

1 **Characterising Sediment Thickness beneath a Greenlandic Outlet Glacier using Distributed**
2 **Acoustic Sensing: Preliminary Observations and Progress Towards an Efficient Machine Learning**
3 **Approach**

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7
8 **Abstract**

9 Distributed Acoustic Sensing (DAS) is increasingly recognised as a valuable tool for glaciological
10 seismic applications, although analysing the large data volumes generated in acquisitions poses
11 computational challenges. We show the potential of active-source DAS to image and characterise
12 subglacial sediment beneath a fast-flowing Greenlandic outlet glacier, estimating the thickness of
13 sediment layers to be 20-30 m. However, the lack of subglacial velocity constraint limits the accuracy
14 of this estimate. Constraint could be provided by analysing cryoseismic events in a counterpart 3-day
15 record of passive seismicity, via (e.g.) seismic tomography, but locating them within the 9 TB data
16 volume is computationally inefficient. We describe experiments with data compression using the
17 frequency-wavenumber (f-k) transform ahead of training a convolutional neural network, that
18 provides a ~300-fold improvement in efficiency. In combining active and passive-source and our
19 machine learning framework, the potential of large DAS datasets could be unlocked for a range of
20 future applications.

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22
23 **Introduction**

24 Seismic methods are widely used to explore the internal and basal properties of glaciers and ice
25 sheets (Podolskiy and Walter, 2016). Although seismic phenomena can be recorded at high temporal
26 resolution, the spatial resolution of passive seismic data is often limited by the sparsity of
27 seismometer arrays. This is partly addressed by the use of nodal seismic technologies (Karplus and
28 others, 2021), but the recent development of Distributed Acoustic Sensing (DAS) offers the potential
29 for metre-scale sampling along profiles that are many kilometres in length. The principle of DAS is
30 reported elsewhere (Hartog, 2017; Lindsey and Martin, 2021) and it is sufficient here to understand
31 that DAS effectively converts a length of fibre-optic cable into a continuous string of pseudo-
32 seismometers (Zhu and others, 2021). DAS allows seismic vibrations to be recorded wherever fibre-
33 optic cable can be deployed and coupled sufficiently well to the ground. Glaciological deployments
34 of DAS include examples in the European Alps (Walter and others, 2020), Antarctica (Brisbourne and

35 others, 2021; Hudson and others, 2021), Greenland (Booth and others, 2020) and Iceland (Fichtner
36 and others, 2022), for both controlled-source and passive seismic applications.

37

38 Borehole DAS can be particularly valuable since fibre-optic cable is installed more simply and
39 inexpensively than the same number of conventional seismic sensors for equal sample density.
40 Booth and others (2020) reported the first glaciological deployment of borehole DAS, at RESPONDER
41 project site S30 (70.56793°N , 50.08697°W) on *Sermek Kujalleq* (Store Glacier), a major marine-
42 terminating outlet of the Greenland Ice Sheet (Figure 1a). Fibre-optic cable was installed in a 1043
43 m-long vertical borehole drilled to the glacier bed. A Silixa iDAS™ system was used to acquire active-
44 source vertical seismic profiles (VSPs) at various offsets and azimuths around the borehole, and a 3-
45 day record of passive seismicity.

46

47 The vertical borehole geometry allows englacial and subglacial seismic structure to be determined
48 more robustly than from surface seismic deployments, and thus improves the characterisation of
49 physical properties including englacial water and ice fabric. Booth and others (2020) used active-
50 source VSPs to determine a high-resolution depth profile of compressional (P-) wave velocity (Figure
51 1b), detecting the transition from isotropic to anisotropic ice at 84% of Store Glacier's thickness.
52 Basal temperate ice was detected in the lowermost 100 m, confirmed separately by distributed
53 temperature sensing in the same cable (Law and others, 2021). Reflections in the VSPs (Figure 2a)
54 were observed but did not originate from the glacier bed, generated instead at a deeper horizon
55 interpreted as the base of subglacial sediment. The time lag between a pair of direct and reflected
56 waves implied a sediment thickness of 20 [-2, +17] m, assuming a sediment velocity of 1873 [-94,
57 +1618] m s^{-1} (Hofstede and others, 2018).

58

59 The same approach was applied to the full suite of reflections in the active-source VSPs, allowing
60 sediment thickness estimates to be mapped around the borehole up to radial distances of 200 m.
61 This is possible because reflected energy measured at shallower borehole depth must reflect from a
62 subsurface point at greater lateral offset (Figure 2b). Direct and reflected rays were traced through a
63 1-D velocity model, with deviations indicating a change in sediment thickness and/or velocity. Having
64 no additional velocity constraint, we attributed all deviations to a thickness change, but our
65 interpretation also neglects anisotropy and any local change in glacier thickness. Under these
66 assumptions, preliminary estimates show sediment thickness varies between 20-30 m, with thinner
67 sediment typically observed north of the borehole (Figure 2c).

68

69 Although the active-source shots provide rich azimuthal coverage, the velocity through the
70 subglacial sediment remains unconstrained. The necessary constraint is potentially available, subject
71 to location uncertainties, through analysis of subglacial cryoseismicity in the passive DAS record, via
72 (e.g.) travel-time tomography (Zhang and others, 2020) but this is challenging given the volume of
73 the recorded dataset: although only 3 days long, the record features 1043 seismic channels sampled
74 at 4000 Hz and thus exceeds 9 TB in size. We are therefore exploring the implementation of
75 convolutional neural networks (CNN) to efficiently identify and isolate cryoseismic events in the
76 passive dataset, partly to complement active-source velocity analysis but also to elucidate the focal
77 mechanism of seismic emissions.

78

79 **Developing an Efficient CNN for recognising Cryoseismic Events**

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81 The complete architecture and performance of our CNN will be reported in a forthcoming
82 publication, and the following summary is intended to provide sufficient information to appreciate
83 preliminary results. The CNN was trained with an Adam optimizer (Kingma and Ba, 2015), using
84 36680 data windows of 0.25 s duration labelled as to whether they did (18360 windows, ~50%), or
85 did not (18320 windows, ~50%), contain a cryoseismic arrival. Figure 3a shows an example of a
86 prominent cryoseismic event, labelled (i), interpreted as arising from a crevassing event originating
87 ~300 m deep in the glacier (consistent with crevasse observations at this depth in optical televiewer
88 images; Hubbard and others, 2021). The arrivals at (i) are interpreted as the shear- (S-) wave
89 component of the seismic wavefield; they are preceded, by ~0.1 s, by (ii) low-amplitude arrivals
90 interpreted as the P-wave component. With velocities of 1800 m s^{-1} and 3750 m s^{-1} fit to the S- and
91 P-wave components, the 0.1 s lag between them implies that crevassing occurs at a radial distance
92 of ~350 m from the borehole. S-wave reflections from the glacier surface are observed at (iii).

93

94 29344 such windows were initially used to train the CNN, with 7336 for validation. Training took 100
95 epochs and was run on a standard specification laptop, but proved to be computationally inefficient:
96 129 s was required for the CNN to process 30 s of passive data, representing just 0.01% of the full
97 data volume. We therefore explored an approach of training the CNN on data windows transformed
98 into the frequency-wavenumber (f-k) domain. To the best of our knowledge, this strategy has not
99 been explored before, likely because passive seismic arrays conventionally lack the high density of
100 spatial samples of the DAS cable to make the f-k transformation worthwhile. On making this
101 conversion (e.g., Figure 3b), the information contained in time domain windows is expressed using
102 fewer data samples: the shape information in the time domain is preserved in the spread of
103 apparent velocities in the f-k image, yet frequencies and wavenumbers outside of the range 0-150

104 Hz and ± 0.4 m $^{-1}$, respectively, are redundant. When transformed to the f-k domain, the data volume
105 in each 0.25 s window is reduced by a factor of ~ 350 , and the analysis of 30 s data windows takes
106 just 1.2 s (plus an additional 5.6 s to implement the transform). The success of the CNN is currently
107 being assessed with a validation dataset that incorporates englacial, basal and subglacial seismicity
108 and their different f-k expressions. We obtain an accuracy of 98% when testing with this validation
109 dataset. CNN performance in the f-k domain is therefore considered promising both from accuracy
110 and efficiency standpoints. Although more sophisticated machine learning approaches may be
111 available (e.g., the residual neural network described by Dumont and others, 2020), we consider that
112 the capabilities of our CNN may be sufficient for reliable event identification.

113

114 **Outlook**

115 Interest is growing in DAS deployments, but these need to happen alongside methodological
116 developments to make data analysis practical. Our efficient compression of the passive seismic
117 wavefield with frequency-wavenumber transforms makes analysis of the dataset tractable on
118 standard CPUs, rather than GPUs or with specialist accelerators. The implementation of such
119 algorithms could be vital for real-time monitoring of passive DAS deployments, allowing efficient
120 recognition of cryoseismic events to trigger storage and/or transmission of data from a remote
121 monitoring station.

122 Further development of such tools can benefit passive DAS applications for many glaciological
123 studies. In addition to constraining subglacial velocities, integrated passive DAS and synchronous 3-
124 component seismometer records allows the focal mechanism of cryoseismicity to be determined,
125 thus improving our understanding of glacier dynamics. DAS data are also amenable to ambient
126 noise cross-correlation, and recent results (Tribaldos and Ajo-Franklin, 2021) highlight how variations
127 in seismic velocity are linked to changes in thermoelastic strain and hydrological dynamics.

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129 **Acknowledgments**

130 Data acquisition was funded by the European Research Council as part of the RESPONDER project
131 under the European Union's Horizon 2020 research and innovation program (Grant 683043). AB and
132 BL were supported by Royal Society International Exchanges 2019 Round 3 funding, IES/R3/193115.
133 BH was supported by a HERCW/Aberystwyth University Capital Equipment Grant. AP and ECS are
134 funded by the NERC/NSF International Thwaites Glacier Collaboration *TIME* project (NE/S00677X/1).
135 AN is funded by NERC project *Mantle Convection Constrained (MC²)*; NE/T012684/1). Silixa is thanked

136 for supporting the DAS acquisition. We thank editor Francisco Navarro, Fabian Walter and an
137 anonymous reviewer for constructive comments on this manuscript.

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191 **FIGURE CAPTIONS**

192 Figure 1. a) Site S30 on Store Glacier. Active-source shots (stars) are at various offsets and azimuths
193 around a DAS-instrumented borehole. The offset VSP shown in Figure 2a uses the highlighted
194 shotpoint. Inset panel: location in West Greenland. b) Vertical P-wave velocity trend, derived from
195 zero-offset VSP data (Booth and others, 2020).

196

197 Figure 2. a) VSP record highlighting direct and reflected waves, and the lag time between them.
198 b) Schematic VSP ray diagram for direct raypaths (blue) and subglacial reflections (red) from the
199 base of a 30 m thick sediment layer. The lateral offset of the reflection point from the borehole
200 increases the shallower the reflections are observed. c) Subglacial sediment thickness around the
201 borehole, from analysis of lag times in VSP data.

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203 Figure 3. A cryoseismic event recorded in the passive DAS acquisition, shown as a) time-space
204 domain, labelling (i) S-, (ii) P-wave arrivals and (iii) S-wave surface reflections, and b) frequency-
205 wavenumber (f-k) response, and the apparent velocities (m s^{-1} ; white annotations) it implies.
206 Meaningful information to reconstruct the event in the time-space domain is captured with fewer
207 samples in the f-k domain.

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