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Electromagnetic induction prediction of soil salinity and groundwater properties in a Tunisian Saharan oasis

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Abstract Electromagnetic induction measurements (EM) were taken in a saline gypsiferous soil of the Saharan-climate Fatnassa oasis (Tunisia) to predict the electrical conductivity of saturated soil extract (ECe) and shallow groundwater properties (depth, Dgw, and electrical conductivity, ECgw) using various models. The soil profile was sampled at 0.2 m depth intervals to 1.2 m for physical and chemical analysis. The best input to predict the log-transformed soil salinity (lnECe) in surface (0–0.2 m) soil was the EMh/EMv ratio. For the 0–0.6 m soil depth interval, the performance of multiple linear regression (MLR) models to predict lnECe was weaker using data collected over various seasons and years ($R_a^2 = 0.66$ and $MSE = 0.083 \text{ dS m}^{-1}$) as compared to those collected during the same period ($R_a^2 = 0.97$, $MSE = 0.007 \text{ dS m}^{-1}$). For similar seasonal conditions, for the Dgw–EMv relationship, R^2 was 0.88 and the MSE was 0.02 m for Dgw prediction. For a validation subset, the R^2 was 0.85 and the MSE was 0.03 m. Soil salinity was predicted more accurately when groundwater properties were used instead of soil moisture with EM variables as input in the MLR.

Key words electromagnetic induction; ground conductivity meter EM38; soil salinity; oasis; gypsiferous soil; water table

Estimation de la salinité des sols et des propriétés de la nappe par induction électromagnétique dans une oasis du Sahara tunisien

Résumé Des mesures par induction électromagnétique (EM) ont été réalisées sur des sols gypso-salins de l'oasis à climat saharien de Fatnassa (Tunisie) pour estimer la conductivité électrique de l'extrait de la pâte saturée du sol (CEe) et les propriétés de la nappe superficielle (profondeur, Dgw, et conductivité électrique, ECgw) à l'aide de différents modèles. Des échantillons de sol ont été prélevés tous les 0,2 m jusqu'à une profondeur de 1,2 m pour des analyses physico-chimiques. La meilleure variable indépendante pour estimer la transformée logarithmique de la salinité des sols (ln CEe) à la surface du sol (0–0,2 m) était le rapport EMh/EMv. Pour l'horizon du sol 0–0,6 m, la performance de la régression linéaire multiple (RLM) pour estimer ln CEe était plus faible en utilisant des mesures collectées pour différentes saisons et années ($R_a^2 = 0,66$; EQM = 0,083 dS m⁻¹) plutôt que celles collectées durant la même campagne de mesure ($R_a^2 = 0,97$; EQM = 0,007 dS m⁻¹). En utilisant des mesures réalisées durant des saisons similaires, le R^2 de la relation Dgw–EMv était égal à 0,88 et l'erreur quadratique moyenne (EQM) était de 0,02 m pour l'estimation de Dgw. Pour la phase de validation, le R^2 était de 0,85 et l'EQM sur la prédiction de Dgw était de 0,03 m. Une meilleure précision était obtenue par la RLM lorsque les propriétés de la nappe superficielle ont été utilisées au lieu de la teneur en eau du sol avec les variables EM comme variables indépendantes pour estimer la salinité du sol.

Mots clefs induction électromagnétique; EM38; salinité du sol; oasis; sol gypseux; nappe

1 INTRODUCTION

Gypsiferous soils cover 9.3% of Tunisia and are mainly located in the south where rainfall is less than 250 mm year⁻¹. In southern Tunisia, the soils of most oases are gypsiferous. The physical, chemical and thermal properties of gypsiferous soil are different from those of other mineral soils (FAO 1990, Bouksila *et al.* 2008), as gypsum is a soluble salt (hydrous calcium sulphate, CaSO₄·2H₂O) containing 20.9% water. In arid and semi-arid regions, irrigation is often associated with increased risks for water logging and soil salinization (e.g. Masoud and Koike 2006, Gugesarajah *et al.* 2007). In Tunisia, about 36% of the irrigated areas are highly sensitive to salinization (DGACTA 2007). In Tunisian oases, poor soil and water management has reduced soil quality and agricultural production (CRUESI 1970). To prevent further soil degradation, soil salinity monitoring is essential so that proper and timely decisions regarding soil management can be made. For this purpose, precision agriculture can be used. The EM38 ground conductivity meter (Geonics Ltd, Canada) is considered one of the best tools for the appraisal of soil salinity in a geospatial context (Corwin and Lesch 2003, 2005). By using electromagnetic induction, non-invasive, rapid response and real-time measurements of apparent soil electrical conductivity (ECa) can be made. The EM38 is designed to estimate salinity in the root zone. It has an intercoil spacing of 1 m, which results in a penetration depth of about 0.75 and 1.5 m in the horizontal and vertical dipole orientations, respectively (Corwin and Lesch 2003).

Several factors influence ECa measurements, including soil salinity, water content, porosity, structure, temperature, clay content, mineralogy, cation exchange capacity and bulk density (e.g. McNeill 1980, Malicki *et al.* 1989, Persson and Berndtsson 1998, Rhoades *et al.* 1999, Doolittle *et al.* 2000, Brevik and Fenton 2002, 2004, Friedman 2005, Brevik *et al.* 2006, Corwin *et al.* 2006, Weller *et al.* 2007, Saey *et al.* 2009, Hossain *et al.* 2010, Zhu *et al.* 2010). Measurement by EM38 for soil salinity appraisal should be calibrated against the standard electrical conductivity of a saturated soil extract (ECe), which is used in salt-tolerance plant studies. The relationship between ECa and ECe is soil-specific, and for an accurate calibration, measurements of ECa are preferably made at field capacity (Kachanoski *et al.* 1988, McKenzie *et al.* 1989, Lesch *et al.* 1992, Rhoades *et al.* 1999, Herrero *et al.* 2003, Brevik *et al.* 2006). The water table is

assumed to be at a depth that does not interfere with the electromagnetic induction (EM) measurements (Weller *et al.* 2007), and soil temperature should be recorded for ECa correction (Slavich and Petterson 1990, Doolittle *et al.* 2000, Brevik *et al.* 2004). By taking the initial experimental conditions into account, many models were proposed to calibrate the EM38 measurement with ECe (Slavich and Petterson 1990, Lesch *et al.* 1992, Corwin and Lesch 2003), including simple linear regression (SLR, Slavich and Petterson 1990, Aragüés *et al.* 2004), multiple linear regression (MLR) done with and without consideration of the theoretical EM depth response function (Corwin and Rhoades 1984, Slavich 1990, Rongjiang and Jingsong 2010), and logistic profile models, which involve a mix of empirical and physically-derived coefficients to model the salinity profile (Triantafyllis *et al.* 2000).

It is well established that the shape of the soil salinity profile has a significant impact on EM38 measurements and on the EM–ECe calibrations. For non-uniform soil profiles, a retrieval algorithm based on horizontal and vertical dipole EM measurements (EMh and EMv, respectively) is often used to separate data for EM–ECe calibration. Corwin and Rhoades (1990) found EMh/EMv > 1.05 for inverted profiles (salinity decreasing with depth) and EMh/EMv ≤ 1.05 for normal or leached profiles. Lesch *et al.* (1992) provided a more robust universal calibration approach that does not depend on profile shape. Furthermore, Lesch *et al.* (1995a, 1995b) developed and applied MLR calibration models capable of producing multiple types of soil salinity estimates.

In almost all the references cited above, the soil moisture was considered homogeneous, usually close to the field capacity. Unfortunately, these important conditions for calibrating the EM38 are not satisfied in many situations (e.g. Job 1992, Ceuppens and Wopereis 1999, Brenning *et al.* 2008, Heilig *et al.* 2011). Lesch and Corwin (2003) discussed the effects of measuring in fields with water contents significantly below field capacity. In practice, this can occur due to infrequent irrigation and to poor irrigation uniformity. Hence, Lesch and Corwin (2003) recommend that, when conducting a salinity survey, the minimum water content should be at least 65% of the field capacity whenever possible. In arid and semi-arid regions, the limited quantity of rainfall and water available for irrigation usually explains the large variation in gravimetric soil water content θ (%) between plots (e.g. Job 1992, Sols de Tunisie 1994). However, the standard θ measurement is tedious and

time-consuming. Also, most ECe–EM38 calibration studies were performed in the field on a short time scale under homogenous climatic conditions and land uses. Temporal changes in ECe–EM38 calibrations are not unusual and they reflect the complex dynamics of the EM measurements (Corwin *et al.* 2006, Brenning *et al.* 2008, Aragüés *et al.* 2010).

Some studies have shown the possibility to use the EM38 for monitoring the depth (Dgw) and salinity (ECgw) of shallow groundwaters. A study by Doolittle *et al.* (2000) related ECa to the depth to the water table and changes in soil moisture; the relationships were different in riparian and upland areas. In a humid climate, Sherlock and McDonnell (2003) found a significant correlation between EMv and Dgw ($0.5 < R^2 < 0.9$). Johnson *et al.* (2005) found a highly significant linear correlation between ECgw and EMv ($R^2 = 0.9$). Also, in a saline soil in Western Australia, Silberstein *et al.* (2007) found that EM38 readings and soil salt storage were poorly correlated and that the EMv–Dgw relationship was significant ($R^2 = 0.75$, $P < 0.001$).

According to the research cited above, the relationship between ECe and EM38 readings is well established, and relationships between EM38 readings and groundwater properties (Dgw, ECgw) have also been indicated in recent research. In the present study, we investigate the possibility of using the EM38 to predict field ECe in a Saharan climate oasis with limited water available for irrigation (heterogeneous and non-uniform soil water content) and with gypsiferous soils over shallow and saline groundwater. Field surveys were performed over 4 years (2001–2004) and for different seasons (winter and summer). The objectives of the study were to (a) assess the performance of the EM38 in gypsiferous soils, (b) investigate the robustness of the EM38 for monitoring ECe, and (c) explore the possibility to use the EM38 to predict

groundwater depth (Dgw) and groundwater electrical conductivity (ECgw).

2 MATERIALS AND METHODS

2.1 Experimental site

Experiments were conducted in the irrigated area of Fatnassa, an ancient oasis located at $33^{\circ}47'26.6''\text{N}$, $8^{\circ}44'11.2''\text{E}$ (about 500 km south of Tunis, Tunisia). The oasis altitude varies from 24 m a.s.l. in the north to 17 m a.s.l. in the south and the land slope is about 3 to 5 per 1000. In the northeast, the oasis is delimited by Fatnassa village and in the southwest by Chott El Jerid (Fig. 1), a natural salt depression (below sea level) which constitutes the only natural drainage outlet in this region. The bioclimatic classification is Saharan. The rainfall is irregular and low ($<100 \text{ mm year}^{-1}$) and the potential evapotranspiration is about $2500 \text{ mm year}^{-1}$ (Bahri *et al.* 2004). The study was conducted in the northern part of Fatnassa oasis, which covers 114 ha. The oasis contains 467 farming plots with an average surface of 0.25 ha (Ben Aïssa *et al.* 2005). The farming system is essentially composed of two traditional crop layers, with date palms and fodder crops constituting the principal and second crop layers, respectively. The soil texture is coarse and the soils are classified as Gypsic aridisol. Before 2000, irrigation water was distributed through dug canals and drainage was mainly supplied by open ditches. Currently, a water tower (Fig. 1) allows water transport by gravity through three open concrete channels to the farms. Surface irrigation by flooding is still the main irrigation system used in the oasis. A water rota is organized within the fields, relying on each of the three open water channels that serve three irrigated sectors in the oasis. The duration of a water turn can be up to 25 days, due to both poor

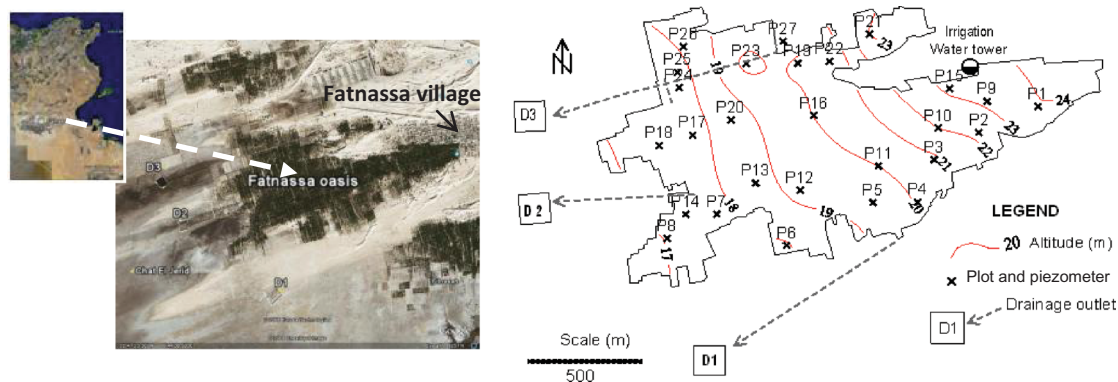


Fig. 1 Study area and sampling locations.

irrigation management and the uncontrolled expansion of date palm plantations (Omrani 2002). The present drainage system is composed of collectors and tile drains buried at about 1.5 m depth with 100 m spacing between drains. Because of the low slope to the natural drainage outlet (Chott El Jerid), the drain collectors (D1, D2 and D3) lead to a deep open artificial pond (Fig. 1). The irrigation and drainage system was restored between November 2000 and July 2002 (SAPI study team 2005). To reduce the impact of high soil salinity on fodder plants, farmers apply sand and organic matter as soil amendments (Omrani 2002). Due to the climatic conditions, the irrigation system (water rota) and the great variation in agricultural management by farmers, the soil moisture (θ) and groundwater properties (Dgw, ECgw) vary widely over the experimental area and by time of measurement (Bahri *et al.* 2004).

2.2 Data collection

An experimental network system of 27 agricultural plots was chosen for monitoring soil properties and groundwater (θ , ECa, ECe, Dgw and ECgw). Measurements were made over 4 years (2001–2004) on 12 dates (March, April, August and October 2001; March, July, September and November 2002; January, March and July 2003; and March 2004). Coordinates (x , y) and altitude (z) for the 27 plots were measured by GPS (Trimble, model 4600LS) with an accuracy of 0.01 m for x and y and 0.02 m for z . Over the period 2001–2004, four samples of irrigation water were collected for analysis. The average electrical conductivity of the irrigation water is about 3.7 dS m^{-1} , $\text{pH} = 7.7$ and the sodium adsorption ratio $\text{SAR} = 4.9$.

2.2.1 Groundwater measurements Twenty-seven (27) observation piezometers were installed to a depth of 2.5 m in the Fatnassa oasis (Fig. 1). Piezometers were used for measurements of Dgw and for sampling groundwater for chemical analysis (ECgw, pH, anions and cations). The altitude was used to calculate piezometric level ($\text{PL} = \text{plot altitude} - \text{Dgw}$).

2.2.2 Soil sampling At each of the 27 piezometers sites, the soil was sampled at 0.2 m depth intervals to 1.2 m. Due to the labour-intensive nature of soil sampling, the samples were only taken at an average of about nine of the 27 plots

on each sampling date. In total, about 630 soil samples were collected from 105 soil profiles. To avoid dehydration of soil gypsum, the samples were dried in a ventilated oven at 50°C for a minimum of two days until the soil weight became constant. After that, the soil properties were measured. For the first date of experiment (March 2001), for each of the 27 plots and six soil depths (0 to 1.2 m), the soil particle size was determined and the percentage of gypsum analysed according to the FAO (1990) method. Because of the coarse soil texture and the occurrence of clay flocculation in gypsiferous soils, eight sieves with different diameters (1, 0.5, 0.25, 0.2, 0.149, 0.105, 0.063 and 0.05 mm) were used to determine the soil particle size fraction. Soil samples collected over the 12 dates (2001–2004) were used for laboratory determination of the ECe and physical soil properties, such as soil moisture (θ) and water content at saturation (PS).

2.2.3 EM38 measurements The EM38 was used to estimate salinity in the root zone. Measurements were taken at the surface of the soil and the receiving end was aligned in four directions (N, NE, S and SE) in both horizontal (EMh) and vertical (EMv) coil mode configurations (at the location of each piezometer plot). Consequently, for each coil mode configuration, the EMh or EMv measurements were the average of four measurements. For each of the 27 plots, EM readings were taken during all 12 surveys. The most extremely saline profiles ($\text{ECe} > 40 \text{ dS m}^{-1}$) were omitted from further analysis because it was desired to only include profiles within the plant response range (Slavich 1990). These extremely saline profiles were observed on 11 dates in two more-or-less abandoned plots (P11, P27, see Fig. 1), where the average ECe at 0–0.4 m soil depth was 54 dS m^{-1} and at 0.2 m soil depth at plot P11 it was 115 dS m^{-1} . Therefore, of the 105 soil sampling profiles only 94 were used for ECe calibration. During the field visits it was found that some piezometers were degraded or destroyed and could thus not be read. Therefore, only 87 and 73 measurements of Dgw and ECgw, respectively, were achieved (Table 1).

2.3 ECe models

To predict ECe from the EM38 readings, soil and groundwater properties, three methods were compared. In the first method, used in Tunisia since the 1980s (Job and Marai 1990, Job 1992, Sols de

Table 1 Summary statistics of soil properties at various soil depths, groundwater properties, and EM38 measurements collected in various seasons and years (2001–2004). *N*: number of observations.

Parameter		<i>N</i>	Minimum	Maximum	Mean	Median	CV(%)
0–0.2 m	Gypsum (%)	27	40	69	57	59	11
	θ (%)	94	3	35	15	15	46
	ECe (dS m ⁻¹)	94	3.28	37.70	7.53	5.14	94
0.2–0.4	Gypsum (%)	27	31	70	61	62	14
	θ (%)	94	4	39	18	18	45
	ECe (dS m ⁻¹)	94	3.24	23.50	7.13	5.20	62
0.4–0.6	Gypsum (%)	27	28	78	61	66	21
	θ (%)	94	6	49	22	22	45
	ECe (dS m ⁻¹)	94	3.13	27.70	8.04	6.18	60
0.6–0.8	Gypsum (%)	27	21	78	63	66	22
	θ (%)	94	8	46	24	23	38
	ECe (dS m ⁻¹)	94	3.80	20.90	9.25	8.25	49
0.8–1.0	Gypsum (%)	27	39	72	64	67	13
	θ (%)	94	10	47	26	25	35
	ECe (dS m ⁻¹)	94	3.84	25.00	10.43	9.72	46
1.0–1.2	Gypsum (%)	27	48	78	66	64	13
	θ (%)	94	8	52	27	27	35
	ECe (dS m ⁻¹)	94	3.66	23.00	11.05	10.38	41
Groundwater	Dgw (m)	87	0.31	2.27	1.23	1.14	38
	PL (m)	87	16.08	23.09	19.36	19.17	11
	ECgw (dS m ⁻¹)	73	4.73	41.20	15.12	15.03	41
EM38	EMh (dS m ⁻¹)	94	0.255	2.705	0.945	0.756	59
	EMv (dS m ⁻¹)	94	0.460	3.025	1.304	1.205	44
	EMh/EMv	94	0.480	1.107	0.690	0.653	19

Tunisie 1994), ECe is calculated from the predictors EMh and θ . The second method, developed by Lesch *et al.* (2000), uses the spatial coordinates (x, y) and EM38 readings in a multiple linear regression (MLR) model. The third method applies a sensitivity test to find the best MLR model to predict field ECe (Bouksila *et al.* 2010). In the following, the three methods are referred to as the Job, Lesch and Bouksila models, respectively.

2.3.1 ECe prediction with the Job model In arid irrigated land, soil moisture content is highly variable and its impact cannot be neglected when taking EM readings. In these situations, ECe is usually better estimated using both EM and θ . To avoid the colinearity between EMh and θ , EMh readings were converted to EMh at reference θ , according to (Job 1992):

$$ECe = aEMh(\theta_2) + b \quad (1)$$

$$EMh(\theta_2) = EMh(\theta_1) + \delta(\theta_2 - \theta_1) \quad (2)$$

where EMh(θ_2) is the EMh expressed at the reference soil water field capacity (θ_2 , %), EMh(θ_1) is the EM reading relative to the field soil moisture θ_1 , and δ is an empirical parameter depending mainly on soil type.

For several types of soils in Tunisia, the empirical parameter (δ) was found to be 5.4 (Hachicha and Job 1994), a typical value that fits most soils. In El Guettar oasis (in the south of Tunisia), characterized by similar soil properties to Fatnassa (sandy gypsiferous soil, $5 \leq \theta(\%) \leq 31$ and $2 \leq ECe \text{ (dS m}^{-1}\text{)} \leq 45$), the empirical parameter δ was equal to 5.12 (Sols de Tunisie 1994). In the analysis we used both of these δ values in equation (1). Since θ also is used to predict ECe, equation (1) was considered an MLR model.

2.3.2 ECe prediction with the Lesch model

The calibration equation for converting EM38 readings (EMh and EMv) into ECe values was obtained using a stochastic calibration model which is a spatially-referenced MLR model (Lesch *et al.* 2000). In the regression equation, transformed and

decorrelated signal data (i.e. the principal component scores), rather than raw signal readings, were used as predictor variables. The decorrelation procedure was used to eliminate colinearity between the EM readings, and scaling techniques of the trend surface parameters were used to increase the accuracy of predictions (Lesch *et al.* 1995b). For that, natural log-transformed variables were used (lnEMh, lnEMv, lnECe). The MLR model included the EM38 readings and spatial coordinates (x , y) of each survey site. The following regression model was used (Lesch *et al.* 2000):

$$\ln \text{ECe} = \beta_0 + \beta_1(Z_1) + b_2(Z_2) + b_3X + b_4Y \quad (3)$$

where Z_1 and Z_2 are the decorrelated signal readings (principal component scores), X and Y are the scaled spatial coordinates of each survey point, and β_i and b_i are empirical parameters. The EMh and EMv readings were converted to Z_1 and Z_2 using the following transformation:

$$Z_1 = a_1[\ln \text{EMv} - \text{mean}(\ln \text{EMv})] + a_2[\ln \text{EMh} - \text{mean}(\ln \text{EMh})] \quad (4)$$

$$Z_2 = a_3[\ln \text{EMv} - \text{mean}(\ln \text{EMv})] + a_4[\ln \text{EMh} - \text{mean}(\ln \text{EMh})] \quad (5)$$

where a_1 , a_2 , a_3 and a_4 are determined by the principal component algorithm.

The first principal component score (Z_1) is an approximate average of the two EM readings at each survey point and the second principal component score (Z_2) represents a weighted linear contrast between the two readings (Lesch *et al.* 1995a). The spatial coordinates of the EM38 data were centred and scaled as follows:

$$X = [x - \min(x)]/k \quad (6)$$

$$Y = [y - \min(y)]/k$$

where k is greater than $[\max(x) - \min(x)]$ or $[\max(y) - \min(y)]$.

2.3.3 ECe prediction with the Bouksila model Since colinearity between EMh and EMv is a constraint when computing the regressions of the ECe–EM38 relationships, we explored the retrieval algorithm based on EM measurements. Inspired by Lesch *et al.* (1995a, 1995b, 2000, 2005), the retrieval

algorithm based on EM measurements was used as input candidate variables instead of EMv or EMh (e.g. $(\ln \text{EMh} - \ln \text{EMv})$, $\text{EMh} - \text{EMv}$, $(\text{EMh} + \text{EMv})/2$, $(\text{EMv} - \text{EMh})/2$, $\text{EMh}/(\text{EMv} - \text{EMh})$, EMh/EMv). Also, the Z_1 , Z_2 , X and Y variables (equations (4)–(6)) were used with EMh and EMv to find the best MLR model. To eliminate any colinearity between groundwater properties (Dgw, ECgw) and EM readings, the retrieval algorithm (ECgw/Dgw, centred and scaled, standardized Dgw, etc.) and decorrelated data (using principal component scores instead of the observed Dgw and ECgw data) were used as predictors with the EM variables. Thus, the principal component scores for the Dgw and ECgw were denoted PCgw ($= \varphi \text{Dgw} + \tau \text{ECgw}$).

To predict ECe using the EM readings and soil and groundwater properties, the first step was to select the best input variables for the MLR. This was done by selecting an SLR model between the EM38 readings and each predictor. The goal of the SLR analysis was to avoid any dependency between the predictor variables, and to detect potential parameters that may affect the EM readings and that could be used together with the EM observations to predict the ECe using an MLR model. Three groups of independent variables were used in the MLR models: (a) EM readings and their retrieval algorithms, (b) centred and scaled plot coordinates and altitude together with the EM variables, and (c) groundwater and soil properties together with group (b) predictors to estimate the field soil salinity (ECe).

The Statgraphics 5 Plus software (Manugistics, Inc., Bethesda, MD, USA) was used to find the best model to estimate soil salinity (ECe). For linear models, the software uses the least square or resistant estimation procedure (Statgraphics manual). The best SLR model to predict soil salinity was obtained by comparing the coefficient of determination R^2 and mean square error (MSE) of 27 linear models. The best SLR models were not necessarily mathematically linear (e.g. exponential, squared, multiplicative variables were used). For the MLR model, the software uses all combinations of input variables and calculates R^2 , adjusted R^2 (R_a^2) and MSE. The best models will have a minimum MSE and maximum R_a^2 . The regression models were computed to predict the soil salinity at six successive soil depths (the ECe at depth intervals of 0–0.2, 0–0.4, 0–0.6, 0–0.8, 0–1.0 and 0–1.2 m), as well as the entire salinity profile (six different ECe values between 0.2 and 1.2 m at 0.2 m intervals). To explore the impact of the measurement time (including changes in land

use, soil management, climatic condition, etc.), the performance of the ECe–EM38 relationship was computed and compared using separate validation data collected in various seasons and years (e.g. all data 2001–2004, only March 2001–2004, March 2002/03, March 2001).

2.4 Prediction of groundwater properties from EM38 reading

The groundwater properties (Dgw, ECgw) were estimated from EM38 reading (EMh or EMv) or its retrieval algorithm. For this, only an SLR model was used. The methodology described above used to predict ECe was also used to find the best SLR model to predict groundwater properties.

3 RESULTS AND DISCUSSION

3.1 Exploratory data analysis

Tables 1 and 2 show descriptive statistics of soil measurements at various depths, groundwater properties (Dgw, ECgw) and EM readings for different periods. The average soil sand content at the 0–1.2 m soil depth interval in the study area is about 99% and the gypsum content is about 62%. The soil moisture

profile was very heterogeneous varying from very dry to saturation (from 3 to 52%) which could affect the EM readings. The ECe varied from 3 to 38 dS m⁻¹ and the coefficient of variation of the mean (CV) decreased from 94% at 0.2 m to 41% at larger depths. The Kolmogorov-Smirnov test rejected the test of normal distribution of ECe for all soil depths. Therefore, the log-transformed variables were used for ECe data to give a Gaussian distribution of soil salinity (Herrero *et al.* 2003). The average gypsum content and soil saturation (saturation percentage, SP) varied from 56 to 66% (CV ≤ 22%) and from 42 to 45% (CV ≤ 17%), respectively. Similar to results by Corwin *et al.* (2006), gypsum content and SP were not correlated with EM measurement ($R < 0.35$).

The range in groundwater properties reflects the important variability in water management and drainage efficiency for different seasons. The average Dgw was 1.23 m and ECgw was 15 dS m⁻¹. Thus, the shallow and saline groundwater affects the water content and salinity profile and therefore the EM signal. The correlation coefficients R of the Dgw–EMv and ECgw–EMv relationships were equal to -0.64 ($P < 0.001$) and 0.37 ($P < 0.01$), respectively. Therefore, the observed groundwater properties cannot be used with EM readings in the MLR model to predict ECe.

Table 2 Summary statistics of soil properties for 0–0.6 and 0–1.2 m soil depths, groundwater properties, and EM38 readings collected during different March visits. N : number of observations.

Date	Parameter	0–0.6 m		0–1.2 m		EM38		Groundwater	
		θ	ECe	θ	ECe	EMh	EMv	Dgw	ECgw
Mar 2001 $N = 10$	Minimum	11	3.70	12	4.34	0.26	0.50	0.35	8.44
	Maximum	34	23.18	35	17.36	2.25	2.45	2.27	41.20
	Average	20	10.17	24	10.55	1.00	1.33	1.30	20.19
	CV (%)	44	66	33	44	74	51	51	47
Mar 2002 $N = 10$ $N(\text{Dgw}) = 9$ $N(\text{ECgw}) = 7$	Minimum	5	4.37	8	4.66	0.28	0.46	0.75	8.14
	Maximum	23	18.85	27	15.63	1.82	1.64	1.93	19.39
	Average	15	7.30	20	8.22	0.83	1.12	1.26	13.61
	CV (%)	40	60	31	41	55	38	34	34
Mar 2003 $N = 9$ $N(\text{Dgw}) = 6$ $N(\text{ECgw}) = 5$	Minimum	6	3.85	9	4.10	0.28	0.48	0.73	8.77
	Maximum	25	10.56	26	13.90	1.46	1.83	1.94	22.60
	Average	13	6.80	16	8.23	0.83	1.21	1.30	14.74
	CV (%)	46	44	34	44	50	41	35	41
Mar 2004 $N = 24$	Minimum	6	3.50	8	3.65	0.43	0.53	0.31	4.73
	Maximum	24	17.16	26	15.65	1.86	2.05	1.43	23.20
	Average	17	5.98	21	7.35	0.94	1.32	0.96	12.76
	CV (%)	43	47	30	35	42	34	28	46
Mar 2001 and 2004 $N = 53$ $N(\text{Dgw}) = 49$ $N(\text{ECgw}) = 46$	Minimum	5	3.50	8	3.65	0.26	0.46	0.31	4.73
	Maximum	34	23.18	35	17.36	2.25	2.45	2.27	41.20
	Average	16	7.16	20	8.27	0.91	1.26	1.13	14.72
	CV (%)	44	60	33	42	53	39	39	49

Also, EMh and EMv were highly correlated ($EMv = 0.98EMh + 0.38$, $R^2 = 0.91$, $P < 0.001$). Therefore, it is necessary to avoid the colinearity between EMh and EMv when predicting ECe.

Four typical salinity profiles were observed: leached, uniform, inverted and heterogeneous. The inverted salinity profiles have an EMh/EMv ratio ≥ 0.9 . This was lower than the 1.05 value proposed by Corwin and Rhoades (1990). According to McNeill (1980), part of the salts present in high-saline surface soils may not be in solution due to low water contents. Thus, these precipitated salts will not contribute to the EM38 readings. Accordingly, for conditions similar to our study, the EMh/EMv ratio should not be used to distinguish the salinity profiles for EM–ECe calibration.

3.2 Soil salinity prediction (ECe)

The soil salinity values (ECe) of the soil profile and of the six successive soil depths were predicted using SLR and MLR models. In the following, MLR1 is the MLR where the predictors are the EM variables and the plot coordinates, MLR2 is the MLR using these same predictors plus the groundwater properties.

3.2.1 Seasonal soil salinity prediction (ECe)

The data used for ECe prediction were collected in different seasons and years (12 dates from winter to summer, 2001–2004). The performance of the different models to predict soil salinity at the six successive soil depths is presented in Fig. 2. For the six soil depths, the performance of the best SLR model to

predict lnECe increased from the surface 0–0.2 m ($R^2 = 0.62$, $MSE = 0.12$ dS m⁻¹) to the deeper soil 0–1.2 m profile ($R^2 = 0.66$, $MSE = 0.07$ dS m⁻¹). For the surface soil layers (0–0.2 and 0.2–0.4 m), the best input for SLR was the ratio EMh/EMv. Indeed, for the 0–0.2 m soil depth interval, R^2 to predict lnECe was 0.53 and 0.62 with the predictors EMh and EMh/EMv ratio, respectively. These results can be explained by the dry soil surface that almost did not contribute to the EM readings, and the high vertical variation of θ due to the presence of a shallow water table. In arid Tunisia, the saline soil profile and the salt accumulation in the upper soil are associated with the presence of a shallow and salty water table (Bahri *et al.* 2004, Bouksila *et al.* 2010), which could explain the performance of the EMh/EMv ratio in predicting the salinity at the surface soil. When EM variables and spatial coordinates (X or/and Y , equation (6)) were used to predict lnECe using the MLR model (MLR1 in Fig. 2), the R_a^2 was 0.61 ($MSE = 0.12$ dS m⁻¹) at 0–0.2 m and increased to 0.67 ($MSE = 0.062$ dS m⁻¹) at 0–1.2 m soil depth. The performance of the MLR1 model was similar to the best SLR model results. The observed groundwater properties were significantly correlated to θ with $P < 0.001$. When the retrieval algorithm of the groundwater properties and the plot coordinate variables were introduced as input candidates together with the EM readings the performance of the lnECe prediction was significantly improved (MLR2 in Fig. 2). Using the MLR2 model to predict lnECe, R_a^2 varied from 0.69 to 0.72 ($P < 0.001$) and MSE from 0.11 to 0.05 dS m⁻¹. Using the Lesch model to predict lnECe (equation (3) in Fig. 2), a

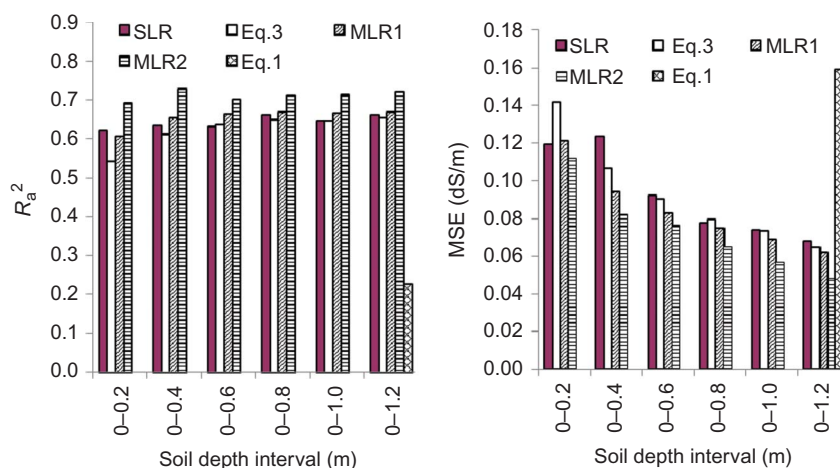


Fig. 2 Adjusted R^2 (R_a^2) and mean square error (MSE) of predicting lnECe observed at various soil depth intervals and seasons (12 dates from 2001 to 2004) with various models (best SLR, equations (1) and (3), and MLR). MLR1: EM variables and plot coordinate as predictors; MLR2: same inputs than MLR1 plus groundwater properties.

significant ($P < 0.001$) and moderately strong relationship was found. At the soil surface (0–0.2 m), R_a^2 was 0.54 and MSE was 0.14 dS m^{-1} and for soil depth interval 0–1.2 m, R_a^2 increased to 0.65 and MSE decreased to 0.06 dS m^{-1} . The performance of the Job model (equation (1) in Fig. 2) to predict ECe at soil depth interval of 0–1.2 m was not so good ($R^2 = 0.25$, $\text{MSE} = 12.75 \text{ dS m}^{-1}$). Because of the poor performance, the Job model is not recommended to predict seasonal lnECe or ECe. In addition to θ and groundwater properties, farm agricultural management (tillage, fertilization, sand amendment, crop cycle, etc.) and climatic conditions could affect the EM readings and therefore the ECe–EM calibration (Brenning *et al.* 2008, Aragüés *et al.* 2010).

3.2.2 Impact of measurement time on soil salinity prediction (ECe) According to the correlation matrix, a strong simple linear correlation was observed between EMh or EMv readings for the various March dates ($0.87 \leq R \leq 0.98$ for EMh and $0.79 \leq R \leq 0.98$ for EMv at $P < 0.001$). According to Brenning *et al.* (2008), time-dependent random effects on EM measurements can be related to crop cultivation or soil moisture variation. In the experimental area, the lowest R value corresponds to the EM readings taken in March 2001 against those taken in the other March periods ($0.79 \leq R \leq 0.87$). This result can be explained by the absence of irrigation during the restoration of the irrigation system in 2001. In March 2001, the salinity profiles were usually inverted, but some farmers used salty drainage water or illegal wells for irrigation (Bahri *et al.* 2004). For 0.2 m soil depth, the correlation coefficient between lnECe and (EMh/EMv) decreased with increases in irrigation ($R = 0.9, 0.78, 0.65$ and 0.47 for March 2001, 2002, 2003 and 2004, respectively). In March 2004, the performance of the ECe–EM relationship was poorer than for the previous March periods (R varied from 0.5 to 0.85). The rainfall at Souk Lahad climatic station (15 km from Fatnassa oasis) was 26.7, 31.2, 144.5 and 69 mm year⁻¹ in 2001, 2002, 2003 and 2004, respectively. The exceptionally high rainfall (103.9 mm) observed during the 6 months before March 2004 (September 2003–February 2004) could have indirectly affected the EM calibration. The rainfall could have caused soil leaching, decreased groundwater depth (average Dgw = 0.96 m) and groundwater salinity (average ECgw = 12.76 dS m^{-1}) (Table 2), decreased soil temperature and improved vegetative soil cover. Also, after this exceptional rainfall event, the variation interval

of both EM readings and ECe was less than before (under normal climate conditions). With lower ECe variation interval, the EM readings could be more affected by other physical or chemical soil properties, surface cover and groundwater properties than by soil salinity. Indeed, the statistics of soil and groundwater properties observed in March 2004 showed the lowest average, CV and range of ECe (Table 2). According to Lesch and Corwin (2003), when the spatial variation in soil salinity decreases and the spatial variation in other soil properties increases, one or more of these other properties (SP, percentage clay, θ) will eventually supersede the soil salinity as the dominant soil property. Furthermore, when the water content drops too far below field capacity, the spatial variation in water content can become the dominant factor influencing the EM data, even in the presence of a large spatial variation in salinity (Lesch and Corwin 2003).

The performance of different models to predict soil salinity at different measurement times and soil depths (0–0.6 and 0–1.2 m) (Fig. 3) corroborates these interpretations. The performance was weaker using data collected over several seasons and years (2001–2004) relative to those collected only during March in different years. The best model to predict lnECe was generally the MLR1 model, followed by the best SLR (equations (3) and (1), respectively). For the four 2001–2004 March visits, R_a^2 of the MLR model was 0.73 ($\text{MSE} = 0.06 \text{ dS m}^{-1}$) at 0–0.6 m (maximum density of forage roots) and 0.76 ($\text{MSE} = 0.04 \text{ dS m}^{-1}$) at 0–1.2 m (maximum density of palm roots). For the 0–1.2 m soil depth interval, R_a^2 decreased to about 0.68 and 0.38 for equations (3) and (1), respectively. It is relevant to indicate that when groundwater properties were not used as predictors, the performance of the best SLR was almost the same as that of the MLR model. By using data collected only for March 2002 and March 2003 (the exceptional March 2001 and March 2004 data were discarded), R_a^2 of the MLR increased to 0.92 ($\text{MSE} = 0.02 \text{ dS m}^{-1}$) for 0–0.6 m and to 0.80 ($\text{MSE} = 0.03 \text{ dS m}^{-1}$) for the 0–1.2 m soil depth interval. Consequently, for better accuracy of soil salinity prediction using the EM38, it is advisable to perform the calibrations for each measurement period. If this is not possible, it could be preferable to use a lnECe–EM calibration for similar periods (such as season or crop cycle). To verify this conclusion and to predict soil salinity using EM38 readings, the data collected in March 2002 were used for calibration and those in March 2003 for validation. The performance (R^2 , MSE) of the three models (best SLR, equations (1) and (3)) to

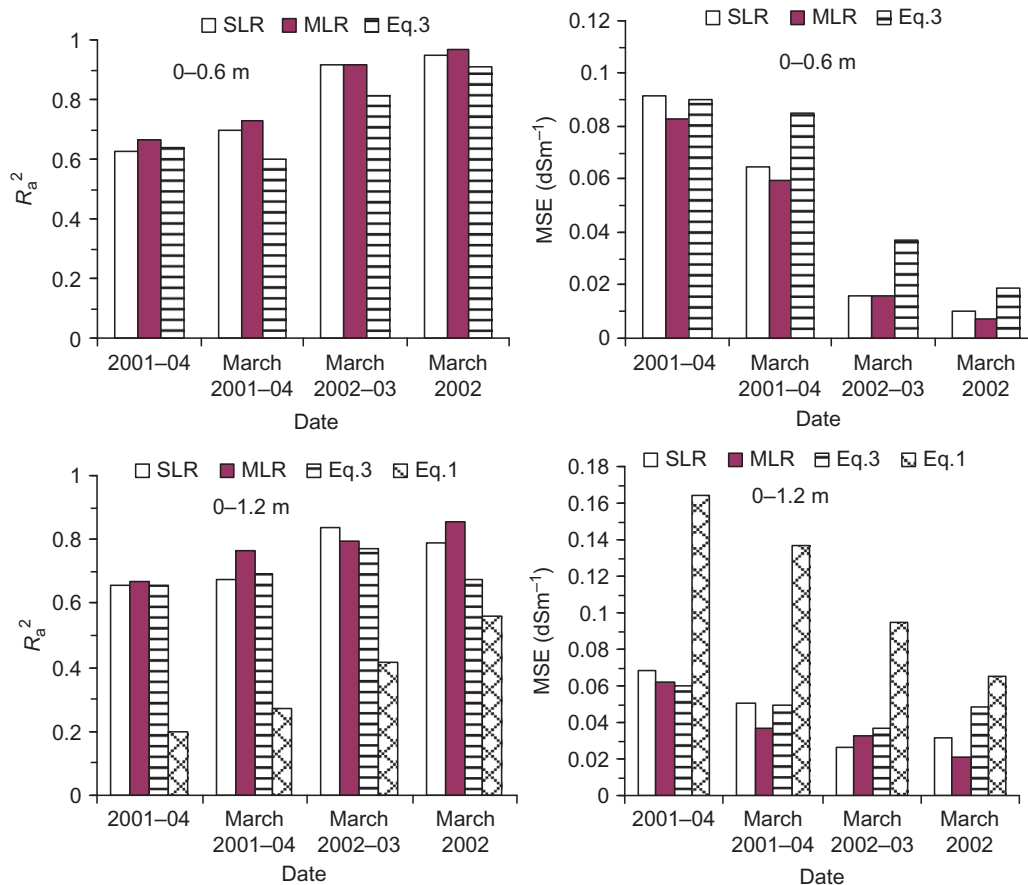


Fig. 3 The R_a^2 and MSE of predicting $\ln EC_e$ at various soil depths and dates of measurement using various models (equations (1) and (3), best SLR and MLR1 models).

predict $\ln EC_e$ at various soil depths and various data subsets (training, validation, total) are presented in Table 3. The best model to predict soil salinity at the different soil depths was SLR, followed by equations (3) and (1). Poorer results were observed for deeper

composite soil depths (0–1.0 and 0–1.2 m), probably due to the impact of the shallow groundwater on EM38 readings. The same trend was observed when equations (1) and (3) were used. Using the Job model to predict $\ln EC_e$ for the 0–1.2 m soil depth

Table 3 Performance of three models (SLR, equations (1) and (3)) to predict the soil salinity ($\ln EC_e$) from EM38 readings.

Soil depth (m)	Model	Training ^(a)		Validation ^(b)		Total ($N = 19$)	
		R^2	MSE	R^2	MSE	R^2	MSE
0–0.2	SLR	0.943	0.022	0.953	0.025	0.925	0.024
0–0.4		0.965	0.009	0.906	0.018	0.939	0.013
0–0.6		0.971	0.005	0.838	0.037	0.897	0.020
0–0.8		0.953	0.008	0.837	0.034	0.887	0.020
0–1.0		0.893	0.015	0.750	0.051	0.807	0.032
0–1.2		0.814	0.025	0.760	0.045	0.780	0.034
0.6–1.2		0.586	0.054	0.805	0.045	0.699	0.050
0–0.6	Equation (3)	0.949	0.015	0.690	0.112	0.820	0.044
0–1.2		0.820	0.040	0.776	0.075	0.792	0.041
0–1.2	Equation (1) ^(c)	0.608	0.052	0.424	0.149	0.405	0.098
0–1.2	Equation (1)	0.689	3.168	0.411	9.820	0.465	6.319

^(a) March 2002, $N = 10$.

^(b) March 2003, $N = 9$.

^(c) Equation (1) applied to predict $\ln EC_e$ instead of EC_e .

interval, a fairly good fit was achieved for the calibration subset, but the model performance decreased for the validation subset (Table 3). According to the results in Table 3, for similar time measurements, the best SLR model can be used with acceptable errors to predict soil salinity.

3.3 Prediction of groundwater properties from EMv readings

The EM38 readings were positively correlated with ECgw, although the R^2 of the ECgw–EMv relationship was low (0.16 and 0.25 using data collected on all 12 dates and the March measurements, respectively). Improvements in ECgw predictions were obtained when the ratio EMh/EMv was used to classify the data in different groups for the SLR model. The best ECgw–EMv relationship was obtained after exceptional events at the time of measurement. Indeed, in March 2001 (absence of irrigation and mainly upward water and salt flow), R^2 was 0.36 and increased to 0.52 in March 2004 (exceptional rainfall, important soil leaching and groundwater dilution). The simple linear regression model was used to predict Dgw from EMv for different time periods and various subsets (calibration and validation) (Fig. 4). The EM38 readings were negatively correlated with Dgw. These results corroborate previous findings for semi-arid conditions (Aragüés *et al.* 2004, Silberstein *et al.* 2007). The observed significant relationships between Dgw and soil properties ($\ln EC_e$,

θ , at $P < 0.001$) showed that in arid climates, shallow groundwater depth could be the major driver of water and solutes towards the soil surface. When the March measurements were used separately, the R^2 of the Dgw–EMv relationship varied (except in the March 2004 measurements) from 0.83 to 0.90 and MSE from 0.02 to 0.08 m (Fig. 4(a)). Using data collected on the four March dates, R^2 was 0.5 (MSE = 0.10 m), and model performance decreased when all 2001–2004 data were used (Fig. 4). Figure 4(b) shows the observed and predicted Dgw for the calibration and validation data subsets, respectively.

In the following, the data corresponding to exceptional events (March 2001 and March 2004) were excluded from the Dgw prediction using the EMv readings. The data collected in March 2002 and March 2003 were used for calibration and validation, respectively. These two measurement dates correspond to almost standard climate and water management conditions in the oasis, and where soil salinity was the result of successive phases of leaching (mainly by irrigation) and accumulation (capillarity rise processes). For the calibration subset, a highly significant ($P < 0.0001$) Dgw–EMv relationship was obtained: $Dgw \text{ (m)} = 3.189 - 1.864\sqrt{EMv \text{ (dS/m)}}$ ($R^2 = 0.90$ and $MSE = 0.017 \text{ m}$). For the validation subset, 85% of the variance was explained by the SLR model, and the MSE of the Dgw prediction was 0.025 m. For the total data (March 2002 and 2003), the R^2 was 0.88 and $MSE = 0.020 \text{ m}$, indicating that it is possible to predict Dgw from EMv readings with acceptable accuracy.

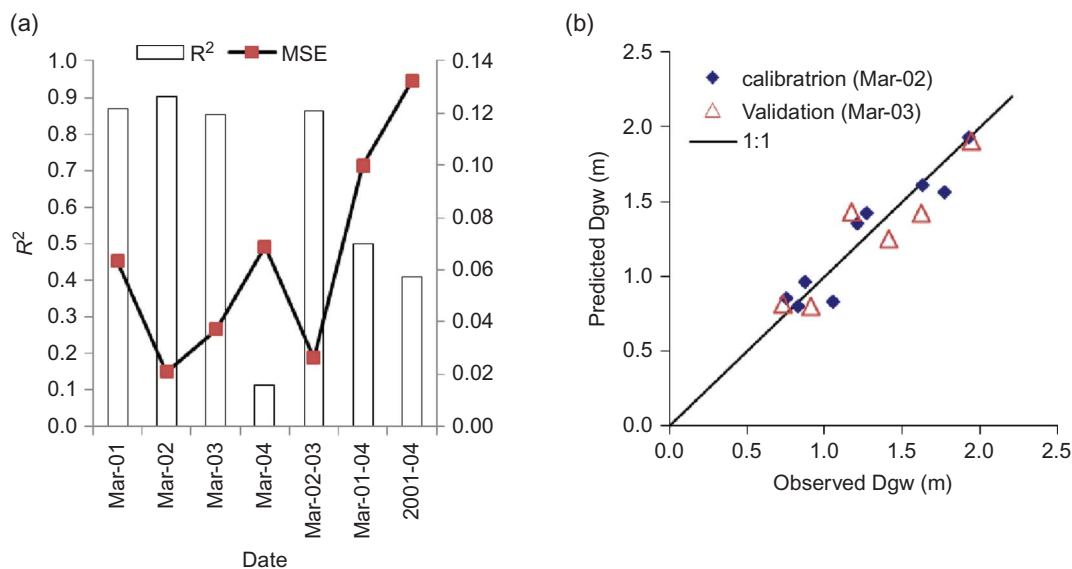


Fig. 4 (a) Performance of the best SLR model to predict Dgw from EMv at various time measurements. (b) Observed and predicted Dgw (m) for calibration (March 2002) and validation (March 2003) subsets.

4 SUMMARY AND CONCLUSIONS

Poor soil and water management results in water logging and soil salinization. This reduces soil quality and agricultural production. Accurate and rapid estimation of soil salinity can be used in precision agriculture to help land developers and farmers make appropriate decisions about crop production and soil and water management. In this study, we investigated the use of EM38 measurements to predict both the electrical conductivity of the saturated soil extract (ECe) and groundwater properties (depth, Dgw and electrical conductivity, ECgw). The study was conducted in the oasis of Fatnassa in southern Tunisia, which is characterized by limited water available for irrigation, gypsiferous soils and shallow and saline groundwater. Soil profiles were sampled at 0.2 m depth intervals to 1.2 m for soil property analysis. The plot spatial coordinates (x , y) and altitude (z) were measured by GPS. Besides soil profile characteristics, Dgw and ECgw were also measured. Groundwater and soil measurements were collected over 4 years (2001–2004) at 12 different periods. The collected data were used to predict soil salinity using different models (SLR, MLR, Job and Lesch).

Gypsum content (59–66%) and soil saturation (PS) did not correlate well with EM measurements ($R < 0.35$). The ratio EMh/EMv was the best independent variable to predict soil surface ECe. When all data collected during various seasons and years were combined, the best model to predict lnECe was the MLR, followed by either the SLR or the Lesch models (depending on the soil depth). Using the MLR models, the R_a^2 varied from 0.61 to 0.67 and the MSE from 0.06 to 0.12 dS m⁻¹.

The performance of all models improved when data were reduced to those collected during the same season (March 2001, 2002, 2003 and 2004). When data corresponding to an exceptional event were discarded from the analysis, a very strong and significant lnECe–EM relationship was obtained. At similar time measurements, the R^2 of the SLR model for the lnECe–EMh relationship was 0.90 (MSE = 0.02 dS m⁻¹) and about 0.78 (MSE = 0.03 dS m⁻¹) for the 0–0.6 m and 0–1.2 m soil depth intervals, respectively. For the validation subset (March 2003 data), R^2 of the lnECe–EMh relationship was 0.84 (MSE = 0.04 dS m⁻¹) and 0.76 (MSE = 0.05 dS m⁻¹) for 0–0.6 m and 0–1.2 m soil depths, respectively.

For various seasons and years, a significant and negative simple linear relationship was obtained

between Dgw, soil properties (ECe and θ) and EM readings. The ECgw was positively but weakly correlated to ECe and EM readings. Over various seasons and years, using the SLR model for the Dgw–EMv relationship gave an R^2 value of 0.41 and MSE of 0.13 m. For seasonal data (March 2002 and 2003), the R^2 value of the Dgw–EMv relationship was 0.88 and MSE was 0.02 m. For the validation subset, 85% of the variance was explained by the SLR model and the MSE for the Dgw prediction was 0.03 m. These results indicate that EM38 readings can be used effectively to predict both soil salinity and groundwater depth in irrigated and arid areas with a shallow water table.

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