

# Moving Average Processes

Econ 211C – Unit 1, Section 3

Eric M. Aldrich

UC Santa Cruz

# White Noise Revisited

White noise,  $\epsilon_{\mathcal{T}}$  is a fundamental building block of canonical time series processes.

- ▶ For most of this course we will assume  $\mathcal{T} = \{\dots, -2, -1, 0, 1, 2, \dots\}$ .
- ▶ That is,  $\epsilon_{\mathcal{T}} = \{\epsilon_t\}_{t=-\infty}^{\infty}$ .
- ▶ We will often use the abbreviation  $\{\epsilon_t\}$ .

Given white noise  $\{\varepsilon_t\}$ , consider the process

$$Y_t = \mu + \varepsilon_t + \theta\varepsilon_{t-1},$$

where  $\mu$  and  $\theta$  are constants.

- ▶ This is a *first-order moving average* or  $MA(1)$  process.
- ▶ We can rewrite in terms of the lag operator:

$$Y_t = c + \theta(L)\varepsilon_t, .$$

where  $\theta(L) = (1 + \theta L)$ .

## MA(1) Mean and Variance

The mean of the first-order moving average process is

$$\begin{aligned}\mathrm{E}[Y_t] &= \mathrm{E}[\mu + \varepsilon_t + \theta\varepsilon_{t-1}] \\ &= \mu + \mathrm{E}[\varepsilon_t] + \theta\mathrm{E}[\varepsilon_{t-1}] \\ &= \mu.\end{aligned}$$

## MA(1) Autocovariances

$$\begin{aligned}\gamma_j &= \text{E} [(Y_t - \mu)(Y_{t-j} - \mu)] \\ &= \text{E} [(\varepsilon_t + \theta\varepsilon_{t-1})(\varepsilon_{t-j} + \theta\varepsilon_{t-j-1})] \\ &= \text{E} [\varepsilon_t\varepsilon_{t-j} + \theta\varepsilon_t\varepsilon_{t-j-1} + \theta\varepsilon_{t-1}\varepsilon_{t-j} + \theta^2\varepsilon_{t-1}\varepsilon_{t-j-1}] \\ &= \text{E} [\varepsilon_t\varepsilon_{t-j}] + \theta\text{E} [\varepsilon_t\varepsilon_{t-j-1}] + \theta\text{E} [\varepsilon_{t-1}\varepsilon_{t-j}] + \theta^2\text{E} [\varepsilon_{t-1}\varepsilon_{t-j-1}].\end{aligned}$$

- If  $j = 0$

$$\gamma_0 = \text{E} [\varepsilon_t^2] + \theta\text{E} [\varepsilon_t\varepsilon_{t-1}] + \theta\text{E} [\varepsilon_{t-1}\varepsilon_t] + \theta^2\text{E} [\varepsilon_{t-1}^2] = (1 + \theta^2)\sigma^2.$$

- If  $j = 1$

$$\gamma_1 = \text{E} [\varepsilon_t\varepsilon_{t-1}] + \theta\text{E} [\varepsilon_t\varepsilon_{t-2}] + \theta\text{E} [\varepsilon_{t-1}^2] + \theta^2\text{E} [\varepsilon_{t-1}\varepsilon_{t-2}] = \theta\sigma^2.$$

- If  $j > 1$ , all of the expectations are zero:  $\gamma_j = 0$ .

# MA(1) Stationarity and Ergodicity

Since the mean and autocovariances are independent of time, an MA(1) is weakly stationary.

- This is true *for all values of  $\theta$*

The condition for ergodicity of the mean also holds:

$$\begin{aligned}\sum_{j=0}^{\infty} |\gamma_j| &= \gamma_0 + \gamma_1 \\ &= (1 + \theta^2)\sigma^2 + |\theta\sigma^2| < \infty\end{aligned}$$

- If  $\{\varepsilon_t\}$  is *Gaussian* then  $\{Y_t\}$  is also ergodic *for all moments*.

## $MA(1)$ Autocorrelations

The autocorrelations of an  $MA(1)$  are

►  $j = 0$ :  $\rho_0 = 1$  (*always*).

►  $j = 1$ :

$$\rho_1 = \frac{\theta\sigma^2}{(1 + \theta^2)\sigma^2} = \frac{\theta}{1 + \theta^2}$$

►  $j > 1$ :  $\rho_j = 0$ .

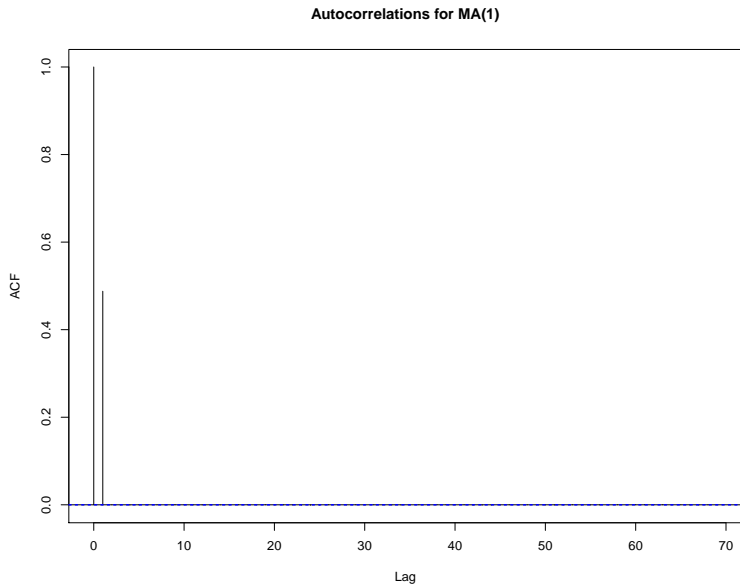
► If  $\theta > 0$ , first-order lags of  $Y_t$  are *positively* autocorrelated.

► If  $\theta < 0$ , first-order lags of  $Y_t$  are *negatively* autocorrelated.

►  $\max\{\rho_1\} = 0.5$  and occurs when  $\theta = 1$ .

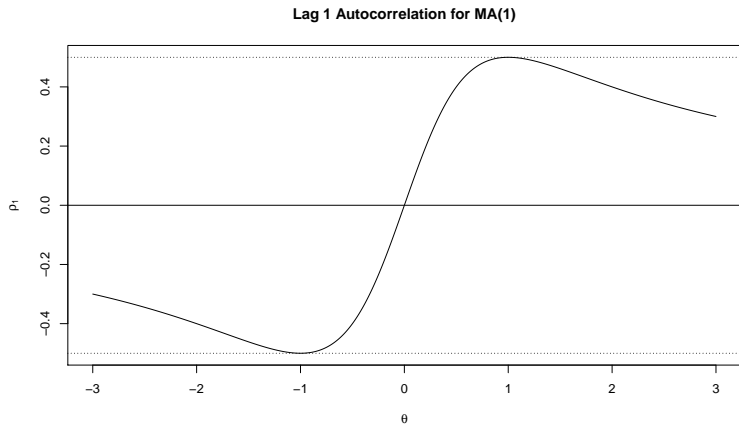
►  $\min\{\rho_1\} = -0.5$  and occurs when  $\theta = -1$ .

# $MA(1)$ Autocorrelations





# MA(1) Autocorrelations



## MA(1) Autocorrelations

From the figure above we see that there are two values of  $\theta$  that generate each value of  $\rho_1$ .

- In fact,  $\theta$  and  $1/\theta$  correspond to the same  $\rho_1$ :

$$\rho_1 = \frac{1/\theta}{1 + (1/\theta)^2} = \frac{\theta^2}{\theta^2} \frac{1/\theta}{1 + (1/\theta)^2} = \frac{\theta}{1 + \theta^2}.$$

- Consider:

$$Y_t = \varepsilon_t + 0.5\varepsilon_{t-1}$$

$$Y_t = \varepsilon_t + 2\varepsilon_{t-1}$$

- Then:

$$\rho_1 = \frac{0.5}{1 + 0.5^2} = \frac{2}{1 + 2^2} = 0.4.$$

A  $q$ th-order moving average or  $MA(q)$  process is

$$Y_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q},$$

where  $\mu, \theta_1, \dots, \theta_q$  are any real numbers.

- We can rewrite in terms of the lag operator:

$$Y_t = \mu + \theta(L)\varepsilon_t,$$

where  $\theta(L) = (1 + \theta_1 L^1 + \dots + \theta_q L^q)$ .

As with the  $MA(1)$ :

$$\begin{aligned} E[Y_t] &= E[\mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q}] \\ &= \mu + E[\varepsilon_t] + \theta_1 E[\varepsilon_{t-1}] + \dots + \theta_q E[\varepsilon_{t-q}] \\ &= \mu. \end{aligned}$$

## MA( $q$ ) Autocovariances

$$\begin{aligned}\gamma_j &= \text{E} [(Y_t - \mu)(Y_{t-j} - \mu)] \\ &= \text{E} [(\varepsilon_t + \theta_1\varepsilon_{t-1} + \dots + \theta_q\varepsilon_{t-q}) \\ &\quad \times (\varepsilon_{t-j} + \theta_1\varepsilon_{t-j-1} + \dots + \theta_q\varepsilon_{t-j-q})].\end{aligned}$$

- ▶ For  $j > q$ , all of the products result in zero expectations:  
 $\gamma_j = 0$ , for  $j > q$ .
- ▶ For  $j = 0$ , the squared terms result in nonzero expectations, while the cross products lead to zero expectations:

$$\gamma_0 = \text{E} [\varepsilon_t^2] + \theta_1^2 \text{E} [\varepsilon_{t-1}^2] + \dots + \theta_q^2 \text{E} [\varepsilon_{t-q}^2] = \left( 1 + \sum_{j=1}^q \theta_j^2 \right) \sigma^2.$$

## MA( $q$ ) Autocovariances

- For  $j = \{1, 2, \dots, q\}$ , the nonzero expectation terms are

$$\begin{aligned}\gamma_j &= \theta_j \mathbb{E}[\varepsilon_{t-j}^2] + \theta_{j+1} \theta_1 \mathbb{E}[\varepsilon_{t-j-1}^2] \\ &\quad + \theta_{j+2} \theta_2 \mathbb{E}[\varepsilon_{t-j-2}^2] + \dots + \theta_q \theta_{q-j} \mathbb{E}[\varepsilon_{t-q}^2] \\ &= (\theta_j + \theta_{j+1} \theta_1 + \theta_{j+2} \theta_2 + \dots + \theta_q \theta_{q-j}) \sigma^2.\end{aligned}$$

The autocovariances can be stated concisely as

$$\gamma_j = \begin{cases} (\theta_j + \theta_{j+1} \theta_1 + \theta_{j+2} \theta_2 + \dots + \theta_q \theta_{q-j}) \sigma^2 & \text{for } j = 0, 1, \dots, q \\ 0 & \text{for } j > q. \end{cases}$$

where  $\theta_0 = 1$ .

# MA(q) Autocorrelations

The autocorrelations can be stated concisely as

$$\rho_j = \begin{cases} \frac{\theta_j + \theta_{j+1}\theta_1 + \theta_{j+2}\theta_2 + \dots + \theta_q\theta_{t-q}}{\theta_0^2 + \theta_1^2 + \theta_2^2 + \dots + \theta_q^2} & \text{for } j = 0, 1, \dots, q \\ 0 & \text{for } j > q. \end{cases}$$

where  $\theta_0 = 1$ .

## $MA(2)$ Example

For an  $MA(2)$  process

$$\gamma_0 = (1 + \theta_1^2 + \theta_2^2)\sigma^2$$

$$\gamma_1 = (\theta_1 + \theta_2\theta_1)\sigma^2$$

$$\gamma_2 = \theta_2\sigma^2$$

$$\gamma_3 = \gamma_4 = \dots = 0.$$



# $MA(q)$ Stationarity and Ergodicity

Since the mean and autocovariances are independent of time, an  $MA(q)$  is weakly stationary.

- This is true *for all values of*  $\{\theta_j\}_{j=1}^q$ .

The condition for ergodicity of the mean also holds:

$$\sum_{j=0}^{\infty} |\gamma_j| = \sum_{j=0}^q |\gamma_j| < \infty.$$

- If  $\{\varepsilon_t\}$  is *Gaussian* then  $\{Y_t\}$  is also ergodic *for all moments*.

If  $\theta_0 = 1$ , the  $MA(q)$  process can be written as

$$Y_t = \mu + \sum_{j=0}^q \theta_j \varepsilon_{t-j}.$$

- If we take the limit  $q \rightarrow \infty$ :

$$Y_t = \mu + \sum_{j=0}^{\infty} \theta_j \varepsilon_{t-j} = \mu + \theta(L) \varepsilon_t,$$

where  $\theta(L) = \sum_{j=0}^{\infty} \theta_j L^j$ .

- It can be shown that an  $MA(\infty)$  process is weakly stationary if

$$\sum_{j=0}^{\infty} \theta_j^2 < \infty.$$

Since absolute summability implies square summability

$$\sum_{j=0}^{\infty} |\theta_j| \Rightarrow \sum_{j=0}^{\infty} \theta_j^2,$$

an  $MA(\infty)$  process satisfying absolute summability is also weakly stationary.

- In general

$$\sum_{j=0}^{\infty} \theta_j^2 \not\Rightarrow \sum_{j=0}^{\infty} |\theta_j|.$$

Following the same reasoning as above,

$$\begin{aligned} E[Y_t] &= \mu \\ \gamma_j &= \sigma^2 \sum_{i=0}^{\infty} \theta_{j+i} \theta_i. \end{aligned}$$

- ▶  $\sum_{j=0}^{\infty} |\theta_j| \Rightarrow \sum_{j=0}^{\infty} |\gamma_j|$ .
- ▶ So if the  $MA(\infty)$  has absolutely summable coefficients, it is ergodic for the mean.
- ▶ Further, if  $\{\varepsilon_t\}$  is *Gaussian* then  $\{Y_t\}$  is also ergodic *for all moments*.