

Distributed Adaptive Systems (DAS) Unit

Adaptive Gossip-based Broadcast

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Gossip in Distributed Systems



- Every node that receives a message, buffers it, and then forwards it a certain number of times, each time to a randomly selected subset of processes.
 - Strong Assumption: enough buffering resources exist on all nodes.
 - Real Context: the nodes must be equipped with enough
 resources to ensure that messages are gossiped a sufficient
 number of times.
 - If a node does not have enough resources, it may drop a large number of messages than are being forwarded.
 - If several nodes do not have enough resources, reliability might end up being drastically impacted.

Problem Definition - I



- A large scale publish-subscribe application
 - Publishers which brodcast information
 - Subscribers which register interest in receiving certain types of information.
- Gossip-based broadcast is typically used to disseminate the information from the publishers to the interested subscribers.
- Since different nodes are interested in different type of information we can have different broadcasts groups.
- Any node may belong to more than one broadcast group, and this
 number varies as nodes dynamically subscribe to new types or cancel
 previous subscriptions.
- The resources at each node are limited, every node has to dynamically divide the available resources among the groups it belongs to.

Problem Definition - II



- We need a dynamic feedback mechanism where each node has different and varying amount of resources.
- Classical gossip-based algorithms discard messages in overload conditions, without providing to the source (the sender) any feedback regarding the reliability of the operation.
- The rate of new messages in the system is unpredictable and depends on the sum of the individual emission rates.
- To estimate the global congestion and control the message emission at each sender.

The Idea



To disseminate and gather information about the resources available in a broadcast group such that every sender can adjust its emission accordingly.

To ensure that senders are able to *perceive the quality of the algorithm operation*, in terms of reliability with the current system configuration, *without interacting with other nodes*.

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Algorithm Mechanisms



- 1. Distributed mechanism to determine resource availability (i.e., the size of buffers), which changes only upon reconfiguration of nodes.
- A local mechanism to determine resource usage (i.e., buffer occupancy), whose variation is far more being frequent and unpredictable as it is affected by the timing of senders and network delays.
- 3. The resulting informations from the combined mechanisms can be then used to adjust the rate at which each node is allowed to send messages.

Distributed Discovery of Resource Availability



```
Initially:
                   Interval for each estimate – period s
     s = \Delta
     \underline{\text{minbuff}_{p}^{r}} = |\underline{\text{events}}|_{m}, for all 1 \leq r \leq \Delta Size of the smallest buffer in the group.
every T ms:
      {Add information to gossip message}
     gossip.s \leftarrow s
                                                    In every gossip round, values s an minBuff
     gossip.minBuff \leftarrow minBuff_n^s
                                                    are included in the message header.
upon RECEIVE(gossip):
                                                                 Every time a node q receives a
     {Compute new known minimum}
                                                                 message from another process p, it
                                                                 updates its own estimate of minBuff
     if gossip.s=s \land gossip.minBuff < minBuff<sup>s</sup> then
                                                                 for period s
        \min Buff_n^s \leftarrow gossip.minBuff
                                                                 (min between p and q in s).
every S ms:
     emph{Enter new period}
     s \leftarrow s + 1
     \min \text{Buff}_v^s \leftarrow |\text{events}|_m
     minBuff = min(minBuff_n^s,...,minBuff_n^s)
```

Estimating Buffer Congestion



```
Initially: \operatorname{avgAge} = (H+L)/2 \\ \operatorname{lost} = \emptyset \operatorname{upon} \ \operatorname{RECEIVE}(\operatorname{gossip}): \\ \dots \\ \{ \textit{Update congestion estimate} \} \\ \operatorname{while} |\operatorname{events} \setminus \operatorname{lost}| > \operatorname{minBuff do} \\ \operatorname{select oldest element e from events} \setminus \operatorname{lost} \\ \operatorname{avgAge} = \alpha \ \operatorname{avgAge} + (1-\alpha) \ \operatorname{e.age} \\ \operatorname{lost} \leftarrow \operatorname{lost} \cup \{ \operatorname{e} \} \\ \{ \textit{Garbage collect events} \} \\ \operatorname{while} |\operatorname{events}| > |\operatorname{events}|_m \ \operatorname{do} \\ \operatorname{remove oldest element e from events}
```

Upon receiving each gossip message, after storing events and updating their ages, minBuff is used as a threshold to select which events would have to be discarded.

Rate Adaptation



To avoid that each sender changes its rate with every minor oscillation of avgAge, causing a continuous oscillation of the system.

```
every T ms:
```

```
\{Throttle\ sender\}
if avgAge > H \land avgTokens < max/2 \land \land rand > W\ then
rate \leftarrow rate \times (1 + r_H)
if avgAge < L \lor avgTokens > max/2\ then
rate \leftarrow rate \times (1 - r_L)
```

Two Threshold L and H.

L -> low-age mark

H -> high-age mark

- When the *system is congested* (i.e., the average age is below L), the sender reduces its rate by some amount denoted *rL*.
- When new resources are released in the system, and the rate can be increased (i.e,. The average age is is above H), the.
- sender increases by an amount denoted rH

System Configuration



- $S = 2 \times T$
- **⊿** = 2
- $\alpha = 0.8$
- H = 7, L = 5
- rH = 5%, rL= 5%
- W = 0.5