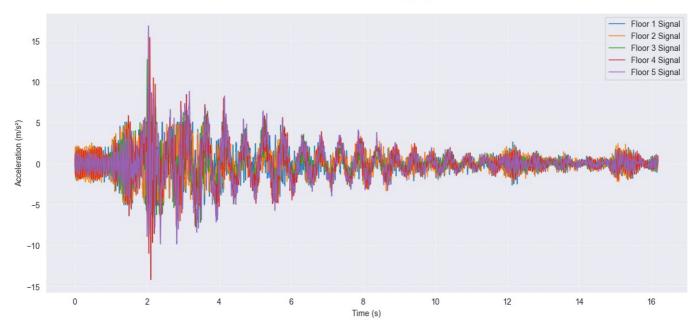
```
import sys
import os
import warnings
warnings.filterwarnings("ignore")
sys.path.append(os.path.abspath('Sources'))
import about_ml_models as mlm
```

```
In [10]: #falla =True -> para obtener datos con fallas estructurales
  #falla =False -> para obtener datos sin fallas estructurales
  #falla =None -> selección aleatoria de los datos

data_IM, X_new_scaled=mlm.get_seismic_signals(falla=False)
```

Seismic Response - E2C_SF_7



SEISMIC SIGNAL REPORT

GENERAL INFORMATION:

Signal ID: E2C_SF_7

Structure E2: 6 columns, 5 levels

Earthquake C: Imperial Valley, 10/15/1979, El Centro

Damage Status: Undamaged

INTENSITY MEASURES BY FLOOR:

| Floor 1 | Floor 2 | Floor 3 | Floor 4 | Floor 5 | | IM | Description | PGA | Peak Ground Acceleration | 4.1353 | 4.2185 | 6.8303 | 6.9516 | 9.2652 | | PGV | Peak Ground Velocity | 0.4199 | 0.5065 | 0.3443 | 0.4141 | 0.4943 | | 1.6165 | 2.2863 | 3.5114 | 4.623 | 6.831 | | IA | Arias Intensity | CAV | Cumulative Absolute Velocity | 8.0352 | 10.0499 | 11.8299 | 14.082 | 16.3044 | | RMS | Root Mean Square Acceleration | 0.8204 | 0.9757 | 1.2092 | 1.3874 | 1.6865 | | DS | Significant Duration | 7.261 | 7.243 | 6.1 | 6.087 | 6.053 | | FP | Predominant Frequency | 15.625 | 7.8125 | 3.9062 | 3.9062 | 3.9062 | | 2.9583 | 3.1667 | 0.8984 | 1.0516 | 1.2558 | | IH | Housner Intensity | 10.0953 | 14.2789 | 21.9294 | 28.872 | 42.6613 | | ET | Time Energy | EWT | Wavelet Energy Total | 10615.9 | 17125.1 | 21966.1 | 29929.6 | 43151.4 |

```
In [11]: # Load models
    models_det = mlm.load_models()

# Make predictions
    results, consensus = mlm.predict_damage(X_new_scaled, models_det)
```

STRUCTURAL DAMAGE PREDICTION REPORT

Random Forest [0] 0.00%

XGBoost [0] 0.60%

WARNING:tensorflow:5 out of the last 5 calls to <function TensorFlowTrainer.make_predict_function.<locals>.one_s tep_on_data_distributed at 0x0000024C856B0C20> triggered tf.function retracing. Tracing is expensive and the exc essive number of tracings could be due to (1) creating @tf.function repeatedly in a loop, (2) passing tensors wi th different shapes, (3) passing Python objects instead of tensors. For (1), please define your @tf.function out side of the loop. For (2), @tf.function has reduce_retracing=True option that can avoid unnecessary retracing. F or (3), please refer to https://www.tensorflow.org/guide/function#controlling_retracing and https://www.tensorflow.org/api_docs/python/tf/function for more details.

1/1 — 0s 99ms/step

Neural Network [0] 0.34%

MODEL PREDICTIONS:

+	+	++
Model	Prediction	Damage Probability +=======
Random Forest	No Damage	0.00%
XGBoost	No Damage	
Neural Network	No Damage	+
+	+	++

CONSENSUS ANALYSIS:

Model Agreement: 0%

Final Assessment: LOW PROBABILITY OF DAMAGE

```
In [12]: # damage location prediction
   if consensus>0.5:
        mlm.ubicar falla(data IM)
```

In []:

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