

Multi Modal Route Planning

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Introduction

For a traveler it is often reliable to use different modes of transport for a travel whenever it is available. But there are very few efficient systems to find such a travel plan, there are systems that aid traveler to choose different modes of transport, such as Google Transit.

Multimodal Route Planning(MRP) is a system that provides the traveler with optimal, feasible and personalized route plan between a given source and destination in Bangalore city. The system is designed to provide combinations of various public travel approaches like bus and metro.



Related Work

- Multi-Modal Route Planning [1] by Thomas Pajor performs multimodal route planning on a large scale networks involving roads, railways and flights. He combined the different realistic models for road, railway and flight networks into multi-modal graphs. He used dijkstras algorithms with labelled constraints.
- In another paper Multi-Modal Journey Planning in the Presence of Uncertainty by Adi Botea et la (2013) [2] solves the multimodal planning problem by introducing a heuristic search planner, based on Weighted AO* (WAO*).



Proposed Solution

Dataset used

Bus Network:

BMTC Bus network data in csv format.

Files:

- <u>Routes.csv</u>: Description of all bus routes in Bangalore city.
- <u>UniqueBusStops.csv</u>: List of unique bus stops along with Longitude and Latitude information

Metro Network:

Data scraped from BMRC web page.(manually)



Modeling The Network

Road Network:

Nodes: Bus stops.

Edge between two bus stations is inserted if there exists a route

between them.

Edge weight: Haversine Distance.

Total Bus stops: 5338

Metro Network:

Nodes: Metro station.

Edge between two metro stations is inserted if there exists a route.

Edge weight: Haversine Distance.

Total Metro stations: 42

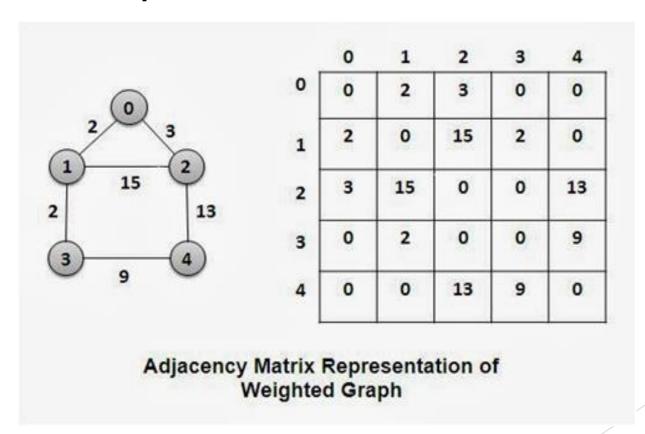
Combining The Unimodal Networks

Both unimodal networks were combined to the nearest node (<1km distance) which gives the multimodal network.



Data Structures Used

A. Graph



Data Structures Used (cont..)

B. Priority Queue

It is implemented as a binary heap which supports following operations:

- FindMin in $\Theta(1)$
- DeleteMin in Θ(log n)
- Insert Θ(log n)
- Update Key Θ(log n)

Our Graph Node

Each node of graph stores following information required for further processing:

- Bus Stop/ Metro Stop Names
- Longitude and Latitude Information
- List of routes passing through the given nodes



Our Transit Algorithms:

We used following two approaches for finding shortest path:

- A* algorithm with haversine heuristics
- Using simple Dijkstra's Algorithm



Dijkstra Algorithm (Pseudo Code)

```
(distance to source vertex is zero)
dist[s] \leftarrow o
for all v \in V - \{s\}
     do dist[v] \leftarrow \infty
                                            (set all other distances to infinity)
S←Ø
                                             (S, the set of visited vertices is initially empty)
O←V
                                             (Q, the queue initially contains all vertices)
                                             (while the queue is not empty)
while Q ≠∅
                                             (select the element of Q with the min. distance)
do u \leftarrow mindistance(Q,dist)
                                             (add u to list of visited vertices)
    S \leftarrow S \cup \{u\}
    for all v \in neighbors[u]
         do if dist[v] > dist[u] + w(u, v)
                                                        (if new shortest path found)
                then d[v] \leftarrow d[u] + w(u, v)
                                                        (set new value of shortest path)
                                                        (if desired, add traceback code)
```

return dist

Complexity Analysis

- Time complexity of algorithm = O(ELogV)
- Total number of nodes = 5380
- Time taken for result = 5380 * 5380 tp <= 2 sec (Approx)

Demo



Multi Model Routing Magadi Road Metro Station Choose a source from the list Magadi Road Metro Station Choose a destination from the list Distance Destination Kms.) 14th main hsr layout koramangala K-5 0.678 1.709 koramangala jn of 80 and 100 feet road 171G 171G, 171J, 163A, 166, K-5, 173A, 164, 201K, 201, 171, 201L, 201N, 171E, 201A jn of 80 and 100 feet road Halasuru Metro Station 0.893 Halasuru Metro Station lingarajapura Metro2 0.352 lingarajapura hennur depot 293A, G-11 1.275 293B, 293, 293K, 296F, 293D, 293M, 294B, 294A, 294, 294C, 293F, 293C, 296D, 295, 412. 295E, 294D, 293L, 292, 292B, 295C, 293H, 293P, 293A, 293J, 292C, MF-4, 295A, 296N, G-0.421 hennur depot nagavara junction 11, 294F, 293E, 294E, 296A, 296B, 296K manyatha tech park nagavara 290N, MBS-14, 290B, 415H, 290Q, 290, 290S, 290E, 290R, 291H, 290J, 290T, 290A, 291P, nagavara junction in front of ibm manyata 0.797 291J, G-10, 290RA, 415E, 291A, BC-9, 290Z, 296K embassy business park manyatha tech park nagavara dasarahalli dasarahalli beside in front of ibm manyata 0.736 embassy business park 18th cross srirampura dasarahalli dasarahalli beside amruthahalli in front of open 291L 0.697 annaporna temple Total Distance: 7.556 Kms. *Metro1: Green Line, *Metro2: Purple Line

App in Motion



Technologies Used

- Back-End
 - Python Programming Language
 - Django Web Development Framework
 - Django Rest API
- Front-End
 - Django Web Development Framework
 - Bootstrap Framework

Key Challenges

- A* algorithm with haversine distance as heuristics criteria didn't work well since the heuristic criteria is not found admissible. The algorithm takes exponential time in unbound space, $O(b^d)$ and depends on the heuristics.
- Combining unimodal networks road and metro was challenging.



Future Work

- Incorporating Pedestrians
- Duration Constraint
- Caching Repetitive queries
- User location detection
- Expanding model to other cities



References

1. Adi Botea IBM Research, Evdokia Nikolova Dept. of Computer Science and Engineering Texas A&M University, Michele Berlingerio IBM Research - "Multi-Modal Journey Planning in the Presence of Uncertainty" 2013.

https://www.aaai.org/ocs/index.php/ICAPS/ICAPS13/paper/view/6023

2. Thomas Pajor, Universität Karlsruhe (TH), Germany "Multi-Modal Route Planning" 2009 http://i11www.iti.uni-karlsruhe.de/extra/publications/p-mmrp-09.pdf



Questions?



Thank You!

