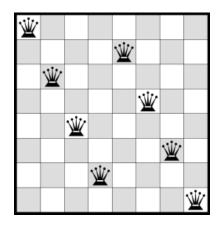
# N-queen Problem - hill climbing and its variants



### **DOCUMENTATION REPORT**

PROGRAMMING PROJECT II

ITCS 6150 - Intelligent Systems

DEPARTMENT OF COMPUTER SCIENCE

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## **Table of Contents**

| 1 PROBLEM FORMULATION      |    |
|----------------------------|----|
|                            |    |
| 1.1 Introduction           | 2  |
| 1.2 Algorithm Pseudocode   | 3  |
| 2 PROGRAM STRUCTURE        | 3  |
| 2.1 Functions/Procedures   | 3  |
| 2.2 Global/Local variables |    |
| 2.3 Code                   | 5  |
| 2.4 Sample Output          | 16 |
| 3 CONCLUSIONS              | 18 |
| DEEEDENCES                 | 10 |

#### PROBLEM FORMULATION

#### 1.1 INTRODUCTION

#### N-queen problem:

The eight queens puzzle is the problem of placing eight chess queens on an 8×8 chessboard so that no two queens threaten each other. Thus, no two queens should share the same row, column, or diagonal.

For example- The solution for 8-Queen problem looks something like this.

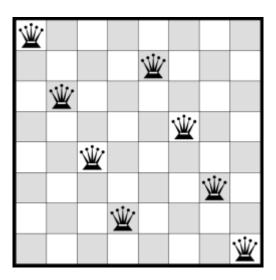


Fig 1- Solution of 8-queen problem

#### Hill-climbing:

This algorithm is simply a loop that continually moves in a direction of increasing value- uphill. It terminates when it reaches the peak where no neighbor has the highest value. The algorithm does not maintain a search tree and therefore only record the state and the value of the objective function.

#### PROGRAM STRUCTURE

#### 2.1 Introduction

Number of queens are treated as N variable and input can enter the value N. Following 3 are implemented

- 1) Steepest-ascent hill climbing
- 2) Hill-Climbing with sideways move
- 3) Random-restart hill-climbing with and without sideways move The N-queens problem is described below by an example.

The N Queen is the problem of placing N chess queens on an N×N chessboard so that no two queens attack each other.

#### 2.2 Functions and Procedures

- def \_\_init\_\_(self, queen\_positions=None, queen\_num=8, parent=None, path\_cost=0,
   f\_cost=0, side\_length=8) it's the path constructor for the QueenState.
- random\_position(self) placing each queen in a random row in a different column.
- get children(self) fetching all the possible queen moves.
- random child(self) selecting random child for allow sideways move algorithm
- queen attacks(self) queen to check for attacking queen
- num queen attacks(self) reporting violation
- init (self, start state=None) default constructor for initial board
- goal test(self, state) check if goal state is attained
- cost function(self, state) calculate number of violation
- avg steps(result list, key) calculate the average number of steps needed
- print data(results) prints result of all the hill climbing algorithm
- print data row(row title, data string, data func, results) print data row wise

• print results(results) – print results

- analyze\_performance(problem\_set, search\_function) function takes problem set and calls passed (parameter) search function and calculates steps
- analyze\_all\_algorithms(problem\_set) function to solve problem with steepest ascent, steepest ascent 100 sideway moves, random restart and random restart 100 sideways move
- steepest\_ascent\_hill\_climb(problem, allow\_sideways=False, max\_sideways=100) –
   steepest ascent hill climbing with and without sideways

#### 2.2 Global and Local variables

#### Local variables-

- queen positions
- queen num
- parent
- path cost
- f cost
- side\_length
- parent queen positions
- random queen index
- attacking pairs
- start state
- result list
- results
- num iterations
- section break
- freq
- queens problem set
- children
- children cost
- min cost
- node
- node cost
- sideways moves
- path
- best child
- best child cost

## **Program Code:**

#### 1. simulations.py

```
from statistics import mean
from search import steepest ascent hill climb, random restart hill climb
from queens import QueensProblem
#calculates the average number of steps needed
def avg steps(result list, key):
  results = [result[key] for result in result list]
  if len(result list) == 1:
     return {'avg': result_list[0][key]}
  elif not result list:
     return {'avg': 0}
  return {'avg': mean(results)}
#Prints results of all the hill climbing algorithms
def print data(results):
  title col width = 30
  data col width = 15
  #Prints data row wise
  def print data row(row title, data string, data func, results):
     nonlocal title_col_width, data_col_width
     row = (row title + '\t').rjust(title col width)
     for result group in results:
       row += data string.format(**data func(result group)).ljust(data col width)
     print(row)
```

```
num iterations = len(results[0])
#prints table headings
print('\t'.rjust(title col width) +
   'All Problems'.ljust(data col width) +
   'Successes'.ljust(data col width) +
   'Failures'.ljust(data col width))
#print total iterations
print_data_row('Iterations:',
         '{count:.0f}',
         lambda x: {'count': len(x)},
         results)
#print rates in percentages for success and failure
print data row('Percentage:',
         '{percent:.1%}',
         lambda x: {'percent': len(x) / num_iterations},
         results)
#print Average steps for success and failure
print data row('Average Steps:',
         '{avg:.0f}',
         lambda x: avg_steps(x, 'path_length'),
         results)
#print (results['restarts'])
#if 'total nodes' in results[0][0].keys():
   print data row('Average nodes generated:',
#
             '{avg:.0f}',
#
             lambda x: avg steps(x, 'total nodes'),
#
             results)
```

```
#prints results
def print results(results):
  print data(results)
#function takes problem set and calls passed (parameter) search function and calculates
steps
def analyze performance(problem set, search function):
  num_iterations = len(problem set)
  restart = 0
  results = []
  for problem num, problem in enumerate(problem set):
     #printing 3 search sequence from 3 randon initial configurations
     if problem num == 0 or problem num == 1 or problem num == 2:
       print("Interation :" + str(problem num + 1))
     result = search function(problem, problem num)
     result['path length'] = len(result['solution'])-1
     restart += int(result['restarts'])
    results.append(result)
  print(' '*50 + '\r', end=", flush=True)
  print('\n')
  print ("Average Random Restart Required:"+ str((restart + freq) / int(freq)) + '\n')
  results = [results,
         [result for result in results if result['outcome'] == 'success'],
         [result for result in results if result['outcome'] == 'failure']]
  print results(results)
```

```
#function to solve problem using steepest ascent, steepest ascent (100 sideways moves),
random restart, randon restart (100 sideways moves)
def analyze all algorithms(problem set):
  section break = \frac{n' + ' *100 + n'}{n'}
  print(section break)
  print('Steepest ascent hill climb (no sideways moves allowed):\n')
  analyze performance(problem set, steepest ascent hill climb)
  print(section break)
  print('Steepest ascent hill climb (up to 100 sideways moves allowed):\n')
  analyze performance(problem set, lambda x, y: steepest ascent hill climb(x, y,
allow sideways=True))
  print(section break)
  print('Random restart hill climb:\n')
  analyze performance(problem set, lambda x, y:
random restart hill climb(problem set[0]. class , y))
  print(section break)
  print('Random restart hill climb (up to 100 sideways moves allowed):\n')
  analyze performance(problem set, lambda x, y:
random restart hill climb(problem set[0]. class , y, allow sideways=True))
  print(section break)
print('N-QUEENS PROBLEMS BY HILL CLIMBING:')
#number of iterations input from user
freq=int(input("Enter Number of iterations:"))
n=int(input('Enter Number of queens:'))
```

```
#QueensProblem to generate random queen state and calculate heuristic queens_problem_set = [QueensProblem() for _ in range(freq)] analyze_all_algorithms(queens_problem_set)
```

#### 2. Queens.py

```
from random import randrange
from copy import deepcopy
from heapq import heappop, heappush
from timeit import default timer as timer
from random import choice, shuffle, random
from math import exp
from search import steepest ascent hill climb
class QueensState:
  instance\_counter = 0
  #default constructor for QueensState
  def init (self, queen positions=None, queen num=8, parent=None, path cost=0,
f cost=0, side length=8):
    self.side length = side length
    if queen_positions is None:
       self.queen num = queen num
       self.queen positions = frozenset(self.random position())
    else:
       self.queen positions = frozenset(queen positions)
```

```
self.queen num = len(self.queen positions)
    #print
#print (self.queen positions)
    self.path cost = 0
    self.f cost = f cost
    self.parent = parent
    self.id = QueensState.instance counter
    QueensState.instance counter += 1
  #placing each queens in a random row in a different column
  def random position(self):
    open columns = list(range(self.side length))
    queen positions = [(open columns.pop(randrange(len(open columns))),
randrange(self.side length)) for in
               range(self.queen num)]
    return queen positions
  #fetching all the possible queen moves
  def get children(self):
    children = []
    parent queen positions = list(self.queen positions)
    for queen index, queen in enumerate(parent queen positions):
      new positions = [(queen[0], row) for row in range(self.side length) if row !=
queen[1]]
      for new position in new positions:
         queen positions = deepcopy(parent queen positions)
         queen positions[queen index] = new position
         children.append(QueensState(queen positions))
    return children
  #selecting randon child for allow sideways move algorithm
```

```
def random child(self):
     queen positions = list(self.queen positions)
     random queen index = randrange(len(self.queen positions))
     queen positions[random queen index] =
(queen positions[random queen index][0],
       choice([row for row in range(self.side length) if row !=
queen positions[random queen index][1]]))
     return QueensState(queen_positions)
  #function to check for attacking queens
  def queen attacks(self):
     def range between(a, b):
       if a > b:
          return range(a-1, b, -1)
       elif a < b:
          return range(a+1, b)
       else:
          return [a]
     def zip repeat(a, b):
       if len(a) == 1:
          a = a*len(b)
       elif len(b) == 1:
          b = b*len(a)
       return zip(a, b)
     def points between(a, b):
       return zip repeat(list(range between(a[0], b[0])), list(range between(a[1], b[1])))
     def is attacking(queens, a, b):
```

```
if (a[0] == b[0]) or (a[1] == b[1]) or (abs(a[0]-b[0]) == abs(a[1] - b[1])):
          for between in points between(a, b):
            if between in queens:
               return False
          return True
       else:
          return False
     attacking pairs = []
     queen positions = list(self.queen positions)
     left to check = deepcopy(queen positions)
     while left to check:
       a = left to check.pop()
       for b in left to check:
          if is attacking(queen positions, a, b):
            attacking pairs.append([a, b])
    return attacking pairs
  #reporting violations
  def num_queen_attacks(self):
     return len(self.queen attacks())
  def str (self):
    return '\n'.join([' '.join(['.' if (col, row) not in self.queen positions else '*' for col in
range(
       self.side length)]) for row in range(self.side length)])
  def hash (self):
    return hash(self.queen positions)
  def eq (self, other):
```

```
return self.queen positions == other.queen positions
  def lt (self, other):
    return self.f_cost < other.f_cost or (self.f_cost == other.f_cost and self.id > other.id)
class QueensProblem:
  #default constructor for initail board
  def __init__(self, start_state=None):
     if not start_state:
       start state = QueensState()
     self.start_state = start_state
  #check if goal sate is attained
  def goal_test(self, state):
    return state.num_queen_attacks() == 0
  #calculate number of violations
  def cost_function(self, state):
    return state.num_queen_attacks()
```

## 3. search.py

```
from random import choice, random
from math import exp
from heapq import heappop, heappush
#steepest ascent hill climbing with and without sideways moves
def steepest ascent hill climb(problem, problem num, allow sideways=False,
max sideways=100):
  #funtion to get next best state (queen move)
  def get best child(node, problem):
     children = node.get children()
    children cost = [problem.cost function(child) for child in children]
    min cost = min(children cost)
    best child = choice([child for child index, child in enumerate(children) if
children cost[
       child index] == min_cost])
    return best child
  node = problem.start state
  node cost = problem.cost function(node)
  path = []
  sideways moves = 0
  while True:
    #print 3 search sequence from 3 randon initial configurations
    #uncomment to print path
    if problem num == 0 or problem num == 1 or problem num == 2:
       print (node)
       print ('\n')
    path.append(node)
```

```
best child = get best child(node, problem)
    best child cost = problem.cost function(best child)
    if best_child_cost > node_cost:
       break
     elif best child cost == node cost:
       if not allow sideways or sideways moves == max sideways:
         break
       else:
         sideways moves += 1
     else:
       sideways\_moves = 0
    node = best child
    node cost = best child cost
  return {'outcome': 'success' if problem.goal_test(node) else 'failure',
       'solution': path,
       'problem': problem,
       'restarts': 0}
#random restart hill climbing with and without sideways moves
def random restart hill climb(random problem generator, problem num,
num restarts=100, allow sideways=False, max sideways=100):
  path = []
  restarts = 0
  for _ in range(num_restarts):
    result = steepest ascent hill climb(random problem generator(), problem num,
allow sideways=allow sideways,
```

```
max_sideways=max_sideways)
path += result['solution']
#counter to count randon restart
if result['outcome'] == 'failure':
    restarts += 1
if result['outcome'] == 'success':
    break

result['solution'] = path
result['restarts'] = restarts
return result
```

## **Sample Output:**

- 1. For 100 iteration, please see the file "Output for 100 iteration" in this folder.
- 2. For 200 iteration, please see the file "Output for 200 iteration" in this folder.
- 3. For 300 iteration, please see the file "Output for 300 iteration" in this folder.
- 4. For 400 iteration, please see the file "Output for 400 iteration" in this folder.
- 5. For 500 iteration, please see the file "Output for 500 iteration" in this folder.

### 3.1 References

- <a href="https://en.wikipedia.org/wiki/Hill\_climbing">https://en.wikipedia.org/wiki/Hill\_climbing</a>
- https://en.wikipedia.org/wiki/Eight\_queens\_puzzle