## Algorithm Fully symbolic memory: naive implementation

```
formula\_types = \{ft_{concrete}, ft_{symbolic}, ft_{memset}, ft_{memcpy}\}
                                   := memory of state s
                                   := \{e \to (ft, e, v, t, \delta)\} where e must be a concrete expression
    M_s.concrete
    M_s.symbolic
                                   :=\{(ft,a,b,e,v,t,\delta)\}
    M_s.memcpy
                       := \{(ft, \alpha, \beta, size, t, \delta)\}\
    M_s.memset
                       := \{(ft, e, size, v, t, \delta)\}
  Immutable objects:
                           := timestamp (initially set to 0)
     t_{pos}
                           := timestamp (initially set to 0)
     t_{neg}
                           := an expression over symbols and concrete values
     e
                           := a 1-byte expression over symbols and concrete values
     V
                           := ordered set of 1-byte values
     \pi
                           := set of assumptions
 1: function STORE(e, V, size):
2:
         for k = 0 to size - 1 do
3:
             \_STORE(e+k, v_k)
 4:
         end for
5: end function
 1: function \_STORE(e, v):
 2:
         a \leftarrow min(e)
3:
        b \leftarrow max(e)
 4:
        t_{pos} \leftarrow t_{pos} + 1
         if a == b then
5:
             M_s.concrete[a] \leftarrow M_s.concrete[a] \cup \{(ft_{concrete}, e, v, t_{pos}, true)\}
 6:
 7:
         else
             M_s.symbolic \leftarrow M_s.symbolic \cup \{(ft_{symbolic}, a, b, e, v, t_{pos}, true)\}
8:
9:
         end if
10: end function
1: function SEARCH(a, b, t):
2:
         P \leftarrow \varnothing
         for k \leftarrow a to b do
3:
 4:
             P \leftarrow P \cup \{x \mid x \in M_s.concrete[k] \land x(t) \leq t\}
 5:
 6:
         P \leftarrow P \cup \{x \mid x \in M_s \land [x(a), x(b)] \cap [a, b] \neq \emptyset \land x(t) \leq t\}
 7:
         P \leftarrow P \cup \{x \mid x \in M_s.memcpy \land x(t) \leq t\}
         P \leftarrow P \cup \{x \mid x \in M_s.memset \land x(x) \leq t\}
8:
9:
         return P
10: end function
```

```
1: function LOAD(e, size):
 2:
          V = \langle \rangle
 3:
          for k = 0 to size - 1 do
 4:
              v_k = \bot \text{LOAD}(e + k, t_{pos})
              V = V \cdot v_k
 5:
 6:
          end for
          return V
 7:
 8: end function
 1: function _LOAD(e, t):
         a \leftarrow min(e)
 2:
 3:
          b \leftarrow max(e)
 4:
          P \leftarrow \text{SEARCH}(a, b, t)
          P \leftarrow \text{SORT\_BY\_INCREASING\_TIMESTAMP}(P)
 5:
 6:
          v \leftarrow \text{SYMBOLIC\_INPUT}()
                                                                                                                                ▶ unintialized memory
 7:
          t_{neg} \leftarrow t_{neg} - 1
 8:
          M_s.symbolic \leftarrow M_s.symbolic \cup \{(a, b, e, v, t_{neg}, true)\}
                                                                                                                                          ▷ implicit store
 9:
          for x \in P do
10:
              if x(ft) == ft_{concrete} \lor x(ft) == ft_{symbolic} then
11:
                   v \leftarrow ite(x(e) = e \land x(\delta), x(v), v)
12:
              else if x(ft) == ft_{memset} then
13:
                   v \leftarrow ite(x(e) \le e \le x(e) + x(size) \land x(\delta), x(v), v)
14:
              else if x(ft) == ft_{memcpy} then
                   v \leftarrow ite(x(\beta) \le e \le x(\beta) + x(size) \land x(\delta), \bot OAD(e - \beta + \alpha, x(t)), v)
15:
              end if
16:
17:
          end for
          return v
18:
19: end function
 1: function MEMCPY(e_{dst}, e_{src}, size):
          M_s.memcpy \leftarrow M_s.memcpy \cup \{(ft_{memcpy}, e_{src}, e_{dst}, size, t, true)\}
 3: end function
 1: function MEMSET(e, size, v):
          M_s.memset \leftarrow M_s.memset \cup \{(ft_{memset}, e, size, v, t, true)\}
 3: end function
 1: function MERGE((S_1, \delta_1), (S_2, \delta_2), S_{ancestor}):
                                                                                                                                             \triangleright S_1 := sel f
         t_{pos}^{anc} = S_{ancestor}.t_{pos}
t_{neg}^{anc} = S_{ancestor}.t_{neg}
 2:
 3:
          M_s \leftarrow S_{ancestor}.M_s
 4:
         for \{x \in S_1.M_s \mid (x(t) > 0 \land x(t) > t_{pos}^{anc}) \lor (x(t) < 0 \land x(t) < t_{neg}^{anc})\} do
 5:
              x(\delta) = x(\delta) \wedge \delta_1
 6:
              M_s.ADD((x(a), x(b)), x))
 7:
          end for
 8:
          for \{x \in S_2.M_s \mid (x(t) > 0 \land x(t) > t_{pos}^{anc}) \lor (x(t) < 0 \land x(t) < t_{neg}^{anc})\} do
 9:
              x(\delta) = x(\delta) \wedge \delta_2
10:
11:
              M_s.ADD((x(a), x(b)), x))
12:
          end for
13:
          t_{pos} = max(S_1.t_{pos}, S_2.t_{pos})
          t_{neg} = min(S_1.t_{neg}, S_2.t_{neg})
14:
15: end function
```