Table of Contents

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% Author(s): Noah Vavoso, Andrew Patella, Karina Li
% Assignment title: APPM 2360 Project 2
% Creation date: 10/26/2023
%Purpose: Analyze probability and susceptibility to disease using Markov
%chains.
% S = susceptible
% E = exposed
% I = infected
% R = Recovered
% Im = immune
% V = vaccinated
clear, clc, close all
```

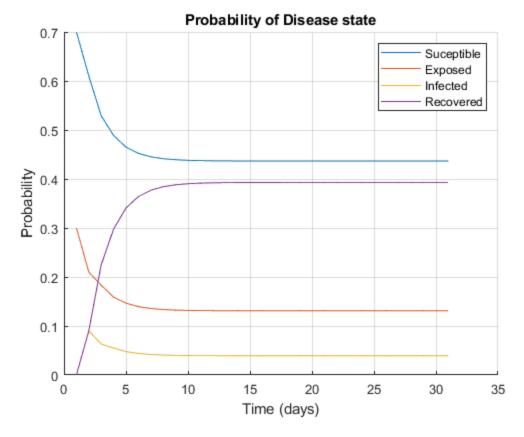
Task A

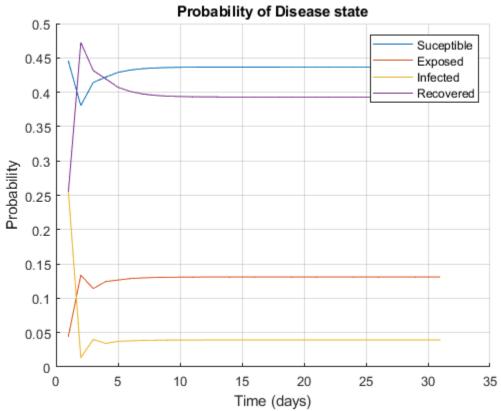
```
%Initial probabilities for task set A
Ps = 0.7;
Pe = 0.4;
Pi = 1;
Pr = 0.8;
%P matrix
         S
                E
                            Т
P\_SEIR = [Ps,
                Pe,
                            0, 1-Pr; %S
                            0, 0;
          1-Ps, 0,
                0.5*(1-Pe), 0, 0;
          0,
                0.5*(1-Pe), Pi, Pr]; %R
          Ο,
%Initial state for problem A3
S = [0; 1; 0; 0];
%Probability for Problem A3
A3 = Markov(P_SEIR,S,1);
% Initial state for problem A4
S = [1; 0; 0; 0];
% Probability for Problem A4
```

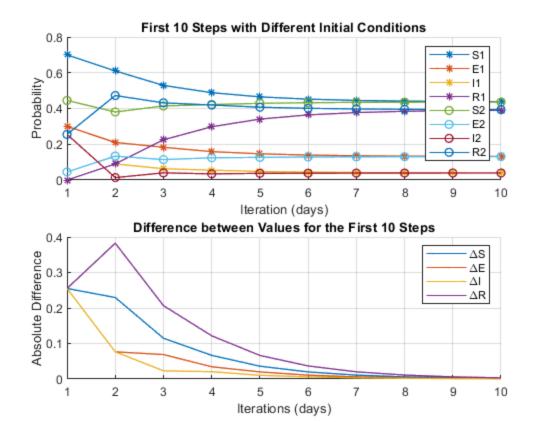
```
A4 = Markov(P_SEIR,S,5);
```

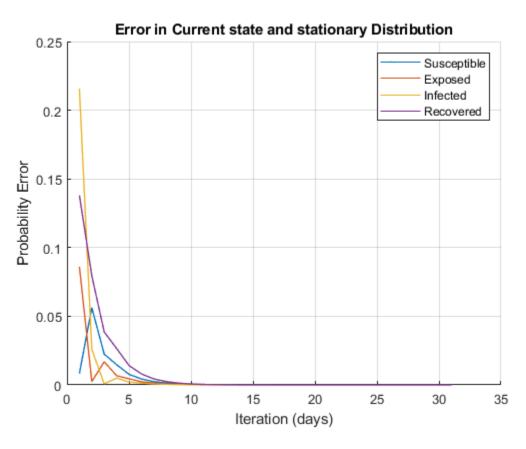
Task B

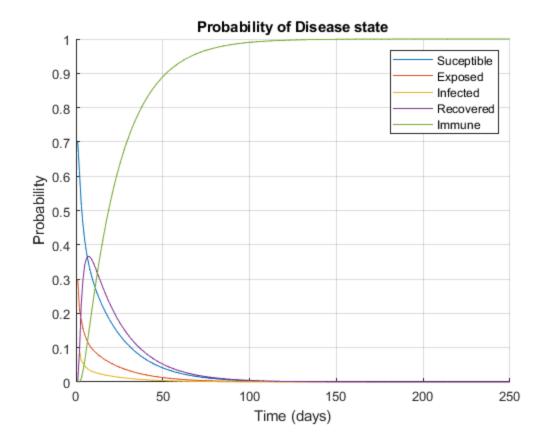
```
%Initial state
S1 = [1; 0; 0; 0];
%time vector for all the days being calculated
interval = 1:31;
%Plotting results for the time interval and initial state
x_b1 = PlotPls(P_SEIR,S1,interval);
x_finalb1 = x_b1(:,end);
%Second initial state, B2.
S2=[.15;.85;0;0];
x_b2 = PlotPls(P_SEIR,S2,interval);
x_finalb2 = x_b2(:,end);
%Calculating the stationary distribution using a function
x_inf = StationaryDistribution(P_SEIR,S2);
% Comparing the probabilities for 2 different initial states 1-10
% iterations
compare_interval = 1:10;
compare_steps(x_b1,x_b2,compare_interval,3);
%Calculating the error between the limit and the actual solution
err = abs_error(x_inf,x_b2,interval);
% B5
%Same process, now with an immune state
Pim = 0.5;
            S.
                  Ε.
                              I.
                                     R.
                                          Ιm
                              0,
                                     0.5*(1-Pr), 0; %S
P_SEIRIm = [Ps,
                Рe,
            1-Ps, 0,
                              0,
                                     0,
                                           0; %E
                  0.5*(1-Pe), 0,
                                           0; %I
                                     Ο,
                  0.5*(1-Pe), Pi, Pr,
                                        0; %R
                              0,
                                   0.5*(1-Pr),
            0,
                  Ο,
                                                  1]; %Im
%Initial state, time interval
S3 = [1; 0; 0; 0; 0];
interval2 = 1:250;
%Plotting and calculating the matrix of SEIR values
x_B5 = PlotPls(P_SEIRIm,S3,interval2);
Warning: Ignoring extra legend entries.
```











Task C

```
Pv = 0.25;
                    Ε.
                                        R.
              S.
                                I.
                                               Im.
                                        1-Pr, 0,
P SEIRVIM = [Ps,
                   Ο,
                                0,
                                                      0;
                                                            %S
             1-Ps, 0,
                                0,
                                               0,
                                                      0;
                                                            %E
                   0.5,
                                0,
                                        0,
                                               0,
                                                      0;
                                                            %Ι
             0,
                   0.5,
                                Ρi,
                                        Pr,
                                               0,
                                                      0;
                                                            %R
                                                     1-Pv; %Im
             0,
                   Ο,
                                Ο,
                                        0,
                                               1,
             0,
                   0,
                                0,
                                               0,
                                                     Pv]; %V
                                        0,
```

```
%Initial state S4
S4 = [1 ;0; 0; 0; 0; 0];

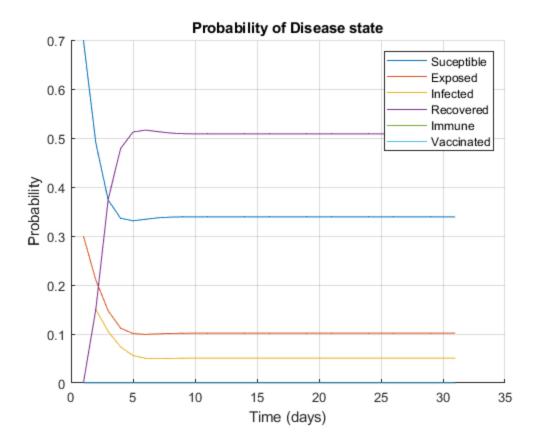
%Calculating the probabilites with interval states, for S4 initial
x_c1 = PlotPls(P_SEIRVIm,S4,interval);

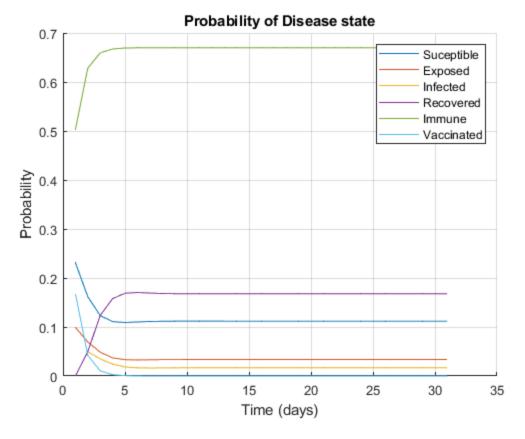
%Calculating the stationary distribution of the P_SEIRVIm matrix
x_inf_C1 = StationaryDistribution(P_SEIRVIm,S4);

%Initial state S5
S5 = [.33; 0; 0; 0; 0; 0.67];
```

 $Calculating probabilities with interval states, for S5 initial <math>x_C2 = PlotPls(P_SEIRVIm, S5, interval);$

 $Calculating the stationary distribution of the P_SEIRVIm matrix with S5 x_inf_C2 = StationaryDistribution(P_SEIRVIm,S5);$





Displaying Values

```
fprintf('A3: Probability with S1, 1 iteration = %f\n',A3);
disp(' ');
% disp(A3);
%disp(A4(4));
fprintf('A4: Probability of Recovered after 5 steps = %f\n',A4(4));
disp(' ');
fprintf('B1: Approximate Stationary Distribution: %f\n',x_finalb1);
disp(' ');
fprintf('B2: Approximate Stationary Distribution: %f\n',x_finalb2);
disp(' ');
fprintf('B4: Actual Stationary Distribution: %f\n',x_inf);
disp(' ');
fprintf('C1: Stationary Distribution: %f\n',x_inf_C1);
disp(' ');
fprintf('C1: Stationary Distribution: %f\n',x_inf_C2);
A3: Probability with S1, 1 iteration = 0.400000
A3: Probability with S1, 1 iteration = 0.000000
A3: Probability with S1, 1 iteration = 0.300000
A3: Probability with S1, 1 iteration = 0.300000
A4: Probability of Recovered after 5 steps = 0.340830
B1: Approximate Stationary Distribution: 0.436681
```

```
B1: Approximate Stationary Distribution: 0.131004
B1: Approximate Stationary Distribution: 0.039301
B1: Approximate Stationary Distribution: 0.393013
B2: Approximate Stationary Distribution: 0.436681
B2: Approximate Stationary Distribution: 0.131004
B2: Approximate Stationary Distribution: 0.039301
B2: Approximate Stationary Distribution: 0.393013
B4: Actual Stationary Distribution: 0.436681
B4: Actual Stationary Distribution: 0.131004
B4: Actual Stationary Distribution: 0.039301
B4: Actual Stationary Distribution: 0.393013
C1: Stationary Distribution: 0.000000
```

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