### NCSU Linear Algebra for Data Science Python

# **Matrix Transformations & Decomposition**

Centering and standardizing, correlation and covariance matrix, projection and rotation matrices, matrix decomposition, Principal Component Analysis (PCA), Singular Value Decomposition (SVD), eigenvalues, eigenvectors

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# **Vector Transformation CENTERING AND STANDARDIZING**

# **Centering and Standardizing**

Let  $x = (x_1, x_2, ..., x_n)$  be the column vector

#### The mean of the vector:

$$\overline{x} = \frac{x_1 + x_2 + \dots + x_n}{n} = \frac{1}{n} \sum_{i=1}^n x_i$$

$$\overline{x} = \frac{2.1 + 2.5 + 4.0 + 3.6}{4} = 3.05$$

### **Example in R:**

### **Example in Python:**

	<pre>x = np.array([2.1,2.5,4.0,3.6]) np.mean(x)</pre>
3.0	5

Economic Growth % (x <sub>i</sub> )	S & P 500 Returns % (y <sub>i</sub> )
2.1	8
2.5	12
4.0	14
3.6	10

# Centering

Let  $x = (x_1, x_2, ..., x_n)$  be the column vector

The mean of the vector:

$$\overline{x} = \frac{x_1 + x_2 + \dots + x_n}{n} = \frac{1}{1} \sum_{i=1}^{n} x_i + \text{scalar, number}$$

**Centering** the vector: center *x* at its mean

Note: The mean of the centered vector is zero:  $\overline{x_c} = 0$ 

$$\overline{x} = \frac{2.1 + 2.5 + 4.0 + 3.6}{4} = 3.05$$

$$x_c = (2.1 - 3.05, 2.5 - 3.05, 4.0 - 3.05, 3.6 - 3.05)$$

$$= (-.95, -0.55, 0.95, 0.55)$$

Economic Growth % (x <sub>i</sub> )	S & P 500 Returns % (y <sub>i</sub> )
2.1	8
2.5	12
4.0	14
3.6	10

# Centering in Python and in R

# Centering the vector: center x at its mean

$$x_c = x - \overline{x} = (x_1 - \overline{x}, x_2 - \overline{x}, \dots, x_n - \overline{x})$$
 \rightarrow vecto

### **Example in R:**

# Centering the vector: center x at its mean

### **Example in Python:**

Economic Growth % (x <sub>i</sub> )	S & P 500 Returns % (y <sub>i</sub> )
2.1	8
2.5	12
4.0	14
3.6	10

# Standardizing in R

Let  $x = (x_1, x_2, ..., x_n)$  be the column vector

**Centered vector:** 

$$x_c = x - \overline{x} = (x_1 - \overline{x}, x_2 - \overline{x}, \dots, x_n - \overline{x})$$

Economic Growth % (x <sub>i</sub> )	S & P 500 Returns % (y <sub>i</sub> )
2.1	8
2.5	12
4.0	14
3.6	10

Variance:  $var(x) = \frac{(x_1 - \bar{x})^2 + (x_2 - \bar{x})^2 + \dots + (x_n - \bar{x})^2}{n-1}$ 

Standard Deviation:  $sd(x) = \sqrt{var(x)}$ 

**Standardizing** using standard deviation:

$$x_s = \frac{x}{sd(x)}$$

**Standardizing** using mean & standard deviation (Z-score):

**Z-score** = 
$$\frac{x-\overline{x}}{sd(x)} = \frac{x_c}{sd(x)}$$

### **Example in R:**

```
> x <- c(2.1, 2.5, 4.0, 3.6)
> var(x)
Γ11 0.80333
> sd(x)
[1] 0.89629
> sd(x) * sd(x)
[1] 0.80333
[1] 0.9025 0.3025 0.9025 0.3025
> sum (xc * xc)
[1] 2.41
> sum (xc * xc) / (4-1)
[1] 0.80333
> xs <- x / sd(x)
[1] 2.3430 2.7893 4.4628 4.0166
> Z.score <- xc / sd(x)</pre>
 Z.score
[1] -1.05993 -0.61364 1.05993 0.61364
```

# Standardizing in Python

```
x = np.array([2.1,2.5,4.0,3.6])
 2 | var_x = np.var(x,ddof=1)
  sd = np.std(x,ddof=1)
   sd squared = sd**2
  xc squared = xc**2
  sum_xc_squared = np.sum(xc_squared)
   var = sum_xc_squared/(len(x)-1)
  xs = x/sd
   z score = xc/sd
10
   print(round(var x, 5))
   print(round(sd, 5))
   print(round(sd_squared, 5))
   print(xc_squared)
   print(round(sum_xc_squared, 2))
   print(round(var, 5))
   print(xs)
   print(z_score)
```

Economic Growth % (x <sub>i</sub> )	S & P 500 Returns % ( <i>y</i> <sub>i</sub> )
2.1	8
2.5	12
4.0	14
3.6	10

### **Output:**

```
0.80333

0.89629

0.80333

[0.9025 0.3025 0.9025 0.3025]

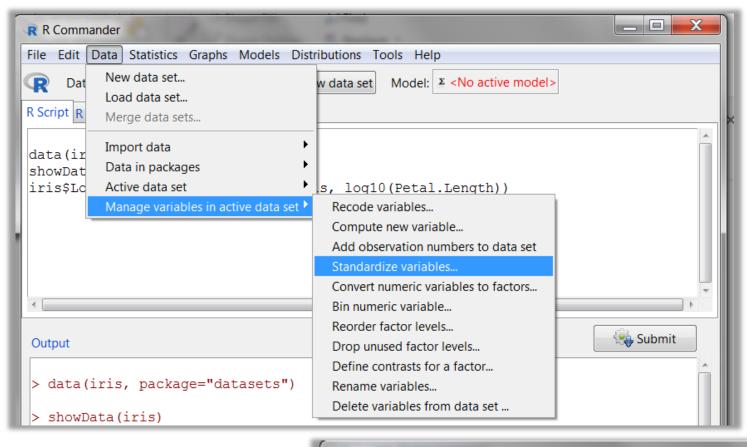
2.41

0.80333

[2.34299521 2.78928001 4.46284802 4.01656322]

[-1.0599264 -0.6136416 1.0599264 0.6136416]
```

# **Apply Transformations: Standardize Variables**



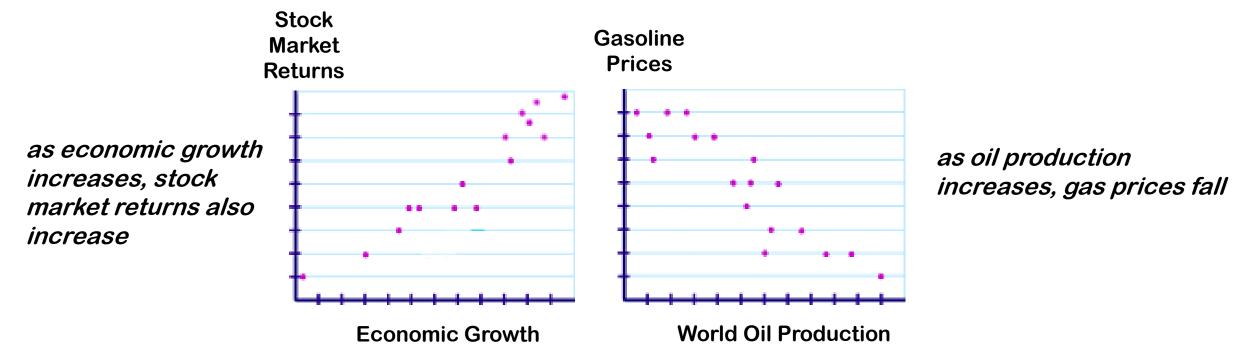
R iris	R iris					
	Species	Log10.Petal.Length	Z.Petal.Length	Z.Petal.Width	Z.Sepal.Length	Z.Sepa
1	setosa	0.14612804	-1.33575163	-1.3110521482	-0.89767388	1.0
2	setosa	0.14612804	-1.33575163	-1.3110521482	-1.13920048	-0.1
3	setosa	0.11394335	-1.39239929	-1.3110521482	-1.38072709	0.3
	setosa	0.17609126	-1.27910398	-1.3110521482	-1.50149039	0.0
© 2019 Nagiza F. Samatova, NC State Univ. All right	setosa	0.14612804	-1.33575163	-1.3110521482	-1.01843718	1.2

# Other Types of Matrices CORRELATION AND COVARIANCE MATRIX

### **Covariance and Correlation**

Covariance and correlation describe how two variables are related.

- Variables are positively related if they move in the same direction.
- Variables are inversely related if they move in opposite directions.



# Covariance: Formula

 $x = (x_1, x_2, ..., x_n)$ : the independent variable

 $y = (y_1, y_2, ..., y_n)$ : the dependent variable

 $\overline{x}$ : the mean of x

 $\overline{y}$ : the mean of y

n: the number of points in the sample

$$cov(x,y) = \frac{\sum_{i=1}^{n} (x_i - \overline{x})(y_i - \overline{y})}{n-1}$$

$$cov(x,y) = \frac{1}{n-1} x_c^T y_c$$

Cross-product (inner product) of centered variables normalized by the sample size minus 1 (n-1).

# Covariance: Example in Python

centering

centering

normalized cross-product covariance

Economic Growth % (x <sub>i</sub> )	S & P 500 Returns % (y <sub>i</sub> )
2.1	8
2.5	12
4.0	14
3.6	10

```
1  x = np.array([2.1,2.5,4.0,3.6])
2  xc = x - np.mean(x)
3  y = np.array([8,12,14,10])
4  yc = y - np.mean(y)
5
6  norm_cross_prod = np.sum(np.matmul(xc.T,yc))/(len(y)-1)
7  print(norm_cross_prod)
8  np.cov(x,y)[1,0]
```

1.533333333333333

1.533333333333333

# Covariance: Example in R

$$cov(x,y) = \frac{1}{n-1} x_c^T y_c$$

Cross-product (inner product) of centered variables normalized by the sample size minus 1 (n-1).

Economic Growth % (x <sub>i</sub> )	S & P 500 Returns % (y <sub>i</sub> )
2.1	8
2.5	12
4.0	14
3.6	10

$$cov(x,y) = \frac{\sum_{i=1}^{n} (x_i - \overline{x})(y_i - \overline{y})}{n-1}$$

```
centering > x <- c(2.1, 2.5, 4.0, 3.6)
> xc <- x - mean(x)
> y <- c(8, 12, 14, 10)
centering > yc <- y - mean(y)
>
normalized > sum (t(xc) %*% yc) / (length(y) - 1)
cross-product [1] 1.5333
> cov (x, y)
covariance [1] 1.5333
```

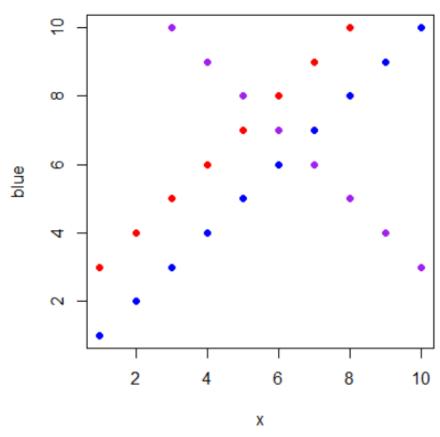
### **Correlation: Formula**

$$cor(x,y) = \frac{cov(x,y)}{sd(x) \times sd(y)}$$

- Correlation is a scaled version of covariance (i.e., scaled by the standard deviations)
- Correlation and covariance always have the same sign (positive, negative, or 0)
  - when the sign is positive, the variables are said to be positively correlated
  - when the sign is negative, the variables are said to be negatively correlated
  - and when the sign is 0, the variables are said to be uncorrelated
- Correlation is dimensionless, since the numerator and denominator have the same physical units.
- Correlation will always take on a value between 1 and 1:
  - If the correlation coefficient is +1, the variables have a perfect positive correlation. This
    means that if one variable moves a given amount, the second moves proportionally in the
    same direction.
  - If correlation coefficient is -1, the variables are perfectly negatively correlated (or inversely correlated) and move in opposition to each other. If one variable increases, the other variable decreases proportionally.
  - If correlation coefficient is zero, no relationship exists between the variables. If one variable moves, no predictions about the movement of the other variable can be made.

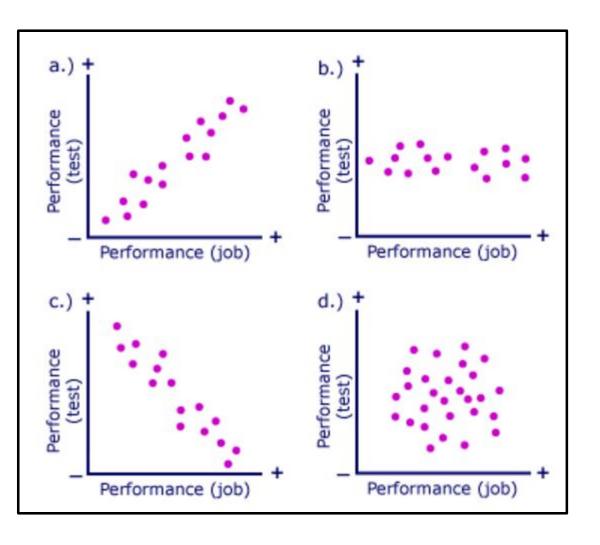
# **Understanding Correlation (correlation.R)**

```
> x <- c(1:10)
> blue <- c(1:10)
> red <- c(3:12)
> purple <- sort(red, decreasing=TRUE)
>
> plot(x,blue,col="blue",pch=19)
> points(red,col="red",pch=19)
> points(purple,col="purple",pch=19)
> cor(blue,red)
[1] 1
> cor(red,purple)
[1] -1
```



```
> noise <- abs(rnorm(10, mean=5))
> noise
[1] 5.0548 6.2234 4.0714 3.4522 4.9278 4.6648 4.8472 5.1168 4.3224 5.5515
> points(noise, col="grey", pch=19)
> cor(blue,noise)
[1] 0.0073982
```

# **Correlation: Examples**



In each of the graphs, are job performance and test performance shown to be positively related, inversely related, or unrelated?

#### **Answers:**

- a) positively related
- b) unrelated
- c) inversely related
- d) unrelated

# **Exercise: Compute Covariance & Correlation**

Month	Return of Stock A	Return of Market Index
1	2.3	1.3
2	2.5	5.0
3	1.9	0.8
4	2.4	1.9
5	2.1	1.1

- 1. Using the table, show your calculations and R codes for computing the correlation of Stock A's returns and the return of the market index.
- 2. Do the same for the covariance.

### **Exercise: Solution**

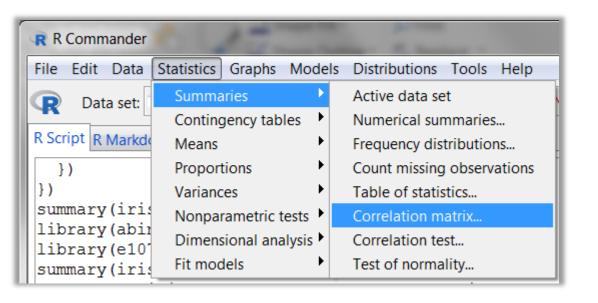
Month	Return of Stock A	Return of Market Index
1	2.3	1.3
2	2.5	5.0
3	1.9	0.8
4	2.4	1.9
5	2.1	1.1

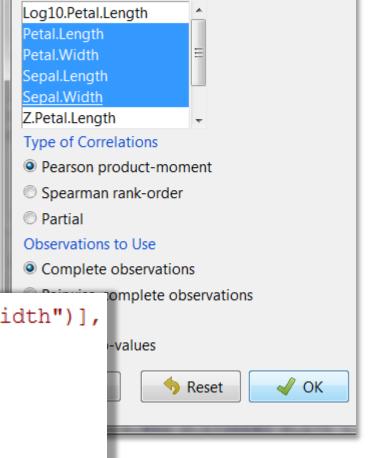
			step 1	step 2
	Stock A	Market Return	$(x_i - \overline{x})^2$	$(y_i - \overline{y})^2$
	2.30	1.30	0.0036	0.5184
	2.50	5.00	0.0676	8.8804
	1.90	0.80	0.1156	1.4884
	2.40	1.90	0.0256	0.0144
	2.10	1.10	0.0196	0.8464
Sum			0.2320	11.7480
Average	2.24	2.02		
Sum ÷ 4			0.0580	2.9370
Standard deviation			0.2408	1.7138

$$cor(x,y) = \frac{cov(x,y)}{sd(x)sd(y)} = \frac{0.31}{(0.24)(1.71)} = \frac{0.31}{0.41} = 0.76$$

```
> x < c(2.3,2.5,1.9,2.4,2.1)
> y <- c(1.3,5.0,0.8,1.9,1.1)
> mean(x)
[1] 2.24
> mean(y)
[1] 2.02
> sd(x)
[1] 0.24083
> sd(y)
[1] 1.7138
> cov(x,y)
> cor(x,y)
[1] 0.76079
> cov(x,y) / (sd(x)*sd(y))
[1] 0.76079
```

### **Correlation Matrix with R Commander**

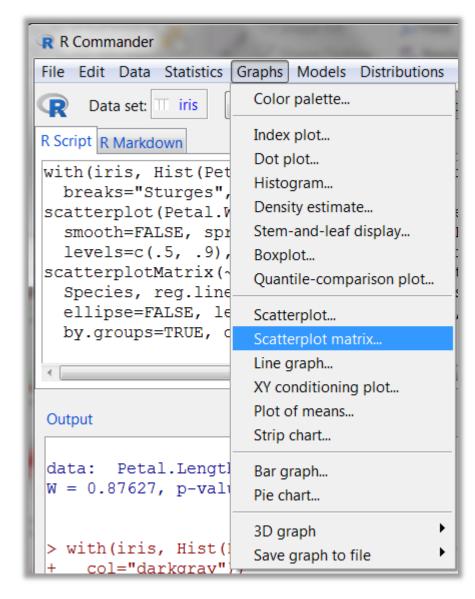


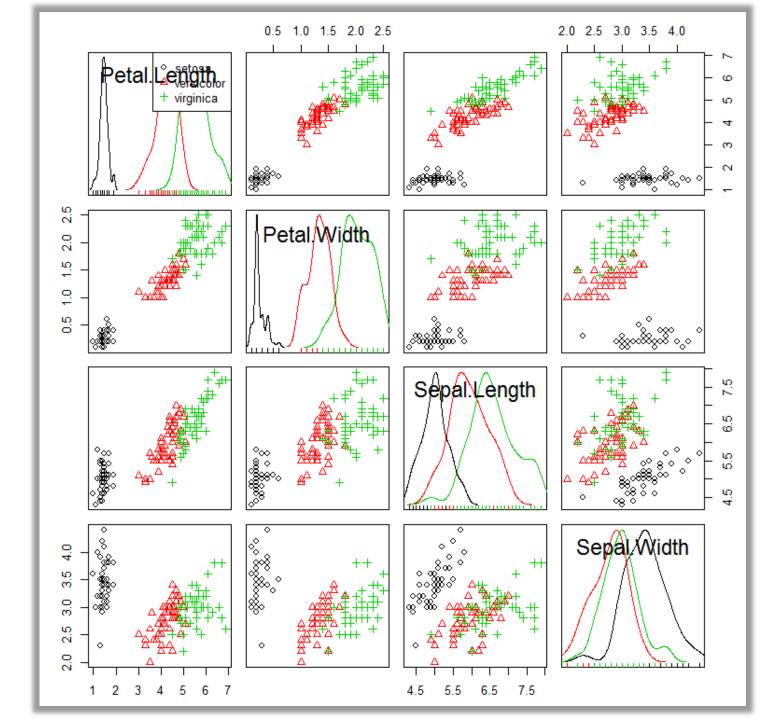


R Correlation Matrix

Variables (pick two or more)

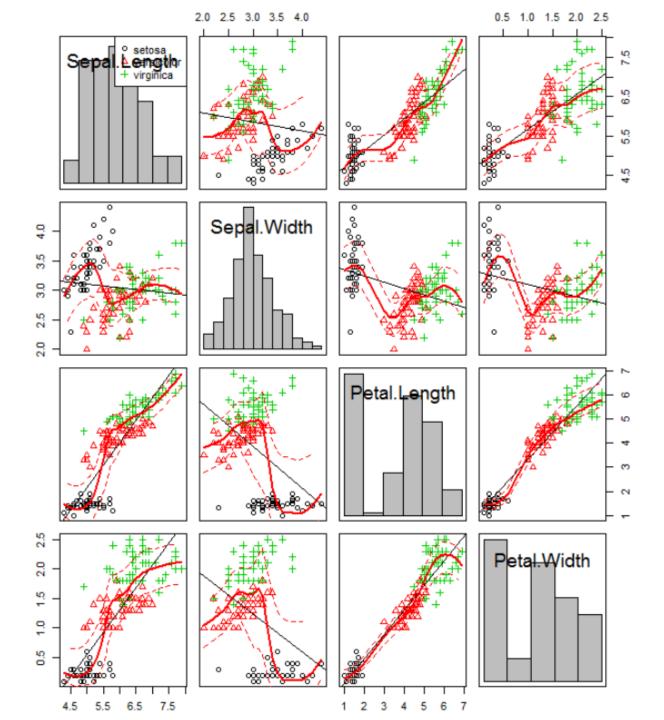
# **Scatterplot Matrix**





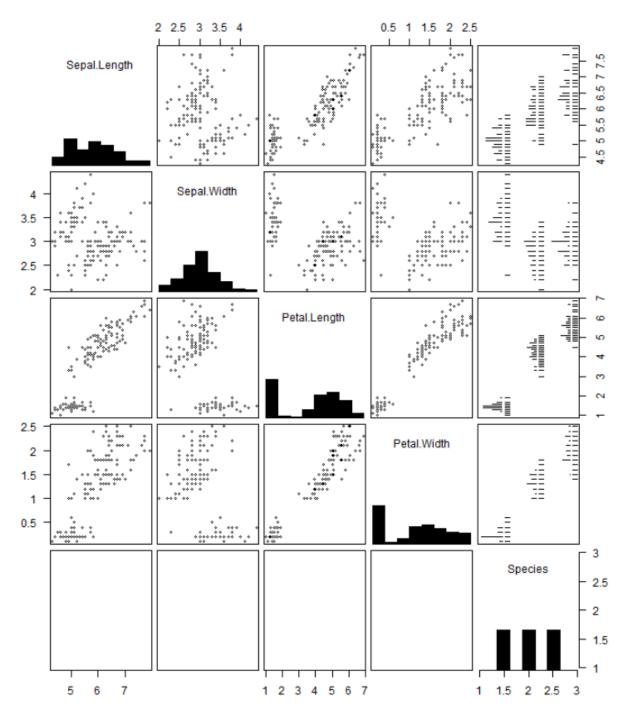
# Visualizing Relationships: Continuous Variables

install.packages ("car")
library (car)
scatterplotMatrix (~
Sepal.Length + Sepal.Width +
Petal.Length + Petal.Width |
Species, data=iris,
diagonal="histogram")



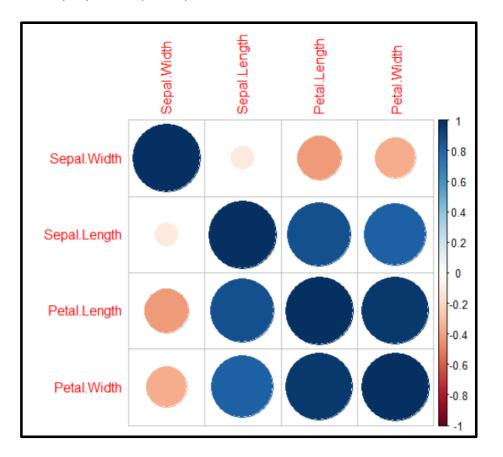
# Visualizing Relationships: Continuous & Discrete

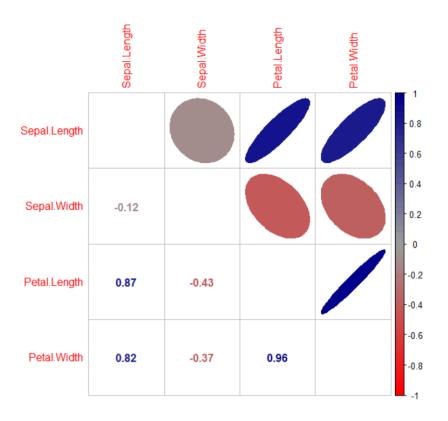
install.packages ("gpairs")
library (gpairs)
gpairs (iris[, 1:5])
help (gpairs)



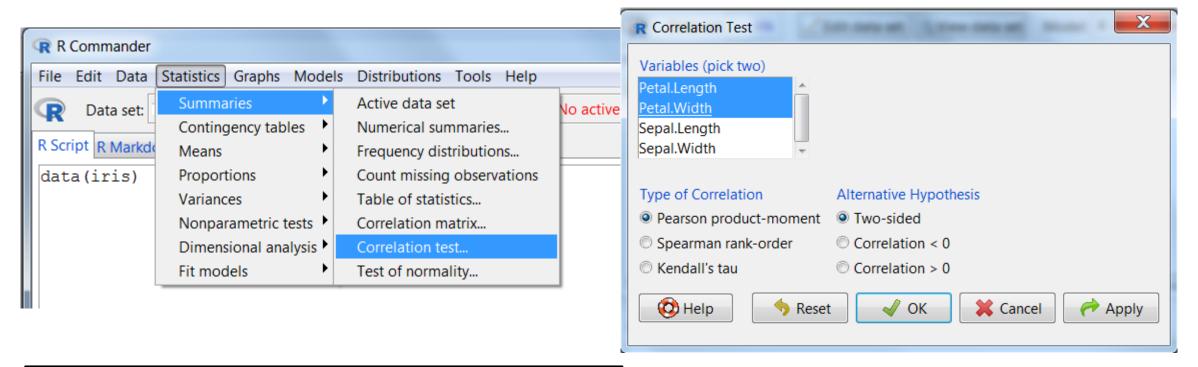
# **Visualizing Correlation Matrix**

install.packages ("corrplot")
library (corrplot)
corrplot (cor (iris[, 1:4], order="hclust")
help (corrplot)





# Statistical Significance of Correlations



```
Pearson's product-moment correlation

data: Petal.Length and Petal.Width

t = 43.387, df = 148, p-value < 2.2e-16

alternative hypothesis: true correlation is not equal to 0

95 percent confidence interval:
    0.9490525 0.9729853

sample estimates:
    cor

0.9628654
```

p-value < 0.05: statistically significant

# Linear Transformation Matrix SCALING, REFLECTION, ROTATION

## **Linear Transformation Matrix**

### **Matrix-based Transformation of Vectors**

$$\left| \begin{array}{c} \mathcal{V}_{old} & \longrightarrow \\ \mathrm{matrix}, A \end{array} \right| \quad ext{via vector-matrix multiplication}$$

- Scaling Matrix
- Reflection Matrix
- Rotation Matrix
- Projection Matrix

# **Notation**

$$u = [u_1, u_2, ..., u_p]$$
 - row vector

$$\mathbf{v} = \begin{bmatrix} v_1 \\ \dots \\ v_m \end{bmatrix} - \text{column vector}$$

$$\mathbf{A} = \mathbf{A}_{m \times p} = \begin{bmatrix} a_{11} & \dots & a_{1p} \\ \dots & \dots & \dots \\ a_{m1} & \dots & a_{mp} \end{bmatrix} - m \times p \text{ matrix}$$

$$\boldsymbol{I} = \boldsymbol{I}_{m \times m} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ & & & & \\ 0 & 0 & 0 & 1 \end{bmatrix} - \text{ identity matrix}$$

# **Scaling Matrix**

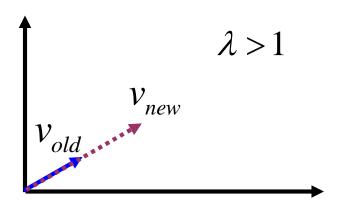
#### **Row vectors:**

$$v_{old} \in R^p \xrightarrow[\text{matrix}, A]{} v_{new} = \lambda \cdot v_{old} \in R^p$$

$$\boldsymbol{A}_{\lambda} = \lambda \cdot \boldsymbol{I}_{p \times p} = \begin{bmatrix} \lambda & 0 & \dots & 0 \\ 0 & \lambda & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \lambda \end{bmatrix} - \text{Scaling Matrix}$$

$$v_{new} = v_{old} \times A_{\lambda} = v_{old} \cdot \lambda \cdot I_{p \times p}$$

- Unchanged:
  - Direction of a vector if  $\lambda > 0$
- Changed:
  - Vector norm/length  $\|v_{new}\| = \lambda \cdot \|v_{old}\|$
  - Direction of a vector if  $\lambda < 0$



## **Reflection Matrix**

#### Row vectors:

$$v_{old} \in R^p \xrightarrow[\text{matrix}, A]{} v_{new} = v_{old} \cdot A \in R^p$$

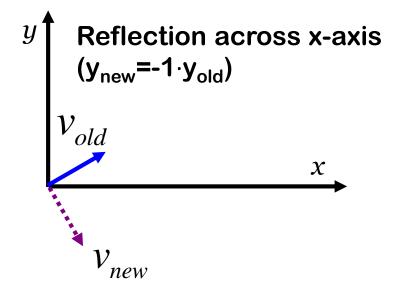
$$A = I'_{p \times p} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & -1 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 1 \end{bmatrix} - \begin{array}{c} \textbf{Reflection Matrix: Identity Matrix with} \\ \textbf{some diagonal elements set to -1} \\ \textbf{A} = I'_{p \times p} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & -1 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Changed:

- Direction of a vector
- Reflects across one/more axis
- Unchanged:
  - Vector norm/length

$$v_{new} = v_{old} \cdot A$$

Equivalent to: multiplying one or more vector components by -1



# **Rotation Matrix**

#### **Row vectors:**

$$v_{old} \in R^p \underset{\substack{\text{matrix, } A \\ \det(A)=1 \\ A^T = A^{-1}}}{\longrightarrow} v_{new} = v_{old} \cdot A \in R^p$$

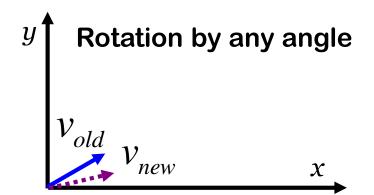
- Direction of a vector
- •Unchanged:
  - Vector norm/length

$$\boldsymbol{A} = \boldsymbol{A}_{p \times p} = \begin{bmatrix} a_{11} & \dots & a_{1p} \\ \dots & \dots & \dots \\ a_{p1} & \dots & a_{pp} \end{bmatrix} - \text{Rotation Matrix: } \boldsymbol{p} \times \boldsymbol{p} \text{ orthogonal matrix}$$

$$A^{T} = A^{-1}$$
 – orthogonal matrix  $det(A)=1$ 

### Example: p = 2

$$A(\theta) = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} - \theta \text{-angle rotation: clockwise } (A \times v_{old}) \text{ or counterclockwise } (v_{old} \times A)$$



# **Linear Transformation Matrix PROJECTION**

# **Projection Matrix**

#### **Row vectors:**

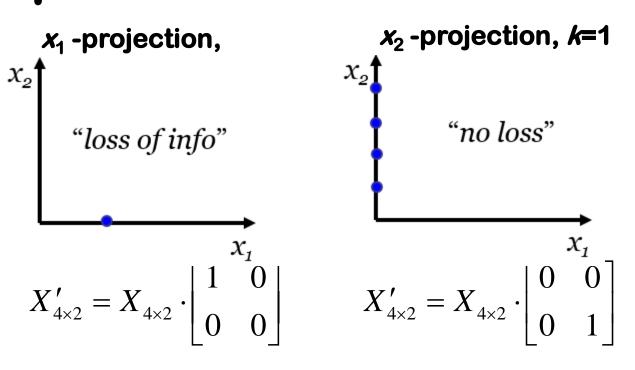
$$v_{old} \in \mathbb{R}^p \longrightarrow v_{new} = v_{old} imes A_{p imes d} \in \mathbb{R}^d$$
,  $d < p$ 

- Changed:
  - Dimensionality of a vector
  - Direction of a vector
  - Vector norm/length

# Example 1: $p=2\rightarrow d=1$

# Original data, *p*=2

"loss of info"
$$X_{2} = X_{4\times 2} \cdot \begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix}$$

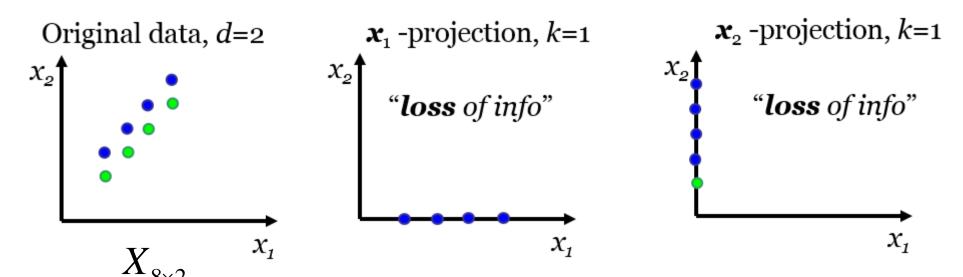


$$X'_{m \times d} = X_{m \times d} \cdot P_{d \times d}$$

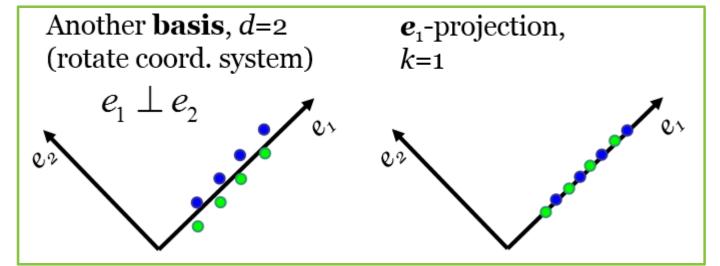
$$\boldsymbol{P}_{d\times d} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 1 \end{bmatrix} - \text{projection matrix; some diagonal elements are } 0$$

### Which projection is "better"?

### **Example 2: Linear, Orthogonal Projection**



### Is there a "better" projection?



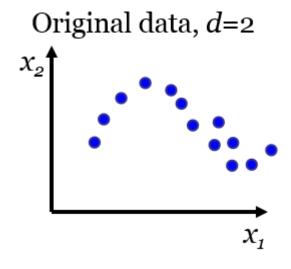
### **Projection:**

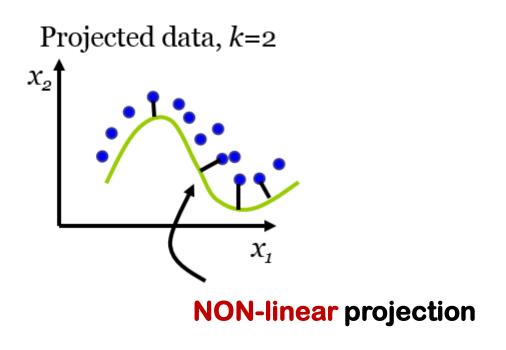
- Linear, e<sub>1</sub> line
- Orthogonal

$$e_1 \perp e_2$$

 $e_1$ ,  $e_2$  – eigenvectors of X

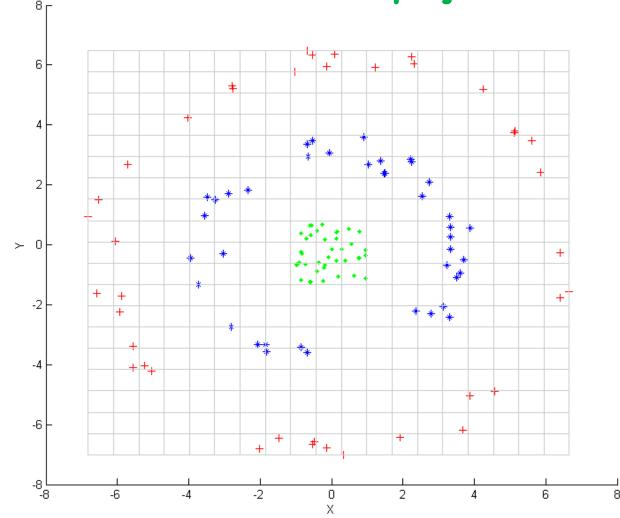
# **Example 3: Non-linear projection**





# **Example 4: Projection for Labeled Data**

### What is a "better" projection?



### Ideal for machine learning (ML) algorithm:

- Points within the same group come from a Gaussian distribution (spherical shapes)
- Points from different groups are linearly separable

#### **Summary: Types of Dimension Reduction**

- Linear vs. NON-linear
- Orthogonal vs. non-orthogonal
- Unsupervised (unlabeled data) vs. supervised (labeled data)

#### **Linear dimension reduction:**

- Interpretable in original space
- Preserves non-linearity for visualization
- Orthogonal projections
- Non-orthogonal projections
- Favored for structure discovery

#### Non-linear dimension reduction:

- Lower-dimensional representation
- Interpretable w.r.t. Non-linear transformation
- 1 to 3 orders of magnitude more computation
- Favored for prediction or classification

- A lower-dimensional representation that contains the essence of the high dimensional data
- Blessing of dependence/correlation that saves us from the curse of dimensionality

# Linear Orthogonal Projection PCA: PRINCIPAL COMPONENT ANALYSIS

# What is "better" projection: $d \rightarrow k (k < d)$ ?

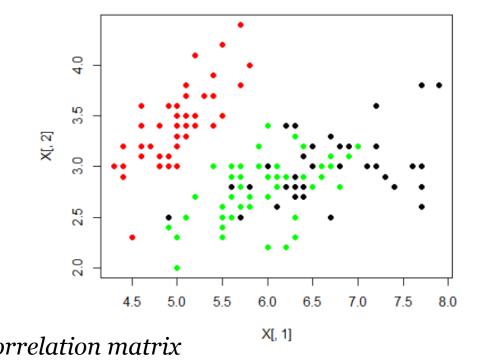
- Many definitions are possible
- Definition 1:
  - Projection that maximizes the VARIANCE of the original d-dimensional data upon its projection onto the target k-dimensions (k < d)

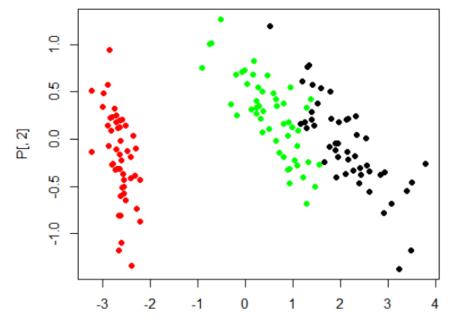
# R Example: PCA with prcomp()

```
data (iris)
View (iris)
X <- iris [ , 1:4]
plot (X[ ,1], X[ ,2], pch=19)
points (X [1:50, 1], X[1:50,2], col="red", pch=19)
points (X [51:100, 1], X[51:100,2], col="green", pch=19)
```

```
pca.model <- prcomp (X)
pca.model$sdev  # square roots of eigenvalues covariance/correlation matrix
plot (pca.model, type="l") # screeplot
pca.model$rotation  # matrix of eigenvector columns
pca.model
summary (pca.model) # check proportion of variance
```

```
P <- pca.model$x  # projection of X onto eigenvectors
dim (P)
head (P)
plot (P[ ,1], P[ ,2], pch=19)
points (P [1:50, 1], P[1:50,2], col="red", pch=19)
points (P [51:100, 1], P[51:100,2], col = "green", pch=19)</pre>
```

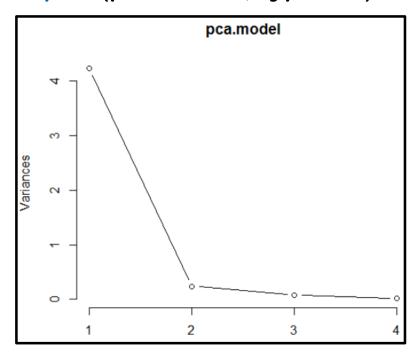




# **Visualizing PCA results**

#### Screeplot

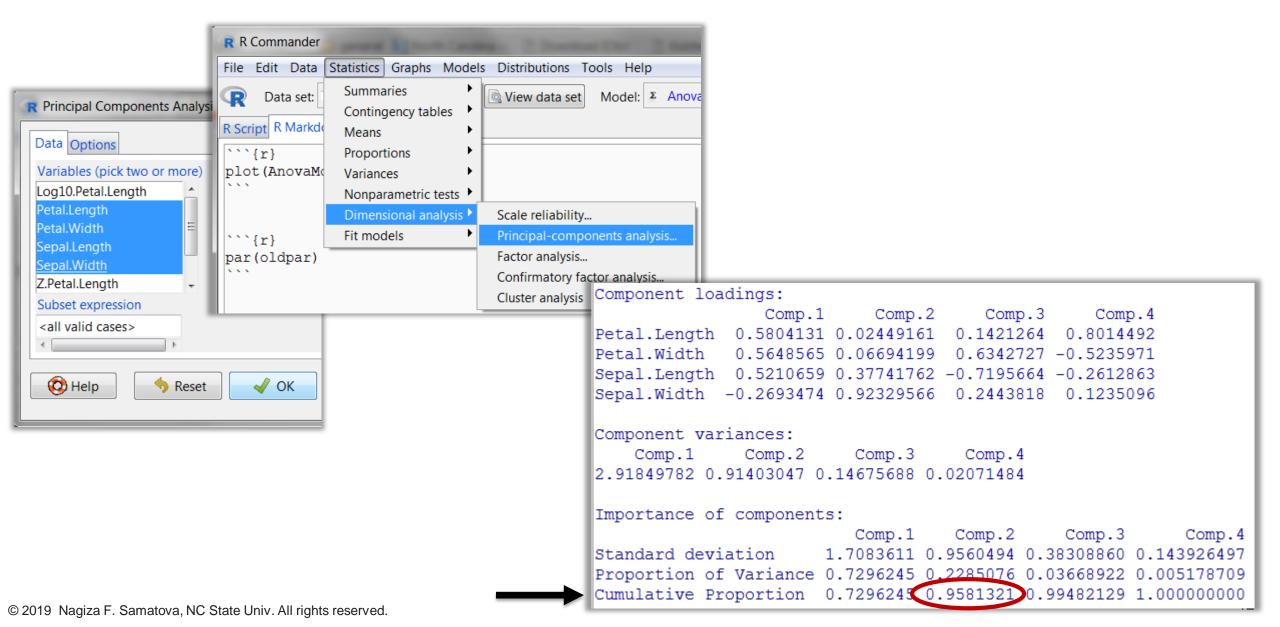
plot (pca.model, type="l")



Successive variance accounted by each component

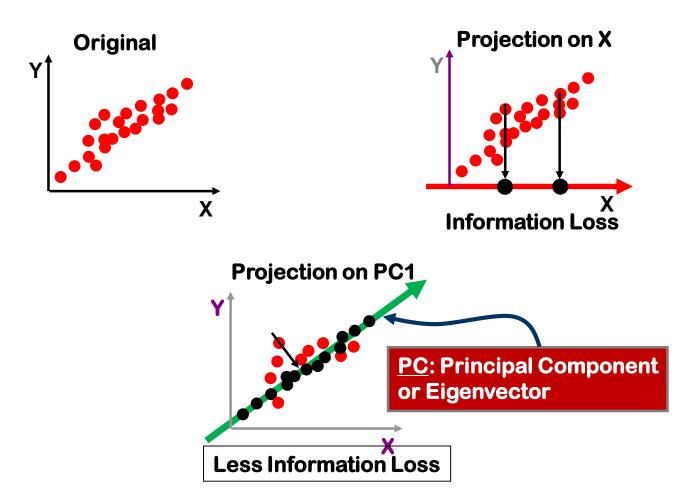
biplot (pca.model)

# Principal Component Analysis with R Commander



# **PCA: Linear Orthogonal Dimension Reduction**

Principal Component Analysis (PCA) finds intrinsic dimensionality and allows for low-dimensional representation.



Principal Component Analysis is the Spectral Decomposition of the Covariance Matrix.

# Matrix Decomposition PCA: SVD OF COVARIANCE MATRIX

#### PCA is the SVD of Covariance/Correlation Matrix

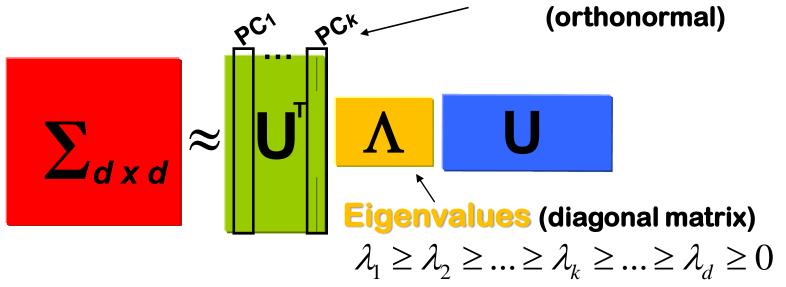
#### **Singular Value Decomposition (SVD)**

The technique underlying PCA analysis

#### **PCA = SVD (Covariance Matrix)**

PCA is the SVD applied to a covariance matrix

**Eigenvectors/ Principal Components** 

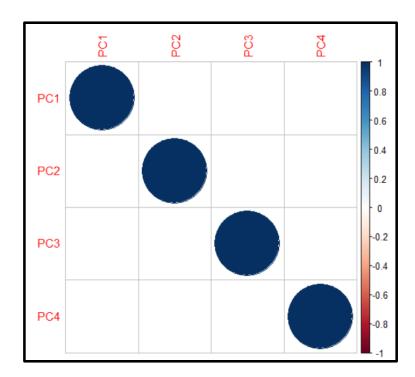


#### Details

princomp is a generic function with "formula" and "default" methods.

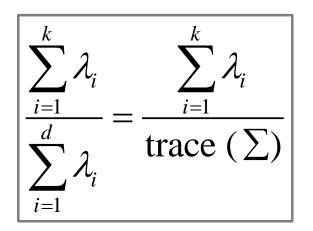
© 2019 Nagiza F. Samatova, N. Decade Calculation is done using eigen on the correlation or covariance matrix, as determined by cor.

#### Extracted Principal Components (PCs) are Uncorrelated

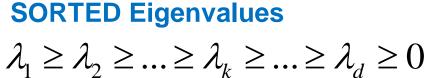


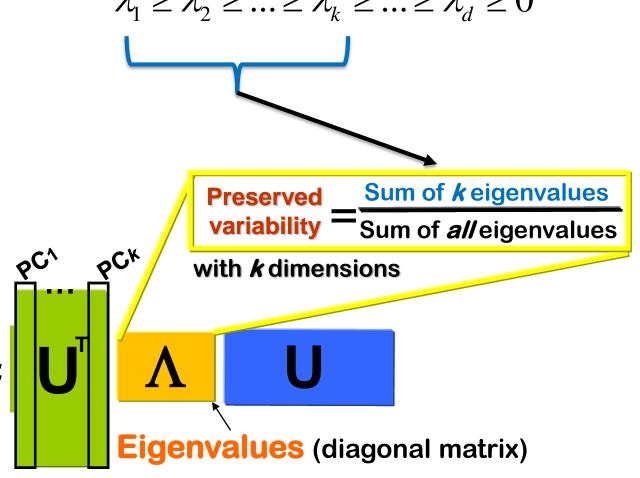
# Preserved Variability for Top-k PCs

Percentage of variability preserved if the first k PCs are used for projection:









# **Key Points about PCA**

- PCA = SVD (Covariance Matrix, ∑)
- Linear, orthogonal projection:
  - "Best" linear orthogonal k-dimensional (k < a) view of data
- How "good" the *k*-dimensional view is:

$$\frac{\sum_{i=1}^{k} \lambda_{i}}{\sum_{i=1}^{d} \lambda_{i}} = \frac{\sum_{i=1}^{k} \lambda_{i}}{\operatorname{trace}(\Sigma)}$$

# Eigenvalues: Importance of eigenvectors

$$\lambda_1 \ge \lambda_2 \ge \dots \ge \lambda_k \ge \dots \ge \lambda_d \ge 0$$

#### Importance of Principal Components (PC), or Eigenvectors, or Rotations

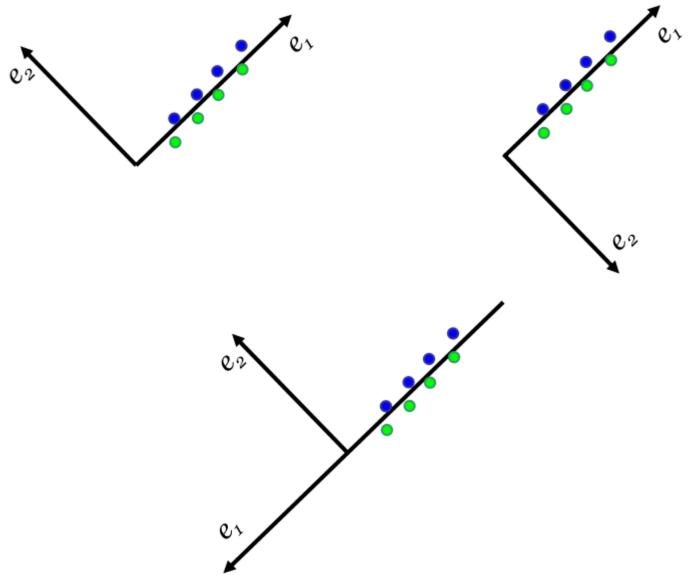
PC1 preserves more variance than PC2 PC2 preserves more variance than PC3

• • • •

#### Proportion of Variance Preserved if only k PCs are used:

$$\frac{\sum_{i=1}^{k} \lambda_{i}}{\sum_{i=1}^{d} \lambda_{i}} = \frac{\sum_{i=1}^{k} \lambda_{i}}{\operatorname{trace}(\Sigma)}$$

# Eigenvectors are NOT unique



#### **PCA: Covariance vs. Correlation Matrix**

- PCA results depend on the scales at which the variables are measured:
  - PCA should only be used with the raw data if all variables have the same units of measure
- PCA results depend on the variances of the variables: the ones with the highest sample variances will tend to be emphasized in the first few principal components:
  - Use PCA with covariance matrix only if you wish to give variables with higher variances more weight in the analysis
- If the variables either have different units of measurement (i.e., pounds, feet, gallons, etc), or if we wish each variable to receive equal weight in the analysis, then the variables should be standardized (Z-scores) before a principal components analysis is carried out.

# Matrix Decomposition PCA: DIMENSION REDUCTION VIA FEATURE EXTRACTION

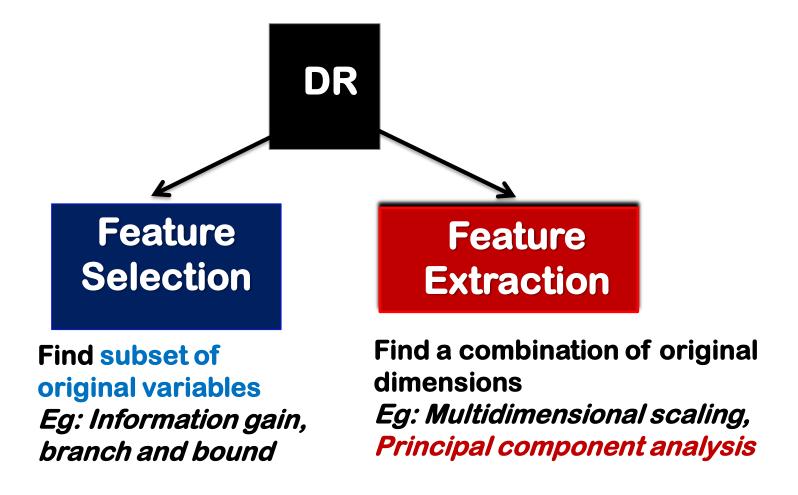
#### PC is a weighted linear sum of original features

#### Extracted Feature -> PCA-based Feature Extraction:

$$PC = w_1 * f_1 + w_2 * f_2 + \cdots + w_d * f_d$$

The magnitude of each weight indicates how important the corresponding feature is → it could be used as a *feature selection* technique!

# Classification of Dimension Reduction (DR) Methods



#### **Motivation for Dimension Reduction**

- Not all the measured variables are important for understanding the underlying "interesting" phenomena – could complicate the process of data analysis
- Decrease the computational cost for other data mining tasks:
  - Proximity measure calculations:  $O(a) \rightarrow O(k)$
- Reduce the noise in the data
- Improve the accuracy of predictive models
- Reduce collinearity among variables/features

# What is Dimensionality Reduction?

Objective: To transform data from a high-dimensional space to a corresponding representation in some low-dimensional space, while "best" preserving the information.

#### Given dataset with *m* objects:

$$X \in \mathbb{R}^{m \times n}$$
  $\longrightarrow$   $Y \in \mathbb{R}^{m \times p}$   $p$  dimensions  $p$  dimensions