

Feynman's Operational Calculus and the Evolution Equation

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- Born out of a need to compute functions of non-commuting operators, which arise frequently in quantum mechanics.
- In the 1951 paper, Feynman introduced three heuristic rules to compute such functions and determine the order in which the operators would act.
- Abstract approach used here was developed later by B. Jefferies, M. L. Lapidus, G. W. Johnson, and L. Nielsen, starting from the early 80's.

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- Example: an $m \times n$ matrix A is an operator that takes a vector in \mathbb{R}^n and returns a vector in \mathbb{R}^m . If A is a $m \times p$ matrix and if B is a $p \times n$ matrix, then A corresponds to a linear map $T_A : \mathbb{R}^p \rightarrow \mathbb{R}^m$ and B corresponds to a linear map $T_B : \mathbb{R}^n \rightarrow \mathbb{R}^p$. Matrix multiplication AB corresponds to a linear map $T_{AB} : \mathbb{R}^n \rightarrow \mathbb{R}^m$. But BA may not be defined!

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- In a product, the operators act in succession from right to left: $(AB)(x) = A(B(x))$. If we have $(AB)(x) = (BA)(x)$ for all x , then A and B are said to commute. Composition is, in general, non-commutative (think of matrices).

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- Let A and B are operators: what can we say about $f(A, B)$?
- If A and B commute, then there's no ambiguity in writing $f(A, B) = AB^2$. If however they do not commute, then their order in the expression matters and one has to choose how to write that product: AB^2 , BAB , B^2A , $\frac{1}{3}AB^2 + \frac{1}{3}BAB + \frac{1}{3}B^2A$ or any expression that would give back AB^2 if A and B commuted.

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 - ③ “Disentangle” the expression by restoring the conventional order of the operators.
- Of the disentangling process, Feynman states “The process is not always easy to perform and, in fact, is the central problem of this operator calculus.” One should note that Feynman did not attempt to supply rigorous proofs of his results and, in fact, it is not always clear how Feynman's rules are to be applied, even heuristically.

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- This process is better understood with an example.

Rule 1: Attaching time indexes

- If A and B are operators, then we define

$$A(t_1)B(t_2) = \begin{cases} AB & \text{if } t_2 < t_1 \\ BA & \text{if } t_1 < t_2 \\ \text{undefined} & \text{if } t_1 = t_2 \end{cases}$$

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- The most common way to attach a time index to A is through an integral:

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- Note: the integral in this example is the usual integral over the real line (i.e. with respect to Lebesgue measure), but a variety of different measures (and hence integrals) can be used, as we will see.

Rule 2: Computing the function

- Let $f(x, y) = xy$. Associate Lebesgue measure ℓ to both operators A and B , i.e. set

$$A = \frac{1}{t} \int_0^t A(s_1) ds_1 \quad \text{and} \quad B = \frac{1}{t} \int_0^t B(s_2) ds_2,$$

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- Then we have

$$f_{\ell, \ell}(A, B) = \left(\frac{1}{t} \int_0^t A(s_1) ds_1 \right) \left(\frac{1}{t} \int_0^t B(s_2) ds_2 \right)$$

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where the subscripts serve to emphasize the measures assigned to the two operators.

Rule 3: Disentangling

- We can now split the square $[0, t] \times [0, t]$ in two triangles in which the order of the indices is unambiguous:

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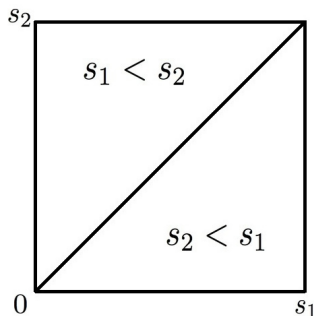
- We can now split the square $[0, t] \times [0, t]$ in two triangles in which the order of the indices is unambiguous:

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- It is worth noting that if A and B commute then $f_{\ell,\ell}(A, B) = AB$, like we expected.

Exponential of a bounded operator

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- Given its similarity to the differential equation that defines the exponential function, we write its solution as

$$u = u_0 e^{tA} := u_0 \sum_{k=0}^{\infty} \frac{(tA)^k}{k!},$$

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- Note that, since A is a bounded operator, the series will always converge, and it is thus well defined. But what would happen if A was unbounded?

Exponential of an unbounded operator

- Take, for example the heat equation

$$\frac{\partial u}{\partial t} = \Delta u,$$

or the Schrödinger equation (in natural units)

$$\frac{\partial \Psi}{\partial t} = -i \left(-\frac{1}{2} \Delta + V \right) \Psi,$$

where $\Delta = \frac{\partial^2}{\partial x_1^2} + \cdots + \frac{\partial^2}{\partial x_n^2}$ is the Laplacian, V is a potential function, and $i^2 = -1$.

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- The operator $A = \frac{i}{2} \Delta$ is unbounded and (the operator of multiplication by $-iV$) $B = -iV$ may be unbounded, and so e^{tA} and e^{tB} cannot be defined using a power series.

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- The operator $A = \frac{i}{2} \Delta$ is unbounded and (the operator of multiplication by $-iV$) $B = -iV$ may be unbounded, and so e^{tA} and e^{tB} cannot be defined using a power series.
- The operational calculus will allow us to evaluate expressions like $e^{t\Delta} e^{tV}$ in a rigorous fashion.

Disentangling the exponential function: setup

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- We begin by disentangling a function of one unbounded operator A and one bounded operator, multiplication by $V(s)$.
- A will be the infinitesimal generator of a strongly continuous (C_0) semigroup of operators: that is, a family $\{T(t)\}_{t \geq 0}$ of linear operators for which $T(t)T(s) = T(t+s)$ for all $t, s \geq 0$ and $T(0) = I$, and

$$Ax = \lim_{t \searrow 0} \frac{T(t)x - x}{t}.$$

Furthermore, we usually write $T(t) = e^{tA}$

Disentangling the exponential function: setup

- In particular, for $\zeta \in \mathbb{C}_+$, we set $A = \frac{H_0}{\zeta} = -\frac{1}{2\zeta}\Delta$ and we associate Lebesgue measure ℓ on $[0, T]$ to A . We know that the operator A is the generator of a strongly continuous semigroup with action

$$\left(e^{-tA}\varphi\right)(\xi) = \left(\frac{\zeta}{2\pi t}\right)^{d/2} \int_{\mathbb{R}^d} \varphi(u) \exp\left(-\frac{\zeta \|\xi - u\|^2}{2t}\right) du$$

for $\varphi \in L^2(\mathbb{R}^d)$ and $\xi \in \mathbb{R}^d$. By the Wiener integration formula, the above is equal to a function-space (or path) integral over

$C_0^t = \{y : [0, t] \rightarrow \mathbb{R}^d \mid y(0) = 0 \text{ and } y \text{ is continuous}\}$ with respect to Wiener measure \mathfrak{m} :

$$\left(e^{-tA}\varphi\right)(\xi) = \int_{C_0^t} \varphi\left(\zeta^{-1/2}y(t) + \xi\right) \mathfrak{m}(dy).$$

Disentangling the exponential function: setup

- We also set $V(s) \in \mathcal{L}(L^2(\mathbb{R}^d))$ to be the operator of multiplication by a bounded function $V : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$: for $f \in L^2(\mathbb{R}^d)$ and $x \in \mathbb{R}^d$, $(V(s)f)(x) = V(s, x)f(x)$. We associate the measure $\lambda = \mu + \omega\delta_\tau$ to V : μ is a continuous measure on $[0, t]$ and $\omega\delta_\tau$ is the Dirac point mass at $\tau \in [0, t]$ and weight ω .

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- Finally, we set $f(z_0, z_1) = e^{z_0}e^{z_1}$ and use the notation

$$f_{\ell; \lambda}^t(-H_0/\zeta; V) = \exp_{\ell, \lambda}^t \left(-t \frac{H_0}{\zeta} + \int_{[0, t]} V(s) \lambda(ds) \right);$$

the subscripts serve to emphasize the measure associated to each operator.

Disentangling the exponential function: computation

- Following Feynman's rules in a mathematically rigorous fashion, we obtain

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$$\begin{aligned}
 & \left(\exp_{\ell, \lambda}^t \left(-t \frac{H_0}{\zeta} + \int_{[0, t]} V(s) \lambda(ds) \right) \varphi \right) (\xi) \\
 &= \sum_{m=0}^{\infty} \frac{1}{m!} \sum_{k=0}^m \frac{m! \omega^{m-k}}{(m-k)!} \sum_{j=0}^k \int_{\Delta_{k,j}^t} \left(e^{-(t-s_k)H_0/\zeta} V(s_k) \dots \right. \\
 & \quad \dots V(s_{j+1}) e^{-(s_{j+1}-\tau)H_0/\zeta} [V(\tau)]^{m-k} e^{-(\tau-s_j)H_0/\zeta} V(s_j) \dots \\
 & \quad \left. \dots V(s_1) e^{-s_1 H_0/\zeta} \varphi \right) (\xi) \mu^k(ds_1, \dots, ds_k)
 \end{aligned}$$

Disentangling the exponential function: computation

$$\begin{aligned} &= \sum_{m=0}^{\infty} \frac{1}{m!} \sum_{k=0}^m \frac{m! \omega^{m-k}}{(m-k)!} \sum_{j=0}^k \int_{\Delta_{k;j}^t} \int_{C_0^t} V\left(\zeta^{-1/2}y(s_1) + \xi, s_1\right) \cdots \\ &\quad \cdots V\left(\zeta^{-1/2}y(s_{j+1}) + \xi, s_{j+1}\right) \left[V\left(\zeta^{-1/2}y(\tau) + \xi, \tau\right)\right]^{m-k} \cdot \\ &\quad V\left(\zeta^{-1/2}y(s_j) + \xi, s_j\right) \cdots V\left(\zeta^{-1/2}y(s_k) + \xi, s_k\right) \\ &\quad \varphi\left(\zeta^{-1/2}y(t) + \xi\right) \mathfrak{m}(dy) \mu^k(ds_1, \dots, ds_k) \end{aligned}$$

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 &\quad \cdots V\left(\zeta^{-1/2} y(s_{j+1}) + \xi, s_{j+1}\right) \left[V\left(\zeta^{-1/2} y(\tau) + \xi, \tau\right) \right]^{m-k} \cdot \\
 &\quad V\left(\zeta^{-1/2} y(s_j) + \xi, s_j\right) \cdots V\left(\zeta^{-1/2} y(s_k) + \xi, s_k\right) \\
 &\quad \varphi\left(\zeta^{-1/2} y(t) + \xi\right) \mathbf{m}(dy) \mu^k(ds_1, \dots, ds_k) \\
 &= \int_{C_0^t} \sum_{m=0}^{\infty} \frac{1}{m!} \sum_{k=0}^m \frac{m! \omega^{m-k}}{(m-k)! k!} \left(\int_{[0,t]} V\left(\zeta^{-1/2} y(s) + \xi, s\right) \mu(ds) \right)^k \cdot \\
 &\quad \left[V\left(\zeta^{-1/2} y(\tau) + \xi, \tau\right) \right]^{m-k} \varphi(\zeta^{-1/2} y(t) + \xi) \mathbf{m}(dy)
 \end{aligned}$$

$$= \int_{C_0^t} \sum_{m=0}^{\infty} \frac{1}{m!} \left(\int_{[0,t]} V \left(\zeta^{-1/2} y(s) + \xi, s \right) (\mu + \omega \delta_\tau)(ds) \right)^m \cdot \varphi(\zeta^{-1/2} y(t) + \xi) \mathfrak{m}(dy)$$

$$\begin{aligned} &= \int_{C_0^t} \sum_{m=0}^{\infty} \frac{1}{m!} \left(\int_{[0,t]} V \left(\zeta^{-1/2} y(s) + \xi, s \right) (\mu + \omega \delta_\tau)(ds) \right)^m \\ &\quad \varphi(\zeta^{-1/2} y(t) + \xi) \mathfrak{m}(dy) \\ &= \int_{C_0^t} \exp \left(\int_{[0,t]} V \left(\zeta^{-1/2} y(s) + \xi, s \right) \lambda(ds) \right) \varphi(\zeta^{-1/2} y(t) + \xi) \mathfrak{m}(dy) \end{aligned}$$

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- The expression in the previous slide, labeled $K(t)$ for convenience, satisfies an evolution equation which represents the time evolution of this disentangled operator as a function of the time t . In fact, if we let

$$K_{\text{dis}}(t) = \int_{C_0^t} \exp \left(\int_{[0,t]} V \left(\zeta^{-1/2} y(s) + \xi, s \right) \omega \delta_\tau(ds) \right) \cdot \\ \varphi(\zeta^{-1/2} y(t) + \xi) \mathfrak{m}(dy)$$

be the discrete part of $K(t)$, then

$$K(t) = K_{\text{dis}}(t) + \int_0^t e^{-(t-s)H_0/\zeta} V(s) K(s) \mu(ds).$$

- The above evolution equation is one particular example of a much more general theorem proved by Nielsen. In his paper, he went on to prove that $K(t)$ is the solution of a class of differential equations analogous to the heat equation and the Schrödinger equation.

- The above evolution equation is one particular example of a much more general theorem proved by Nielsen. In his paper, he went on to prove that $K(t)$ is the solution of a class of differential equations analogous to the heat equation and the Schrödinger equation.
- Right now, I'm working toward finding other differential equations by disentangling exponentials of different generators of (C_0) semigroups, like $A = -(-H_0)^{1/2}$, exploiting the Weiner integration formula when possible. There is also a generalized integral equation that follows from the evolution equation, of which I'm looking into some particular examples.

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- G. W. Johnson, M. L. Lapidus, *The Feynman Integral and Feynman's Operational Calculus*, Oxford Mathematical Monographs (2000).
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