

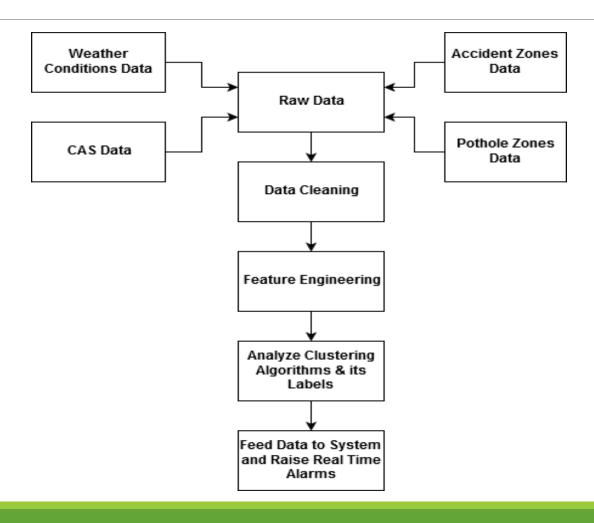




# Driver Profiling and Accident Hotspot Prediction

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#### Architecture



#### Datasets

This information is already provided in the given datasets.

Latitude
Longitude
Location Name
Speed
Time
Alarm Type

They also have crucial effect on accidents and thus we will consider these attributes in our evaluation.

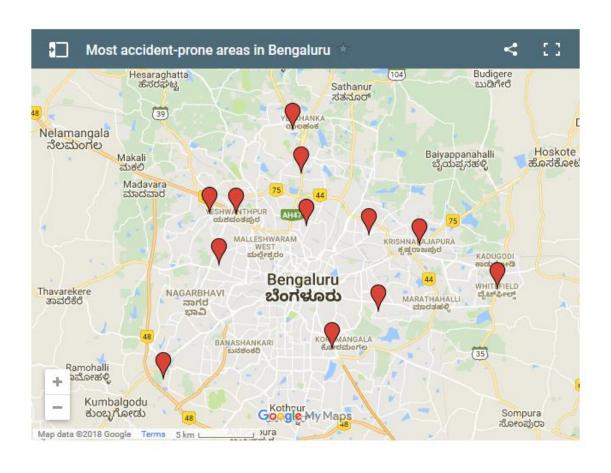


Weather (visibility, sky conditions, etc.)
Peak Hour Timings
Potholes
Accident prone zones

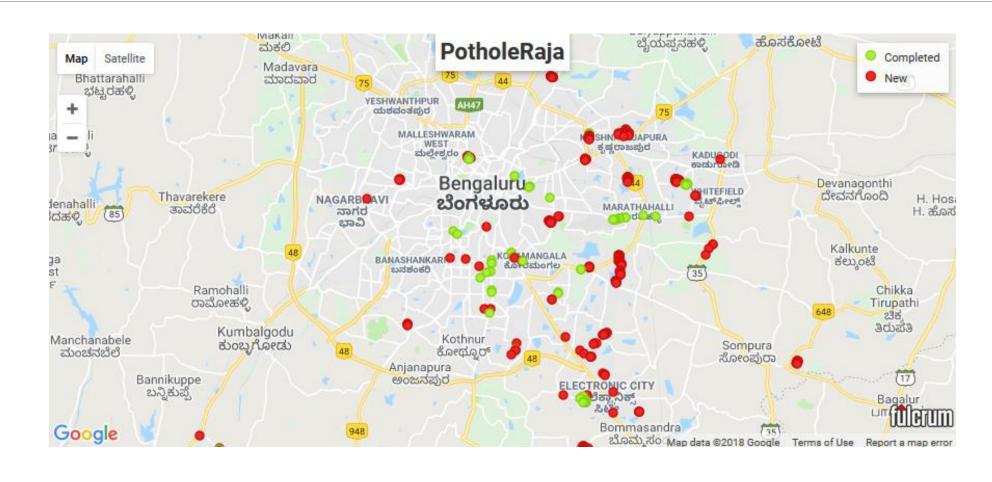
# Scrape Weather Data

	Conditions			Comfort				
Time		Temp	Weather	Wind		Humidity	Barometer	Visibility
<b>14:30</b> Mon, 27 Aug	*	26 °C	Scattered clouds.	19 km/h	1	70%	1009 mbar	8 km
14:00	**	26 °C	Scattered clouds.	15 km/h	$\rightarrow$	70%	1010 mbar	8 km
13:30	*	26 °C	Scattered clouds.	19 km/h	1	70%	1010 mbar	8 km
13:00	<del>-</del>	26 °C	Scattered clouds.	22 km/h	1	65%	1011 mbar	8 km
12:30	*	27 °C	Scattered clouds.	20 km/h	^	62%	1011 mbar	8 km
12:00	<del>*</del>	25 °C	Scattered clouds.	17 km/h	<b>→</b>	69%	1012 mbar	8 km

#### Get Accident Zones Data



#### Get Pothole Zones Data



#### Accident Likelihood Labels

Latitude Longitude **Location Name** Speed Time Alarm Type **Weather Conditions** Peak hour timings **Potholes** Accident prone zones

Evaluate based on clustering algorithms

Labels

High

Low

### Machine Learning Algorithms

Latitude

Longitude

**Location Name** 

Speed

Time

Alarm Type

**Weather Conditions** 

Peak hour timings

**Potholes** 

Accident prone zones



Labels

High

Low



Compare the performance of accident likelihood labelling based on clustering samples

#### Solution

Latitude

Longitude

**Location Name** 

Speed

Time

Alarm Type

**Weather Conditions** 

Peak hour timings

**Potholes** 

Accident prone zones



High Low



ML algorithm training and comparison



Find the best ML solution to predict accident hotspots to raise alarms



## Algorithms Tested

K-Means <= Best Performance
DBSCAN
Gaussian Mixture

Mini Batch K-Means

Birch