```
function [tout,states] = varying_parameters(parameter,test_parameter,tspan)
% This function is made to run multiple calculations of different initial
% parameters.
% A for loop will call ode45 with the const struct changing for each new
% parameter value being changed. Only one parameter can be changed at a
% time, to change multiple different ones, this function must be called
% again.
% INPUTS:
% Parameter is the desired parameter being changed, as a string. This
% should be the name in the const struct (from getConst()) that is being
% changed.
% const is the struct that is used to calculate the trajectory with given
% initial parameters.
% test_parameter is a matrix of values that the changing parameter is
% spanning
% tspan is the required integration time span for ode45
% tout is a cell of length(test_parameter), where each entry is a matrix of
% time values calculated from ode45.
% states is a cell of the same length where each entry is a matrix of the
% state matrix calculated by ode45.
%Preallocation
tout = cell(length(test_parameter),1);
states = cell(length(test parameter),1);
   for i = 1:length(test_parameter)
       % Changing the parameter inside the const struct to the new value
       const = updateConst(parameter,test_parameter(i));
       %Calculating initial conditions for ode45 (some don't change)
       vx0 = const.v_0*cos(const.theta_i);
       vz0 = const.v_0*sin(const.theta_i);
       % Creating a column vector of initial conditions
       initial_conditions = [const.x_0 ; vx0 ; const.z_0 ; vz0 ;
const.m_0tot ; const.V_0a ; const.m_0a];
       %Function handle, passing in the new const struct
```