

TUTORIAL - 5

Q1 Differentiate B/w BFS & DFS

Ans1	BFS	DFS
	Stands for Breadth first search.	Stands for Depth first search.
	BFS uses queue to find the shortest path.	It uses stack to find shortest path.
	BFS is better when target is closer to source.	DFS is better when target is far from source.
	As BFS considers all neighbours so it is not suitable for decision tree.	DFS is more suitable for decision tree.
	BFS is slower than DFS.	DFS is faster than BFS.

Application of DFS:

- Using DFS we can find path between two vertices.
- It can be used to scheduling jobs.
- We can use DFS to detect cycles.

Application of BFS:

- BFS may also be used to detect cycles.
- Finding shortest path and minimal spanning tree.
- In network finding a route for packet transmission.

Ans 2

BFS uses Queue data structure. BFS you mark any node in graph as source node, transfer all the nodes in graph and keep as completed.

BFS visited an adjacent unvisited node, marks it as done and insert it into Queue.

DFS uses stack a graph in a depth mode, motion and uses stack to remember to get the next vertex to start to a search, when a dead end occurs in any iteration.

Ans 3

Sparse graph: A graph in which the number of edges is less than the number of vertices.

Dense graph: A graph in which the number of edges is close to the maximum number of edges.

If the graph is sparse, we should store it as list of edges.

Ans 4

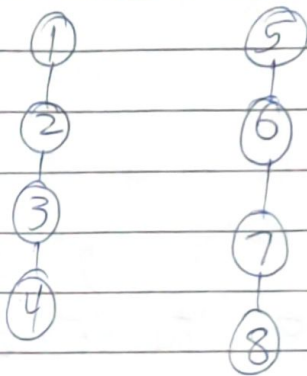
DFS can be used to detect cycle in a graph. DFS for connected graph produces a tree. There is a cycle in graph. Only if graph. A backedge is an edge that is from a node to itself or out of its ancestor in the tree produced by DFS.

BFS can also be used cycles. Perform BFS while keeping a list of previous nodes at each node. Visited or one that is already marked by BFS. I founded a cycle.

Ans 5

Disjoint set data structure:

- It allows to find out whether the two elements are in the same set or not efficiently.



$$S_1 = \{1, 2, 3, 4\}$$

$$S_2 = \{5, 6, 7, 8\}$$

Operation performed:

```

① find int find (v)
   if (v == parent[v])
       return v;
   return parent[v] = find (parent[v]);
  
```

Unions:

```

Void union (int a, int b) {
  
```

```

    a = find (a)
  
```

```

    b = find (b)
  
```

```

    if (a != b)
  
```

```

        if (size[a] < size[b])
  
```

```

            { swap (a, b) }
  
```

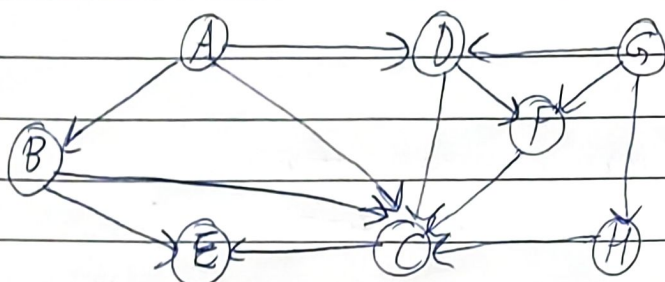
```

        parent [b] = a;
  
```

$$\text{Size}[a] + = \text{Size}[b];$$

3

Q6



Ans 6

BFS: Node: B E C A D E
 B B E A D

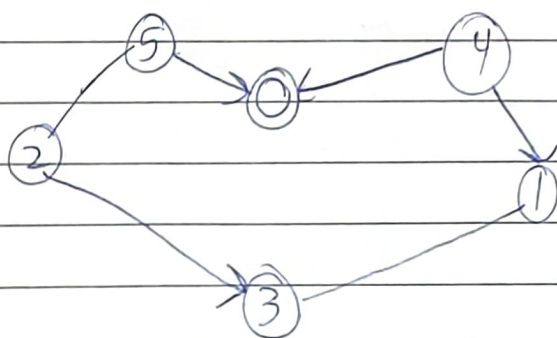
path: B → F → A → D → F

DFS:

Node: B B C E A D F
 Stack: B CE EE AE DE FE E

path B → C → E → A → D → F

Q8



V → Visited

f → false

Ans 8

Adjacency list:

0 →

1 →

2 → 3

3 → 1

5 → 2, 0

4 → 0, 1

0	1	2	3	4	5
F	F	F	F	F	F

stack (Empty)

Step 1: Topological Sort[0], visited[0] = true
Stack 0

Step 2: Topological Sort[1], visited[1] = true
Stack 0 1

Step 3: Topological Sort(2), visited[2] = true;
Topological Sort(3), visited[3] = true;
Stack 0 1 3 2

Step 4: Stack 0 1 3 2 4

Step 5: Stack 0 1 3 2 4 5

Step 6: Print all elements of stack from
top to bottom
→ 5, 4, 2, 3, 1, 0

Ans 10

Min heap

- In min-heap the key present at root node must be less than or equal to among the keys present all its children.

- Used to ascending priority.

Max heap

- In max-heap the key present at root node must be greater or equal to the key present at all its children.

- Used to descending priority.

• The minimum key present
at the root node.

The max- key present
at the root node.