

$$X = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$A = \begin{pmatrix} 0 & 1 & 1 \\ -1 & 2 & 1 \\ 1 & 0 & 1 \end{pmatrix}$$

$$Sp(A) = \{2, 1, 0\}$$

$$X_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$X_2 = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}$$

$$X = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

$$D = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$P = \begin{pmatrix} -1 & 0 & 1 \\ -1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

on  $X' = AX \Leftrightarrow X' = PD P^{-1} X$

$$\Leftrightarrow (P^{-1}X)' = D(P^{-1}X)$$

on pose  $Y = P^{-1}X$

d'où  $Y' = DY \Leftrightarrow \begin{cases} y_1' = 0 \\ y_2' = y_2 \\ y_3' = 2y_3 \end{cases} \Leftrightarrow \begin{cases} y_1 = c_1 \\ y_2 = \lambda e^t \\ y_3 = \mu e^{2t} \end{cases}$

donc  $X = PY \Leftrightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = P \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$