

# Réunion ANR Melody

Analog data assimilation of 1D extremes

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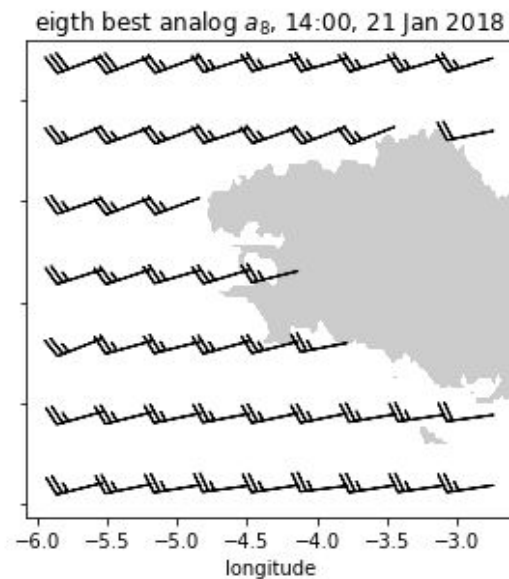
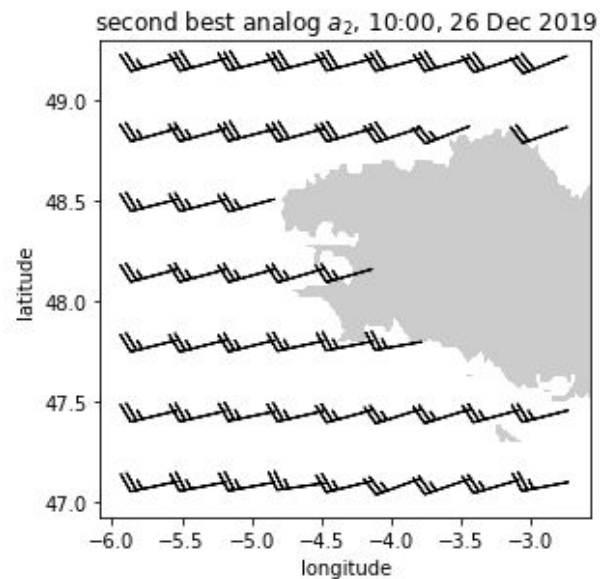
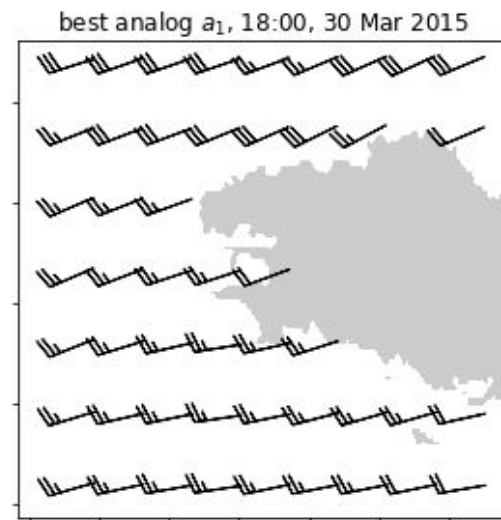
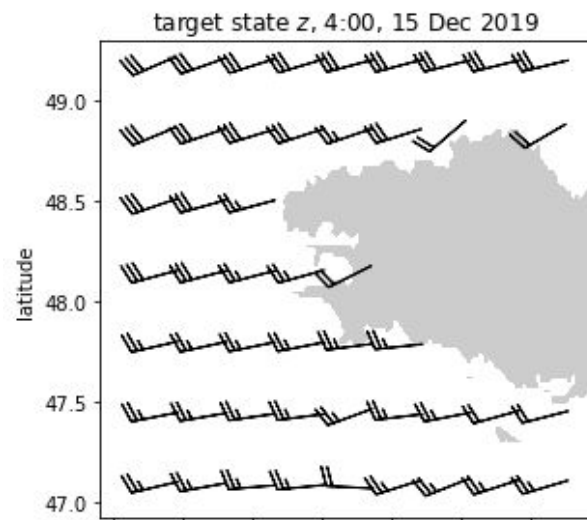
*Joint work with Philippe Naveau, Jean-François Filipot,  
Pierre Tandeo, Pierre Ailliot, Nicolas Raillard, Pascal Yiou*

# What are analogs ?

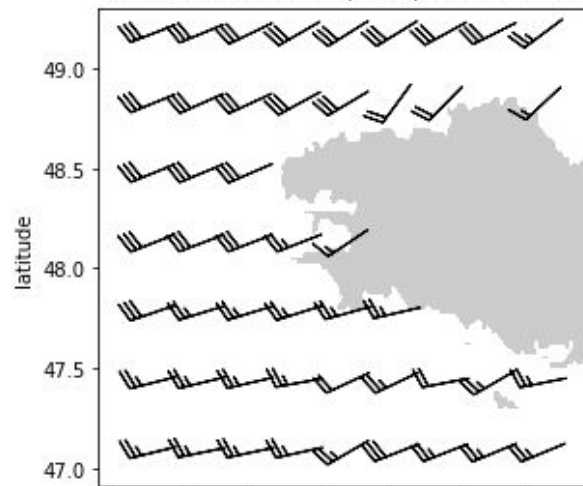
- “k nearest neighbors” in geosciences  
→ dynamical systems, recurrences

## What are they good for ?

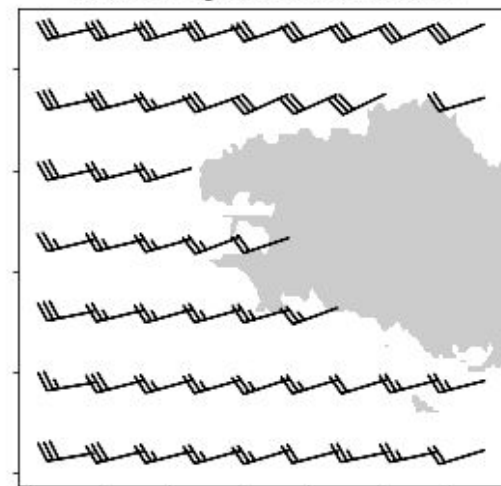
- Forecast (ensembles)
- Downscaling, upscaling
- *Attribution* of extreme events
- Predictability estimation



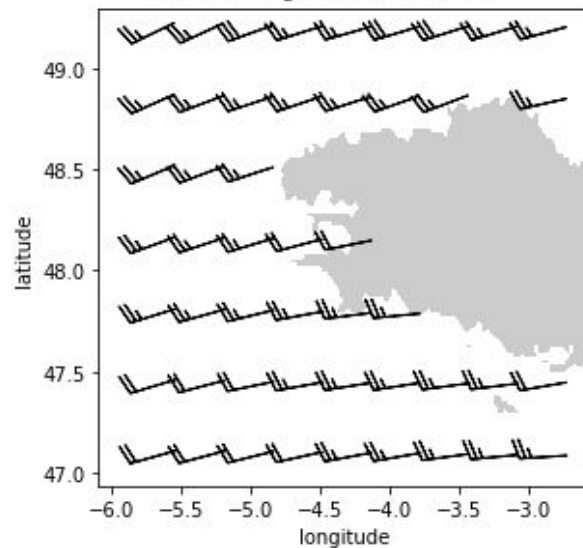
2 hours later state  $z$ , 6:00, 15 Dec 2019



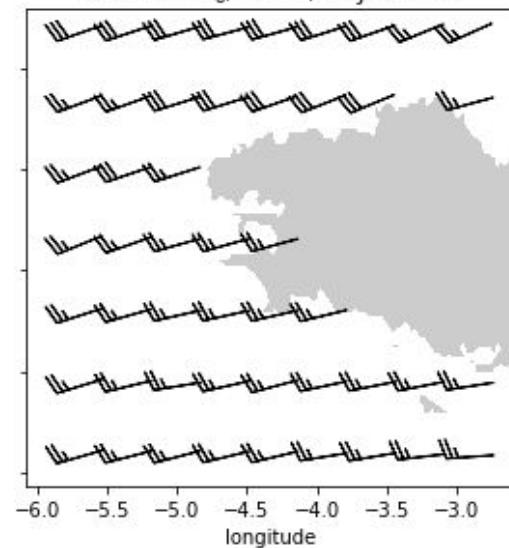
successor  $s_1$ , 20:00, 30 Mar 2015



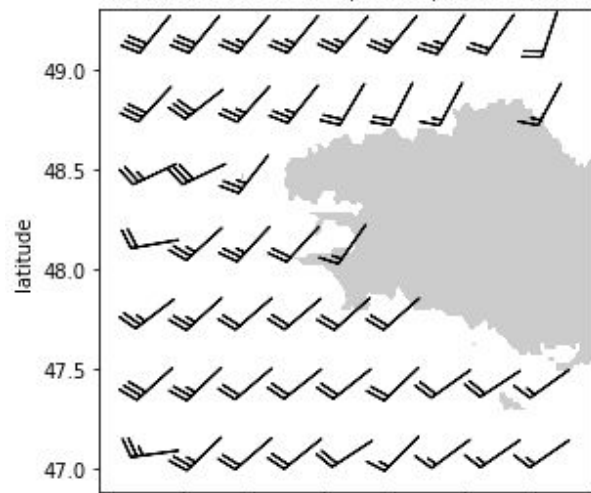
successor  $s_2$ , 12:00, 26 Dec 2019



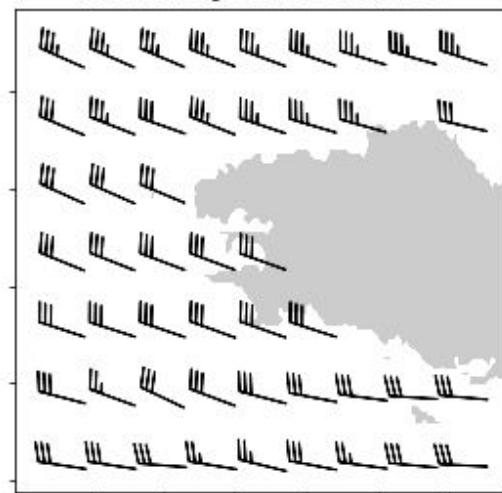
successor  $s_8$ , 16:00, 21 Jan 2018



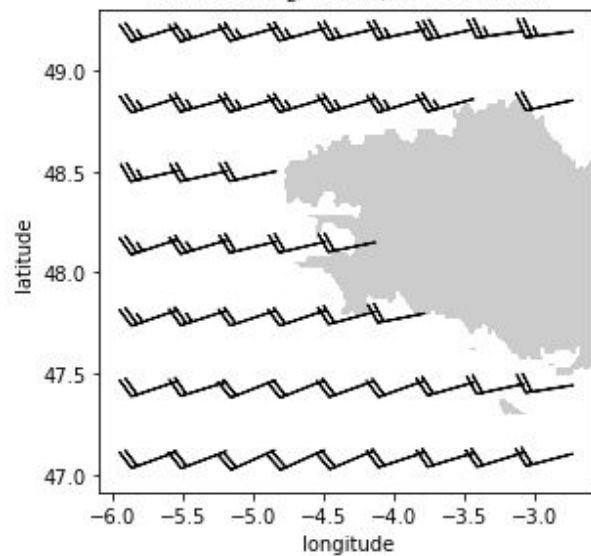
12 hours later state  $z$ , 16:00, 15 Dec 2019



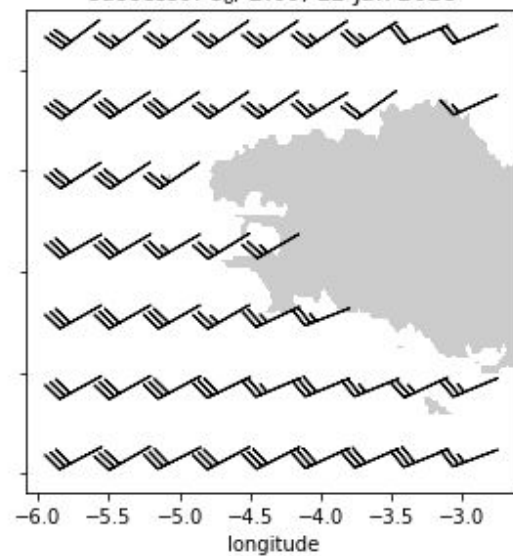
successor  $s_1$ , 6:00, 31 Mar 2015



successor  $s_2$ , 22:00, 26 Dec 2019



successor  $s_8$ , 2:00, 22 Jan 2018



# Why extremes ?

- Important consequences
- Seldom observed → dedicated statistical framework  
→ extreme value theory

## Why analogs of extremes ?

- Never done before because “it shouldn’t work”
- Rare events → few analogs → ?
- Urge to clarify why, when and how “it doesn’t work”

# The experiment

- 1D state-space model with heavy-tailed variables

latent-state:

$$X_t = \mathcal{M}_t(X_{t-1}),$$

model

observation:

$$Y_t = \sigma \frac{E_t}{X_t},$$

noise

# The experiment

- Latent-state : Gamma-distributed

$$X_t \sim \text{Ga}(\xi^{-1}, \xi^{-1}) \quad \text{Corr}(X_t, X_s) = \rho^{|s-t|}$$

$$\mathcal{M}_t^{\text{AR1}}(X_{t-1}) = \rho X_{t-1} + \eta_t,$$

$$\mathcal{M}_t^{\text{THIN}}(X_{t-1}) = B_t X_{t-1} + \zeta_t,$$

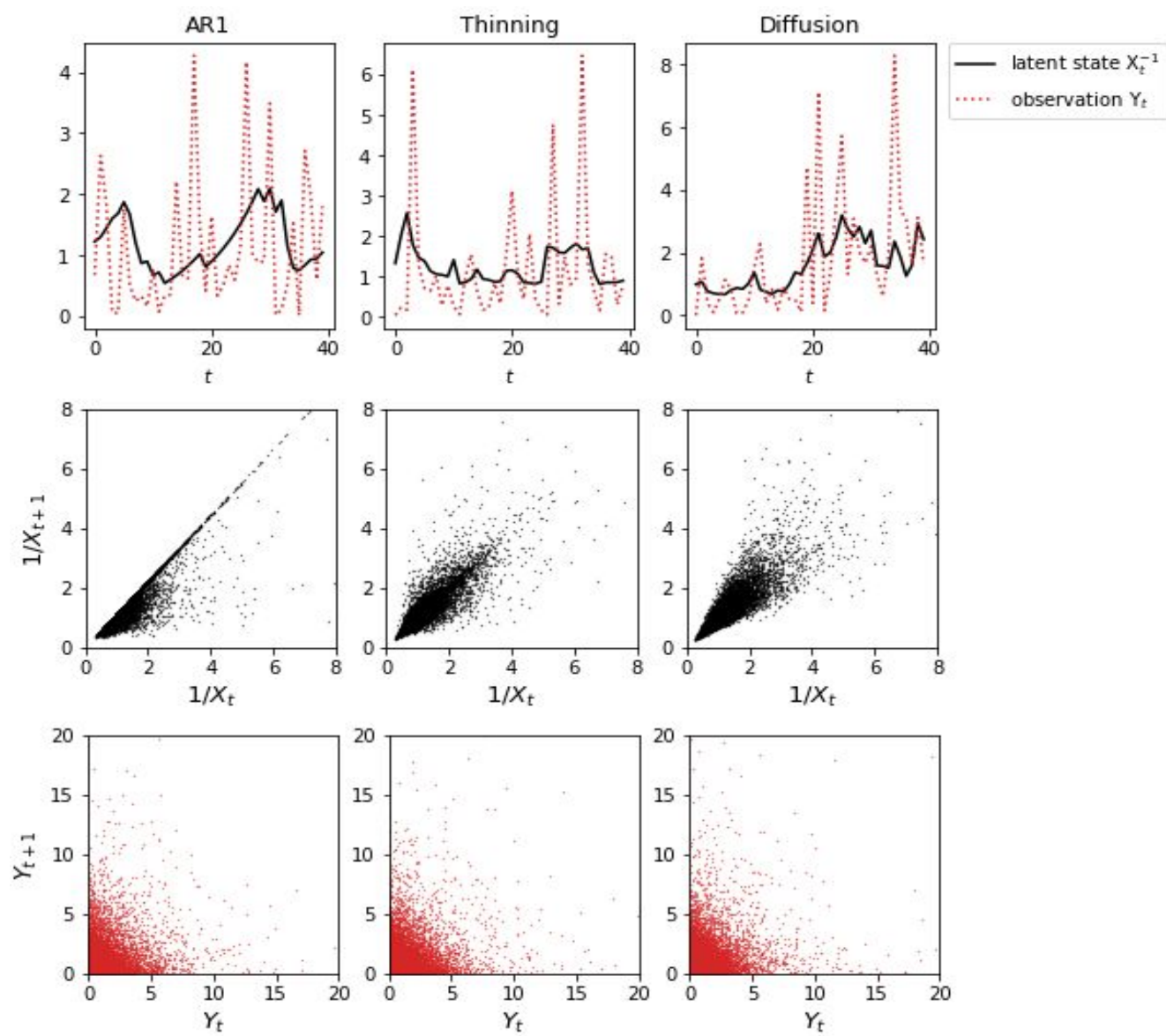
$$\mathcal{M}_t^{\text{OU}}(X_{t-1}) = X_{t-1} + \lambda \int_{t-1}^t (X_s - 1) ds + \sqrt{2\lambda\xi} \int_{t-1}^t \sqrt{X_s} dW_s,$$



# The experiment

- Observations : generalized Pareto distribution

$$\left[ \begin{array}{l} Y_t = \sigma \frac{E_t}{X_t} \\ X_t \sim \text{Ga}(\xi^{-1}, \xi^{-1}) \\ E_t \sim \exp(1) \end{array} \right. \quad \longrightarrow \quad Y_t \sim \text{GPD}(\sigma, \xi)$$



# Objectives

- “reconstruct” the latent-state

$$d\mathbb{P}(X_{1:t} = x_{1:t} \mid Y_{1:t} = y_{1:t}) ,$$

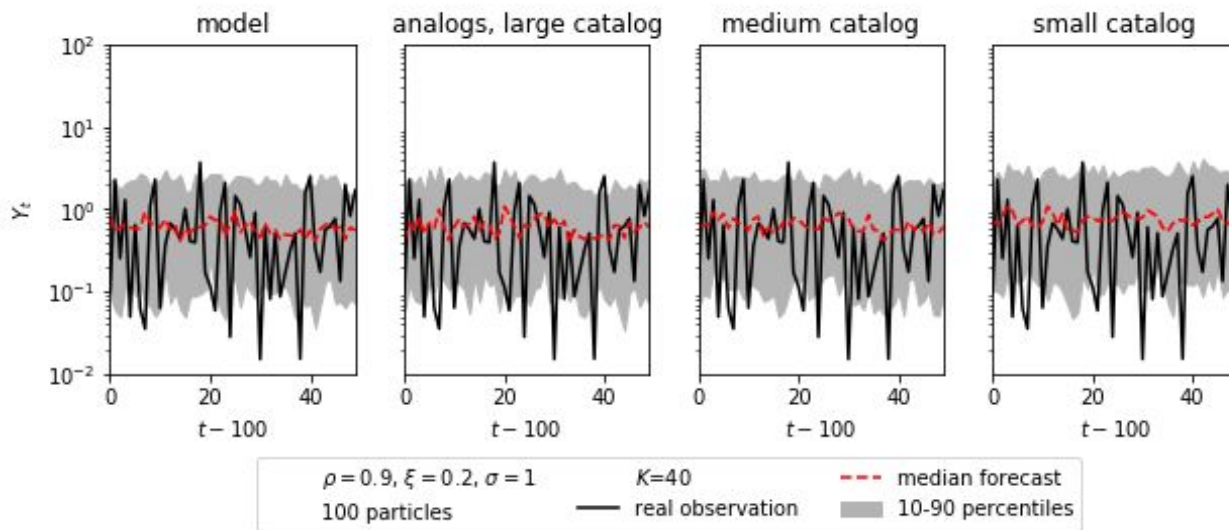
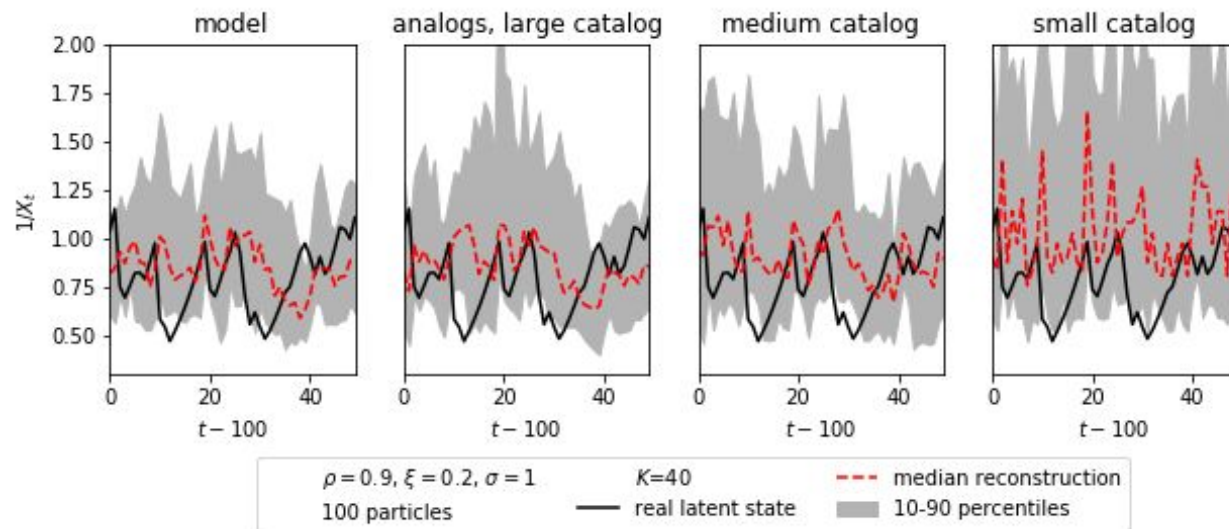
- forecast the next observation

$$d\mathbb{P}(Y_{t+1} = y_{t+1} \mid Y_{1:t} = y_{1:t}) ,$$

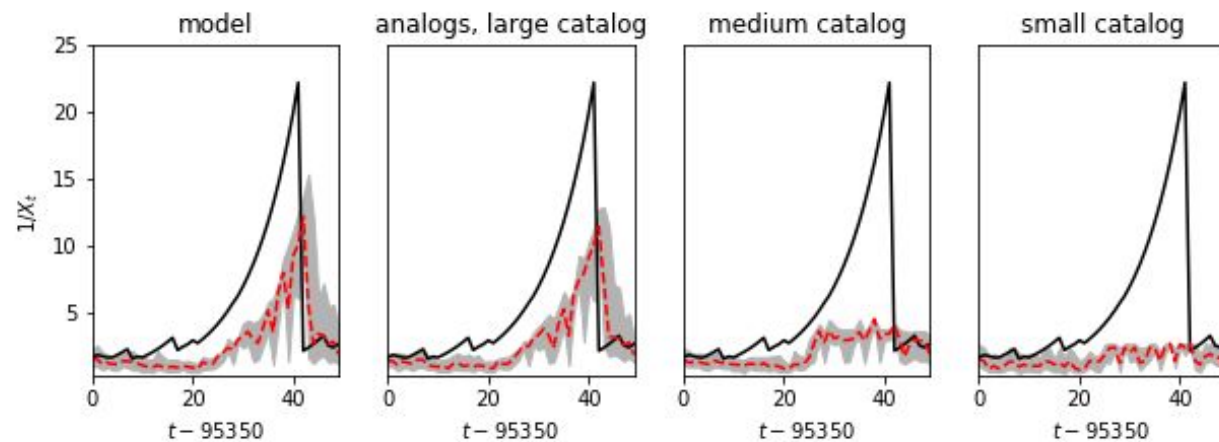
# Tools

- Particle filtering or “sequential Monte-Carlo”
- Analogs with “perfect” catalog generated from the models

## Example of medium values of $1/X_t$



## Example of high values of $1/X_t$

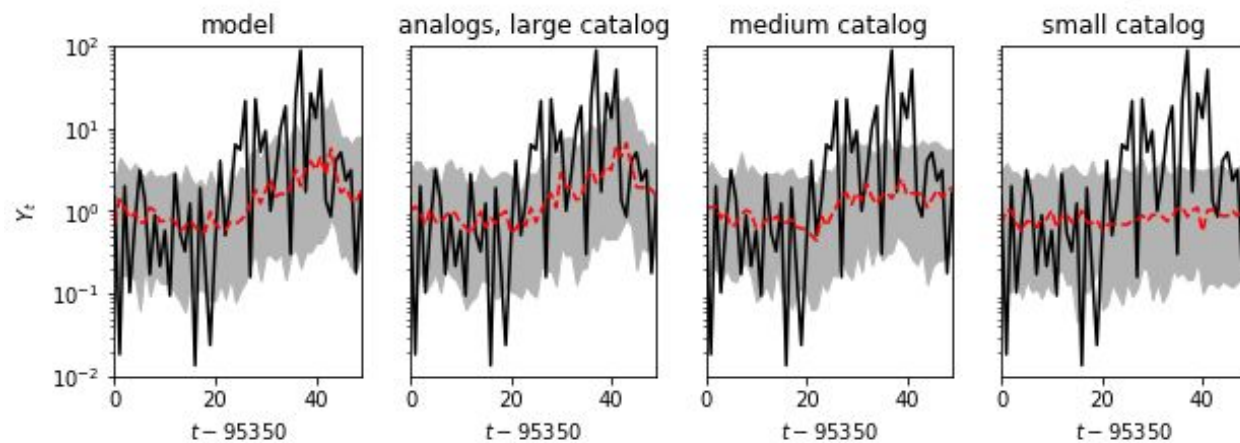


$\rho = 0.9, \xi = 0.2, \sigma = 1$   
100 particles

$K=40$

— real latent state

--- median reconstruction  
■ 10-90 percentiles



$\rho = 0.9, \xi = 0.2, \sigma = 1$   
100 particles

$K=40$

— real observation

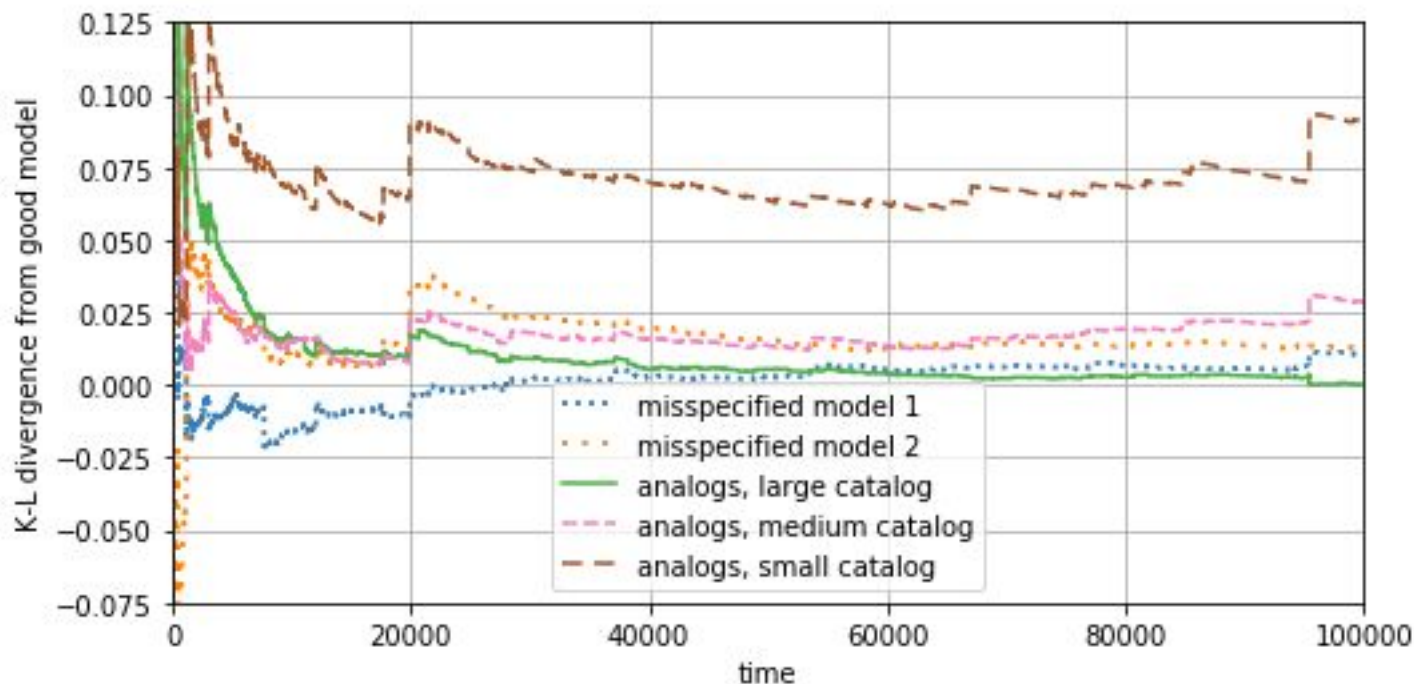
--- median forecast  
■ 10-90 percentiles

# Scores

- log-likelihood  $s(\mathrm{d}\tilde{\mathbb{P}}) = \frac{1}{t} \sum_{k=1}^t \log \mathrm{d}\tilde{\mathbb{P}}(y_{k+1}) ,$

better than  
good model

worse than  
good model



# The chance to find analogs ?

best analog      distance      ball of radius  $r$  around  $z$       catalog      size of catalog

$$\mathbb{P}(\|a_1 - z\| < r) = 1 - [1 - \mathbb{P}(a \in B_{z,r} \mid a \in \mathcal{C})]^L$$

$$= 1 - [1 - P_{z,r}]^L$$

$$\sim LP_{z,r}$$

Dynamical systems:

$$P_{z,r} = \mu(B_{z,r}) \approx \rho_z r^{d_z}$$

dimension

scale factor  $\sim 1$

Van den Dool (1994)  
Nicolis (1998)  
Platzer (2021?)

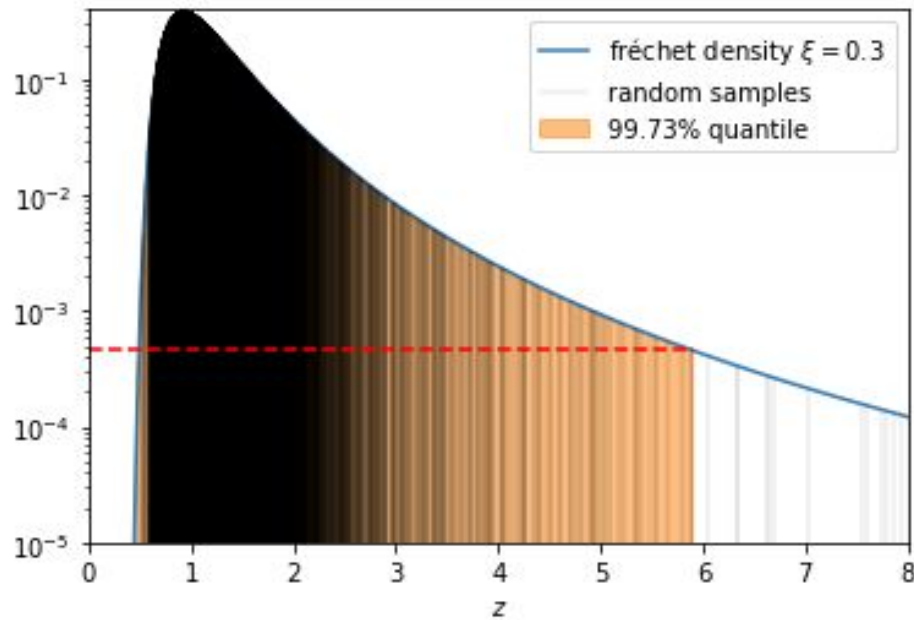
One-dimensional random variable:

$$P_{z,r} = \int_{z-r}^{z+r} f(u) du \approx 2r f(z) \longrightarrow \text{for heavy-tailed variables } f(z) \text{ can be small !}$$

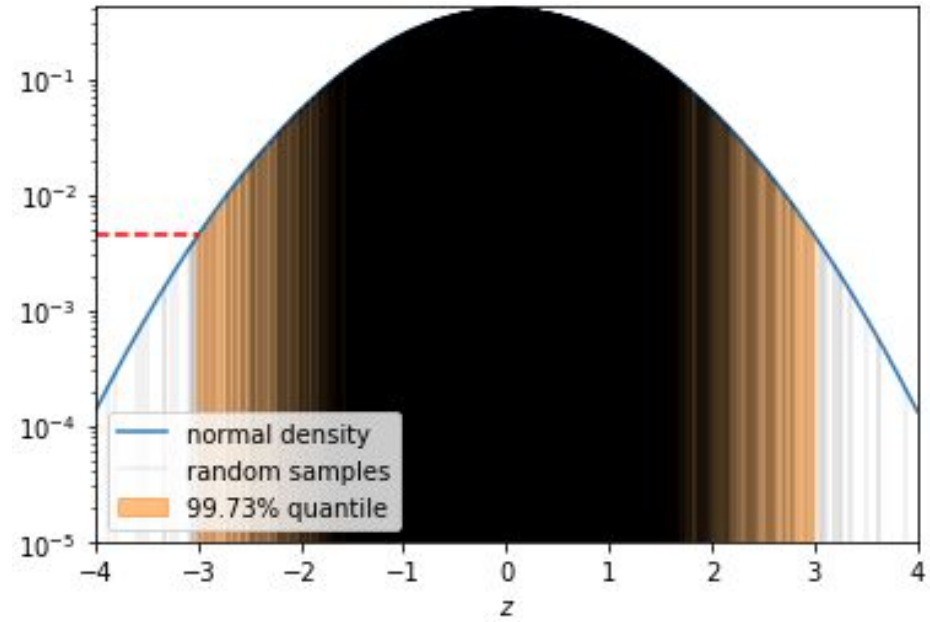


# The chance to find analogs ?

heavy-tailed



light-tailed



# Take-home messages

- Analogs ~ monte-carlo sampling, not limited to a given family of distributions
- Analogs can forecast extreme events, but with a catalog larger than expected for “normal events”
- Dimension is not the only factor of point density

# What to do next

- *Adapt* analog forecasting techniques to extreme events for a *fixed catalog length* (2.1)
- Use other machine-learning tools (NN...) with a structure adapted to state-space models, and a cost-function adapted to extremes (2.2)
- Real data