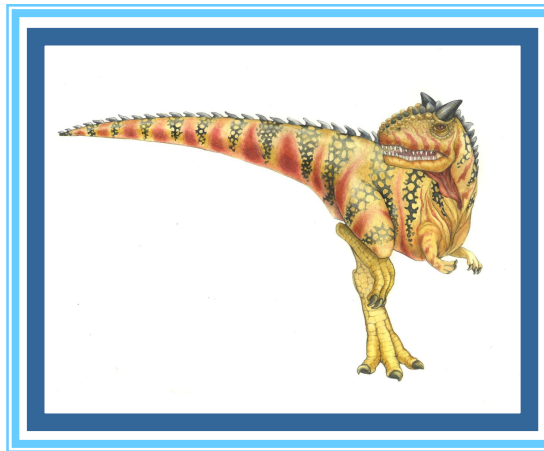


Main Memory





Background

- Program must be brought into memory and placed within a process for it to be executed.
- *Input queue* – collection of processes on the disk that are waiting to be brought into memory for execution.
- User programs go through several steps before being executed.





Binding of Instructions and Data to Memory

Address binding of instructions and data to memory addresses can happen at three different stages.

- ❑ **Compile time:** If memory location known a priori, absolute code can be generated; must recompile code if starting location changes.
- ❑ **Load time:** Must generate *relocatable* code if memory location is not known at compile time.
- ❑ **Execution time:** Binding delayed until run time if the process can be moved during its execution from one memory segment to another. Need hardware support for address maps (e.g., *base* and *limit registers*).





Dynamic Loading

- Routine is not loaded until it is called
- Better memory-space utilization; unused routine is never loaded.
- Useful when large amounts of code are needed to handle infrequently occurring cases.
- No special support from the operating system is required implemented through program design.





Dynamic Linking

- ❑ Linking postponed until execution time.
- ❑ Small piece of code, *stub*, used to locate the appropriate memory-resident library routine.
- ❑ Stub replaces itself with the address of the routine, and executes the routine.
- ❑ Operating system needed to check if routine is in processes' memory address.

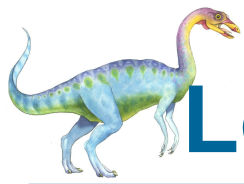




Overlays

- ❑ Keep in memory only those instructions and data that are needed at any given time.
- ❑ Needed when process is larger than amount of memory allocated to it.
- ❑ Implemented by user, no special support needed from operating system, programming design of overlay structure is complex





Logical vs. Physical Address Space

- The concept of a logical *address space* that is bound to a separate *physical address space* is central to proper memory management.
 - *Logical address* – generated by the CPU; also referred to as *virtual address*.
 - *Physical address* – address seen by the memory unit.
- Logical and physical addresses are the same in compile-time and load-time address-binding schemes; logical (virtual) and physical addresses differ in execution-time address-binding scheme.





Memory-Management Unit (MMU)

- ❑ Hardware device that maps virtual to physical address.
- ❑ In MMU scheme, the value in the relocation register is added to every address generated by a user process at the time it is sent to memory.
- ❑ The user program deals with *logical* addresses; it never sees the *real* physical addresses.





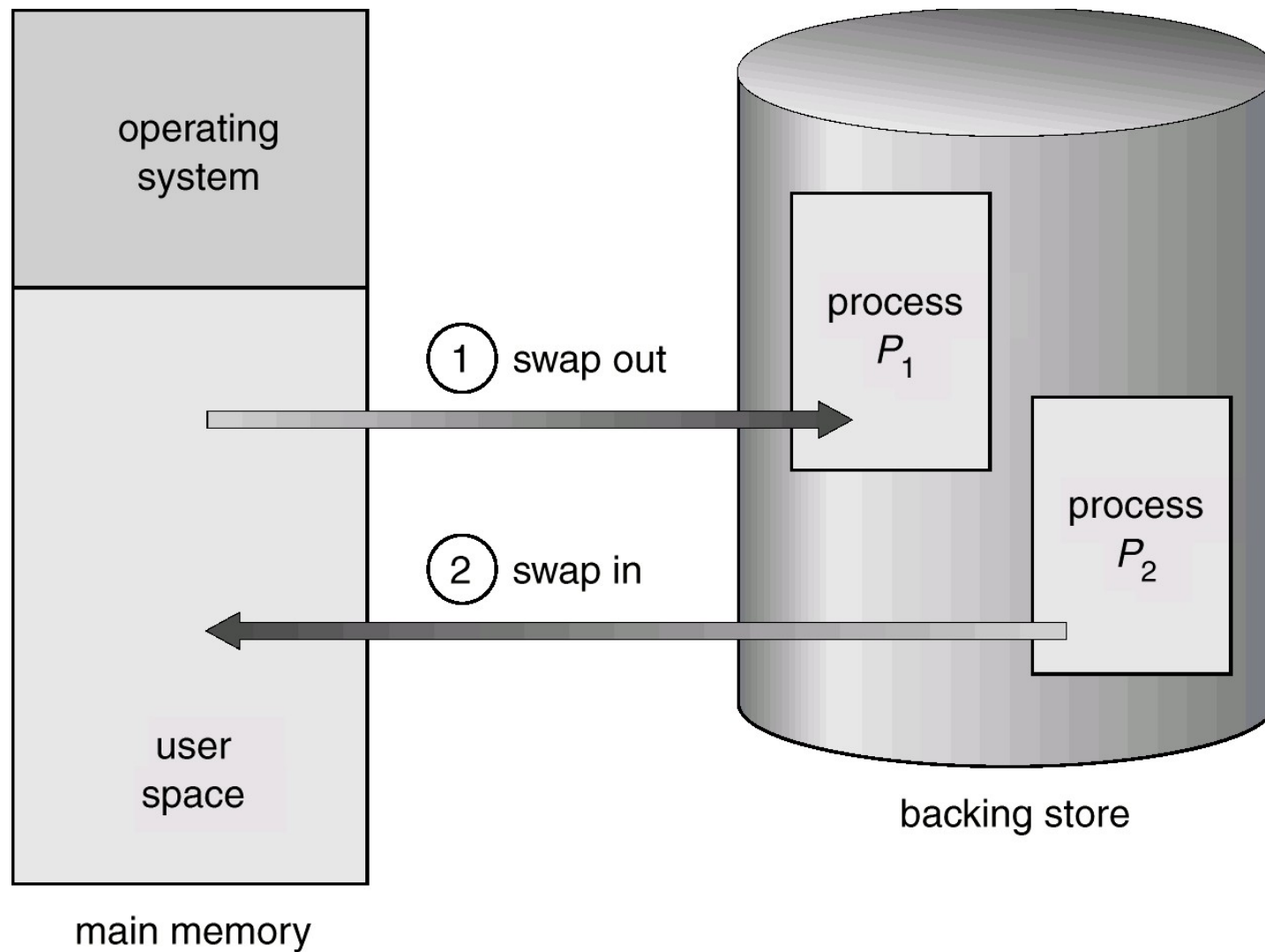
Swapping

- A process can be *swapped* temporarily out of memory to a *backing store*, and then brought back into memory for continued execution.
- Backing store – fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images.
- *Roll out, roll in* – swapping variant used for priority-based scheduling algorithms; lower-priority process is swapped out so higher-priority process can be loaded and executed.
- Major part of swap time is transfer time; total transfer time is directly proportional to the *amount* of memory swapped.
- Modified versions of swapping are found on many systems, i.e., UNIX and Microsoft Windows.





Schematic View of Swapping





Contiguous Allocation

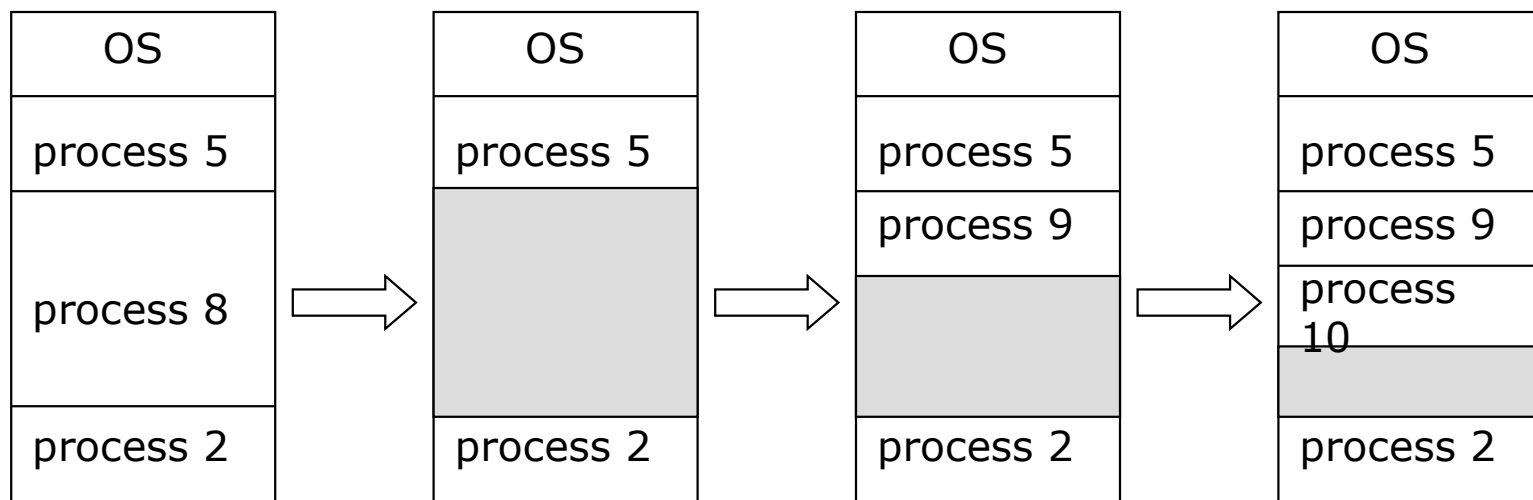
- Main memory usually into two partitions:
 - Resident operating system, usually held in low memory with interrupt vector.
 - User processes then held in high memory.
- Single-partition allocation
 - Relocation-register scheme used to protect user processes from each other, and from changing operating-system code and data.
 - Relocation register contains value of smallest physical address; limit register contains range of logical addresses – each logical address must be less than the limit register.





Contiguous Allocation (Cont.)

- ❑ Multiple-partition allocation
 - ❑ *Hole* – block of available memory; holes of various size are scattered throughout memory.
 - ❑ When a process arrives, it is allocated memory from a hole large enough to accommodate it.
 - ❑ Operating system maintains information about:
 - a) allocated partitions b) free partitions (hole)





Dynamic Storage-Allocation Problem

How to satisfy a request of size n from a list of free holes.

- **First-fit:** Allocate the *first* hole that is big enough.
- **Best-fit:** Allocate the *smallest* hole that is big enough; must search entire list, unless ordered by size. Produces the smallest leftover hole.
- **Worst-fit:** Allocate the *largest* hole; must also search entire list. Produces the largest leftover hole.

First-fit and best-fit better than worst-fit in terms of speed and storage utilization.





Fragmentation

- External fragmentation – total memory space exists to satisfy a request, but it is not contiguous.
- Internal fragmentation – allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used.
- Reduce external fragmentation by compaction
 - Shuffle memory contents to place all free memory together in one large block.
 - Compaction is possible *only* if relocation is dynamic, and is done at execution time.





Paging

- ❑ Logical address space of a process can be noncontiguous; process is allocated physical memory whenever the latter is available.
- ❑ Divide physical memory into fixed-sized blocks called frames (size is power of 2, between 512 bytes and 8192 bytes).
- ❑ Divide logical memory into blocks of same size called pages.
- ❑ Keep track of all free frames.
- ❑ To run a program of size n pages, need to find n free frames and load program.
- ❑ Set up a page table to translate logical to physical addresses.
- ❑ Internal fragmentation.





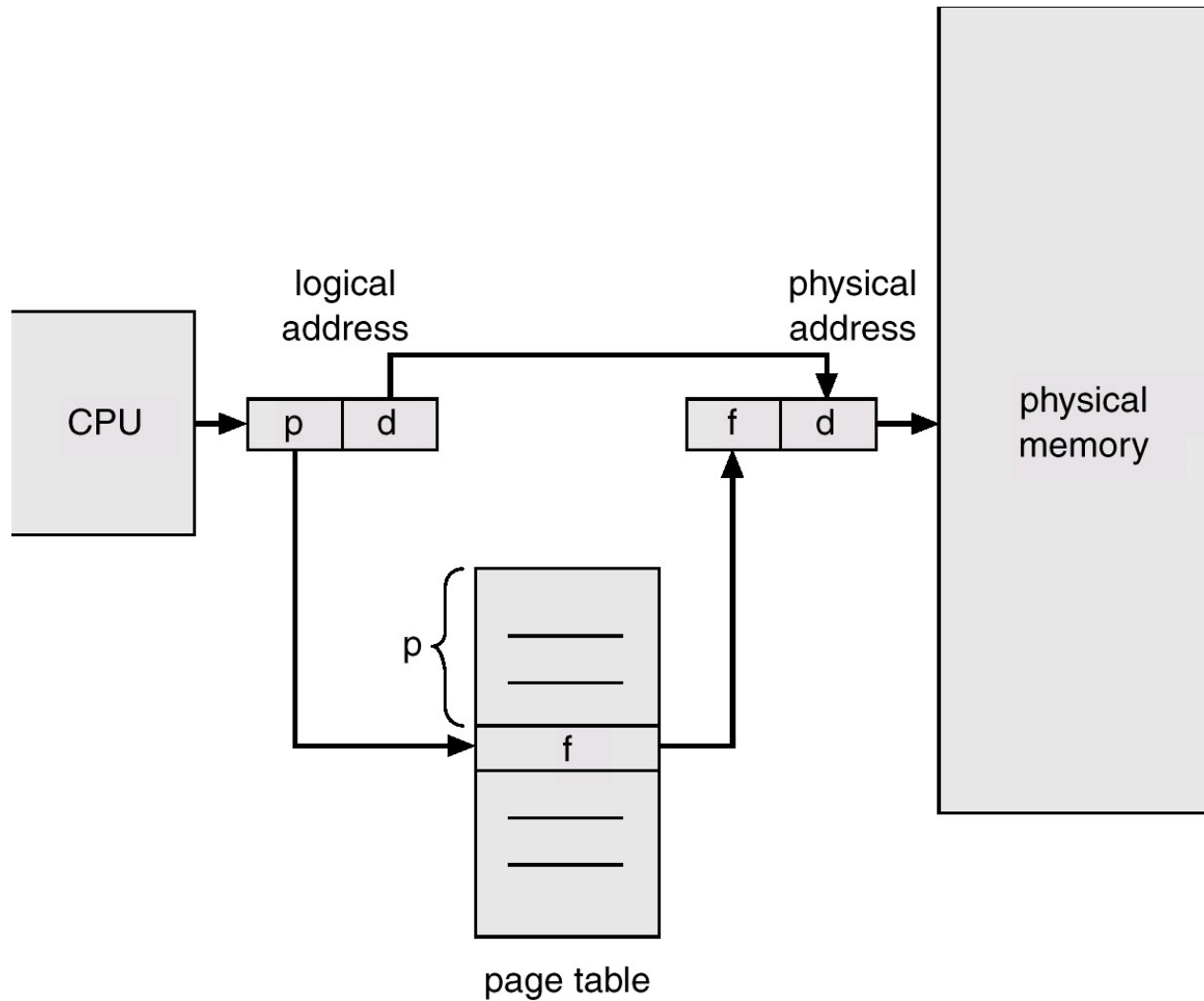
Address Translation Scheme

- Address generated by CPU is divided into:
 - *Page number (p)* – used as an index into a *page table* which contains base address of each page in physical memory.
 - *Page offset (d)* – combined with base address to define the physical memory address that is sent to the memory unit.



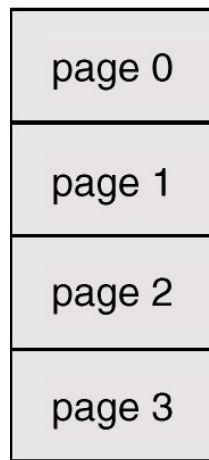


Address Translation Architecture





Paging Example

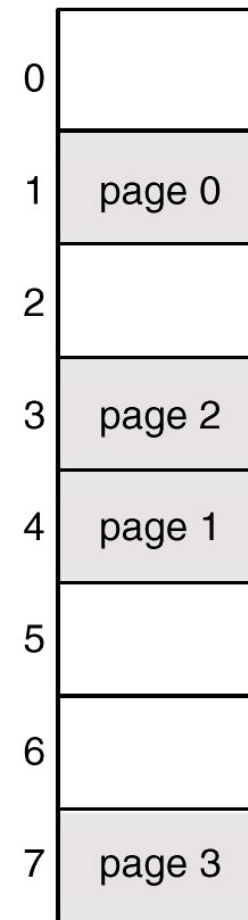


logical
memory

0	1
1	4
2	3
3	7

page table

frame
number



physical
memory





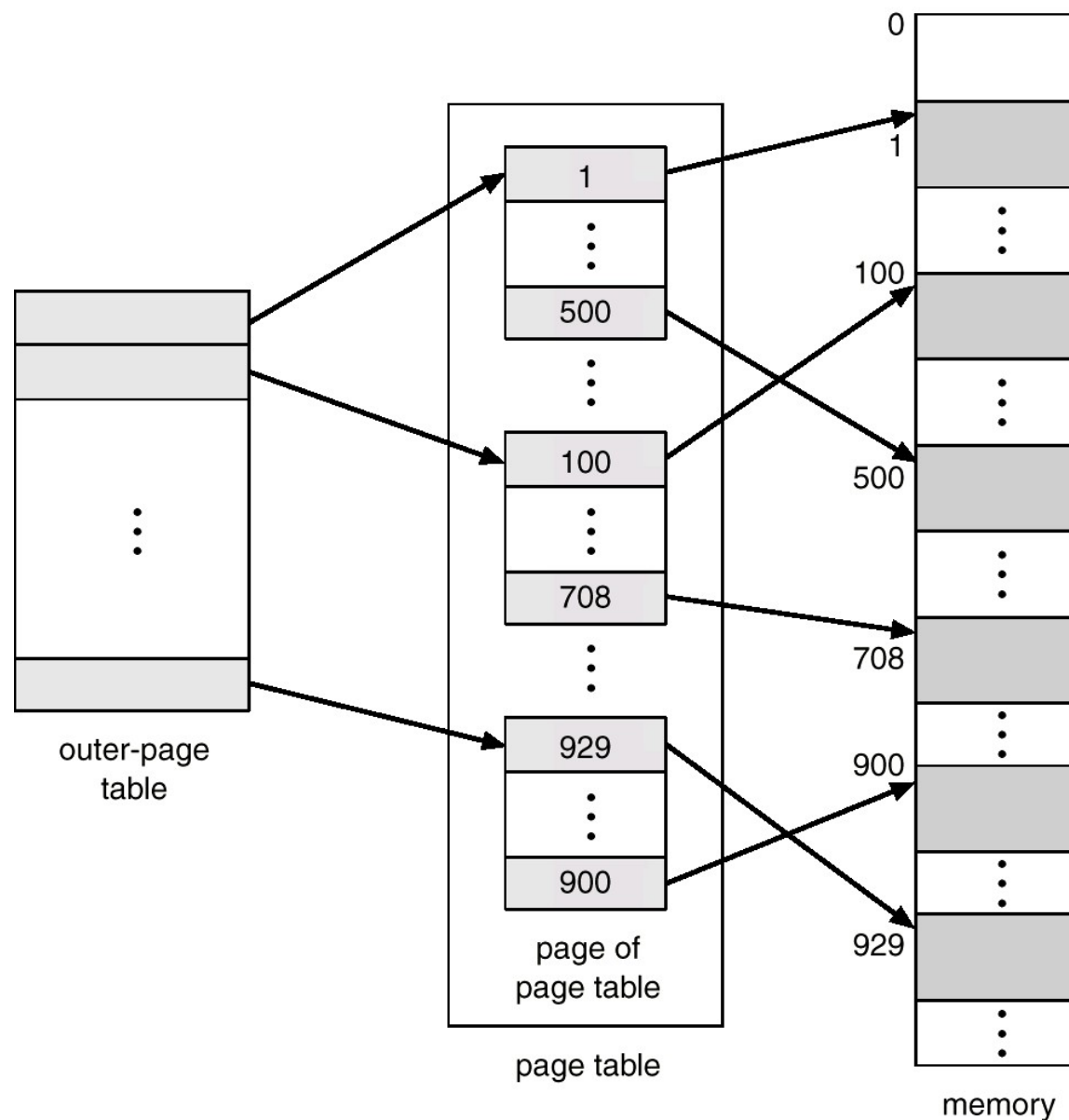
Implementation of Page Table

- Page table is kept in main memory.
- *Page-table base register* (PTBR) points to the page table.
- *Page-table length register* (PRLR) indicates size of the page table.
- In this scheme every data/instruction access requires two memory accesses. One for the page table and one for the data/instruction.
- The two memory access problem can be solved by the use of a special fast-lookup hardware cache called *associative registers* or *translation look-aside buffers* (TLBs)





Two-Level Page-Table Scheme





Two-Level Paging Example

- A logical address (on 32-bit machine with 4K page size) is divided into:
 - a page number consisting of 20 bits.
 - a page offset consisting of 12 bits.
- Since the page table is paged, the page number is further divided into:
 - a 10-bit page number.
 - a 10-bit page offset.
- Thus, a logical address is as follows:

page number		page offset
p_i	p_2	d
10	10	12

where p_i is an index into the outer page table, and p_2 is the displacement within the page of the outer page table.





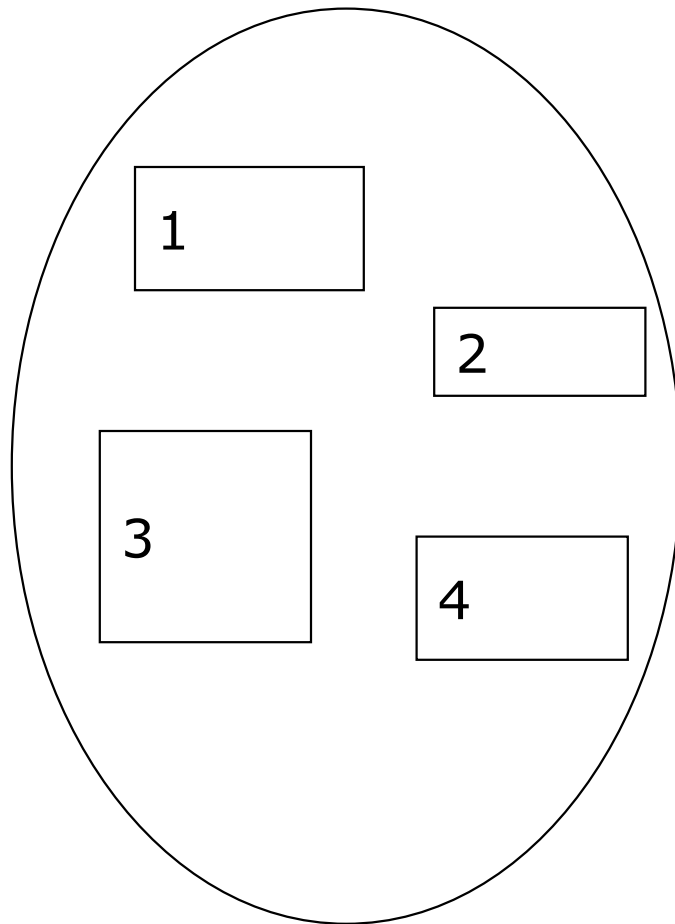
Segmentation

- Memory-management scheme that supports user view of memory.
- A program is a collection of segments. A segment is a logical unit such as:
 - main program,
 - procedure,
 - function,
 - local variables, global variables,
 - common block,
 - stack,
 - symbol table, arrays

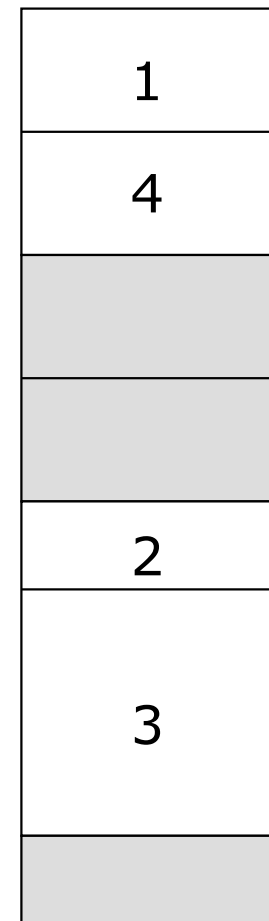




Logical View of Segmentation



user space



physical memory space



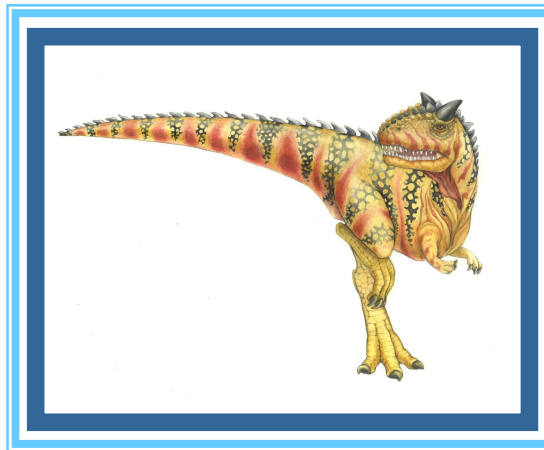


Segmentation Architecture

- Logical address consists of a two tuple:
 <segment-number, offset>,
- *Segment table* – maps two-dimensional physical addresses; each table entry has:
 - *base* – contains the starting physical address where the segments reside in memory.
 - *limit* – specifies the length of the segment.
- *Segment-table base register (STBR)* points to the segment table's location in memory.
- *Segment-table length register (STLR)* indicates number of segments used by a program;
 segment number s is legal if $s < \text{STLR}$.



Virtual Memory





Background

- Code needs to be in memory to execute, but entire program rarely used
 - Error code, unusual routines, large data structures
- Entire program code not needed at same time
- Consider ability to execute partially-loaded program
 - Program no longer constrained by limits of physical memory
 - Each program takes less memory while running -> more programs run at the same time
 - ▶ Increased CPU utilization and throughput with no increase in response time or turnaround time
 - Less I/O needed to load or swap programs into memory -> each user program runs faster





Background (Cont.)

- **Virtual memory** – separation of user logical memory from physical memory
 - Only part of the program needs to be in memory for execution
 - Logical address space can therefore be much larger than physical address space
 - Allows address spaces to be shared by several processes
 - Allows for more efficient process creation
 - More programs running concurrently
 - Less I/O needed to load or swap processes





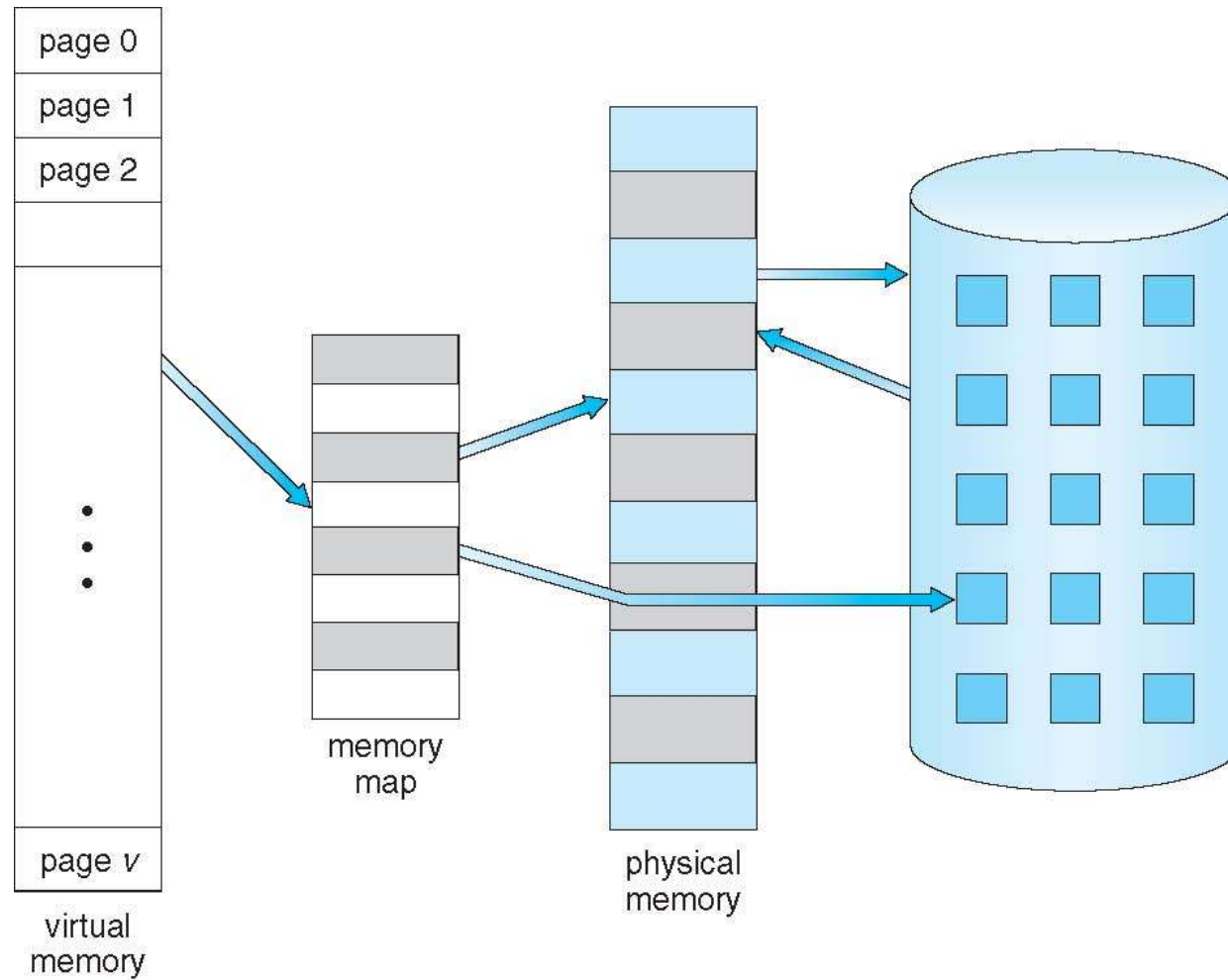
Background (Cont.)

- **Virtual address space** – logical view of how process is stored in memory
 - Usually start at address 0, contiguous addresses until end of space
 - Meanwhile, physical memory organized in page frames
 - MMU must map logical to physical
- Virtual memory can be implemented via:
 - Demand paging
 - Demand segmentation





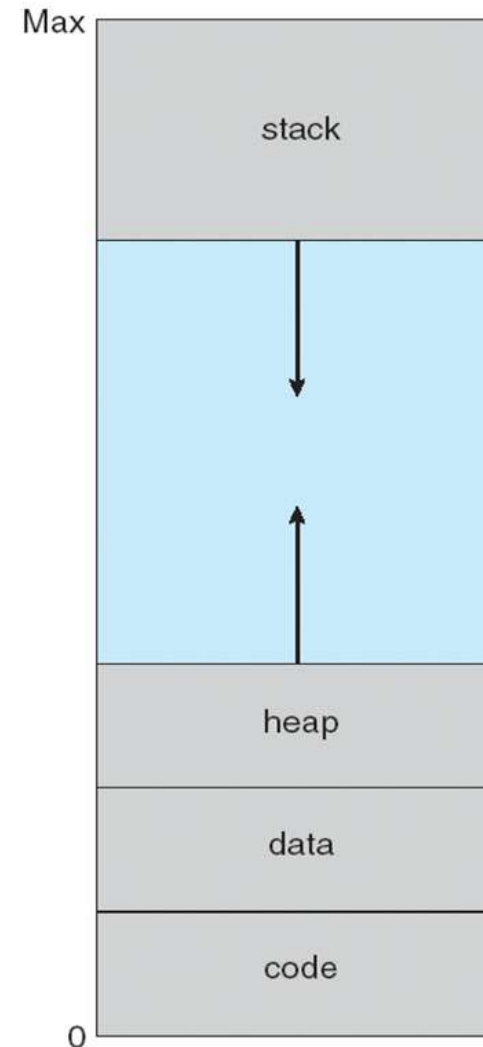
Virtual Memory That is Larger Than Physical Memory





Virtual-address Space

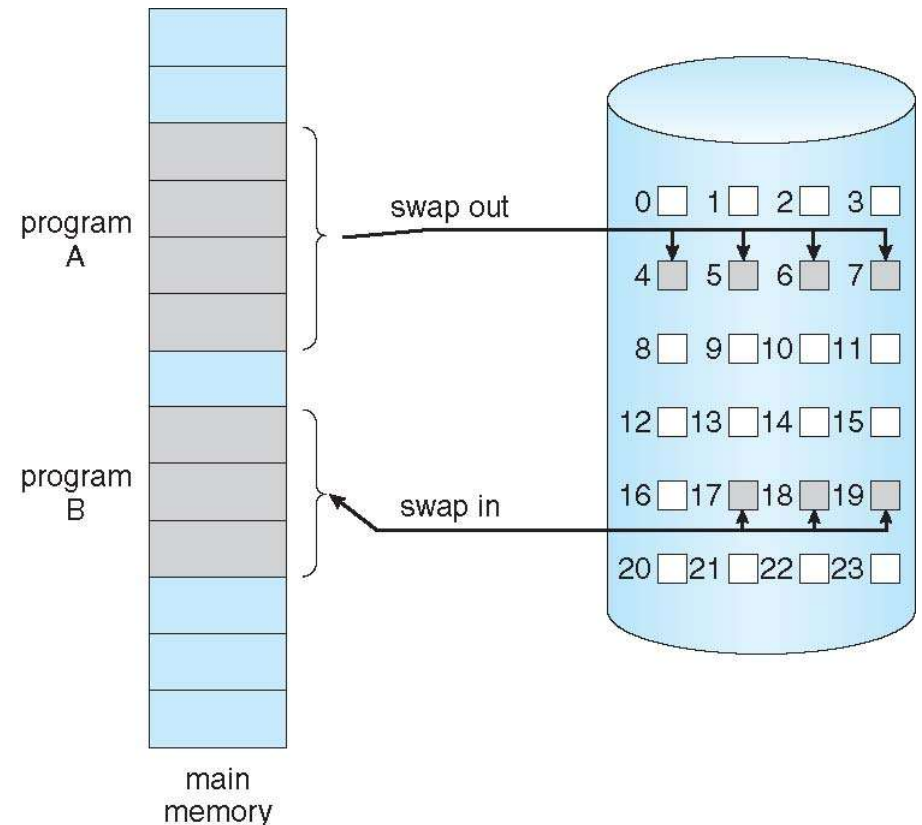
- Usually design logical address space for stack to start at Max logical address and grow “down” while heap grows “up”
 - Maximizes address space use
 - Unused address space between the two is hole
 - ▶ No physical memory needed until heap or stack grows to a given new page
- Enables **sparse** address spaces with holes left for growth, dynamically linked libraries, etc
- System libraries shared via mapping into virtual address space
- Shared memory by mapping pages read-write into virtual address space
- Pages can be shared during `fork()`, speeding process creation





Demand Paging

- ❑ Could bring entire process into memory at load time
- ❑ Or bring a page into memory only when it is needed
 - ❑ Less I/O needed, no unnecessary I/O
 - ❑ Less memory needed
 - ❑ Faster response
 - ❑ More users
- ❑ Similar to paging system with swapping (diagram on right)
- ❑ Page is needed \Rightarrow reference to it
 - ❑ invalid reference \Rightarrow abort
 - ❑ not-in-memory \Rightarrow bring to memory
- ❑ **Lazy swapper** – never swaps a page into memory unless page will be needed
 - ❑ Swapper that deals with pages is a **pager**





Basic Concepts

- With swapping, pager guesses which pages will be used before swapping out again
- Instead, pager brings in only those pages into memory
- How to determine that set of pages?
 - Need new MMU functionality to implement demand paging
- If pages needed are already **memory resident**
 - No difference from non demand-paging
- If page needed and not memory resident
 - Need to detect and load the page into memory from storage
 - ▶ Without changing program behavior
 - ▶ Without programmer needing to change code





Valid-Invalid Bit

- With each page table entry a valid–invalid bit is associated (**v** \Rightarrow in-memory – **memory resident**, **i** \Rightarrow not-in-memory)
- Initially valid–invalid bit is set to **i** on all entries
- Example of a page table snapshot:

Frame #	valid-invalid bit
	v
	v
	v
	i
...	
	i
	i

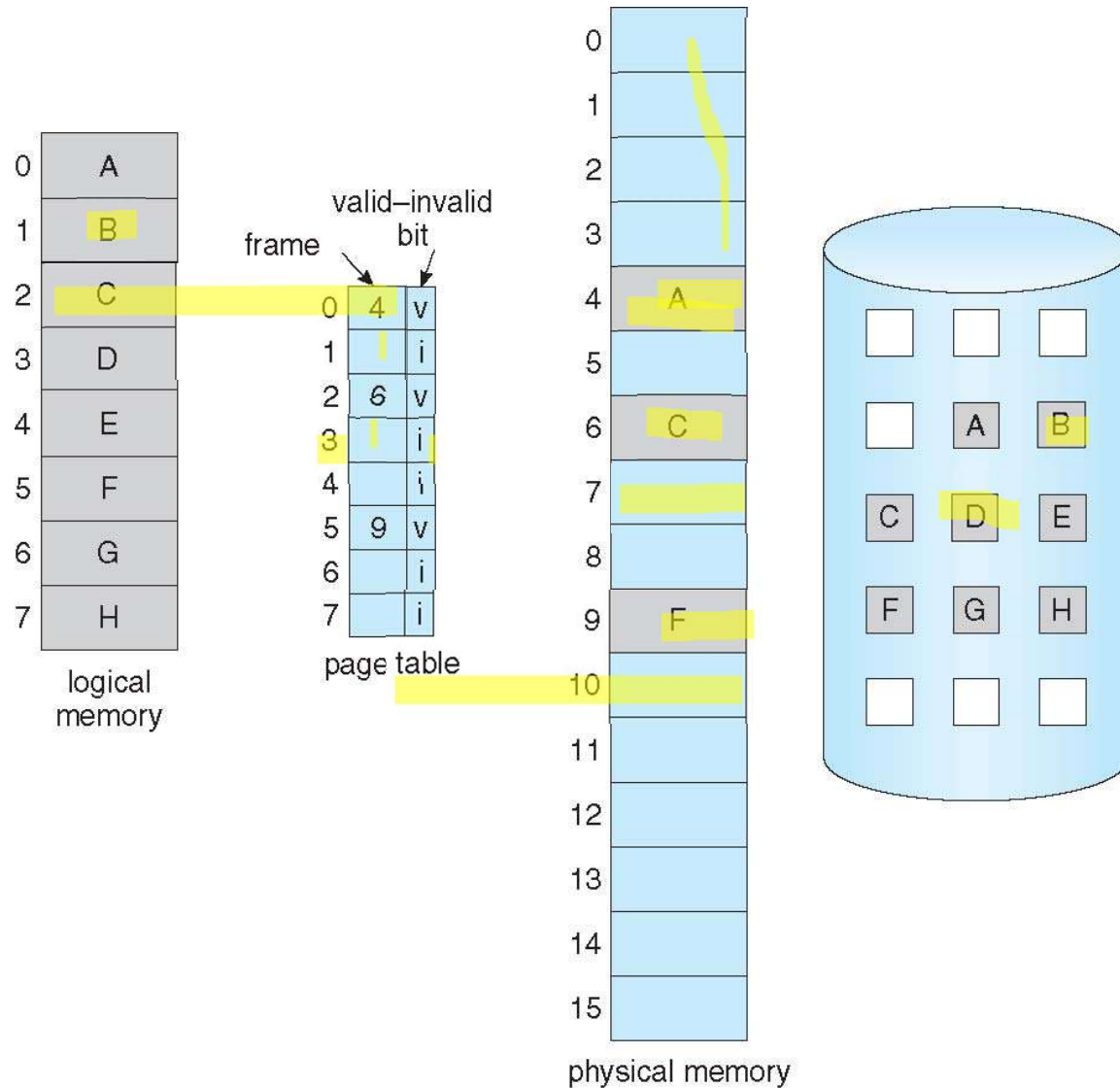
page table

- During MMU address translation, if valid–invalid bit in page table entry is **i** \Rightarrow page fault





Page Table When Some Pages Are Not in Main Memory





Page Fault

- If there is a reference to a page, first reference to that page will trap to operating system:

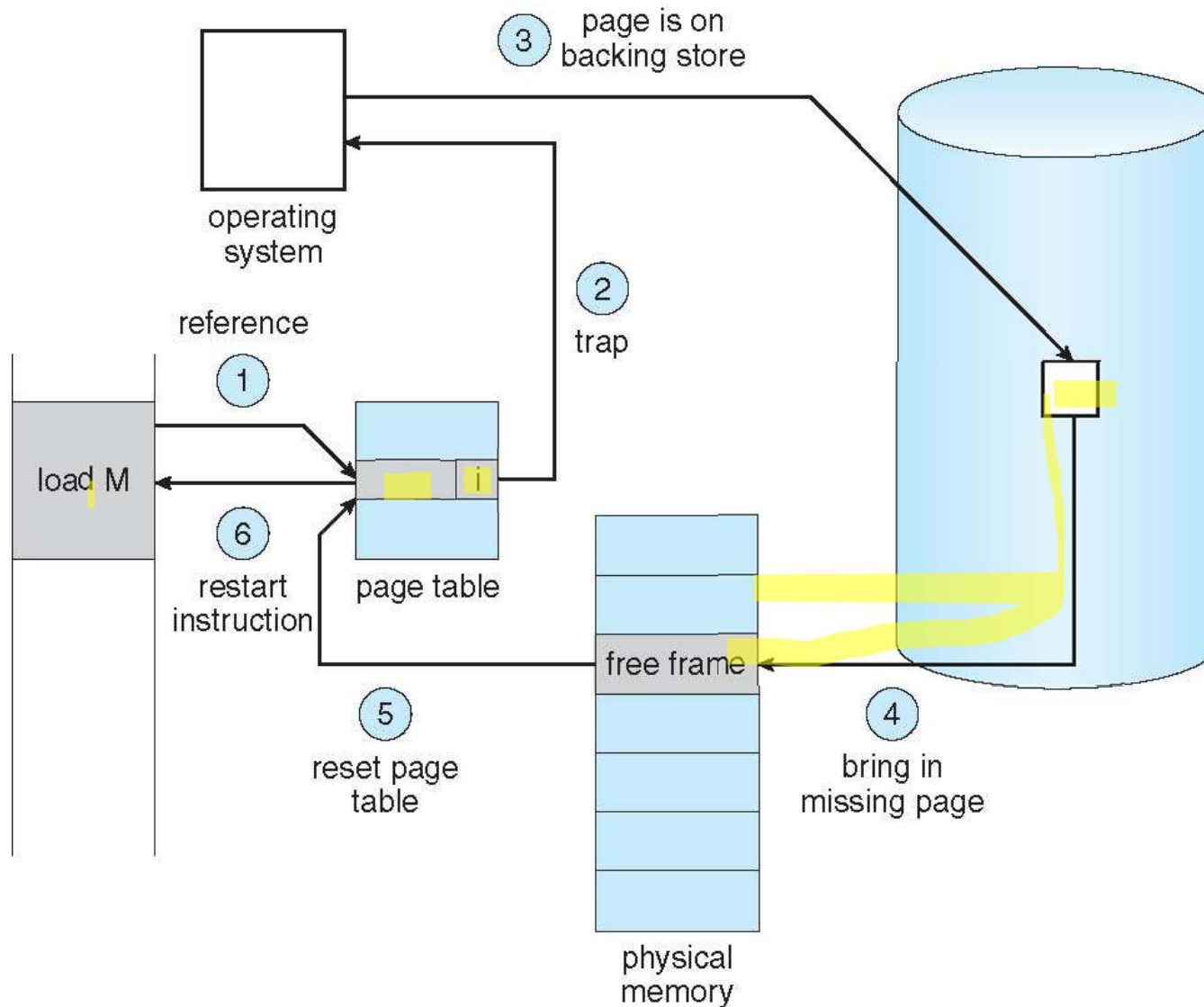
page fault

1. Operating system looks at another table to decide:
 - Invalid reference \Rightarrow abort
 - Just not in memory
2. Find free frame
3. Swap page into frame via scheduled disk operation
4. Reset tables to indicate page now in memory
Set validation bit = **v**
5. Restart the instruction that caused the page fault





Steps in Handling a Page Fault





Aspects of Demand Paging

- Extreme case – start process with *no* pages in memory
 - OS sets instruction pointer to first instruction of process, non-memory-resident -> page fault
 - And for every other process pages on first access
 - **Pure demand paging**
- Actually, a given instruction could access **multiple pages** -> multiple page faults
 - Consider fetch and decode of instruction which adds 2 numbers from memory and stores result back to memory
 - Pain decreased because of **locality of reference**
- Hardware support needed for demand paging
 - Page table with valid / invalid bit
 - Secondary memory (swap device with **swap space**)
 - Instruction restart





Performance of Demand Paging (Cont.)

- Three major activities
 - Service the interrupt – careful coding means just several hundred instructions needed
 - Read the page – lots of time
 - Restart the process – again just a small amount of time
- Page Fault Rate $0 \leq p \leq 1$
 - if $p = 0$ no page faults
 - if $p = 1$, every reference is a fault
- Effective Access Time (EAT)

$$\begin{aligned} \text{EAT} = & (1 - p) \times \text{memory access} \\ & + p \text{ (page fault overhead} \\ & \quad + \text{swap page out} \\ & \quad + \text{swap page in)} \end{aligned}$$





Demand Paging Example

- Memory access time = 200 nanoseconds
- Average page-fault service time = 8 milliseconds
- $EAT = (1 - p) \times 200 + p (8 \text{ milliseconds})$
 $= (1 - p) \times 200 + p \times 8,000,000$
 $= 200 + p \times 7,999,800$
- If one access out of 1,000 causes a page fault, then
EAT = 8.2 microseconds.

This is a slowdown by a factor of 40!!

- If want performance degradation < 10 percent
 - $220 > 200 + 7,999,800 \times p$
 $20 > 7,999,800 \times p$
 - $p < .0000025$
 - < one page fault in every 400,000 memory accesses





What Happens if There is no Free Frame?

- Used up by process pages
- Also in demand from the kernel, I/O buffers, etc
- How much to allocate to each?
- Page replacement – find some page in memory, but not really in use, page it out
 - Algorithm – terminate? swap out? replace the page?
 - Performance – want an algorithm which will result in minimum number of page faults
- Same page may be brought into memory several times





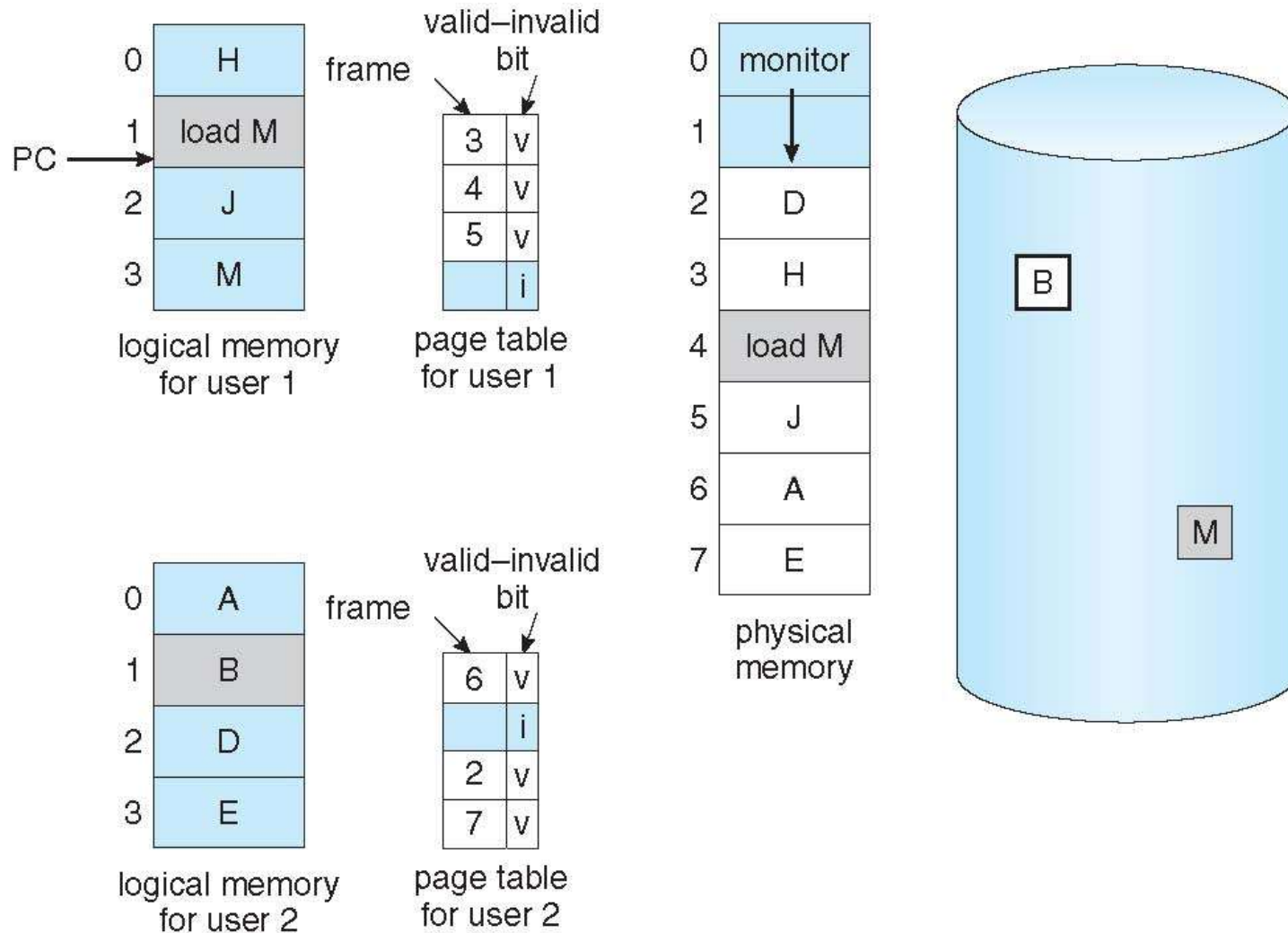
Page Replacement

- ❑ Prevent **over-allocation** of memory by modifying page-fault service routine to include page replacement
- ❑ Use **modify (dirty) bit** to reduce overhead of page transfers – only modified pages are written to disk
- ❑ Page replacement completes separation between logical memory and physical memory – large virtual memory can be provided on a smaller physical memory





Need For Page Replacement





Basic Page Replacement

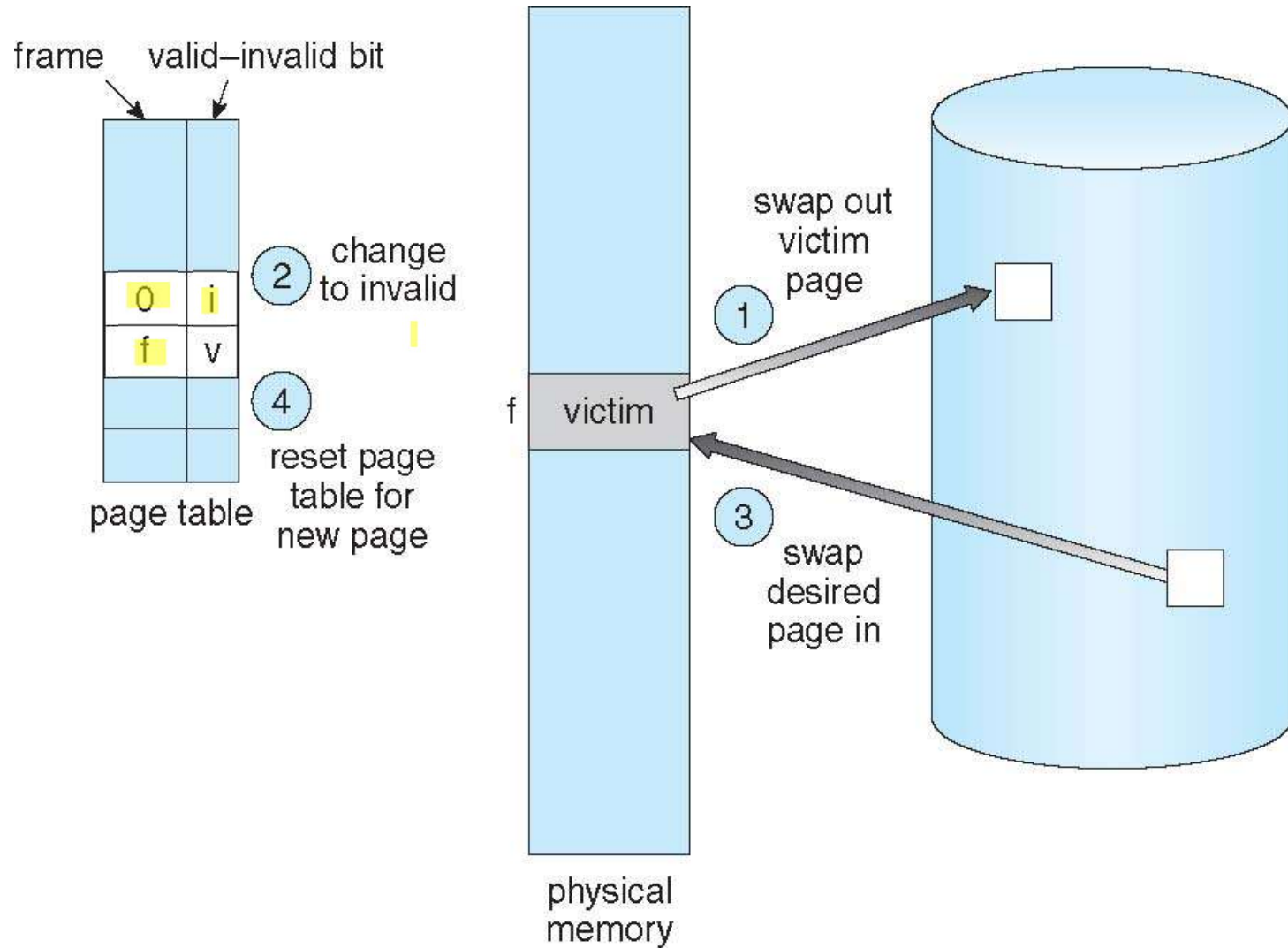
1. Find the location of the desired **page on disk**
2. Find a free frame:
 - If there is a free frame, use it
 - If there is no free frame, use a page replacement algorithm to select a **victim frame**
 - Write victim frame to disk if dirty
3. Bring the desired page into the (newly) free frame; update the page and frame tables
4. Continue the process by restarting the instruction that caused the trap

Note now potentially 2 page transfers for page fault – increasing EAT





Page Replacement





Page and Frame Replacement Algorithms

- **Frame-allocation algorithm** determines
 - How many frames to give each process
 - Which frames to replace
- **Page-replacement algorithm**
 - Want lowest page-fault rate on both first access and re-access
- Evaluate algorithm by running it on a particular string of memory references (reference string) and computing the number of page faults on that string
 - String is just page numbers, not full addresses
 - Repeated access to the same page does not cause a page fault
 - Results depend on number of frames available
- In all our examples, the **reference string** of referenced page numbers is

7,0,1,2,0,3,0,4,2,3,0,3,0,3,2,1,2,0,1,7,0,1

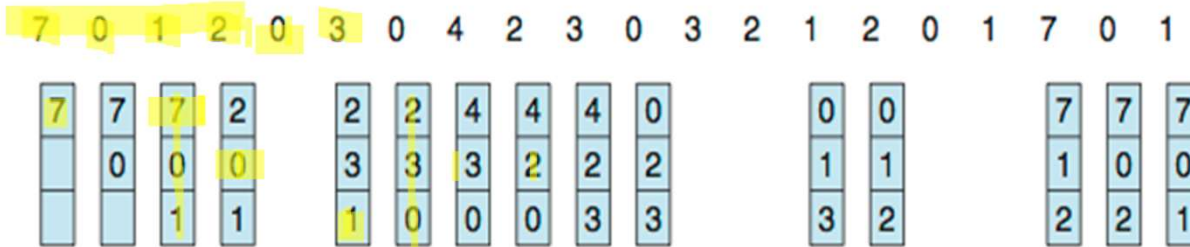




First-In-First-Out (FIFO) Algorithm

- Reference string: 7, 0, 1, 2, 0, 3, 0, 4, 2, 3, 0, 3, 0, 3, 2, 1, 2, 0, 1, 7, 0, 1
- 3 frames (3 pages can be in memory at a time per process)

reference string



page frames

15 page faults

- Can vary by reference string: consider 1, 2, 3, 4, 1, 2, 5, 1, 2, 3, 4, 5
 - Adding more frames can cause more page faults!
 - ▶ **Belady's Anomaly**
- How to track ages of pages?
 - Just use a FIFO queue





Optimal Algorithm

- Replace page that will not be used for longest period of time
 - 9 is optimal for the example
- How do you know this?
 - Can't read the future
- Used for measuring how well your algorithm performs

reference string

7 0 1 2 0 3 0 4 2 3 0 3 2 1 2 0 1 7 0 1

7	7	7	2	2	2	2	2	2	7
	0	0	0	0	4	0	0	0	0
		1	1	3	3	3	1		1

page frames





Least Recently Used (LRU) Algorithm

- Use past knowledge rather than future
- Replace page that has not been used in the most amount of time
- Associate time of last use with each page

reference string

7 0 1 2 0 3 0 4 2 3 0 3 2 1 2 0 1 7 0 1

7	7	7	2		2		4	4	4	0			1		1		1		
	0	0	0		0		0	0	3	3			3		0		0		
		1	1		3		3	2	2	2			2		2		7		

page frames

- 12 faults – better than FIFO but worse than OPT
- Generally good algorithm and frequently used
- But how to implement?





Counting Algorithms

- Keep a counter of the number of references that have been made to each page
 - Not common
- **Least Frequently Used (LFU) Algorithm**: replaces page with smallest count
- **Most Frequently Used (MFU) Algorithm**: based on the argument that the page with the smallest count was probably just brought in and has yet to be used





Page-Buffering Algorithms

- Keep a pool of free frames, always
 - Then frame available when needed, not found at fault time
 - Read page into free frame and select victim to evict and add to free pool
 - When convenient, evict victim
- Possibly, keep list of modified pages
 - When backing store otherwise idle, write pages there and set to non-dirty
- Possibly, keep free frame contents intact and note what is in them
 - If referenced again before reused, no need to load contents again from disk
 - Generally useful to reduce penalty if wrong victim frame selected





Applications and Page Replacement

- All of these algorithms have OS guessing about future page access
- Some applications have better knowledge – i.e. databases
- Memory intensive applications can cause double buffering
 - OS keeps copy of page in memory as I/O buffer
 - Application keeps page in memory for its own work
- Operating system can given direct access to the disk, getting out of the way of the applications
 - **Raw disk** mode
- Bypasses buffering, locking, etc





Allocation of Frames

- Each process needs **minimum** number of frames
- Example: IBM 370 – 6 pages to handle SS MOVE instruction:
 - instruction is 6 bytes, might span 2 pages
 - 2 pages to handle *from*
 - 2 pages to handle *to*
- **Maximum** of course is total frames in the system
- Two major allocation schemes
 - fixed allocation
 - priority allocation
- Many variations





Fixed Allocation

- Equal allocation – For example, if there are 100 frames (after allocating frames for the OS) and 5 processes, give each process 20 frames
 - Keep some as free frame buffer pool
- Proportional allocation – Allocate according to the size of process
 - Dynamic as degree of multiprogramming, process sizes change
 - s_i = size of process p_i
 - $S = \sum s_i$
 - m = total number of frames
 - a_i = allocation for $p_i = \frac{s_i}{S} \times m$

$$m = 64$$

$$s_1 = 10$$

$$s_2 = 127$$

$$a_1 = \frac{10}{137} \times 62 \approx 4$$

$$a_2 = \frac{127}{137} \times 62 \approx 57$$





Priority Allocation

- Use a proportional allocation scheme using priorities rather than size
- If process P_i generates a page fault,
 - select for replacement one of its frames
 - select for replacement a frame from a process with lower priority number





Global vs. Local Allocation

- **Global replacement** – process selects a replacement frame from the set of all frames; one process can take a frame from another
 - But then process execution time can vary greatly
 - But greater throughput so more common

- **Local replacement** – each process selects from only its own set of allocated frames
 - More consistent per-process performance
 - But possibly underutilized memory





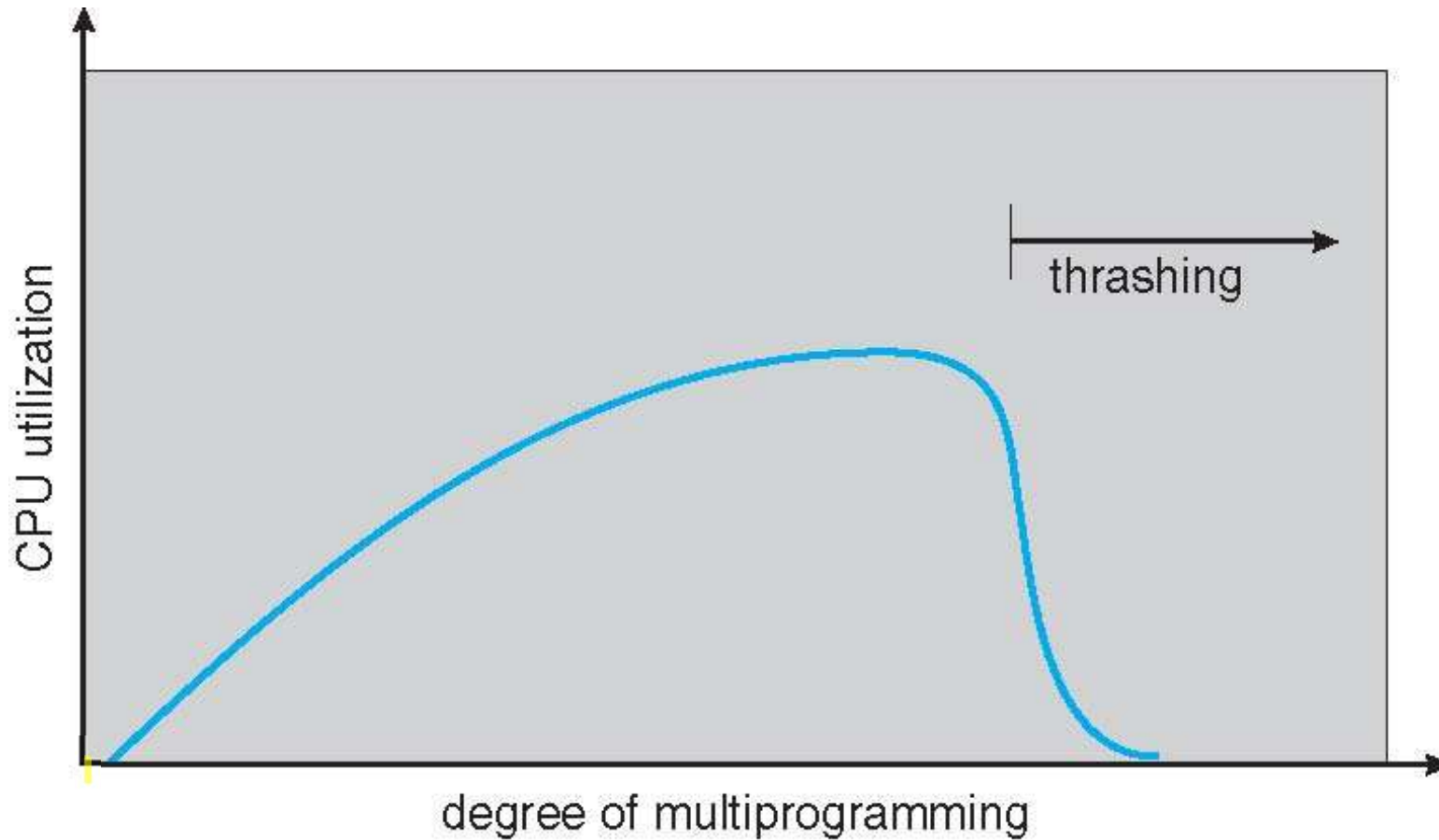
Thrashing

- If a process does not have “enough” pages, the page-fault rate is very high
 - Page fault to get page
 - Replace existing frame
 - But quickly need replaced frame back
 - This leads to:
 - ▶ Low CPU utilization
 - ▶ Operating system thinking that it needs to increase the degree of multiprogramming
 - ▶ Another process added to the system
- **Thrashing** ≡ a process is busy swapping pages in and out





Thrashing (Cont.)





Demand Paging and Thrashing

- Why does demand paging work?
Locality model
 - Process migrates from one locality to another
 - Localities may overlap
- Why does thrashing occur?
 Σ size of locality > total memory size
 - Limit effects by using local or priority page replacement

