me have me giren objective function.
minimize. 1 wTSw - 7f+ & c+ &t
2 t
suspect to
murject to $\Rightarrow \lambda t \left(\omega^{T} 2t + \omega_{0} \right) $
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9 3 0. 3 s is a positive definete
7 S is a positive definite
2 C 76 V
» 7 € [0,1]
me have tre up voice includes the lagrange nuccipies
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- E at [8t (wtat + wo) - 8+ 5t]
and the second s
10 - 2 pt Ept - 2 p - (1)
t
The above equation à a quadratic convex optimization problem
me will now solve the dual problem using Kaushn-Kuhn
Tucker conditions, subject to the gradient Lp w. r.t w, wo, f,
Egt should me = 0.
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similatinte mani
=> Sw = & at yt xt (11)
of spaints
DLP = - Satat = 01
d wo t
£ αt st = 0 —— (111)

we now substitute (11), (111), (11), (1) into (1), int

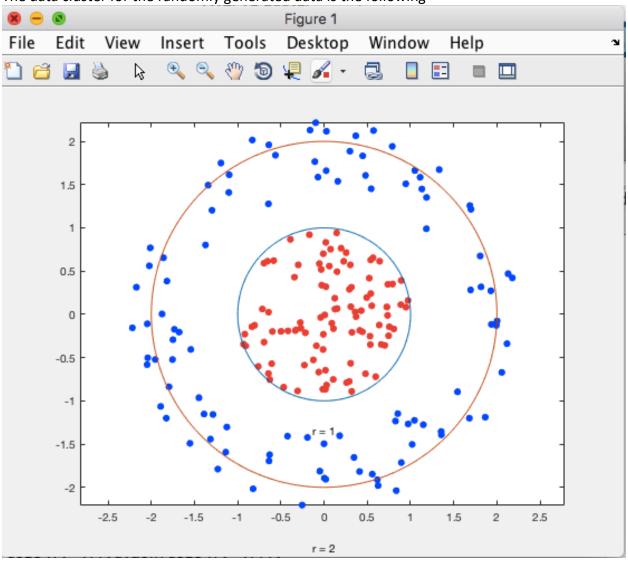
Ld = - 1 wT sat rt at - (vi)

addingmis value to (")

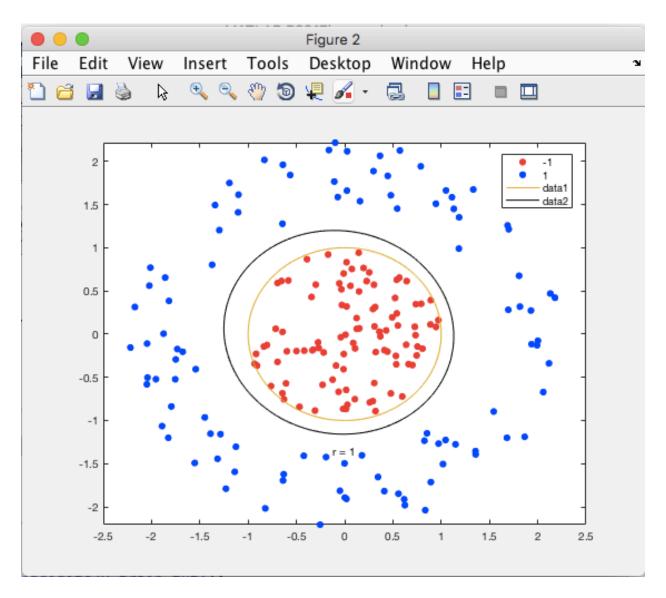
Ld = -1 & xs xs(2s) T s-1 . & xt xt = -1 & & xs xt xs xt (2s) T & -1 .

Subject to Eat st = 0 & 0 < \at < ct.

Q2
The data cluster for the randomly generated data is the following

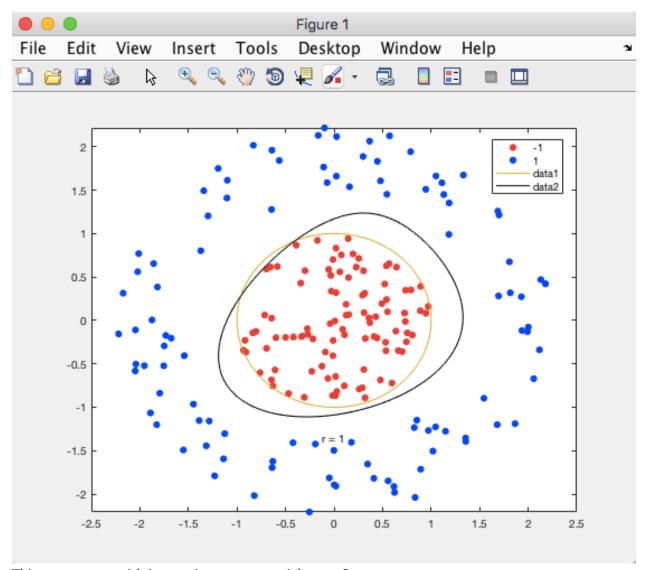


Using a q value of 2, we get the following decision boundary for the polynomial kernel perceptron



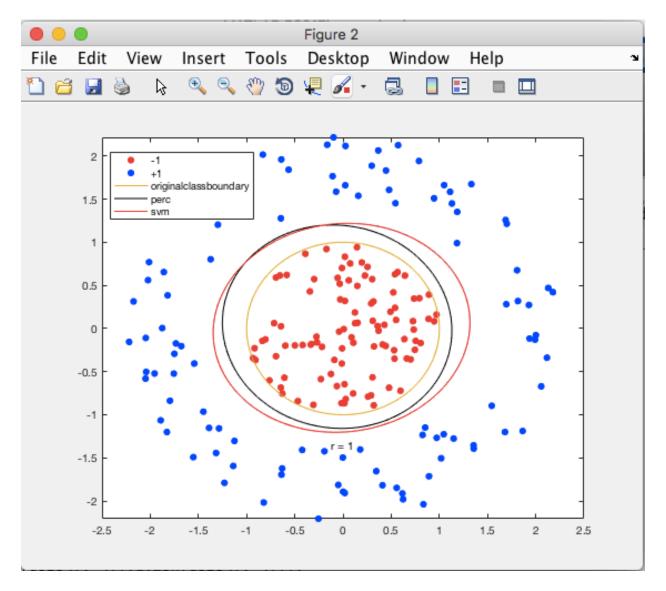
The yellow line approximates the circle around which the data was generated which we use to understand which polynomial order best mimics this decision boundary.

If we use q=3 we get the following,



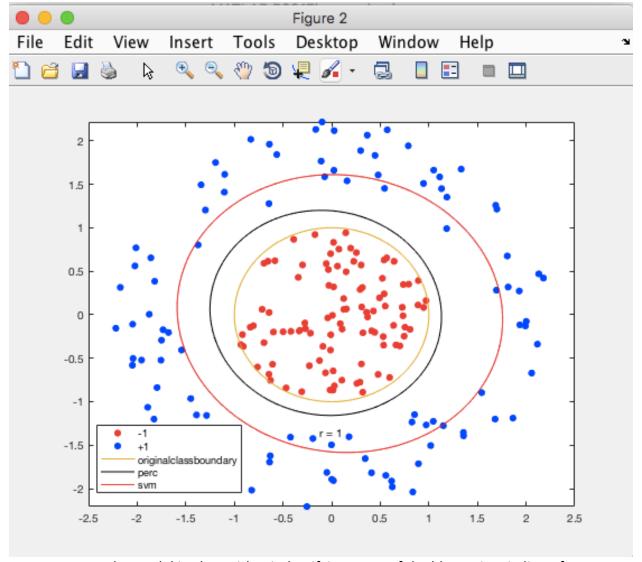
This gets worse with increasing q, so we stick to q=2.

Q2b. We now train the data with the svm model using the same polynomial kernel function and plot the decision boundary. On doing so we get the following.



Here, the red line signifies the svm model's decision boundary and the black line signifies the kernel perceptron model's decision boundary. The svm model aims to maximize the margin of the decision boundary while reducing error unlike the kernel perceptron that only works to minimize the loss function(i.e hinge loss). This causes the svm's boundary to be larger than the kernel perceptron's.

When we reduce the boxconstraint value, which affects the penalty induced when misclassifying points, the algorithm allows for more mistakes in classification while ensuring an increased margin in defining the decision boundary. When we get the box constraint value to 0.0001 we get the following plot.



As we can see, the model is okay with misclassifying some of the blue points in lieu of maximizing the margin between the observed data and the decision boundary.

Q2c When running the kernel perceptron algorithm on the two datasets(train and test) we get the following error rates.

>> Q2 train error rate for 79 data is 0.354610 The test error rate for 79 is 1.773050 The error rate for 49 data training is 49.645390 The error rate for 49 data testing is 3.169014