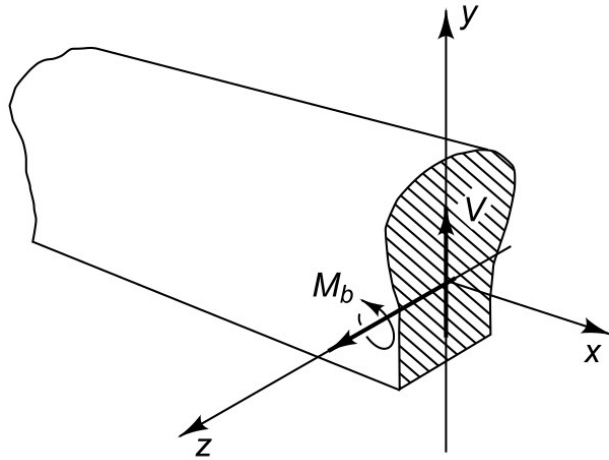


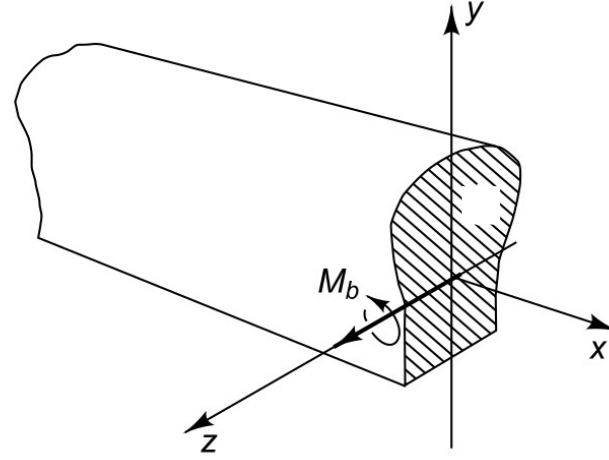
ME231: Solid Mechanics-I

Stresses due to bending

Introduction

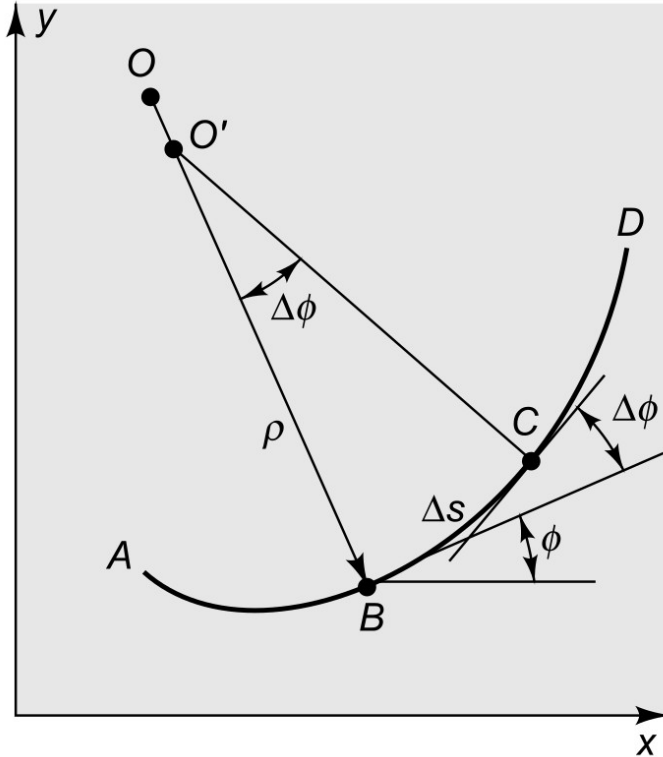


In general, both shear force and bending moment is transmitted through a slender beam



In case of pure bending, a constant bending moment is transmitted

Curvature



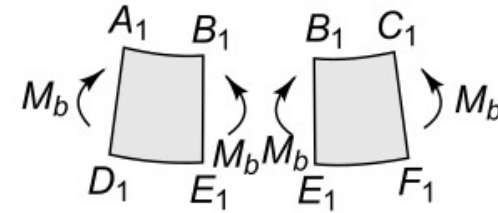
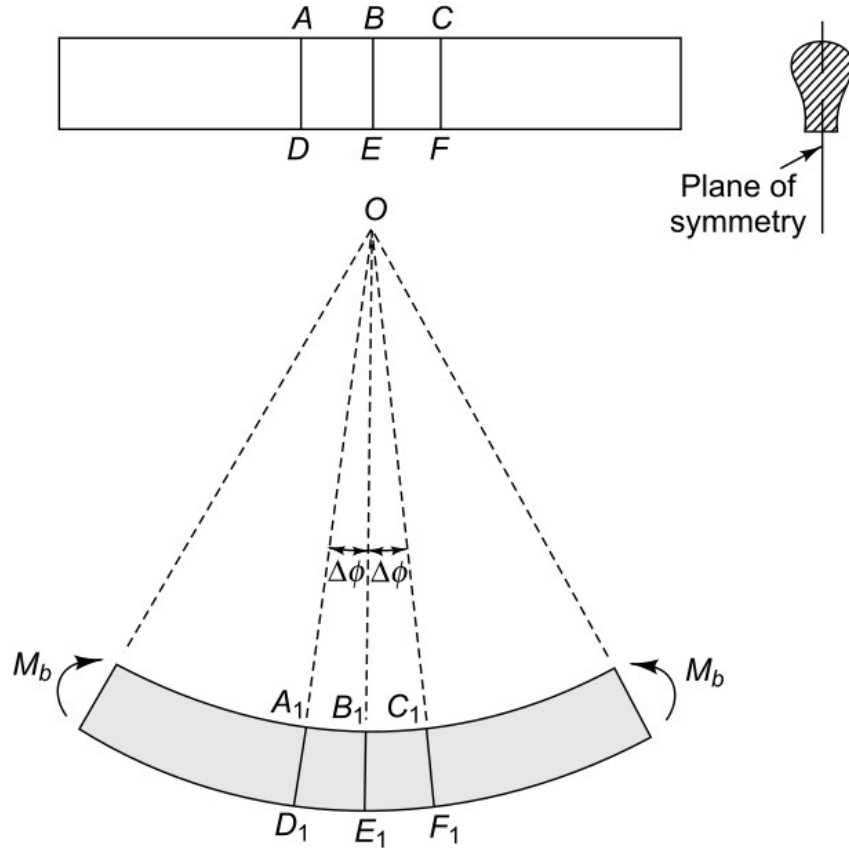
Curvature is the rate of change of *slope angle* of the curve w.r.t. the *distance along the curve*

Curvature at point B is defined as

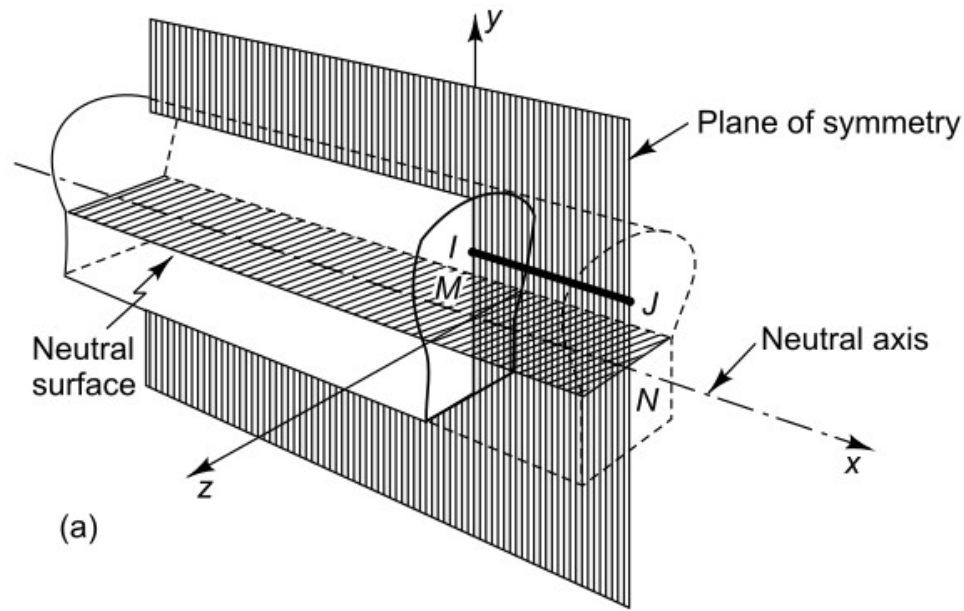
$$\frac{d\phi}{ds} = \lim_{\Delta s \rightarrow 0} \frac{\Delta\phi}{\Delta s} = \lim_{\Delta s \rightarrow 0} \frac{1}{O'B} = \frac{1}{\rho} \dots\dots\dots(1)$$

$\rho = OB$ is the *radius of curvature* at point B .

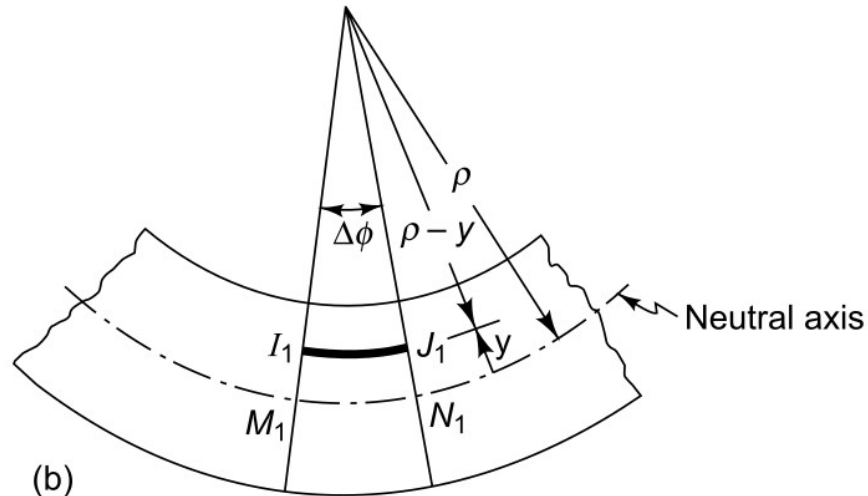
Deformation



Using symmetry arguments, it can be established that in pure bending in a **plane of symmetry plane cross sections remain plane**.



(a)



(b)

Assume that, deformation within the planes are sufficiently small

$$IJ = MN = M_1N_1$$

Strain of I_1J_1 is

$$\varepsilon_x = \frac{I_1J_1 - IJ}{IJ} = \frac{I_1J_1 - M_1N_1}{M_1N_1}$$

$$\varepsilon_x = \frac{(\rho - y)\Delta\phi - \rho\Delta\phi}{\rho\Delta\phi} = -\frac{y}{\rho} = -\frac{d\phi}{ds}y$$

.....(2)

- Strain is **linearly proportional** to the distance from the neural axis
- Derivation is strictly applicable to **the plane of symmetry**, however we **assume** that the longitudinal strain at all points in the c.s. of the beam is given by the same equation.
- As plane sections remain plane

$$\gamma_{xy} = \gamma_{xz} = 0 \Rightarrow \tau_{xy} = \tau_{xz} = 0. \qquad \dots\dots\dots(3)$$

- No quantitative statement about $\varepsilon_y, \varepsilon_z$ and γ_{yz} beyond the remark that they must be symmetrical w.r.t to the xy -plane.

Stresses from stress-strain relation

$$\begin{aligned}\varepsilon_x &= \frac{1}{E} [\sigma_x - \nu(\sigma_y + \sigma_z)] = -\frac{y}{\rho}, \\ \gamma_{xy} &= \frac{\tau_{xy}}{G} = 0, \\ \gamma_{xz} &= \frac{\tau_{xz}}{G} = 0. \qquad \dots\dots\dots(4)\end{aligned}$$

Thus the shear-stress components τ_{xy} and τ_{xz} must vanish in pure bending.

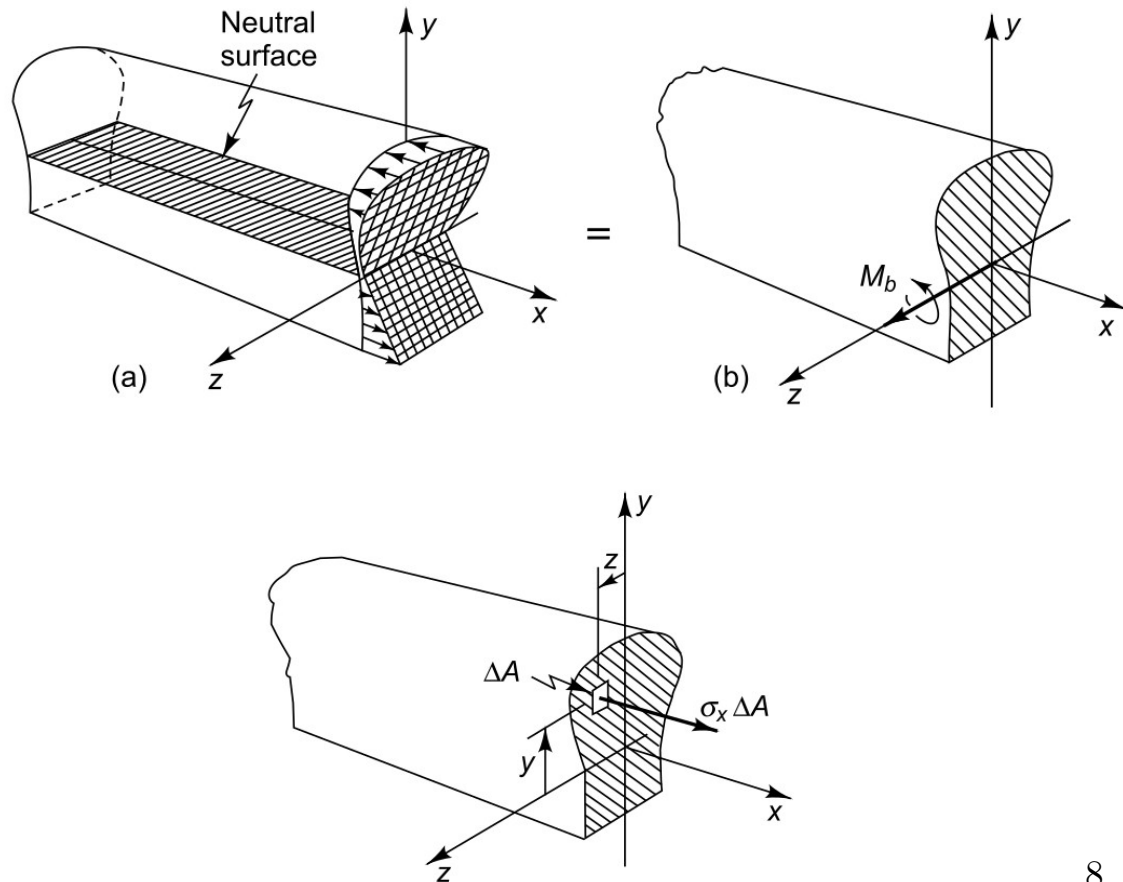
Equilibrium requirements

$$\sum F_x = \int_A \sigma_x dA = 0$$

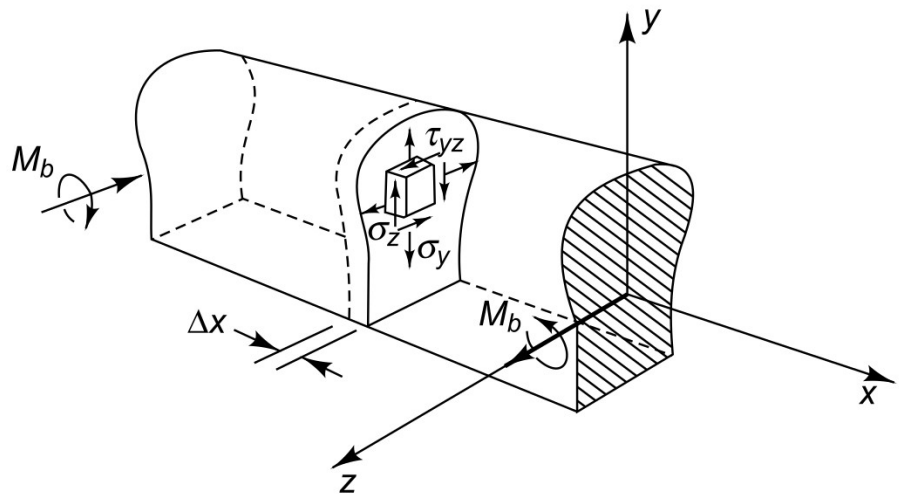
$$\sum M_y = \int_A z \sigma_x dA = 0$$

$$\sum M_z = - \int_A y \sigma_x dA = M_b$$

.....(5)



We can not say anything about ε_y and ε_z at this stage; hence also for σ_y and σ_z .
Hence, we make some assumptions about the transverse behaviour.
Basis of the assumption comes from the slenderness of the beam.



Slenderness of the beam suggests a plausibility of $\sigma_y = \sigma_z = \tau_{yz} = 0$(6)

With this assumption, now we are ready to find the following relations.

$$\begin{aligned} \varepsilon_x &= \frac{1}{E} [\sigma_x - \nu(\sigma_y + \sigma_z)] = \frac{\sigma_x}{E} = -\frac{y}{\rho} \\ \sigma_x &= -E\frac{y}{\rho} = -E\frac{d\phi}{ds}y \\ \sum F_x &= \int_A \sigma_x dA = - \int_A E\frac{y}{\rho} dA = -\frac{E}{\rho} \int_A ydA = 0 \qquad \text{First moment of c.s. area} \qquad \dots\dots\dots(7) \end{aligned}$$

- First moment of cross-sectional area about the neutral surface must be zero.
- The neutral surface must pass through the centroid of the cross-sectional area

$$\sum M_y = \int_A z\sigma_x dA = - \int_A E\frac{y}{\rho} z dA = -\frac{E}{\rho} \int_A yz dA = 0 \qquad \dots\dots\dots(8)$$

- Symmetry of the cross-section about xy -plane will ensure $\int_A yz dA = 0$.

$$\sum M_z = - \int_A y \sigma_x dA = \int_A E \frac{y^2}{\rho} dA = \frac{E}{\rho} \int_A y^2 dA = M_b \quad \dots\dots\dots(9)$$

Second moment of c.s. area

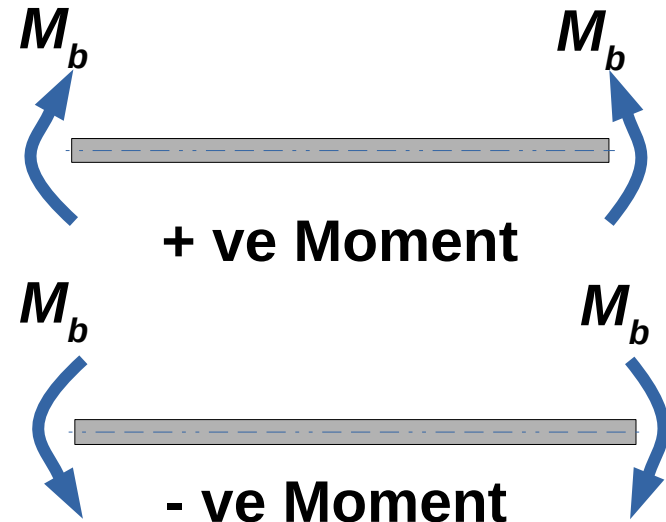
or

Moment of Inertia of the area about the neutral axis

$$M_b = \frac{EI_{zz}}{\rho} \Rightarrow \frac{M_b}{EI_{zz}} = \frac{1}{\rho}.$$

$$\varepsilon_x = -\frac{y}{\rho} = -\frac{d\phi}{ds}y \Rightarrow \frac{1}{\rho} = \frac{d\phi}{ds}.$$

$$\boxed{\frac{1}{\rho} = \frac{d\phi}{ds} = \frac{M_b}{EI_{zz}}} \quad \dots\dots\dots(10)$$



Finally from the expressions of stress and strain, we get

$$\varepsilon_x = -\frac{M_b y}{EI_{zz}}$$

$$\sigma_x = -\frac{M_b y}{I_{zz}}$$

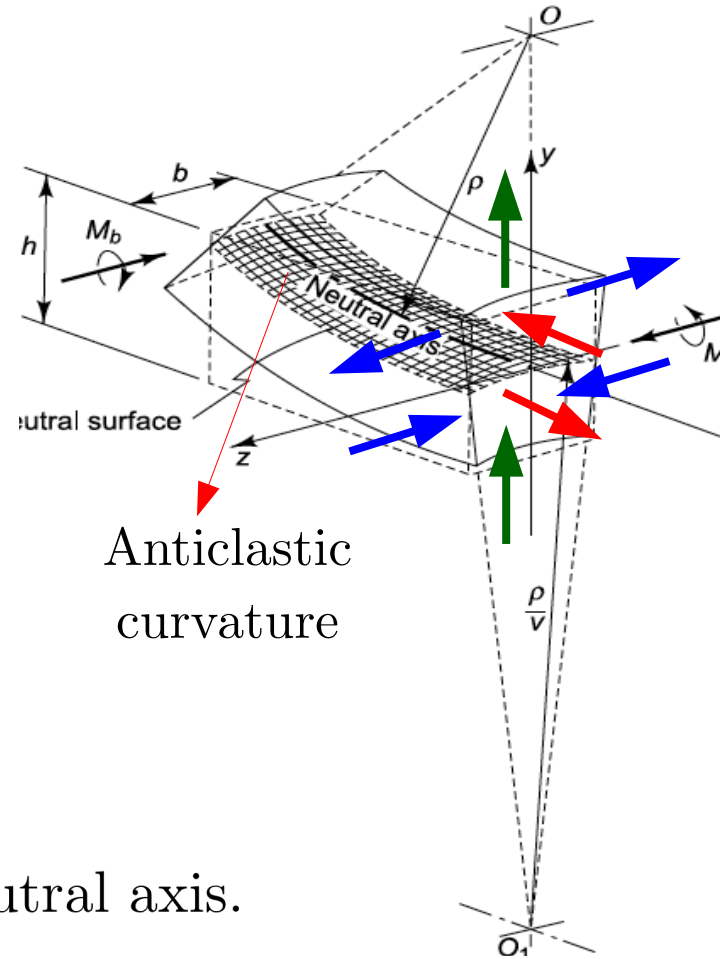
.....(11)

$$\varepsilon_y = -\nu \varepsilon_x$$

$$\varepsilon_z = -\nu \varepsilon_x$$

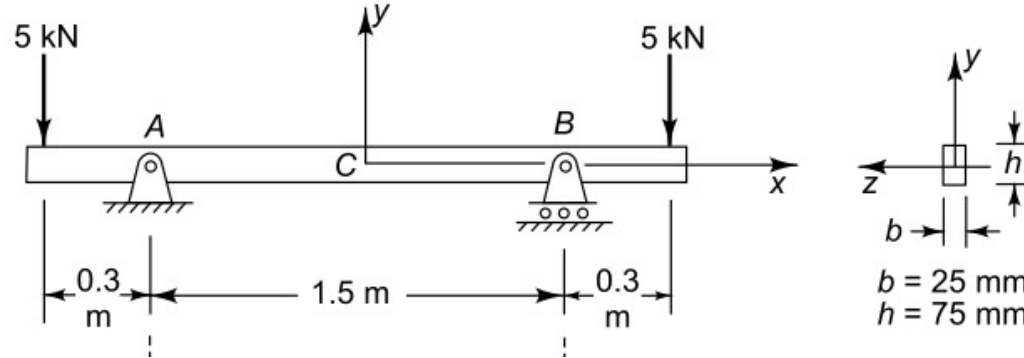
$$\gamma_{yz} = 0$$

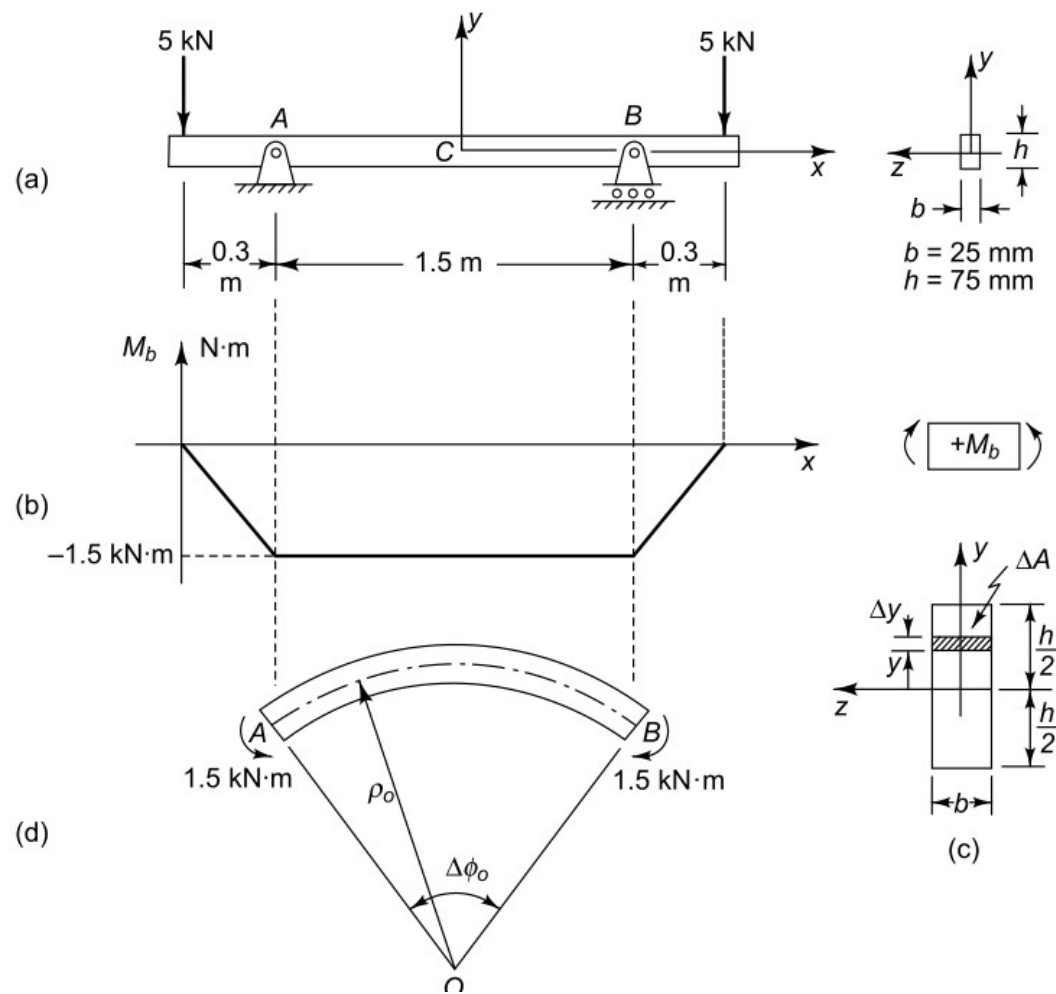
Section Modulus $S = \frac{I}{c}$
where, c is the maximum distance from the neutral axis.



Example 1

A steel beam 25 mm wide and 75 mm deep is pinned to supports at points A and B , as shown in figure, where the support B is on rollers and free to move horizontally. When the ends of the beam are loaded with 5-kN loads, we wish to find the maximum bending stress at the mid-span of the beam and also the angle $\Delta\phi_o$ subtended by the cross sections at A and B in the deformed beam.





Example 2

We wish to find the maximum tensile and compressive bending stresses in the symmetrical T beam of under the action of a constant bending moment M_b .

