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A simplified regional-scale electromagnetic induction — Salinity calibration model using ANOCOVA modeling techniques

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ABSTRACT

Directed soil sampling based on geospatial measurements of apparent soil electrical conductivity (EC_a) is a potential means of characterizing the spatial variability of any soil property that influences EC_a including soil salinity, water content, texture, bulk density, organic matter, and cation exchange capacity. Multi-field EC_a survey data often exhibit abrupt changes in magnitude across field boundaries that complicate the calibration of EC_a to soil salinity (i.e., EC_e, electrical conductivity of the saturation extract) over large spatial extents. The primary objective of this study is to evaluate three regression techniques for calibrating EC_a to EC_e over spatial scales ranging from a few thousand to a hundred thousand hectares, where EC_a was measured using electromagnetic induction equipment. The regression techniques include analysis of covariance (ANOCOVA), field specific regression (FSR), and common coefficient regression (CCR). An evaluation was made by comparing jack-knifed mean square prediction errors (MSPE) of EC_e for two case studies: 2400 ha of the Broadview Water District in California's San Joaquin Valley and roughly 100,000 ha of the west side of Kittson County in the Red River Valley of Minnesota. The ANOCOVA model outperformed the FSR and CCR regression models on a prediction accuracy basis with the smallest MSPE estimates for depth predictions of soil salinity. The implication of this evaluation is that once ANOCOVA models for each depth are established for a representative set of fields within a regional-scale study area, then the slope coefficients can be used at all future fields, thereby significantly reducing the need for ground-truth soil samples at future fields, which substantially reduces labor and cost. Land resource managers, producers, agriculture consultants, extension specialists, and Natural Resource Conservation Service field staff are the beneficiaries of regional-scale maps of soil salinity.

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1. Introduction

The characterization of spatial variability is without question one of the most significant areas of concern in soil science because of its broad reaching influence on field- and landscape-scale processes related to agriculture and the environment, including solute transport, within-field variation in crop yield, and soil salinity accumulation, just to mention a few. Soil salinity accumulation is a major agricultural concern in arid and semi-arid soils throughout the world because it reduces crop yields due to osmotic and specific-ion toxicity effects and impairs soil permeability and tilth. Of the 13.2×10^9 ha of land surface on the earth, only 1.5×10^9 ha is cultivated and 23% of the cultivated land is estimated to be salt-affected, which comprises about 10% of the total arable land (Massoud, 1981). The influence of soil salinity on crop yield is well known in the plant salt tolerance literature (Maas, 1996). Maps of soil salinity assist producers in crop selection, irrigation management, and reclamation. However, spatial variation of dynamic soil properties, such as water content and salinity, are especially challenging to characterize spatially due to their temporal nature and their complex spatial nature.

The geospatial measurement of EC_a is a sensor technology that has played, and continues to play, a major role in addressing the issue of field-scale spatial variability characterization, particularly in mapping soil salinity (Corwin and Lesch, 2005a). Geospatial measurements of EC_a are spatially complex because they reflect the influence of several physical and chemical soil properties, including soil salinity, texture, water content, bulk density, organic matter, and cation exchange capacity. Subsequently, geospatial measurements of EC_a are used to direct soil sampling as a means of characterizing spatial variability of those soil properties that correlate with EC_a at

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that particular study site. Characterizing spatial variability with EC_a-directed soil sampling is based on the notion that when EC_a correlates with a soil property or properties, then spatial EC_a information can be used to identify sites that reflect the range and spatial variability of the property or properties (Corwin and Lesch, 2005b).

In instances where EC_a correlates with a particular soil property, an EC_a-directed soil sampling approach will establish the spatial distribution of that property with an optimum number of site locations, which significantly reduces labor costs compared to grid sampling (Corwin et al., 2003a, 2003b). Details for conducting a field-scale EC_a survey for the purpose of characterizing the soil spatial variability are in Corwin and Lesch (2005b). Protocols specifically for mapping soil salinity with EC_a-directed soil sampling are in Corwin and Lesch (2013). Corwin and Lesch (2005a) provide a compilation of literature pertaining to the soil physical and chemical properties that either directly or indirectly influence EC_a.

Regional-scale maps of soil salinity are needed by policy makers to establish the extent of the soil salinity problem and to monitor the impact of climate change and agriculture on soil salinization. The Red River Valley in the Midwestern USA is a perfect example of where this information is needed (Lobell et al., 2010). However, regional-scale mapping of soil salinity poses new challenges beyond those of field-scale salinity assessment due to the greater spatial extent.

A review paper by Metternicht and Zinck (2003) and a recent special collection of papers in the *Journal of Environmental Quality* (2010, volume 39, issue 1) focusing on remote sensing of soil degradation provide several papers that present regional-scale salinity assessments using remote sensing (Caccetta et al., 2010; Furby et al., 2010; Lobell et al., 2010; Singh et al., 2010). In the study by Lobell et al. (2010) EC_a-directed sampling was used in combination with remote imagery (i.e., MODIS, Moderate Resolution Imaging Spectroradiometer) to map salinity over hundreds of thousands of hectares (Lobell et al., 2010). In essence, the EC_a-directed sampling provided ground-truth measurements of soil salinity to calibrate multi-year MODIS enhanced vegetative index (EVI) imagery, thereby providing a relationship between EVI and soil salinity.

An alternative and less complicated approach for assessing regional-scale soil salinity is to develop a relationship between EC_a measured with electromagnetic induction (EMI) and soil salinity for an entire region. We hypothesize that regression techniques can calibrate EC_a to soil salinity (where soil salinity is measured using the electrical conductivity of the saturation extract, EC_e, expressed in dS m^{-1}) for multiple fields extending over a regional scale, substantially reducing the need for future ground-truth soil sampling. The objective of this research is to evaluate three regression modeling techniques for calibrating EC_a to EC_e for multiple fields extending over a range of a few thousand to over a hundred thousand hectares and to establish the viability of using regression techniques for regional-scale salinity assessment.

2. Rationale for regional calibration with regression models

Being spatial in nature (i.e., referenced across a spatial domain), it is quite reasonable to consider some type of geostatistical modeling technique when attempting to calibrate EC_a survey data to a specific soil property such as salinity. Numerous examples exist in the literature of geostatistical or spatial modeling approaches. The textbooks by Schabenberger and Gotway (2005), Schabenberger and Pierce (2002), Webster and Oliver (2001), Wackernagel (1998), and Isaaks and Srivastava (1989) are particularly relevant to the calibration problem.

However, in addition to the commonly used geostatistical techniques, ordinary linear regression models are often used when calibrating data. In the mainstream statistical literature, it is well known that ordinary linear regression models represent a special case of a much more general class of models commonly known as linear regression models with spatially correlated errors (Schabenberger and Gotway, 2005), hierarchical spatial models (Banerjee et al., 2004), or geostatistical mixed linear models (Haskard et al., 2007). This broader class of models includes many of the geostatistical techniques familiar to soil scientists, such as universal kriging, kriging with external drift and/or regression-kriging, as well as standard statistical techniques like ordinary linear regression and analysis of covariance (ANOCOVA) models.

Lesch and Corwin (2008) review the use of these different modeling techniques for calibrating remotely sensed survey data to soil properties. Lesch and Corwin (2008) also describe the necessary set of statistical assumptions for reducing a geostatistical mixed linear model to an ordinary linear model. Historically, ordinary linear models have often been used to calibrate EC_a survey data to one or more target soil properties, such as salinity, i.e., EC_e (Corwin and Lesch, 2005b). For example, field-scale soil salinity patterns are commonly mapped quite accurately using EC_a survey data and ordinary linear regression models, since the residual error distribution typically exhibits only short-range spatial correlation (Corwin and Lesch, 2005b; Lesch and Corwin, 2008; Lesch et al., 2005). Therefore, a simpler linear regression model can be used in place of the full geostatistical model to generate a map with a high degree of prediction precision, provided that an appropriate sampling strategy is employed (Lesch, 2005).

Multi-field EC_a survey data often exhibit an abrupt change in magnitude across field boundaries, presenting a challenge to the conversion of EC_a to EC_e at large spatial extents of thousands to tens of thousands of hectares. The abrupt change is typically caused by a variety of reasons: (i) between-field variation in field average water content due to irrigation frequency and timing, (ii) between-field variation in soil texture, (iii) condition of the soil surface (e.g., till vs. no-till) due to management practices that effect soil compaction, (iv) surface geometry (i.e., presence or absence of beds and furrows), (v) temperature differences (i.e., EC_a surveys conducted at different times of the year), and (vi) between-field spatial variation in salinity. Calibration models are often used to adjust out an abrupt change. For instance, temperature corrections to EC_a data are typically done using a multiplicative adjustment constant, i.e., $EC_{a,25\ °C} = f_t \cdot EC_{a,t}$ where t is the soil temperature and f_t is the temperature correction factor. Similarly, changes in bed–furrow geometry, surface conditions, soil texture, and water content are approximated in the same manner. Generally speaking, many secondary effects that influence EC_a–EC_e calibration models are modeled as multiplicative in nature, at least to a first-order approximation (Corwin and Lesch, 2005b).

More specifically, consider the case of surface geometry, i.e., presence and absence of beds and furrows in a field, where an EC_a survey has been conducted. In the absence of any surface geometry, a simple power model describes the deterministic component of the EC_e–EC_a relationship, i.e., $EC_{e,i} \approx \beta \cdot EC_{a,i}^{\alpha}$ where β is a coefficient and $i = 1, 2, 3,…,n$. To account for the surface geometry effect an additional dummy variable (x) and associated scaling parameter (θ) are used, i.e., $EC_{e,i} \approx \theta^{x_i} \cdot \beta \cdot EC_{a,i}^{\alpha}$ where $x_i = 1$ if there is a surface geometry effect and $x_i = 0$ otherwise. Under a log transformation, this multiplicative parameter becomes additive as shown in Eq. (1):

$$\ln\left(EC_{e,i}\right) \approx x_i \ln(\theta) + \ln(\beta) + \alpha \ln\left(EC_{a,i}\right) = \beta_{01} + \beta_{02}(x_i) + \alpha \ln\left(EC_{a,i}\right) \tag{1}$$

On a log–log scale, a simple linear regression model with an additional blocking (shift) parameter can adjust an abrupt change in any multiplicative EC_a effect within a field. Note that Eq. (1) is a simple type of ANOCOVA model. In principle, this type of ANOCOVA modeling approach could be used to calibrate multiple-field EC_a surveys to EC_e, provided that the assumptions in Eq. (1) are reasonable.

Consider a scenario where EC_a survey data is acquired across multiple fields and assume that the number of soil sampling locations

collected in any given field is minimal (i.e., $n < 10$). In the absence of any useful spatial or geostatistical modeling approach under these conditions, basic regression modeling techniques are used. The regression techniques include field specific regression (FSR), common coefficient regression (CCR), and ANOCOVA. A FSR model is defined by Eq. (2):

$$\ln\left(EC_{e,ijk}\right) = \beta_{0,jk} + \beta_{1,jk}\ln\left(EM_{v,ik}\right) + \beta_{2,jk}\ln\left(EM_{h,ik}\right) + \varepsilon_{ijk}. \qquad (2)$$

Common coefficient regression model is defined by Eq. (3):

$$\ln\left(EC_{e,ijk}\right) = \beta_{0,j} + \beta_{1,j}\ln\left(EM_{v,ik}\right) + \beta_{2,j}\ln\left(EM_{h,ik}\right) + \varepsilon_{ijk}. \qquad (3)$$

Analysis of covariance model is defined by Eq. (4):

$$\ln\left(EC_{e,ijk}\right) = \beta_{0,jk} + \beta_{1,jk}\ln\left(EM_{v,ik}\right) + \beta_{2,jk}\ln\left(EM_{h,ik}\right) + \varepsilon_{ijk} \qquad (4)$$

where i refers to the soil sample site within a field ($i = 1, 2, 3,\ldots, n_k$), j is the sample depth ($j = 1, 2, 3,\ldots, p$), k is the field ($k = 1, 2, 3,\ldots, M$), EM_v is the EC_a measured with EMI in the vertical coil configuration (dS m^{-1}), and EM_h is the EC_a measured with EMI in the horizontal coil configuration (dS m^{-1}).

In the ANOCOVA model, the intercept parameter is uniquely estimated for each sampling depth and field, but the slope coefficients are only assumed to change across sampling depths (not across fields). For a specific field, the FSR model requires $3p$ parameter estimates (for p depths) and sufficient sample data must be acquired in each field to estimate these parameters; thus, for M fields a total of $3pM$ estimates are needed. In contrast, the CCR model requires just $3p$ estimates for an entire region. A set of calibration fields can be used to develop the CCR equations and no additional samples are needed. Unfortunately, the accuracy of a CCR model tends to be rather poor. With respect to parameter estimate requirements the ANOCOVA approach represents a compromise between the FSR and CCR models. Once a suitable set of calibration fields are identified to develop the ANOCOVA equations, then additional samples collected in new fields are only used to estimate the field-specific intercept values. The set of initial calibration fields require $pM + 2p$ initial parameter estimates. After developing these calibration estimates a new survey field requires just p parameter estimates (for p depths).

3. Materials and methods

Two study sites were selected to evaluate the three regression techniques as potential regional-scale calibration models of EC_a to EC_e. The chosen sites provided a challenging and rigorous evaluation of the regression techniques by testing sites with wide ranging differences in areal extent, soil properties, bed–furrow surface geometry, management, and geographic location, each of which can influence the EC_a to EC_e calibration. To evaluate the prediction accuracy of the three regression techniques the jack-knifed mean square prediction error (MSPE) was calculated for each model at each study site.

3.1. Description of case study sites

Two study sites of disparate size and property characteristics were selected to evaluate the regression techniques: (1) 2396 ha of the Broadview Water District (latitude: 36°50′08″ N; longitude: 120°33′55″ W) located on the west side of the San Joaquin Valley (WSJ) near Firebaugh, CA, and (2) approximately 100,000 ha on the west side of Kittson County, MN (latitude: 48°46′ N; longitude: 96°56′ W) in the Red River Valley (RRV).

The 2396-ha study area within the Broadview Water District consisted of 37 contiguous quarter sections, with each quarter section encompassing approximately 64 ha of land. The dominant agricultural crops within the survey area were alfalfa (*Medicago sativa* L.), cotton (*Gossypium hirsutum*), and tomato (*Lycopersicon Lycopersicum*). Additionally, about 15% of the total survey area was fallow. Thirty-three of the 37 quarter-sections supported a single crop (or no crop). The bed–furrow surface geometry consisted of 90, 100, 110, and 160 cm bed–furrow designs. All fields had been laser leveled. Four quarter-sections contained multiple fields. The remaining 33 quarter-sections were each single fields of 64 ha. Irrigation methods consisted of flood irrigation down furrows and sprinkler irrigation. Irrigation application rates varied between quarter sections. Soil textures ranged from sandy loam to clay, with the clay content usually increasing with depth.

Kittson County resides in the northwest corner of Minnesota, consisting of dryland farms growing spring wheat (*Triticum aestivum* L.), soybeans (*Glycine max* (L.) Merr.), sugar beets (*Beta vulgaris* L.), and alfalfa (*M. sativa* L.). Kittson County is part of the Red River Valley (RRV), which mostly consists of a glacial lake plain of nearly level topography with occasional slight depressions bordered by outwash plains and sloping slightly (about 10 cm for each km) toward the Red River. Soils in the RRV represent some of the more saline soils found in the USA, with negative economic impact of salinity estimated at $50 million annually. Fields varied in size. Unlike Broadview Water District, the soils in Kittson County are relatively uniform, consisting of heavy textures soils with clay contents ranging from 60–80%.

3.2. Electromagnetic induction (EMI) EC_a surveys

Geospatial EC_a measurements were obtained with the Geonics EM38 electrical conductivity meter.[2] The EC_a surveys followed the survey procedures that ultimately led to the protocols and guidelines outlined by Corwin and Lesch (2003, 2005b) and Corwin and Lesch (2013). The EC_a survey was conducted for Broadview Water District in May of 1991 and for Kittson County in the spring of 2007. The surveys consisted of geospatial EC_a measurements taken with mobile EMI equipment. Electromagnetic induction measurements were taken in the horizontal (EM$_h$) and vertical coil configurations (EM$_v$). The inclusion of both EM$_h$ and EM$_v$ measurements provides a shallow (i.e., EM$_h$) and deep (i.e., EM$_v$) measurement of electrical conductance (EC), which provides information regarding the salinity profile with depth. The inclusion of both measurements in soil sample site selection often enhances the characterization of the spatial variability of EC.

The EMI survey for Broadview Water District was one of the first landscape-scale EC_a surveys using first-generation mobile EMI equipment (i.e., Geonics single-dipole EM38) that did not take a steady stream of simultaneous EM$_h$ and EM$_v$ EC_a measurements. Rather, the mobile EMI equipment went from one point to the next, stopping at each point to take an EC_a measurement in the vertical coil configuration and then in the horizontal coil configuration. Measurements were taken in a 10-by-10 grid within each quarter section (i.e., 64 ha), totaling 3800 locations for the entire Broadview Water District.

For Kittson County, EC_a surveys were conducted on 20 fields using mobile EMI equipment that takes a continuous stream of EC_a measurements every 5 s (i.e., Geonics dual-dipole EM38 or EM38DD). The 20 fields were identified using a stratified random sampling of enhanced vegetative index (EVI) data from 7 years of Moderate Resolution Imaging Spectroradiometer (MODIS) imagery as described in Lobell et al. (2010). Geospatial EC_a readings were taken at 2000–5000 locations within each field. Specific details describing the EC_a survey and soil sampling of Kittson County are in Lobell et al. (2010). The EC_a-directed

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[2] Geonics Ltd., Mississaugua, Ontario, Canada. Product identification is provided for the benefit of the reader and does not imply endorsement by USDA.

sampling survey followed the protocols outlined by Corwin and Lesch (2005b).

3.3. Soil sampling

Apparent soil electrical conductivity serves as a surrogate to characterize the spatial variation of those soil properties that are found to influence EC_a within a field. In both studies, soil sample sites that reflect the range and variation in EC_a were selected. To achieve this, the model-based sampling strategy in the ESAP software package was used to select the calibration sampling locations (Lesch et al., 1995a, 1995b, 2000). The model-based sampling strategy is a response surface sampling design, which in essence creates a 3-D surface of the EC_a measurements and based on the range and variation selects locations that characterize the EC_a variation while maximizing the distances between adjacent sampling locations. For Broadview Water District, 4–8 sample site locations were identified in each field using response surface sampling designs. However, only fields with six or more sample site locations were used to develop FSR, CCR, and ANOCOVA calibration models. For Kittson County, six sample site locations were identified in each field using response surface sampling designs. Soil samples were collected at 30-cm depth increments for both Broadview Water District and Kittson County. Samples were collected to a depth of 1.2 m in Broadview Water District and 1.5 m in Kittson County. A saturation extract of each soil sample was prepared and the electrical conductivity of the saturation extract (EC_e, dS m^{-1}) was measured using the method presented in Rhoades (1996). Saturation percentage and water content were determined gravimetrically.

Fig. 1 shows the 43 contiguous fields of Broadview Water District, with 315 sample site locations. Only the 38 fields with six or more sample site locations were used for calibration. Kittson County contained 120 sample site locations, i.e., six locations in each of 20 non-contiguous fields located throughout the county. Additional details concerning the EC_a-directed soil sampling are presented in Corwin et al. (1999) for Broadview Water District and Lobell et al. (2010) for Kittson County.

3.4. Statistical evaluation of prediction error

The prediction accuracy of the three regression techniques was evaluated by a comparison of their jack-knifed mean square prediction error (MSPE) shown in Eq. (5):

$$MSPE = \frac{1}{N_{ijk}} \sum_{i,j,k} (y_{ijk} - \hat{y}_{ijk,(-i)})^2 \tag{5}$$

Table 1
Comparison of FSR (field specific regression), ANOCOVA (analysis of covariance), and CCR (common coefficient regression) model calibration statistics for 4 depth increments of 38 contiguous fields in the Broadview Water District study site with 6–8 soil sample calibration sites per field.

Model	Statistic	Soil depth increment (cm)			
		0–30	30–60	60–90	90–120
FSR	R^2	0.666	0.742	0.805	0.814
	MSE	0.104	0.154	0.148	0.142
ANOCOVA	R^2	0.491	0.580	0.645	0.704
	MSE	0.112	0.177	0.191	0.160
CCR	R^2	0.022	0.215	0.408	0.525
	MSE	0.188	0.289	0.278	0.224

R^2 = coefficient of determination; MSE = mean square error.

where $y_{ijk} = \ln(EC_{e,ijk})$ and $\hat{y}_{ijk,(-i)}$ represents the model predicted $\ln(EC_{e,ijk})$ where the ith observed natural log salinity measurement has not been used to calibrate the model. This 'leave-one-out' approach is commonly used as a quantitative diagnostic tool to test the robustness and accuracy of regression models used for prediction (Myers, 1986).

3.5. Validation of the ANOCOVA approach for Kittson County, MN

Once the ANOCOVA calibration models have been established for each sampling depth from the form of the fitted equations defined by Eq. (6),

$$\ln(\hat{y}_{ijk}) = \hat{\mu}_{jk} + \beta_{1j}\left[\ln\left(EM_{v,ik}\right)\right] + \beta_{2j}\left[\ln\left(EM_{h,ik}\right)\right] \tag{6}$$

where $\hat{y}_{ijk}$ represents the predicted $\ln(EC_{e,ijk})$ for the ith field site, j^{th} depth, and the kth field and $\hat{\mu}_{jk}$ represents the estimated intercept for the jth depth and the kth field, then the EM_v and EM_h slope coefficients, β_{1j} and β_{2j} respectively, can be extracted and used for all future field surveys conducted across the region. In any new field surveyed in the region, these EM_v and EM_h slope coefficients can be used to estimate the field specific intercepts and associated model mean square error (MSE). This can be done using as few as two sampling locations in the field by following the four steps below:

Step 1: For each ith sample location and j^{th} depth at n total locations in a field compute the shifted intercept residual ω_{ji} using Eq. (7),

$$\omega_{ji} = \ln\left(EC_{e,ji}\right) + \beta_{1j}\left[\ln\left(EM_{v,i}\right)\right] + \beta_{2j}\left[\ln\left(EM_{h,i}\right)\right] \tag{7}$$
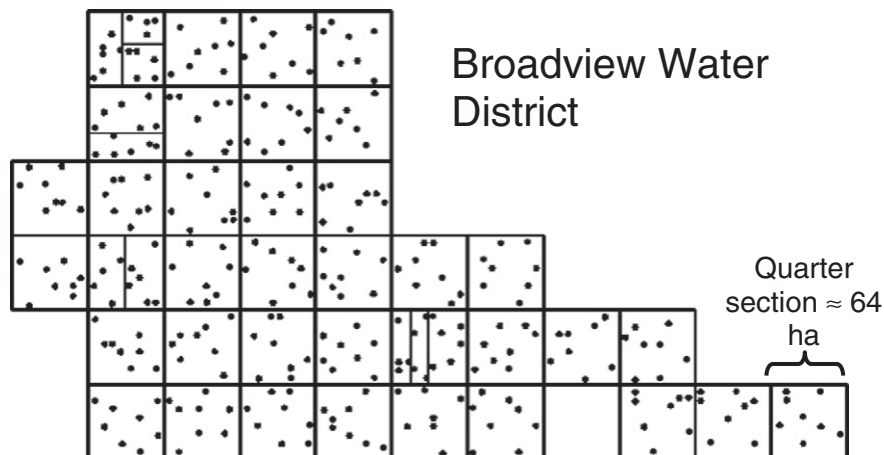

Fig. 1. Physical locations of all 315 soil sample sites for 37 quarter sections of Broadview Water District. Soil samples were taken in May of 1991. Boundary lines delineate 43 fields. Thirty-eight of the 43 fields contained six or more sample sites, which were used for calibration.

Broadview Water District

Quarter section ≈ 64 ha

Table 2
Comparison of FSR (field specific regression), ANOCOVA (analysis of covariance), and CCR (common coefficient regression) jack-knifed prediction statistic (i.e., mean square prediction error) for 4 depth increments of 38 contiguous fields in the Broadview Water District study site with 6–8 soil sample calibration sites per field.

Model	Mean square prediction error (MSPE)			
	Soil depth increment (cm)			
	0–30	30–60	60–90	90–120
FSR	0.202	0.294	0.264	0.278
ANOCOVA	0.131	0.207	0.221	0.187
CCR	0.191	0.292	0.280	0.227

Step 2: Estimate the intercept at depth j, i.e., $\hat{\mu}_j$ from Eq. (8),

$$\hat{\mu}_j = (1/n)\sum_{i=1}^{n} \omega_{ji} \qquad (8)$$

Step 3: Estimate the associated depth-specific variance $\hat{\sigma}_j^2$ from Eq. (9),

$$\hat{\sigma}_j^2 = [1/(n-1)]\sum \left(\omega_{ji} - \hat{\mu}_j\right)^2 \qquad (9)$$

Step 4: Repeat the above three steps for each sampling depth and compute the model MSE estimate by averaging the Step 3 depth-specific variance estimates.

In addition to jack-knifing analysis, in Kittson County the ANOCOVA modeling approach was further validated using an independent data set composed of EC_a survey data taken at five fields in Kittson County in 2006 using mobile EMI equipment. The 2006 EC_a surveys were similar to those conducted in 2007 except that soil samples were only acquired at three or four locations within each field at 30-cm depth increments to a depth of 90 cm. Thus, there were eighteen sample locations across the five fields.

4. Results and discussion

4.1. Broadview Water District

Table 1 displays a summary of the model statistics (i.e., R^2 and mean square error statistics, MSE) for the FSR, ANOCOVA, and CCR calibration models of Broadview Water District at each 30-cm depth increment down to 1.2 m. The data used was restricted to the 38 contiguous fields having 6–8 soil sample calibration sites because the FSR models could not be accurately calibrated using less than six sites. The R^2 and MSE statistics essentially measure how well each model "fits" the sample data. Without question, the CCR models fit the sample data the worst. The FSR models for all four depth increments produce the best-fit model statistics with the

Table 3
Comparison of FSR (field specific regression), ANOCOVA (analysis of covariance), and CCR (common coefficient regression) model calibration statistics for 5 depth increments of 20 non-contiguous fields in Kittson County, MN, with 6 calibration sites per field.

Model	Statistic	Soil depth increment (cm)				
		0–30	30–60	60–90	90–120	120–150
FSR	R^2	0.952	0.927	0.938	0.950	0.940
	MSE	0.075	0.225	0.178	0.115	0.118
ANOCOVA	R^2	0.830	0.851	0.854	0.885	0.882
	MSE	0.162	0.280	0.256	0.161	0.139
CCR	R^2	0.534	0.616	0.595	0.613	0.680
	MSE	0.372	0.601	0.592	0.451	0.316

R^2 = coefficient of determination; MSE = mean square error.

Table 4
Comparison of FSR (field specific regression), ANOCOVA (analysis of covariance), and CCR (common coefficient regression) jack-knifed prediction statistic (i.e., mean square prediction error) for 5 depth increments of 20 non-contiguous fields in Kittson County, MN, with 6 calibration sites per field.

Model	Mean square prediction error (MSPE)				
	Soil depth increment (cm)				
	0–30	30–60	60–90	90–120	120–150
FSR	0.232	0.663	0.506	0.400	0.364
ANOCOVA	0.208	0.352	0.327	0.210	0.182
CCR	0.408	0.644	0.623	0.468	0.327

highest R^2 and lowest MSE. However, the ANOCOVA models outperform the FSR models on a prediction accuracy basis (i.e., MSPE) as shown in Table 2, with the ANOCOVA models for each depth increment having the lowest MSPE. On a per field basis, the ANOCOVA models produce smaller MSPE estimates in 30 out of 38 fields (79%).

In the Broadview Water District survey, the predictions can be improved using advanced spatial modeling techniques because the fields are spatially contiguous. However, the main point is that the simple ANOCOVA approach works very well, particularly with respect to prediction accuracy, even though there is significant between-field textural variation, diverse irrigation management practices, and a wide range of crops and surface geometry conditions.

4.2. Kittson County, MN

Table 3 shows the model statistics for the FSR, ANOCOVA, and CCR calibration models of Kittson County, MN, at each 30-cm depth increment down to 1.5 m for the 20 non-contiguous fields analyzed in this study. As was the case for Broadview Water District, that the FSR calibration models have the best-fit statistics for all five depths with the ANOCOVA model a close second and CCR model trailing. However, Table 4 shows that the ANOCOVA calibration models produce the smallest MSPE estimates for all five depths. Additionally, 15 of the 20 fields exhibit smaller MSPE estimates when compared to the FSR calibration models.

Further data that clearly shows the viability of the ANOCOVA approach as a means of calibrating EC_a measurements to salinity (i.e., EC_e) is presented in Fig. 2, which shows the measured EC_e versus jack-knifed predicted EC_e averaged over 0–150 cm for the 20 fields in Kittson County. The correlation coefficient between measured and predicted EC_e over 0–150 cm at 120 locations is 0.951.
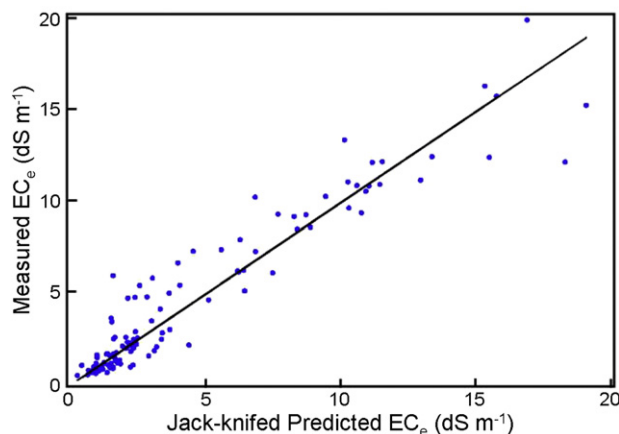

Fig. 2. Measured EC_e versus jack-knifed predicted EC_e averaged over 0–150 cm for 20 fields in Kittson County, MN, using the ANCOVA calibration model. Solid line represents the 1:1 line.

Table 5
Distribution of ANOCOVA jack-knifed MSPE estimates for 0–1.5 m depth of 20 non-contiguous fields in Kittson County, MN.

MSPE Range	Grade	Prediction accuracy	Number of fields (Number of samples)	% of Total sample size	Correlation of observed and predicted salinity
<0.1	A	Excellent	4 (24)	20	0.963
0.1 < MSPE < 0.2	B	Good	4 (24)	20	0.912
0.2 < MSPE < 0.4	C	Fair	7 (42)	35	0.884
MSPE > 0.4	U	Unacceptable	5 (30)	25	0.727

Another way to evaluate the prediction reliability of the ANOCOVA approach is to look at the predictions on a field basis for the MSPE range as shown in Table 5. Table 5 summarizes the distribution of the ANOCOVA model jack-knifed MSPE estimates into four classes; these classes "grade" the reliability of the salinity predictions. Overall, 75% (15 out of 20 fields) exhibit excellent to fair (Grade A, B, or C) prediction reliability. Estimates of MSPE greater than 0.4 suggest that the salinity levels in a particular field are not well described, or more specifically are not strongly correlated with associated EC_a survey data measured with EMI equipment; only 5 of the 20 fields fall into this "unacceptable" class (Grade U). Fig. 3a–d shows the distribution of measured versus jack-knifed predicted salinity (i.e., EC_e) for the groups of fields exhibiting A, B C, and U prediction accuracy grades, respectively, based on the criteria in Table 5. The scatter of points around the 1:1 line in Fig. 3d shows the lack of one-to-one correspondence between measured and predicted EC_e in the five fields graded as unacceptable. The Kittson County electromagnetic induction EC_a slope coefficients of EM_h and EM_v estimated for ANOCOVA calibration Eq. (6) are shown in Table 6 for the five depth increments.

4.3. Validation of the ANOCOVA approach for Kittson County, MN

Validation of the traditional FSR calibration technique was not possible because of insufficient data in the Kittson County validation data set. In contrast, the previously developed ANOCOVA models can be easily validated with the limited validation data set (i.e., EM_h and EM_v measurements and soil samples taken at 30-cm increments to a depth of 90 cm at only 3–4 locations). Using the

EC_a slope coefficients of EM_h and EM_v estimated for ANOCOVA calibration Eq. (6) shown in Table 6 for the top three depth increments (0–30, 30–60, and 60–90 cm) and estimating the intercepts for each of these depth increments from Eqs. (7)–(9), ANOCOVA predicted salinity levels (i.e., EC_es) were estimated from the Kittson County validation data set. The ANOCOVA predicted EC_es are compared to observed EC_es from the validation data set for the three depth increments in Fig. 4. The correlation coefficient for this data is 0.845, indicating high prediction accuracy well within acceptable limits. On a field-by-field basis, the distribution of MSE into the various grades based on the criteria shown in Table 5 indicates that only Field 4 with three sample locations had an unacceptable grade (Table 7).

5. Conclusion

A comparison of ANOCOVA versus FSR shows that one parameter estimate for each field is needed for ANOCOVA, rather than three for FSR, resulting in greater estimation precision and increased model stability as long as the ANOCOVA assumption holds. In addition, the ANOCOVA approach requires less sample data per field once the basic ANOCOVA models have been developed. The ANOCOVA modeling approach completely outperformed the CCR equations. Admittedly, the ANOCOVA approach requires at least two sampling locations in each new field, but the ANOCOVA approach can be used to assess prediction accuracy (i.e., model reliability) based on a limited sample set. The field-specific intercept estimates in the ANOCOVA modeling approach successfully adjust for the majority
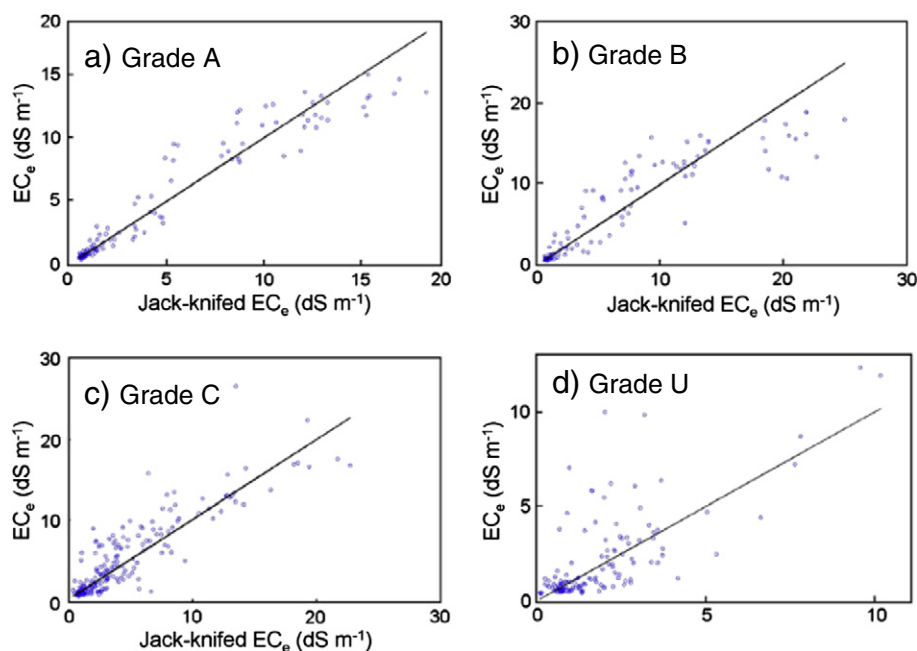

Fig. 3. Distribution of measured versus jack-knifed predicted salinity (i.e., EC_e) for the groups of fields exhibiting (a) Grade A, (b) Grade B, (c) Grade C, and (d) Grade U prediction accuracy grades based on the criteria in Table 5. Solid line represents the 1:1 line.

Table 6
Apparent soil electrical conductivity (EC_a) slope coefficients for EM_h and EM_v (electromagnetic induction EC_a measurements taken in the horizontal and vertical coil configuration, respectively) extracted from the ANOCOVA models for each depth increment (i.e., 0–30, 30–60, 60–90, 90–120, and 120–150 cm) for Kittson County, MN.

Sample depth (j) in cm	Kittson County electromagnetic induction EC_a slope coefficients for ANOCOVA calibration Eq. (6)[†]	
	β_{1j} (EM_v)	B_{2j} (EM_h)
0–30	−0.747	1.282
30–60	1.296	−0.196
60–90	3.965	−1.740
90–120	3.238	−1.607
120–150	3.033	−1.414

[†] ANOCOVA calibration Eq. (6): $\ln\left(\hat{y}_{ijk}\right) = \hat{\mu}_{jk} + \beta_{1j}\left[\ln\left(EM_{v,ik}\right)\right] + \beta_{2j}\left[\ln\left(EM_{h,ik}\right)\right]$ where $\hat{y}_{ijk}$ = predicted $\ln(EC_{e,ijk})$ for the ith site, j^{th} depth, and the kth field and $\hat{\mu}_{jk}$ = estimated intercept for the jth depth and the kth field.

of field specific effects that tend to shift EC_a data patterns multiplicatively from one field to the next under a log transformation.

The ANOCOVA modeling approach performs well and represents a viable regional-scale calibration technique. It represents a practical compromise between individually calibrating a regression model to each field and forcing a common (static) model across all fields in the survey area. Its simplicity is particularly appealing. Once the slope coefficients have been determined, a practitioner does not need any advanced statistical concepts to implement the technique. All calculations are easily performed in a spreadsheet.

Fields can be calibrated with as few as two sampling locations once the ANOCOVA equations have been developed. The ramifications of this finding are significant for irrigation districts in the southwestern USA, the National Resource Conservation Service (NRCS), or any agency or consulting firm that conducts regular field-scale EC_a-directed sampling surveys using EMI within a basin or region. By pooling the EC_a and EC_e data over a region and using the ANOCOVA approach, the calibration of EC_a to EC_e for any new field requires only two to three sampling locations in the new field instead of the customary six or more locations. For instance, NRCS has conducted numerous EC_a surveys in the Red River Valley of Minnesota and the Dakotas. Each survey required a minimum of six sample locations with samples collected at 30-cm increments to a depth of 150 cm. This data can be used to develop ANOCOVA equations specific to the Red River Valley. Any future EC_a surveys in the Red River Valley will only require samples at two to three locations, reducing sample laboratory analysis loads by 50–66%.
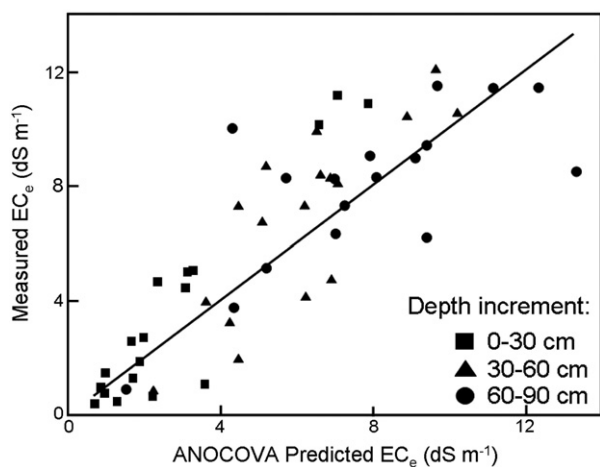

Fig. 4. Measured EC_e versus ANOCOVA predicted EC_e for Kittson County validation data set consisting of five fields and three depth increments of 0–30, 30–60, and 60–90 cm. Solid line represents the 1:1 line.

Table 7
Kittson County ANOCOVA calibration model validation results for each of the five fields based on the mean square error (MSE) classified by the criteria in Table 5.

Field	# of Sample sites	Computed MSE	Grade
1	4	0.176	B
2	4	0.353	C
3	3	0.134	B
4	3	0.593	U
5	4	0.254	C

Acknowledgments

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