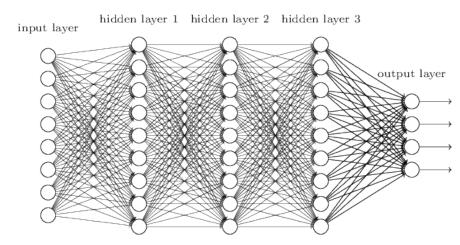
Improving Neural Networks, Overfitting and Regularization techniques

Michael Nielsen's Deep Learning book

Winter School on Quantitative Biology Learning and Artificial Intelligence

Alessio Ansuini ICTP - November 2018

Where we are



Where we are

The Basic Swing: Backpropagation Algorithm

$$C = \frac{(y-a)^2}{2}$$

$$\frac{\partial C}{\partial x} = \frac{\partial C}{\partial x}$$

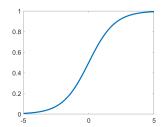
We saw how to compute (and to implement) these derivatives explicitly.

First improvement : $C \rightarrow C$ (cross-entropy loss)



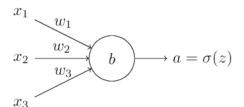
The problem with quadratic loss

$$\frac{\partial C}{\partial w} = a\sigma'(z)$$



$$\frac{\partial C}{\partial b} = a\sigma'(z)$$

Cross-entropy loss



$$C = -\frac{1}{n} \sum_{x} [y \ln a + (1 - y) \ln(1 - a)]$$

Guided exercise: 1) interpretation of the cross-entropy function 2) derivation from the maximum likelihood approach and 3) interpretation (derivation left as an exercise) of the formulas

$$\frac{\partial C}{\partial w_j} = \frac{1}{n} \sum_{x} x_j (\sigma(z) - y) \qquad \frac{\partial C}{\partial b} = \frac{1}{n} \sum_{x} (\sigma(z) - y)$$



Exercise: derivation from MLE

In Nielsen's book you will find different motivations. One heuristic and the other more theoretical: check it for a comparison!

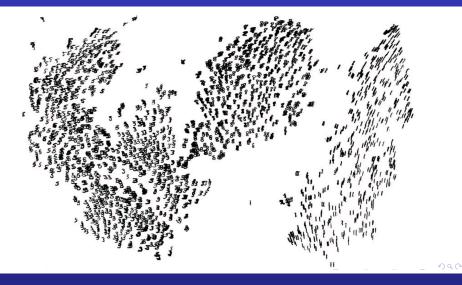
- Define a probabilistic setting : we want to model p(y = k|x) k = 0, 1, ... 9
- Write the MLE problem
- Refactoring and derive the identity with the minimization of the cross-entropy
- Information theoretical approach



Demonstration : slow learning with quadratic C



MNIST T-SNE visualization, van deer Maaten, Hinton 2008 T-SNE on scikit-learn



Straightforward generalization of the loss

$$C = -\frac{1}{n} \sum_{x} \sum_{j} \left[y_{j} \ln a_{j}^{L} + (1 - y_{j}) \ln(1 - a_{j}^{L}) \right] \quad j = 0, 1, \dots 9$$

Go to Jupyter Notebook!



Softmax Layer

Output interpretable as a probability distribution on categories (conditioned to the data) : $a_j^L = p(y = j|x)$

$$z_{j}^{L} = \sum_{k} w_{jk}^{L} a_{k}^{L-1} + b_{j}^{L} \quad \rightarrow \quad a_{j}^{L} = \frac{e^{z_{j}^{L}}}{\sum_{k} e^{z_{k}^{L}}}$$

$$a_j^L \ge 0$$
 $\sum_j a_j^L = 1$

- Look at the interactive sliders in Nielsen's book
- It can be shown that softmax output in combination with log-likelihood loss $C = -\ln a_y^L$ is \sim to sigmoidal output in combination with cross-entropy loss.



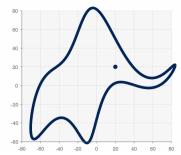
Overfitting

"With four parameters I can fit an elephant, and with five I can make him wiggle his trunk"

John von Neumann

The Elephant

"Jens Morten Hansen (JMH) and co-authors have recently published a study where they use sine-regression to fit 5 oscillations plus a linear trend to a 160-year sea level [...] This result is clearly not significant in any meaningful sense of the word."



The animation

Number of trainable parameters in Neural Networks

- Fully connected [784, 30, 10] : ~ 24K
- Fully connected [784, 100, 10] : ~ 80K
- LeNet (1998) : ~ 60*K*
- AlexNet (2012) : ~ 60M
- VGG-16 (2014) : ~ 138*M*
- **...**

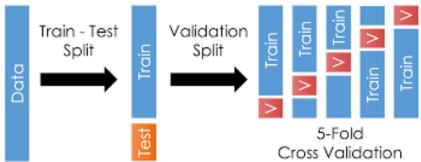
The overfitting problem in neural networks is potentially serious and we will address it.

But it is milder than expected, and this is yet a mystery!



Cross-validation

cross-validation on scikit-learn



Overfitting / Underfitting Example

True model that generates data points

$$y = cos(x) + \varepsilon$$
 ε : stochastic perturbation

We sample randomly 30 points from the true model and then find the best fit of several models

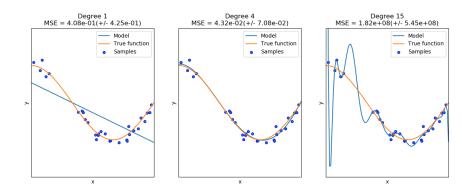
Three models of growing complexity

- $y = \theta_0 + \theta_1 x$ (2 parameters)
- $y = \theta_0 + \theta_1 x + \cdots + \theta_4 x^4$ (5 parameters)
- $y = \theta_0 + \theta_1 x + \dots + \theta_{10} x^{15}$ (16 parameters)

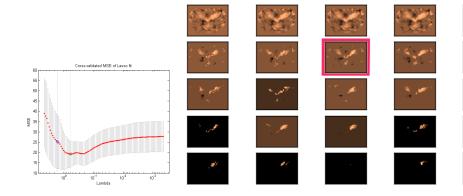
We will use (10-fold) cross-validation



Overfitting / Underfitting Example



Outcome: the Hyper-parameter(s) choice



Regularization

The general approach with Neural Networks

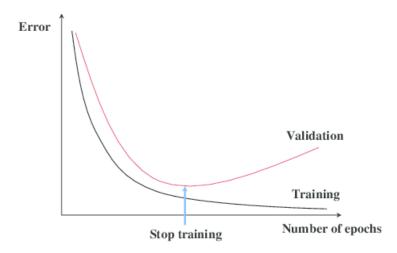
- Choose a model large enough to ensure overfitting (and with the right architectural prior, as we will see in Lecture 3)
- Regularize it in order to tame its complexity, minimizing overfitting

Regularization techniques (* typically requires hyper-parameters search)

- ★ Early stopping → n.of epochs
- \star Weight decay (L_1 (lasso), L_2 (ridge)) $\to \lambda_1, \lambda_2$
- Data augmentation (rotations, translations, etc.)
- \star Dropout $\rightarrow p$
- **.** . . .



Early stopping



Regularization by weight decay

Reduce not the model complexity (number of parameters) but the *effective* model complexity i.e. the number of parameters that play an important role (not applied on the biases)

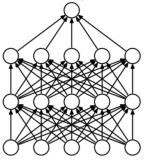
$$C_{\lambda,2} = C_0 + \frac{\lambda}{2n} ||w||_2$$
 $||w||_2 = \sum_{w} w^2$

$$w \rightarrow w - \eta \frac{\partial C_0}{\partial w} - \frac{\eta \lambda}{n} w$$
$$= \left(1 - \frac{\eta \lambda}{n}\right) w - \eta \frac{\partial C_0}{\partial w}.$$

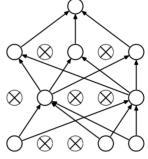


Dropout

Does not modify C but the network's way to operate



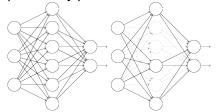
(a) Standard Neural Net



(b) After applying dropout.

Dropout

In each mini-batch we randomly deactivate units with probability p



"it's [...] like we're training different neural networks [...] the different networks will overfit in different ways and so, hopefully, the net effect of dropout will be to reduce overfitting."

"[...] reduces complex co-adaptations of neurons [...]" (We will see Dropout at work in Lecture3)

$$p = 0.5$$
 $w \rightarrow pw = \frac{1}{2}w$



Data augmentation

Horizontal Flip





Crop









Rotate





Data augmentation: MNIST

- small rotations
- small translations
- elastic distortions (emulate the random oscillations found in



hand muscles)

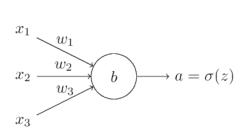
other ...

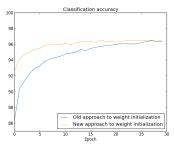
More data means more chance for the network to *make experience* of the natural variability in the data. The data augmentation strategy should reflect this variability.

(We will implement a simple data augmentation for MNIST in Lecture 3)

Weights initialization

$$\mathcal{N}(0,1)$$
 (large weights) $\rightarrow \mathcal{N}(0,\frac{1}{\sqrt{\text{n.of inputs}}})$ (improved weights)







Bibliography

- "Visualizing Data using t-SNE", van deer Maaten, Hinton (2008)
- http://colah.github.io/posts/2015-01-Visualizing-Representations/
- "Dropout: A Simple Way to Prevent Neural Networks from Overfitting", Srivastava et al., (2014)
- "Improving neural networks by preventing co-adaptation of feature detectors", Hinton et al. (2012).
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