

MINE: Mutual Information Neural Estimation

ICML 2018

Motivation

- Mutual information was a powerful tool in statistical models:
 - Feature selection, information bottleneck, casualty
- MI quantifies the dependence of two random variables:

$$I(X; Z) = \int_{\mathcal{X} \times \mathcal{Z}} \log \frac{d\mathbb{P}_{XZ}}{d\mathbb{P}_X \otimes \mathbb{P}_Z} d\mathbb{P}_{XZ}.$$

$$I(X; Z) := H(X) - H(X | Z)$$

Motivation

- MI is tractable only for discrete random variables or known probability distribution
- Common Approaches do not scale well with sample size or dimension:
 - Non-parametric approaches
 - Approximate gaussianity
- Use KL-Divergence for computing MI
- Use dual formulation for estimating f-divergence
 - Adversarial game between neural nets

MI

- KL-Divergence definition:

$$D_{KL}(\mathbb{P} \parallel \mathbb{Q}) := \mathbb{E}_{\mathbb{P}} \left[\log \frac{d\mathbb{P}}{d\mathbb{Q}} \right]$$

- MI:

$$I(X; Z) = \int_{\mathcal{X} \times \mathcal{Z}} \log \frac{d\mathbb{P}_{XZ}}{d\mathbb{P}_X \otimes \mathbb{P}_Z} d\mathbb{P}_{XZ}$$

$$I(X, Z) = D_{KL}(\mathbb{P}_{XZ} \parallel \mathbb{P}_X \otimes \mathbb{P}_Z)$$

MI Estimator

- Donsker-Varadhan representation:

$$D_{KL}(\mathbb{P} \parallel \mathbb{Q}) = \sup_{T: \Omega \rightarrow \mathbb{R}} \mathbb{E}_{\mathbb{P}}[T] - \log(\mathbb{E}_{\mathbb{Q}}[e^T])$$

- So:

$$D_{KL}(\mathbb{P} \parallel \mathbb{Q}) \geq \sup_{T \in \mathcal{F}} \mathbb{E}_{\mathbb{P}}[T] - \log(\mathbb{E}_{\mathbb{Q}}[e^T])$$

MI Estimator

- f-divergence representation:

$$D_{KL}(\mathbb{P} \parallel \mathbb{Q}) \geq \sup_{T \in \mathcal{F}} \mathbb{E}_{\mathbb{P}}[T] - \mathbb{E}_{\mathbb{Q}}[e^{T-1}]$$

- Both representations are tight but Donsker-Varadhan representation is stronger as:

$$x \geq e \log x$$

- Where:

$$\mathbb{E}_{\mathbb{Q}}[e^T]$$

Method

- Estimate function T using neural network:

$$I_{\Theta}(X, Z) = \sup_{\theta \in \Theta} \mathbb{E}_{\mathbb{P}_{XZ}}[T_{\theta}] - \log(\mathbb{E}_{\mathbb{P}_X \otimes \mathbb{P}_Z}[e^{T_{\theta}}])$$

- So:

$$I(X; Z) \geq I_{\Theta}(X, Z)$$

- Estimate $I_{\Theta}(X, Z)$ using:

$$\widehat{I(X; Z)}_n = \sup_{\theta \in \Theta} \mathbb{E}_{\mathbb{P}_{XZ}^{(n)}}[T_{\theta}] - \log(\mathbb{E}_{\mathbb{P}_X^{(n)} \otimes \hat{\mathbb{P}}_Z^{(n)}}[e^{T_{\theta}}])$$

Algorithm

Algorithm 1 MINE

$\theta \leftarrow$ initialize network parameters

repeat

Draw b minibatch samples from the joint distribution:

$$(\mathbf{x}^{(1)}, \mathbf{z}^{(1)}), \dots, (\mathbf{x}^{(b)}, \mathbf{z}^{(b)}) \sim \mathbb{P}_{XZ}$$

Draw n samples from the Z marginal distribution:

$$\bar{\mathbf{z}}^{(1)}, \dots, \bar{\mathbf{z}}^{(b)} \sim \mathbb{P}_Z$$

Evaluate the lower-bound:

$$\mathcal{V}(\theta) \leftarrow \frac{1}{b} \sum_{i=1}^b T_{\theta}(\mathbf{x}^{(i)}, \mathbf{z}^{(i)}) - \log\left(\frac{1}{b} \sum_{i=1}^b e^{T_{\theta}(\mathbf{x}^{(i)}, \bar{\mathbf{z}}^{(i)})}\right)$$

Evaluate bias corrected gradients (e.g., moving average):

$$\hat{G}(\theta) \leftarrow \tilde{\nabla}_{\theta} \mathcal{V}(\theta)$$

Update the statistics network parameters:

$$\theta \leftarrow \theta + \hat{G}(\theta)$$

until convergence

Caveats

- Mini-batch computation is biased:

$$\hat{G}_B = \mathbb{E}_B[\nabla_{\theta} T_{\theta}] - \frac{\mathbb{E}_B[\nabla_{\theta} T_{\theta} e^{T_{\theta}}]}{\mathbb{E}_B[e^{T_{\theta}}]}$$

- Moving Average for estimating $\mathbb{E}_B[e^{T_{\theta}}]$ over full batch
- MI is not bounded and can become infinitely large so it will mask cross-entropy loss:

$$g_a = \min(\|g_u\|, \|g_m\|) \frac{g_m}{\|g_m\|}$$

Properties

- Strong consistency:

$$\forall n \geq N, \quad |I(X, Z) - \widehat{I(X; Z)}_n| \leq \epsilon.$$

- Lemma 1: $|I(X, Z) - I_{\Theta}(X, Z)| \leq \epsilon$

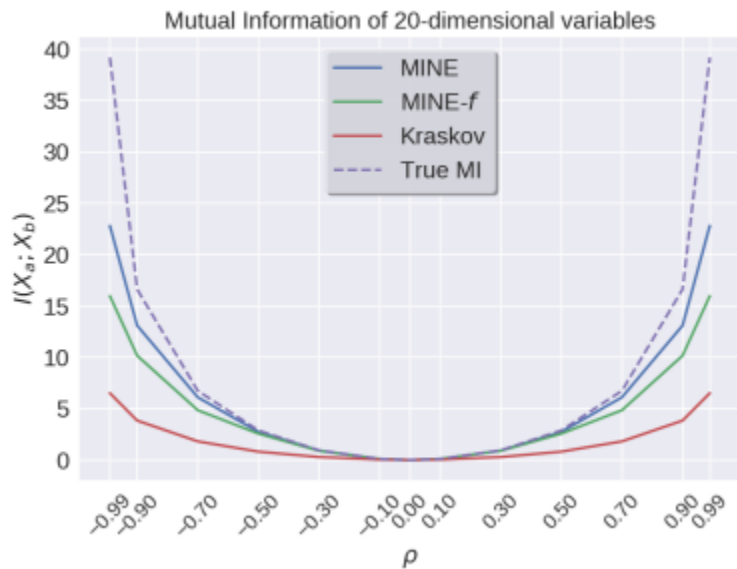
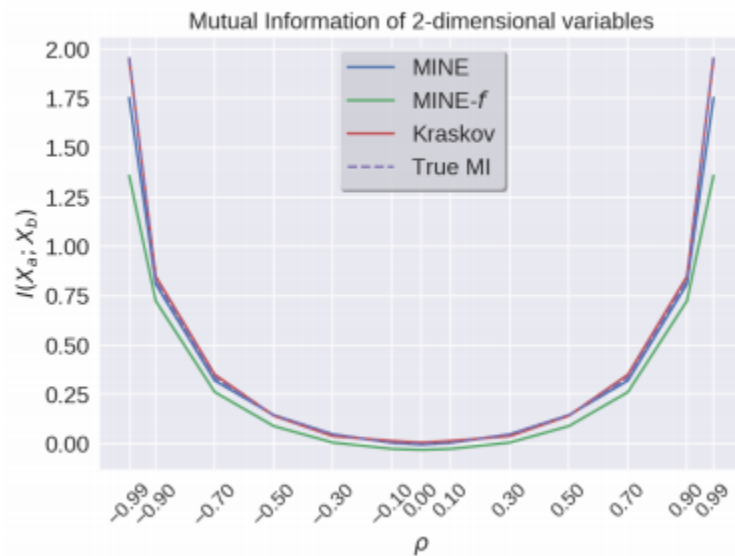
- Lemma 2: $\forall n \geq N, \quad |\widehat{I(X; Z)}_n - I_{\Theta}(X, Z)| \leq \epsilon$

- Sample Complexity:

$$\tilde{O}\left(\frac{d \log d}{\epsilon^2}\right)$$

Comparing to non-parametric estimator

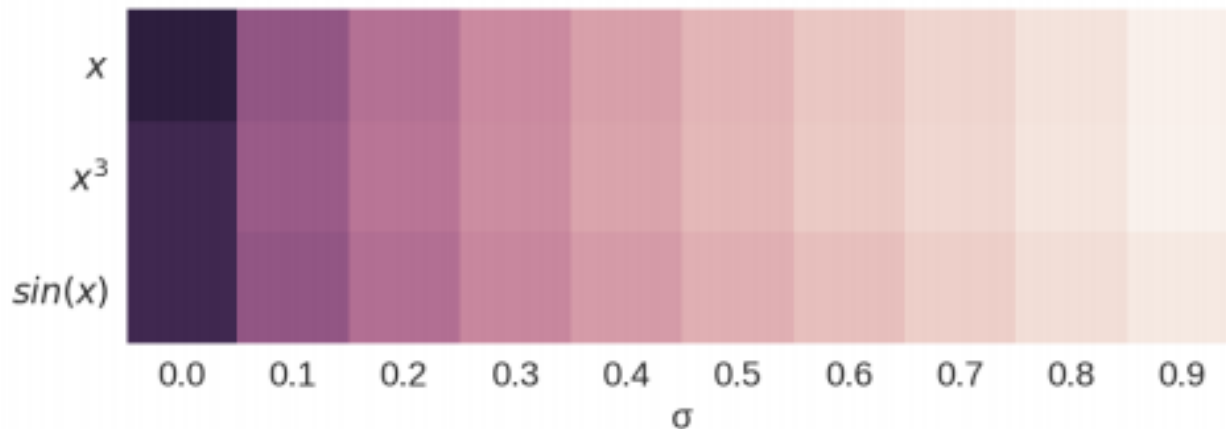
- Two random variables with multivariate Gaussians distribution
- K-NN based estimator
- MINE and MINE-f



Capturing Non-Linear Dependency

- MI is a good measure for capturing non-linearity

$$Y = f(X) + \sigma \odot \epsilon.$$



Improving GAN

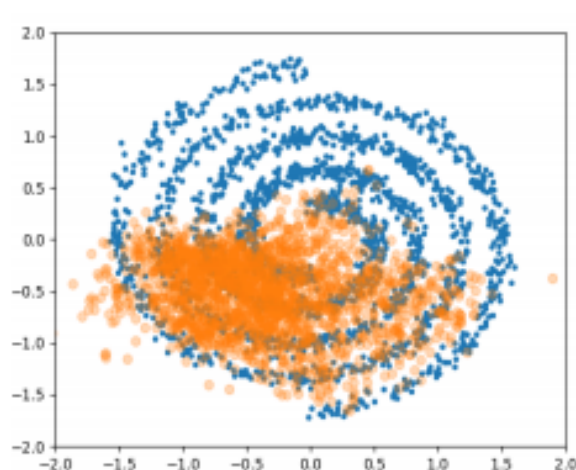
- GAN objective:

$$\min_G \max_D V(D, G) := \mathbb{E}_{\mathbb{P}_X}[D(X)] + \mathbb{E}_{\mathbb{P}_Z}[\log(1 - D(G(Z)))]$$

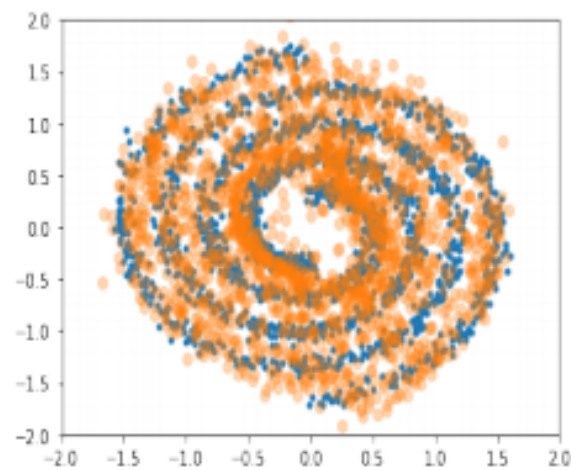
- Mode Collapse:
 - All generated samples are similar
- Maximize the MI between generated samples and code:

$$\arg \max_G \mathbb{E}[\log(D(G([\epsilon, c])))] + \beta I(G([\epsilon, c]); c)$$

Improving GAN - Result



(a) GAN



(b) GAN+MINE

	Stacked MNIST	
	Modes (Max 1000)	KL
DCGAN	99.0	3.40
ALI	16.0	5.40
Unrolled GAN	48.7	4.32
VEEGAN	150.0	2.95
PacGAN	1000.0 \pm 0.0	0.06 \pm 1.0e ⁻²
GAN+MINE (Ours)	1000.0 \pm 0.0	0.05 \pm 6.9e ⁻³

Bi-Directional Adversarial Model

- Encode input and reconstruct it from its encoding:

- Encoder: $p(\mathbf{x}, \mathbf{z}) = p(\mathbf{z} \mid \mathbf{x})p(\mathbf{x})$

- Decoder: $q(\mathbf{x}, \mathbf{z}) = q(\mathbf{x} \mid \mathbf{z})p(\mathbf{z})$

- Reconstruction error:

$$\mathcal{R} \leq D_{KL}(q(\mathbf{x}, \mathbf{z}) \parallel p(\mathbf{x}, \mathbf{z})) - I_q(\mathbf{x}, \mathbf{z}) + H_q(\mathbf{z})$$

- Objectives:
$$\begin{aligned} & \arg \max_D \mathbb{E}_{q(\mathbf{x}, \mathbf{z})} [\log D(\mathbf{x}, \mathbf{z})] + \mathbb{E}_{p(\mathbf{x}, \mathbf{z})} [\log (1 - D(\mathbf{x}, \mathbf{z}))] \\ & \arg \max_{F, G} \mathbb{E}_{q(\mathbf{x}, \mathbf{z})} [\log (1 - D(\mathbf{x}, \mathbf{z}))] + \mathbb{E}_{p(\mathbf{x}, \mathbf{z})} [\log D(\mathbf{x}, \mathbf{z})] \\ & \quad + \beta I_q(\mathbf{x}, \mathbf{z}) \end{aligned}$$

Bi-Directional Adversarial Models- Results

Model	Recons. Error	Recons. Acc.(%)	MS-SSIM
MNIST			
ALI	14.24	45.95	0.97
ALICE(l_2)	3.20	99.03	0.97
ALICE(Adv.)	5.20	98.17	0.98
MINE	9.73	96.10	0.99
CelebA			
ALI	53.75	57.49	0.81
ALICE(l_2)	8.01	32.22	0.93
ALICE(Adv.)	92.56	48.95	0.51
MINE	36.11	76.08	0.99

Information Bottleneck

- Find representation Z for X which has enough data for predicting Y and discards irrelevant information in X

$$\mathcal{L}[q(Z | X)] = H(Y|Z) + \beta I(X, Z)$$

Model	Misclass. rate(%)
Baseline	1.38%
Dropout	1.34%
Confidence penalty	1.36%
Label Smoothing	1.40%
DVB	1.13%
DVB + Additive noise	1.06%
MINE(Gaussian) (ours)	1.11%
MINE(Propagated) (ours)	1.10%
MINE(Additive) (ours)	1.01%

Questions?

Thanks