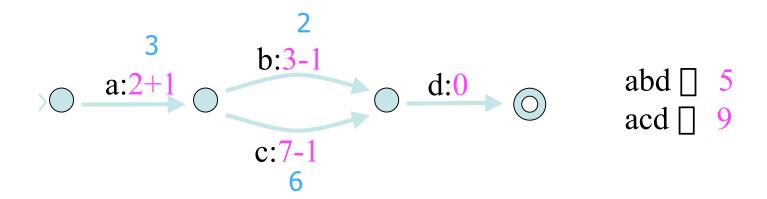


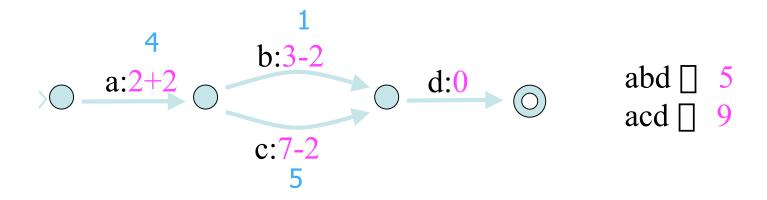


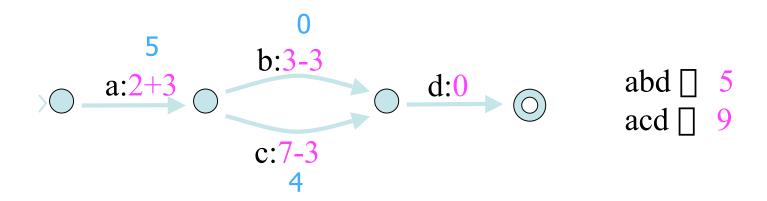


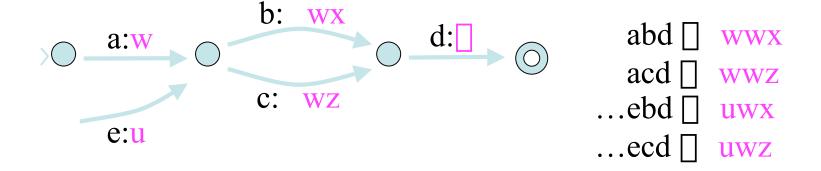




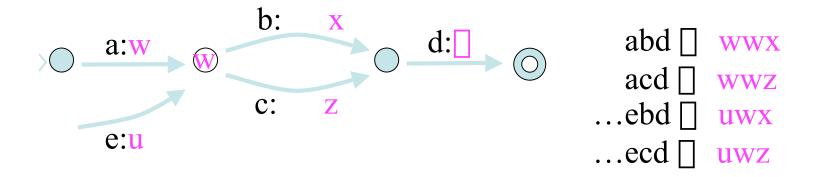




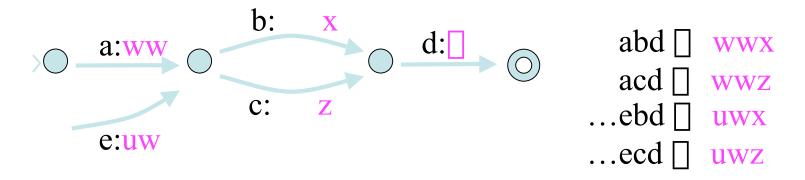


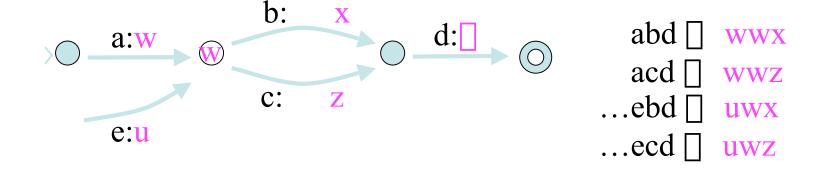


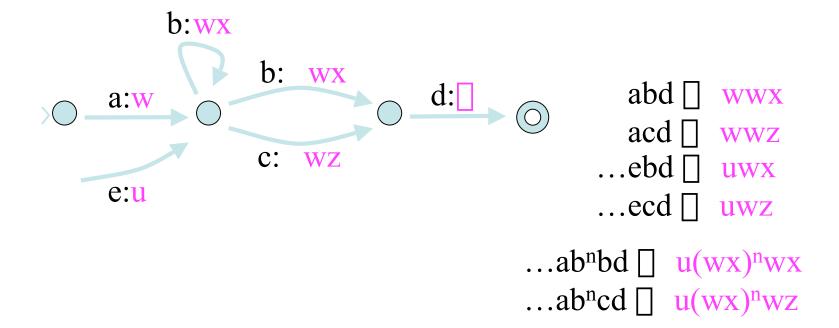
• State sucks back a prefix from its out-arcs

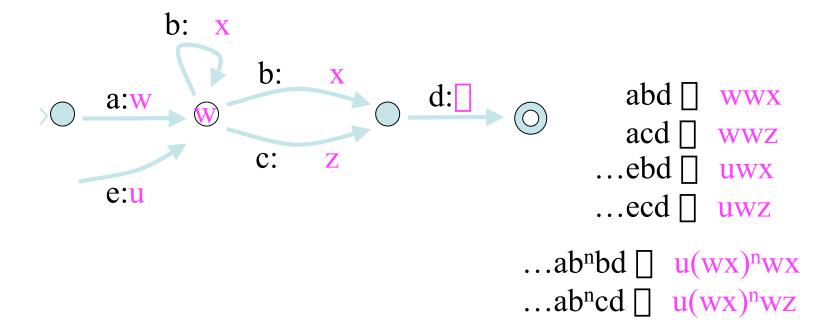


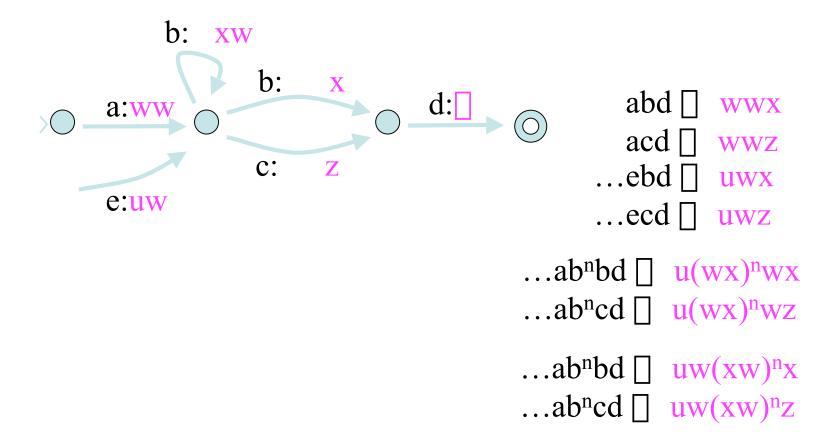
• State sucks back a prefix from its out-arcs and deposits it at end of its in-arcs.



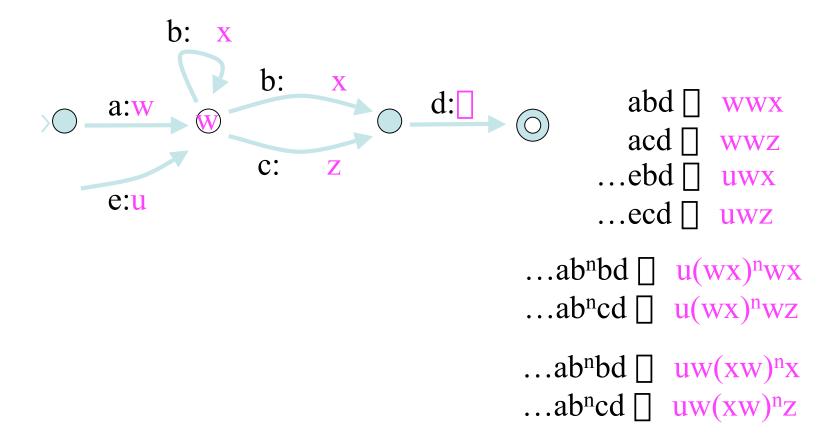




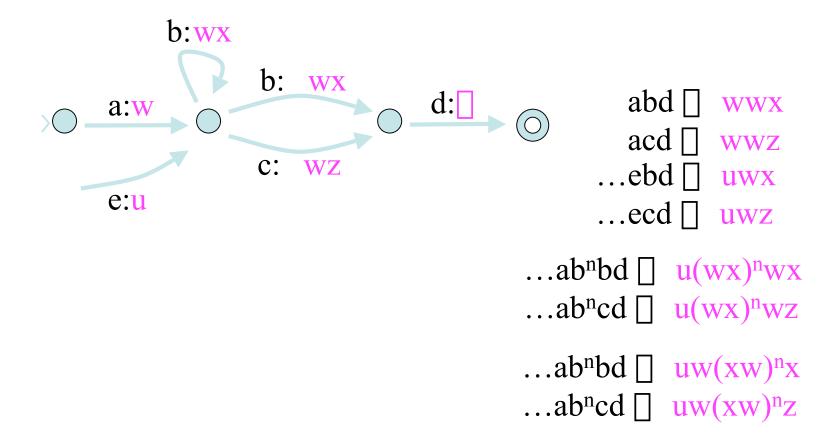




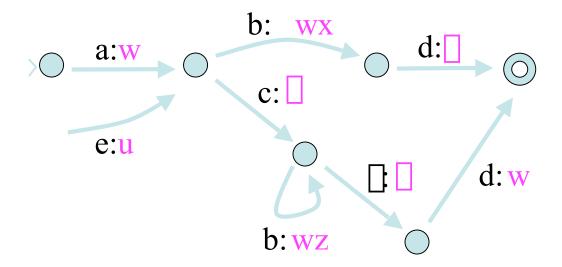
Shifting Outputs Along Paths



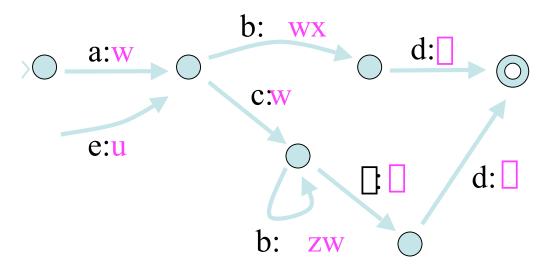
Shifting Outputs Along Paths



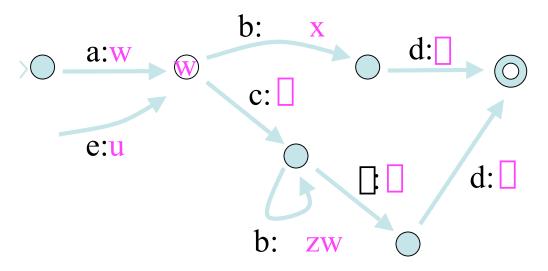
- Here, not all the out-arcs start with w
- But all the out-paths start with w
- Do pushback at later states first:



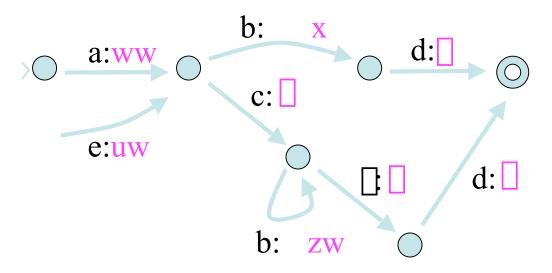
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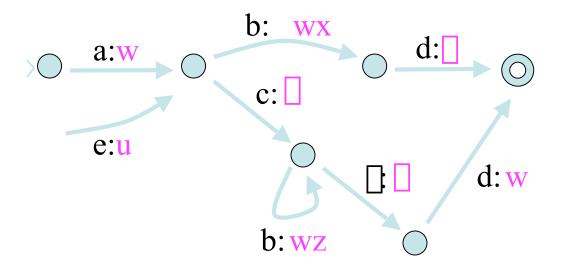
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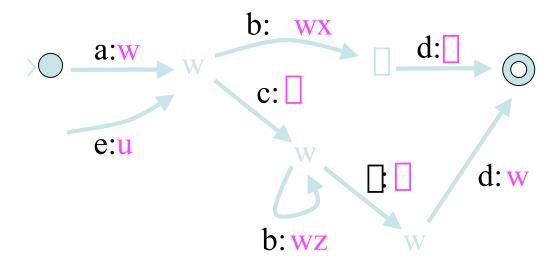
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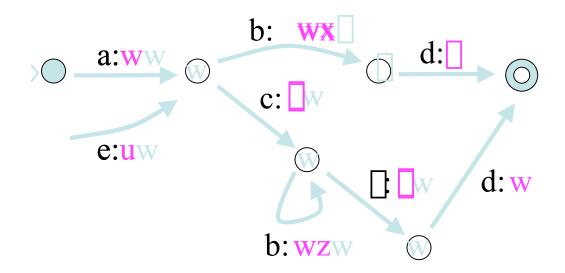
• Actually, push back at all states at once



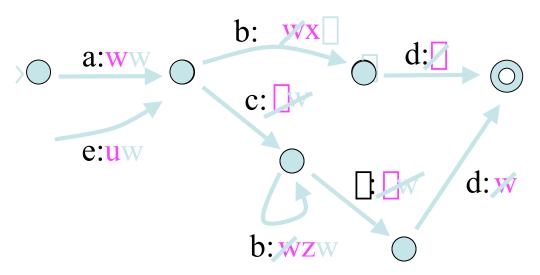
- Actually, push back at all states at once
- At every state q, compute some $\square(q)$



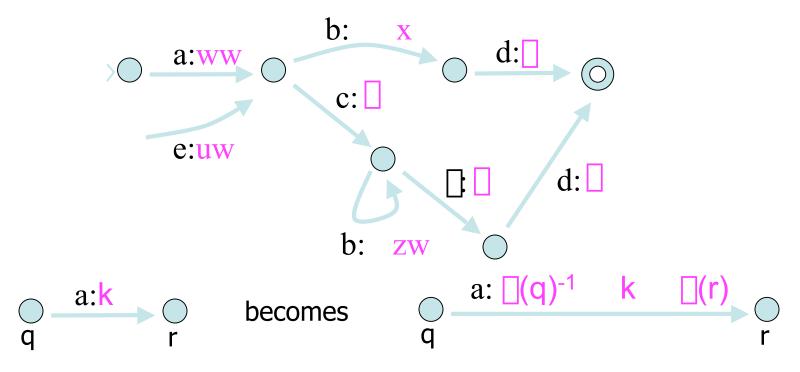
- Actually, push back at all states at once
- Add □(q) to end of q's in-arcs

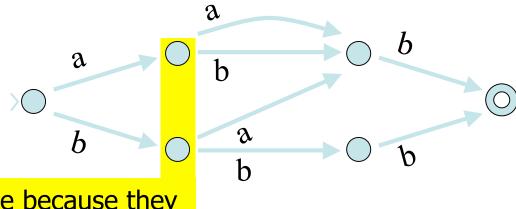


- Actually, push back at all states at once
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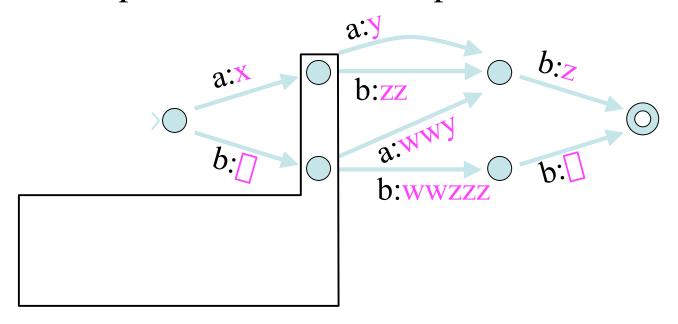
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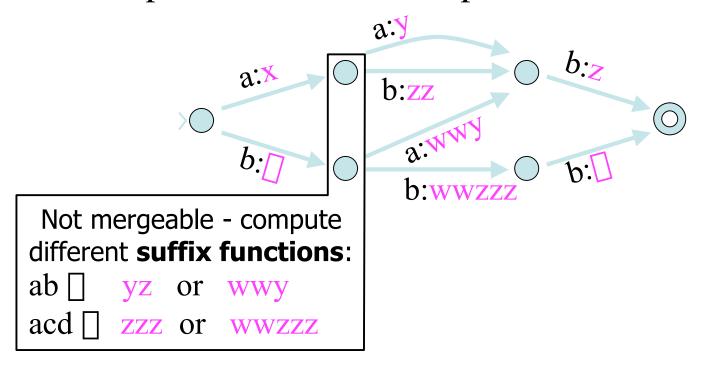


Mergeable because they accept the same **suffix** language: {ab,bb}

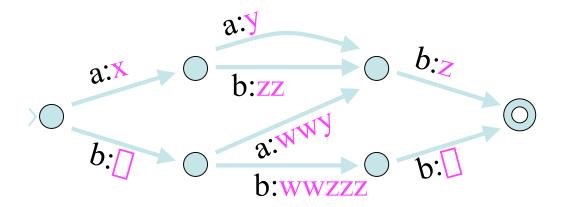
Still accept same suffix language, but produce different outputs on it



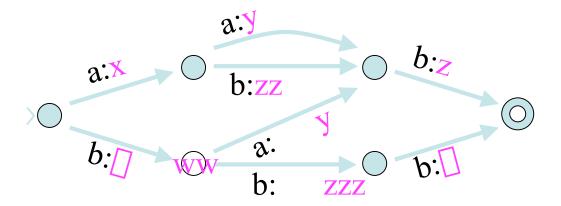
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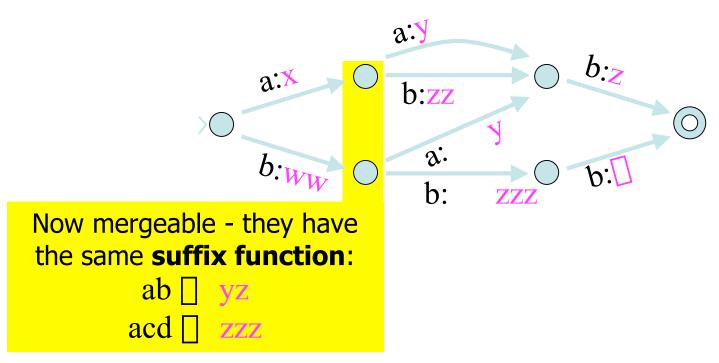
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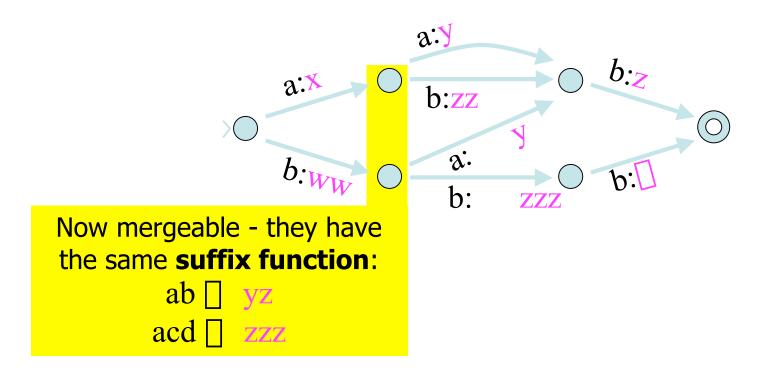


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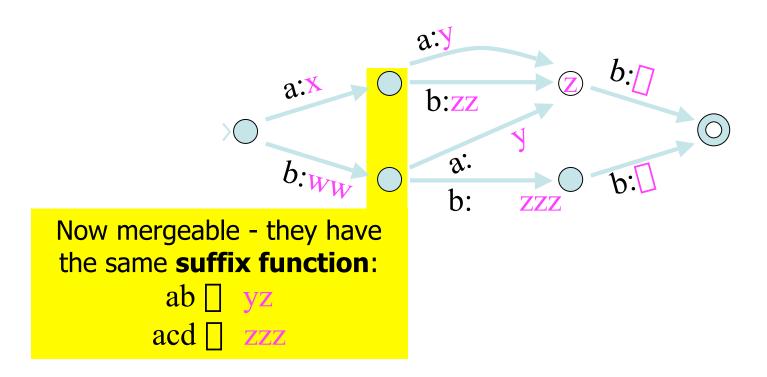


But still no easy way to detect mergeability.

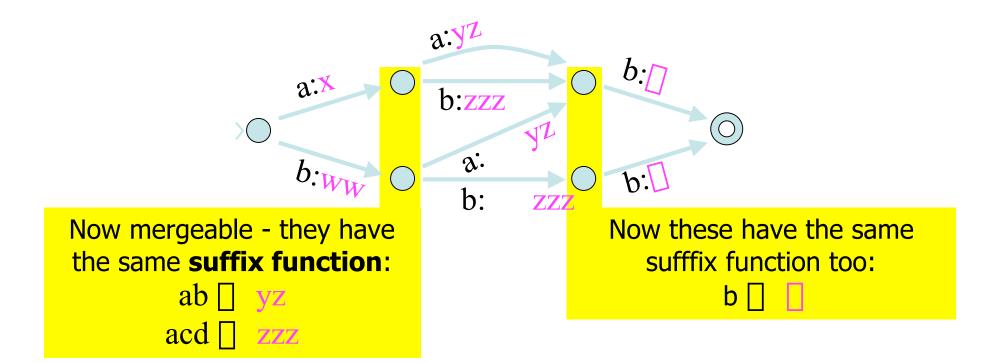
If we do this at all states as before ...



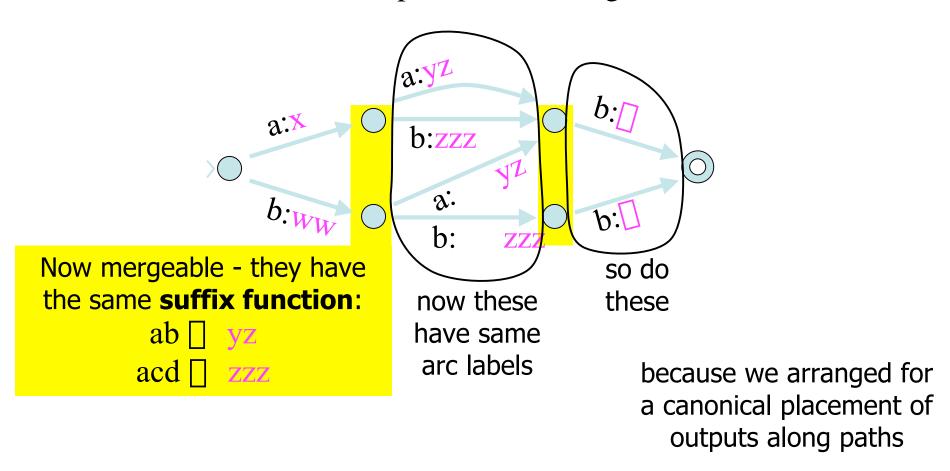
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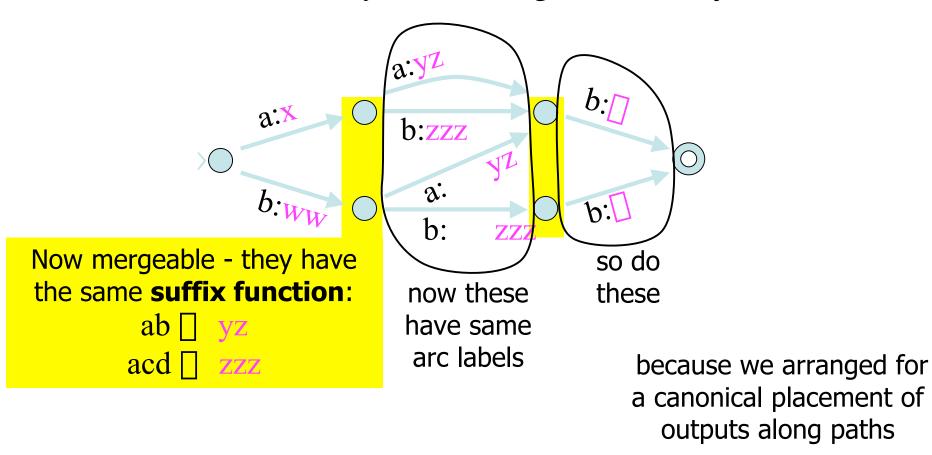
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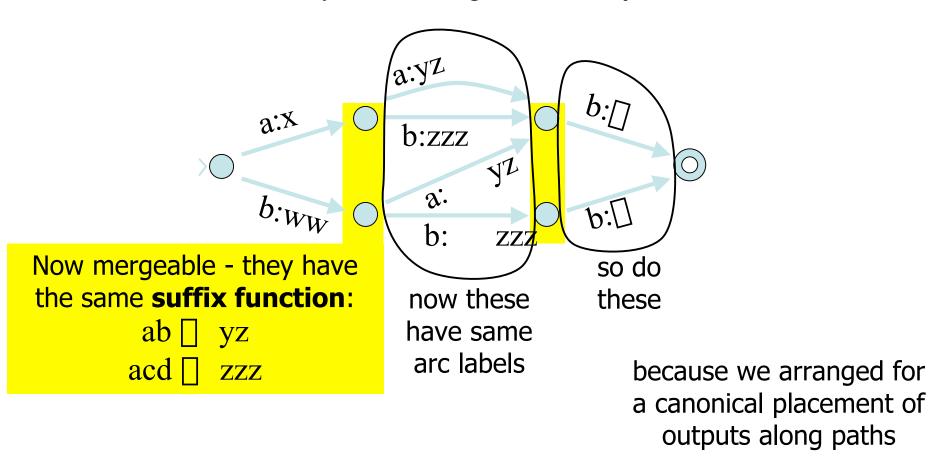
Now we can discover & perform the merges:



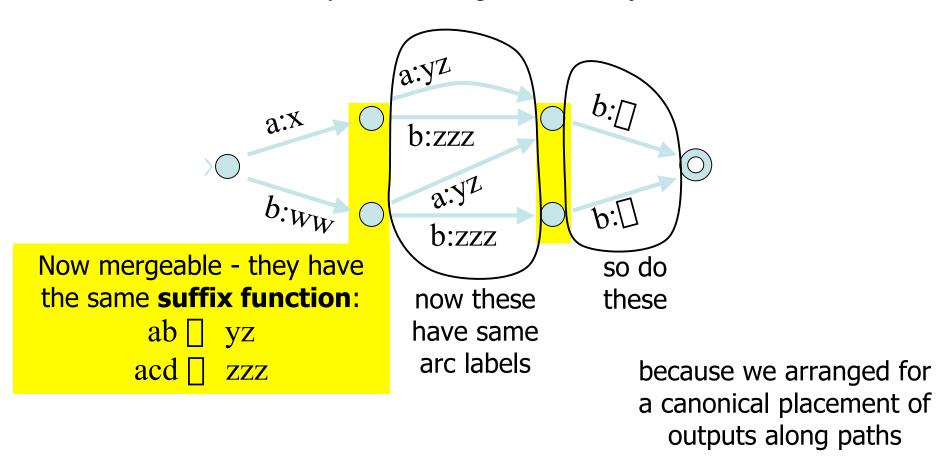
Treat each label "a:yz" as a single atomic symbol



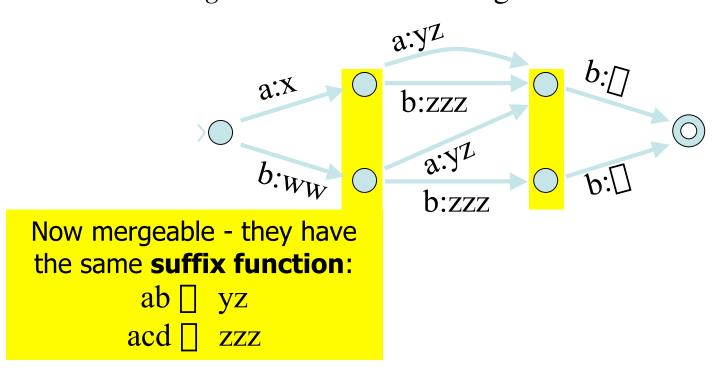
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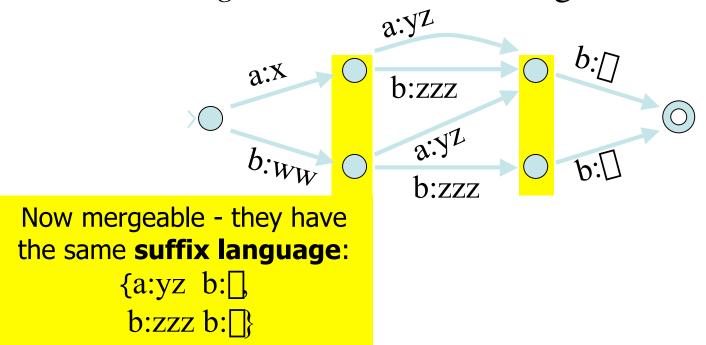
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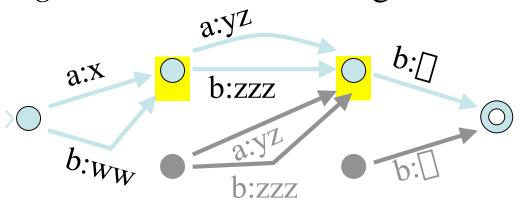
Treat each label "a:yz" as a single atomic symbol Use *unweighted* minimization algorithm!



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Summary of weighted minimization algorithm:

- 1. Compute $\Box(q)$ at each state q
- **2. Push** each □(q) back through state q; this changes arc weights
- 3. Merge states via unweighted minimization

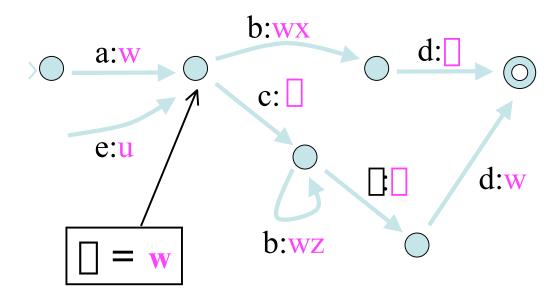
Step 3 merges states

Step 2 allows more states to merge at step 3

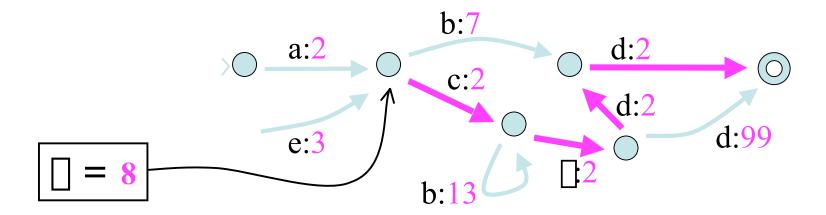
Step 1 controls what step 2 does – preferably, to give states the same suffix function whenever possible

So define $\square(q)$ carefully at step 1!

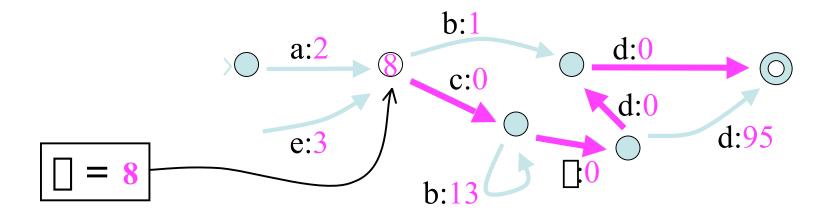
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