SL Project - Scratch

December 14, 2022

```
[1]: import torchvision
      import torch
      import torch.nn as nn
      from torchsummary import summary
 [2]: from torchvision import transforms, datasets
      import matplotlib.pyplot as plt
      from tqdm import tqdm
 [3]: import pandas as pd
      import seaborn as sns
      import matplotlib.pyplot as plt
 [4]: sns.set_style("darkgrid")
 [5]: transform = transforms.Compose([
          transforms.ToTensor()
      ])
 [6]: PATH = "../../data/asl_alphabet_train/"
 [7]: dataset = datasets.ImageFolder(PATH, transform=transform)
 [8]: n = len(dataset)
 [9]: torch.manual_seed(1)
      indices = torch.randperm(n)
[10]: test_proportion = 0.2 # 20 percent of data used for testing
      test_size = int(n * test_proportion)
[11]: train_dataset = torch.utils.data.Subset(dataset, indices[test_size:])
      test_dataset = torch.utils.data.Subset(dataset, indices[:test_size])
[12]: len(train_dataset)
[12]: 69600
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[13]: len(test_dataset)
[13]: 17400
[14]: DEVICE = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
[15]: train_dataloader = torch.utils.data.DataLoader(dataset=train_dataset,
                                                      batch_size=32,
                                                      shuffle=True,
                                                      num workers=4)
      test_dataloader = torch.utils.data.DataLoader(dataset=test_dataset,
                                                     batch size=32,
                                                     shuffle=False,
                                                     num_workers=4)
[16]: classes = dataset.classes
[17]: class ASLNeuralNet(nn.Module):
          def __init__(self, num_classes=1000):
              super(ASLNeuralNet, self).__init__()
              # declare all the layers for feature extraction
              self.features = nn.Sequential(
                  nn.Conv2d(in_channels=3, out_channels=64, kernel_size=11, stride=4,_
       →padding=2),
                  nn.ReLU(inplace=True),
                  nn.MaxPool2d(kernel_size=2, stride=2),
                  nn.Conv2d(in_channels=64, out_channels=192, kernel_size=3,_
       →padding=2),
                  nn.ReLU(inplace=True),
                  nn.MaxPool2d(kernel_size=2, stride=2),
                  nn.Conv2d(in_channels=192, out_channels=256, kernel_size=3,_
       →padding=1),
                  nn.ReLU(inplace=True),
                  nn.MaxPool2d(kernel_size=2, stride=2),)
              # declare all the layers for classification
              self.classifier = nn.Sequential(
                  nn.Linear(6 * 6 * 256, 200),
                  nn.ReLU(inplace=True),
                  nn.Dropout(p=0.5),
                  nn.Linear(200, 500),
                  nn.ReLU(inplace=True),
                  nn.Linear(500, num_classes),)
          def forward(self, x):
              # apply the feature extractor in the input
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# squeeze the spatial dimensions in one
              x = x.view(-1, 6 * 6 * 256)
              # classify the images
              x = self.classifier(x)
              return x
[18]: model = ASLNeuralNet(num_classes=29).to(DEVICE)
[19]: # sanity check
      print(model)
     ASLNeuralNet(
       (features): Sequential(
         (0): Conv2d(3, 64, kernel size=(11, 11), stride=(4, 4), padding=(2, 2))
         (1): ReLU(inplace=True)
         (2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil_mode=False)
         (3): Conv2d(64, 192, kernel_size=(3, 3), stride=(1, 1), padding=(2, 2))
         (4): ReLU(inplace=True)
         (5): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
         (6): Conv2d(192, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (7): ReLU(inplace=True)
         (8): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil_mode=False)
       )
       (classifier): Sequential(
         (0): Linear(in_features=9216, out_features=200, bias=True)
         (1): ReLU(inplace=True)
         (2): Dropout(p=0.5, inplace=False)
         (3): Linear(in_features=200, out_features=500, bias=True)
         (4): ReLU(inplace=True)
         (5): Linear(in_features=500, out_features=29, bias=True)
       )
     )
[20]: from torchsummary import summary
      summary(model, (3, 200, 200))
```

x = self.features(x)

Param #	Output Shape	Layer (type)
23,296	[-1, 64, 49, 49]	Conv2d-1
0	[-1, 64, 49, 49]	ReLU-2
0	[-1, 64, 24, 24]	MaxPool2d-3
110,784	[-1, 192, 26, 26]	Conv2d-4
0	[-1, 192, 26, 26]	ReI.U-5

```
Conv2d-7
                                  [-1, 256, 13, 13]
                                                           442,624
                                  [-1, 256, 13, 13]
                  ReLU-8
                                                                 0
             MaxPool2d-9
                                    [-1, 256, 6, 6]
                                                                 0
                                          [-1, 200]
               Linear-10
                                                         1,843,400
                                          [-1, 200]
                 ReLU-11
              Dropout-12
                                          [-1, 200]
                                                                 0
                                          [-1, 500]
               Linear-13
                                                           100,500
                 ReLU-14
                                          [-1, 500]
               Linear-15
                                           [-1, 29]
                                                            14,529
     _____
     Total params: 2,535,133
     Trainable params: 2,535,133
     Non-trainable params: 0
     Input size (MB): 0.46
     Forward/backward pass size (MB): 5.60
     Params size (MB): 9.67
     Estimated Total Size (MB): 15.73
[21]: batch_size = 64
[22]: def train_one_epoch(train_loader, model, device, optimizer, log_interval,__
       ⇒epoch):
         model.train()
         losses = []
         counter = []
         for i, (img, label) in enumerate(train_loader):
             img, label = img.to(device), label.to(device)
             optimizer.zero_grad()
             output = model(img)
             loss = criterion(output, label)
             loss.backward()
             optimizer.step()
             if (i+1) % log_interval == 0:
                 losses.append(loss.item())
                 counter.append(
                     (i * batch_size) + img.size(0) + epoch * len(train_loader.
       →dataset))
         return losses, counter
[23]: def test_one_epoch(test_loader, model, device):
         model.eval()
         test_loss = 0
```

[-1, 192, 13, 13]

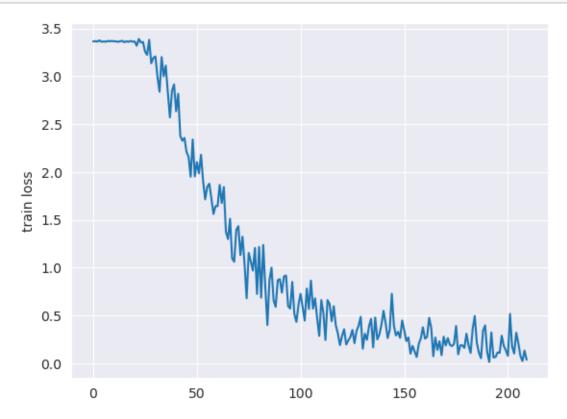
MaxPool2d-6

```
num_correct = 0
          with torch.no_grad():
              for i, (img, label) in enumerate(test_loader):
                  img, label = img.to(device), label.to(device)
                  output = model(img)
                  pred = torch.argmax(output, dim=1)
                  num_correct += (pred == label).sum().item()
                  test_loss += criterion(output, label).item()
          test_loss /= len(test_loader.dataset)
          return test_loss, num_correct
[24]: criterion = nn.CrossEntropyLoss()
[25]: no_of_epochs = 10
[26]: lr = 0.01
      log interval = 100
      optimizer = torch.optim.SGD(model.parameters(), lr=lr)
      train_losses = []
      train counter = []
      test_losses = []
      test_correct = []
      train_correct = []
      for epoch in tqdm(range(no_of_epochs)):
          train_loss, counter = train_one_epoch(train_dataloader, model, DEVICE,_u
       ⇔optimizer, log_interval, epoch)
          test_loss, num_correct = test_one_epoch(test_dataloader, model, DEVICE)
          _, num_correct_train = test_one_epoch(train_dataloader, model, DEVICE)
          # record results
          train losses.extend(train loss)
          train counter.extend(counter)
          test_losses.append(test_loss)
          test_correct.append(num_correct)
          train_correct.append(num_correct_train)
     100%|
                | 10/10 [40:23<00:00, 242.39s/it]
[27]: print(f"test accuracy: {test_correct[-1]/len(test_dataloader.dataset)}")
      print(f"train accuracy: {train_correct[-1]/len(train_dataloader.dataset)}")
     test accuracy: 0.985
     train accuracy: 0.9872557471264368
```

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[28]: SAVE_PATH = "../../data/googlenet_asl_v0.pth"
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[29]: torch.save(model, SAVE_PATH)

[30]: sns.lineplot(train_losses)
plt.ylabel("train loss");



```
[31]: sns.lineplot(test_losses, color="orange")
plt.ylabel("test loss");
```

