

# Anshuman Phadke

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## EDUCATION

<b>Vellore Institute of Technology</b> <i>Bachelor of Technology Electronics and Communication Engineering</i>	July 2019 – July 2023 CGPA: 9.57/10.0
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## EXPERIENCE

<b>Autopilot Developer</b> <i>Drone Research Center - Indian Institute of Technology, Bombay</i>	Sep 2025 – Present <i>Mumbai, India</i>
<ul style="list-style-type: none"><li>Developed a real-time Automatic Target Detection and Surveillance (ATDS) pipeline using YOLOv8-obb model and ByteTrack for multi-object tracking, deployed on NVIDIA Jetson Orin NX</li><li>Building a full-stack UAV Traffic Management (UTM) system featuring 3D airspace corridors, graph-based routing, and scheduling algorithms using Python with a PostgreSQL/PostGIS backend for Maharashtra</li><li>Developing a real-time terrain-following navigation pipeline for GPS-denied environments using Siamese neural network-based scene matching fused with SLAM-based pose estimation</li><li>Trained and fine-tuned deep learning models on custom datasets on NVIDIA A6000 GPUs using PyTorch with CUDA stream-based parallelism; conducted hyperparameter tuning, ablation studies, and evaluation</li></ul>	
<b>ADAS Engineer</b> <i>Mercedes-Benz Research &amp; Development India (MBRDI)</i>	Aug 2023 – Jul 2025 <i>Bengaluru, India</i>
<ul style="list-style-type: none"><li>Developed production-grade radar signal processing software and a Radar Analytics Tool (RAT) enabling multiple ADAS functions, including Blind Spot Monitoring, Active Brake Assist, and Adaptive Cruise Control</li><li>Developed a CNN-based audio perception system using ResNet-50 and MFCC features for emergency vehicle detection, classification, and direction-of-arrival estimation</li><li>Developed internal Python applications that reduced manual workflows by approximately 90% and improved engineering productivity, saving nearly \$125,000</li><li>Filed <b>8 patents</b> with the Indian Patent Office in the autonomous driving domain</li></ul>	

## PROJECTS

<b>SSTV-Based IoT Data Acquisition and Analytics</b>   <a href="#">Research Paper</a>	Feb 2023
<ul style="list-style-type: none"><li>Designed an IoT-based data acquisition and analytics system for remote regions, enabling reliable sensing, transmission, and analysis under constrained connectivity</li></ul>	
<b>Team Assailing Falcons (SAE Aero Design East)</b>   <a href="#">Website</a>	Dec 2020 – May 2023
<ul style="list-style-type: none"><li>Vice Captain and Propulsion Head of a 14-member team competing in SAE Aero Design East (Advanced Class), achieving <b>Global Rank 3</b>, Rank 1 in Technical Presentation, and Rank 1 in Design Report</li><li>Developed a Python-based ground station data acquisition system for real-time avionics telemetry</li><li>Developed a drop zone detection and autonomous navigation system</li></ul>	
<b>ADAMS – Advanced Driver Assistance and Monitoring System</b>   <a href="#">Project Link</a>	Nov 2020 – Jan 2021
<ul style="list-style-type: none"><li>Built a computer vision and deep learning-based driver monitoring and assistance system with features like: facial recognition, emotion classification, drowsiness detection, head movement</li></ul>	
<b>AgriHero – Smart Agriculture Platform</b>   <a href="#">Project Link</a>	April 2021 - June 2021
<ul style="list-style-type: none"><li>Built a distributed IoT sensing and ML platform delivering real-time environmental and agronomic insights to enable data-driven decision support and improved accessibility for rural stakeholders</li></ul>	

## TECHNICAL SKILLS

<b>Programming:</b> Python, C/C++, Embedded C, MATLAB, Linux, HTML, CSS, PostgreSQL
<b>Frameworks &amp; Deployment:</b> PyTorch, TensorFlow, OpenCV, Plotly, Dash, Seaborn, scikit-learn, Matplotlib, Flask, Folium, Pandas, NumPy, ROS, TensorRT, ONNX, Docker, Kubernetes
<b>Hardware &amp; Tools:</b> NVIDIA Jetson (Orin NX, Nano), Raspberry Pi, Arduino, ESP32, STM32, Git, Jira, Confluence, ArduPilot, PX4, Vector CANape/CANoe, ANSYS HFSS & SBR+, QGIS