Adaptive algorithms for low-rank approximation: subspace point of view and goal-oriented approximation

#### **Anthony Nouy**

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Collaborators: Marie Billaud-Friess, Loic Giraldi, Gregory Legrain, Olivier Zahm

• Objective: approximation of a multivariate function

$$u(x_1,\ldots,x_d)$$

seen as an element of a tensor space

$$V_{\|\cdot\|} = \overline{V_1 \otimes \ldots \otimes V_d}^{\|\cdot\|}.$$

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Low-rank approximation

$$u_m(x_1,...,x_d) = \sum_{i=1}^m (v_i^1 \otimes ... \otimes v_i^d)(x_1,...,x_d) = \sum_{i=1}^m v_i^1(x_1)...v_i^d(x_d)$$

• Greedy construction of the approximation (canonical decomposition):

$$\mathcal{E}(u, u_m) = \min_{\substack{v_m^1, \dots, v_m^d}} \mathcal{E}(u, u_{m-1} + v_m^1 \otimes \dots \otimes v_m^d)$$

where  $\mathcal{E}(u,\cdot)$  is a certain distance to u.

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- Convergence may be slow
- Does not exploit the tensor structure
- Redundant representation : linear dependencies in  $\{v_1^k(x_k), \dots, v_m^k(x_k)\}$ ?

#### **Outline**

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## Best approximation in Tucker format: a subspace point of view

• Tucker tensors with bounded multilinear rank:

$$\begin{split} \mathcal{T}_r &= \{v: \textit{rank}_{\mu}(v) \leq r_{\mu}, \forall \mu \in \{1, \dots, d\}\} \\ &= \left\{v = \sum_{i_1=1}^{r_1} \dots \sum_{i_d=1}^{r_d} \textit{a}_{i_1 \dots i_d} \textit{v}_{i_1}^1 \otimes \dots \otimes \textit{v}_{i_d}^d : \textit{v}_k^{\mu} \in \textit{V}^{\mu}, \textit{a} \in \mathbb{R}^{r_1 \times \dots \times r_d}\right\} \end{split}$$

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• Subspace-based parametrization

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• Best approximation — a subspace point of view:

$$\min_{v \in \mathcal{T}_r} \mathcal{E}(u, v) = \min_{\dim(U_1) = r_1} \dots \min_{\dim(U_d) = r_d} \min_{v \in U_1 \otimes \dots \otimes U_d} \mathcal{E}(u, v)$$

This yields sequences of optimal but non necessarily nested subspaces  $\{U_{\mu}^{r_{\mu}}: r_{\mu} > 1\}.$ 

## Adaptive construction of subspaces for higher-order tensors

• Greedy construction of subspaces with nestedness property

$$\mathcal{E}(u, u_m) = \min_{U_1^m \supset U_1^{m-1}} \dots \min_{U_d^m \supset U_d^{m-1}} \min_{v \in U_1^m \otimes \dots \otimes U_d^m} \mathcal{E}(u, v)$$

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Suboptimal greedy construction of subspaces with nestedness property (isotropic enrichment)

$$\begin{split} \mathcal{E}(u, u_{m-1} + \otimes_{\mu=1}^{d} w_{m}^{(\mu)}) &= \min_{w \in \mathcal{R}_{1}} \mathcal{E}(u, u_{m-1} + w), \quad U_{\mu}^{m} = U_{\mu}^{m-1} + span\{w_{m}^{(\mu)}\} \\ \mathcal{E}(u, u_{m}) &\leq (1 + \epsilon) \min_{v \in U_{1}^{m} \otimes \ldots \otimes U_{d}^{m}} \mathcal{E}(u, v) \end{split}$$

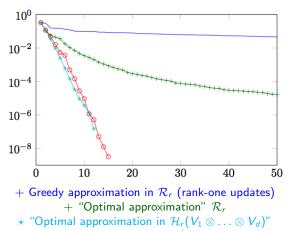
## Simple Benchmark: Poisson equation

$$-\Delta u = 1$$
 on  $\Omega = (0,1)^d$  
$$\mathcal{E}(u,w) = \mathcal{J}(w) - \mathcal{J}(u), \quad \mathcal{J}(w) = \int_{\Omega} \nabla w \cdot \nabla w - 2 \int_{\Omega} w$$
 
$$\mathcal{E}(u,w) = \|w - u\|_{H^1_0}^2$$

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#### Simple Benchmark: Poisson equation in dimension d = 8

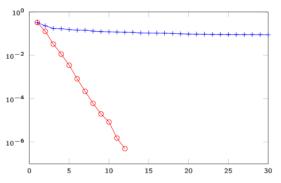
Error (norm of algebraic residual, fixed finite element discretization) with respect to the rank for different tensor formats and algorithms



 $\circ$  Suboptimal greedy construction of subspaces  $U_{\mu}^{r}$  (approximation in  $\mathcal{H}_{r}(U_{1}^{r}\otimes\ldots\otimes U_{d}^{r})$ )

#### Simple Benchmark: Poisson equation in dimension d = 27

Error with respect to the rank for different tensor formats and algorithms



+ Greedy approximation in  $\mathcal{R}_r$  (rank-one updates)

 $\circ$  Suboptimal greedy construction of subspaces  $U_\mu^r$  (approximation in  $\mathcal{H}_r(U_1^r\otimes\ldots\otimes U_d^r)$ )

#### **Outline**

# Eigenvalue problems Virginie Ehrlacher and Loic Giraldi

Computing the lowest eigenvalue of

$$Au = \lambda u, \quad u \in V = \overline{V_1 \otimes \ldots \otimes V_d}$$

with greedy construction of approximation or subspaces.

Algorithm (symmetric operator):

Start from  $u_0 = 0$ . At step m:

• Compute a rank-one correction  $w_m = \bigotimes_{\mu=1}^d w_m^{(\mu)}$  of  $u_{m-1}$ , e.g.

$$\min_{\substack{\mathbf{w}_m \in \mathcal{R}_1}} \frac{\langle A(u_{m-1} + \mathbf{w}_m), u_{m-1} + \mathbf{w}_m \rangle}{\langle u_{m-1} + \mathbf{w}_m, u_{m-1} + \mathbf{w}_m \rangle}$$

- Update of subspaces  $U_{\mu}^{m} = U_{\mu}^{m-1} + span\{w_{m}^{(\mu)}\}, \ U^{m} = U_{1}^{m} \otimes \ldots \otimes U_{d}^{m}$
- Approximate solution of the eigenproblem projected on  $U_m$ :

$$u_m \in U^m = U_1^m \otimes \ldots \otimes U_d^m, \quad \langle v, Au_m \rangle \approx \lambda \langle v, u_m \rangle \quad \forall v \in U^m$$

$$\min_{u_m \in \mathcal{M} \subset U^m} \frac{\langle Au_m, u_m \rangle}{\langle u_m, u_m \rangle}$$

## Illustration: PDE eigenvalue problem

Example considered in [Kressner & Tobler 2011]

$$\begin{cases} -\Delta u(x) + V(x)u(x) = \lambda u(x), & x \in \Omega \\ u(x) = 0, & x \in \partial \Omega \end{cases}$$

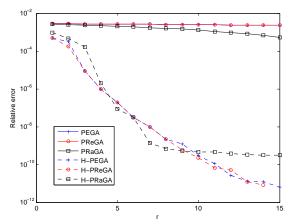
Henon-Heiles potential

$$V(x_1,\ldots,x_d) = \frac{1}{2} \sum_{i=1}^d \sigma_i x_i^2 + \sum_{i=1}^{d-1} \left( \sigma_{\star}(x_i x_{i+1}^2 - \frac{1}{3} x_i^3) + \frac{\sigma_{\star}^2}{16} (x_i^2 + x_{i+1}^2)^2 \right)$$

with  $\sigma_i = 1$  and  $\sigma_{\star} = 0.2$ 

- $\Omega = (-10, 2)^d$ , d = 20
- Finite element approximation with 128 nodes per dimension

Error with respect to the rank for different tensor formats and algorithms



- Solid lines : Greedy approximation in  $\mathcal{R}_r$  (rank-one updates)
- Dashed lines : Suboptimal greedy construction of subspaces  $U^r_\mu$  (approximation in  $\mathcal{H}_r(U^r_1 \otimes \ldots \otimes U^r_d)$ )

$$u_r = \sum_{i_1=1}^r \dots \sum_{i_d=1}^r a_{i_1 \dots i_d}^r w_{i_1}^{(1)} \otimes \dots w_{i_d}^{(d)}$$
 with low-rank approximation of  $a^r$ 

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#### **Outline**

## **Direct approximation**

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$$\alpha \|u - w\| \le \mathcal{E}(u, w) \le \beta \|u - w\|$$

for all  $w \in \mathcal{M}_{\leq r}$ , then

$$u_r = \arg\min_{w \in \mathcal{M}_{< r}} \mathcal{E}(u, w)$$

is such that

$$||u - u_r|| \le \frac{\beta}{\alpha} \min_{w \in \mathcal{M}_{< r}} ||u - w||$$

Interest of working with well conditioned formulations, i.e. such that  $\beta/\alpha \approx 1$ 

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# (Explicit) Preconditioning in tensor format

• Given an operator  $A \in W = \bigotimes_{\mu=1}^d W_\mu$ ,  $W_\mu \simeq \mathbb{R}^{n_\mu \times n_\mu}$ , we want to construct an approximation P of the inverse  $A^{-1}$  using low-rank format

$$P = \sum_{i \in I_1 imes \dots imes I_d} a_i igotimes_{\mu=1}^d P_{i_\mu}^\mu \quad ext{(structured } a)$$

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ullet Given a low rank subset  ${\mathcal M}$  of operators in W, we would like

$$\min_{P \in \mathcal{M}} \|P - A^{-1}\|_{\star}$$

for a norm  $\|\cdot\|_{\star}$  which makes computable the approximate inverse.

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- Letting  $\|\cdot\|$  denote the canonical inner product norm on W induced by Frobenius norms on the  $W_n$ :
  - $||P A^{-1}||_{\star} = ||I AP||$  (approximate right inverse)
  - $||P A^{-1}||_{\star} = ||A^{-1/2} A^{1/2}P||$  (approximate right inverse for symmetric matrices)
  - $||P A^{-1}||_{\star} = ||I PA||$  (approximate left inverse)
  - $\|P A^{-1}\|_{\star} = \|A^{-1/2} PA^{1/2}\|$  (approximate left inverse for symmetric matrices)

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## **Greedy construction of operator subspaces**

Let  $P_0 = 0$ . For m = 1, 2, ..., do

Correction step (possible additional constraints: symmetry, sparsity):

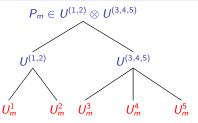
$$Q_m^1 \otimes \ldots \otimes Q_m^d \in \operatorname{arg} \min_{Q \in \mathcal{R}_1(W)} \|A^{-1} - P_{m-1} - Q\|_{\star}$$

• Update of operator subspaces:

$$U_{\mathbf{m}}^{\mu} = span\{Q_1^{\mu}, \dots, Q_m^{\mu}\}, \quad \mu \in \{1, \dots, d\}, \quad \text{and} \quad U_{\mathbf{m}} = U_{\mathbf{m}}^{\mathbf{1}} \otimes \dots \otimes U_{\mathbf{m}}^{\mathbf{d}}$$

• Approximate projection step in  $U_m$  using tree-based format:

$$P_m \in \arg\min_{\mathbf{v} \in \mathcal{H}_m^T(\mathbf{U}_m)} \|A^{-1} - P\|_{\star}$$



## Poisson equation

- d = 20
- Construction of preconditioner using  $\|A^{-1} P\|_{\star} = \|A^{-1/2} PA^{1/2}\|$
- Approximate PCG in  $\mathcal{H}_{15}^T(V)$
- Symmetric approximation

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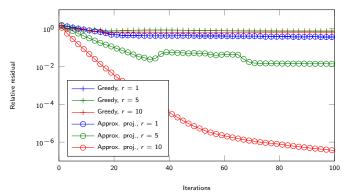


Figure: Convergence of the PCG for different preconditioners

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#### Heat equation with uncertain parameters

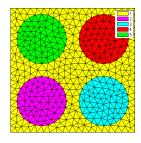


Figure: Geometry and mesh of  $\Omega$ 

$$-\nabla(K(\xi)\nabla u)=1$$
 on  $\Omega,~u=0$  on  $\partial\Omega,$  with a random diffusion field

$$K(\xi) = \sum_{i=1}^5 I_{\omega_i} \xi_i$$

 $\xi_1 \sim U(1,2), \; \xi_2, \dots, \xi_5 \sim \log U(10,100)$ 

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- $u \in V = H_0^1(\Omega) \otimes L_{\mu_1}^2(\Xi_1) \otimes \ldots \otimes L_{\mu_5}^2(\Xi_5)$
- Finite element approximation in space
- Degree 10 Legendre polynomial expansions in parametric dimensions

#### **Heat equation**

- Approximate PCG in  $\mathcal{H}_{15}^T(V)$
- Preconditioners constructed with  $\|A^{-1} P\|_{\star} = \|A^{-1/2} PA^{1/2}\|$
- Symmetric approximation

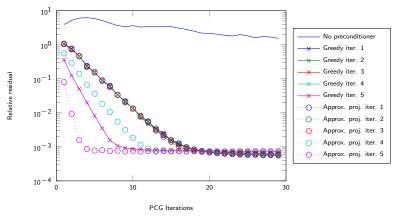


Figure: Convergence of the PCG for different preconditioners

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#### **Outline**

• Greedy construction of subspaces with nestedness property (anisotropic enrichment) At iteration m, given dimensions  $D_m$  for enrichment, let  $U_\mu^m = U_\mu^{m-1}$  for  $\mu \notin D_m$  and

$$\mathcal{E}(u, u_m) = \min_{\substack{U_{\mu}^m \supset U_{\mu}^{m-1} \ \nu \in U_1^m \otimes \ldots \otimes U_d^m \\ \mu \in D_m}} \mathcal{E}(u, v)$$

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- For the selection of the next subset of dimensions  $D_{m+1}$ :
  - $u_m \in U_\mu^m \otimes V_{[\mu]} \subset V_\mu \otimes V_{[\mu]}$ , with  $dim(U_\mu^m) = r_\mu^m$ , admits the following SVD

$$u_m = \sum_{k=1}^{r_\mu^m} \sigma_k^\mu v_k^\mu \otimes w_k^{[\mu]}$$

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• If  $u_m$  is a good approximation of the truncated SVD of u, then

$$\|u-u_m\|_{\vee (V_\mu \otimes V_{[\mu]})} pprox \sigma^\mu_{r^m_\mu+1} \leq \sigma^\mu_{r^m_\mu}$$

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## Anisotropic construction of subspaces for higher-order tensors

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- For the selection of the next subset of dimensions  $D_{m+1}$ :
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• If  $u_m$  is a good approximation of the truncated SVD of u, then

$$||u - u_m||_{\vee (V_\mu \otimes V_{[\mu]})} \approx \sigma^\mu_{r^m_\mu + 1} \le \sigma^\mu_{r^m_\mu}$$

• Letting  $0 \le \theta \le 1$ , choose

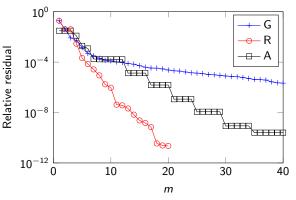
$$D_{m+1} = \left\{ \mu \in \{1, \dots, d\} : \sigma^{\mu}_{r^{m}_{\mu}} \geq \theta \max_{1 \leq \nu \leq d} \sigma^{\nu}_{r^{m}_{\nu}} \right\}$$

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$$\begin{split} -\nabla \cdot \left( \mathsf{K} \nabla u \right) + \xi_2 u &= 1 \quad \text{on} \quad \Omega, \quad u = 0 \quad \text{on} \quad \partial \Omega \\ &\quad \mathsf{K} = 1 + \xi_1 \mathsf{I}_D(x) \\ &\quad \xi_1 \sim \mathit{U}(0, 10), \quad \xi_2 \sim \mathit{U}(0, 1) \\ &\quad u \in \mathit{H}^1_0(\Omega) \otimes \mathit{L}^2(\Xi_1) \otimes \mathit{L}^2(\Xi_2) \end{split}$$

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Error with respect to iteration for different tensor formats and algorithms



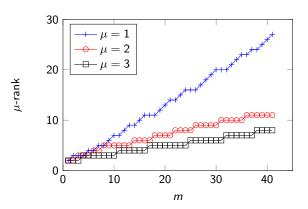
+ Greedy approximation in  $\mathcal{R}_r$  (rank-one updates)

 $\circ$  Suboptimal greedy construction of subspaces based on rank-one corrections (isotropic)

☐ Suboptimal greedy construction of subspaces with anisotropic enrichment

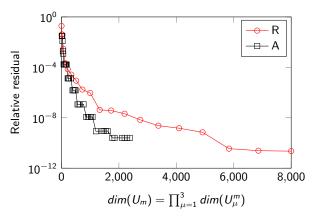
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Ranks with respect to iteration m for anisotropic construction



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Error with respect to the dimension of the reduced space  $U^m$  for greedy constructions of subspaces.



Suboptimal greedy construction of subspaces based on rank-one corrections (isotropic)
 □ Suboptimal greedy construction of subspaces with anisotropic enrichment

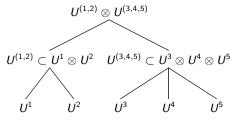
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## Construction of subspaces for tree-based formats

Tensors with bounded tree-based rank

$$\mathcal{H}_r^T = \{ v : v \in U_\alpha \otimes U_{\alpha^c}, \dim(U_\alpha) \leq r_\alpha, \alpha \in T \}$$

s.t. the set of subspaces  $\{U_{\alpha}\}_{{\alpha}\in\mathcal{T}}$  has a hierarchical structure



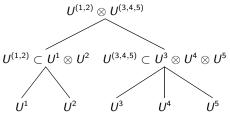
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• Best approximation problems - a subspace point of view

$$\min_{v \in \mathcal{H}_r^T} \|u - v\| = \min_{\substack{U_{\mu} \subset V_{\mu} \\ \dim(U_{\mu}) = r_{\mu} \\ \mu \in \{1, \dots d\}}} \min_{\substack{U_{\alpha} \subset \bigotimes \\ \beta \in S(\alpha) \\ \dim(U_{\alpha}) = r_{\alpha} \\ \alpha \in I(T)}} \min_{v \in \bigotimes \\ \beta \in S(D)} U_{\beta} \|u - v\|$$

define sequences of optimal and non necessarily nested subspaces  $\{U_{\alpha}^{r_{\alpha}}; r_{\alpha} \geq 1\}$ .

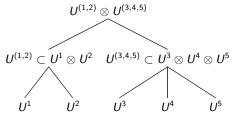
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s.t. the set of subspaces  $\{U_{\alpha}\}_{{\alpha}\in\mathcal{T}}$  has a hierarchical structure



• Best approximation problems - a subspace point of view

$$\min_{v \in \mathcal{H}_r^T} \|u - v\| = \min_{\substack{U_{\mu} \subset V_{\mu} \\ \dim(U_{\mu}) = r_{\mu} \\ \mu \in \{1, \dots d\}}} \min_{\substack{U_{\alpha} \subset \bigotimes \\ \dim(U_{\alpha}) = r_{\alpha} \\ \alpha \in l(T)}} \min_{v \in \bigotimes \\ \beta \in S(D)} U_{\beta} \|u - v\|$$

define sequences of optimal and non necessarily nested subspaces  $\{U_{\alpha}^{r_{\alpha}}; r_{\alpha} \geq 1\}$ .

 Algorithms for the construction of suboptimal sequences of nested subspaces ... strategies of enrichment for non isotropic constructions?

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## **Outline**

## Low-rank approximation based on residual minimization

#### Problem to solve

$$A(u) = b$$
 with  $u \in V = \bigotimes_{\nu=1}^d V^{
u}$ 

Given a low-rank tensor subset  $\mathcal{M}$ , replace

$$\inf_{v \in \mathcal{M}} \|u - v\|$$

by the optimization of a criterium

$$\inf_{v \in \mathcal{M}} \mathcal{E}(v, u)$$

yielding an computable approximation of u in  $\mathcal{M}$ .

$$\mathcal{E}(v, u) = \|b - Av\|_*^2$$
 Good residual norms?

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#### Ideal minimal residual formulation

## Definition of best approximations based on minimal residual formulation

$$\min_{v \in \mathcal{M}} \left\| Av - b \right\|_*$$

with a residual norm such that

$$\boxed{\|Av - b\|_* \approx \|u - v\|_V}$$

with  $\left\|\cdot\right\|_{V}$  a chosen norm on V.

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### Ideal minimal residual formulation

## Definition of best approximations based on minimal residual formulation

$$\overline{\min_{v \in \mathcal{M}} \|Av - b\|_*}$$

with a residual norm such that

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with  $\|\cdot\|_V$  a chosen norm on V.

#### Example: weighted Sobolev norms

$$u \in H_0^1(\Omega) \otimes L_\mu^2(\Xi), \quad \|u\|_V^2 = \int_{\Omega \times \Xi} \alpha(x,\xi) \nabla u^2 dx \, d\mu(\xi)$$
$$\alpha(x,\xi) = \alpha_1(\xi) I_{\Omega_1}(x) + \alpha_2(\xi) I_{\Omega \setminus \Omega_1}(x) \text{ with } \Omega_1 \subset \Omega$$

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$$\|u - v\|_{V,\alpha}^2 = \|u - v\|_{V,0}^2 + \alpha \|Lu - Lv\|_Z^2$$

with

$$L:V\to Z$$

$$\|u - v\|_{V,\alpha}^2 = \|u - v\|_{V,0}^2 + \alpha \|Lu - Lv\|_Z^2$$

with

$$L:V\to Z$$

Example: quantities of interest in uncertainty quantification

$$u\in L^2_\mu(\Xi)\otimes \mathcal{V}$$

$$||u - v||_{V,\alpha}^2 = ||u - v||_{V,0}^2 + \alpha ||Lu - Lv||_Z^2$$

with

$$L:V\to Z$$

Example: quantities of interest in uncertainty quantification

$$u \in L^2_\mu(\Xi) \otimes \mathcal{V}$$

Variable of interest

$$Lu(\xi) = \ell(u(\xi); \xi), \quad Z = L^2_{\mu}(\Xi)$$

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$$||u - v||_{V,\alpha}^2 = ||u - v||_{V,0}^2 + \alpha ||Lu - Lv||_Z^2$$

with

$$L:V\to Z$$

Example: quantities of interest in uncertainty quantification

$$u \in L^2_\mu(\Xi) \otimes \mathcal{V}$$

Variable of interest

$$Lu(\xi) = \ell(u(\xi); \xi), \quad Z = L_u^2(\Xi)$$

Expectation

$$L(u) = \mathbb{E}_{\mu}(\ell(u(\xi); \xi)), \quad Z = \mathbb{R}$$

• Conditional expectation

$$L(u) = \mathbb{E}_{\mu}(\ell(u(\xi);\xi)|\xi_{\nu}), \quad Z = L^2_{\mu_{\nu}}(\Xi_{\nu})$$

### A strategy for weakly coercive problems

$$Au = b$$
,  $u \in V$ ,  $b \in W'$ ,  $A: V \to W'$ 

with A defining an isomorphism such that  $\alpha \|v\|_V \leq \|Av\|_{W'} \leq \beta \|v\|_V$ .

#### Ideal approach

Work with two different norms on V and W such that

$$\|\cdot\|_V=\|A(\cdot)\|_{W'}$$

corresponding to  $\alpha = \beta = 1$ , and therefore

$$||Av - b||_{W'} = ||v - u||_V$$

Denoting by  $R_V:V\to V'$  and  $R_W:W\to W'$  the Riesz maps, it is equivalent to imposing

$$R_W = AR_V^{-1}A^*$$

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Let  $\Lambda^{\delta}: W \to W$  be such that for all y (in a particular subset),

$$\|\Lambda^{\delta}(y) - y\|_{W} \leq \delta \|y\|_{W}.$$

Then, letting

$$||Av - b||_* = ||\Lambda^{\delta} R_W^{-1} (Av - b)||_W$$

we have

$$\boxed{(1-\delta)\|u-v\|_{V} \leq \|Av-b\|_{*} \leq (1+\delta)\|u-v\|_{V}}$$

#### Approximation in a tensor subset

Let  $\mathcal{M} \subset V$  be a given approximation subset. We would like to solve

$$u^{\delta} \in \min_{v \in \mathcal{M}} \|\Lambda^{\delta} R_W^{-1} (Av - b)\|_W$$

## Quasi-best approximation with respect to $\|\cdot\|_V$

$$\|u-u^{\delta}\|_{V} \leq \frac{1+\delta}{1-\delta} \inf_{v \in \mathcal{M}} \|u-v\|_{V}$$

# **Algorithm**

#### Gradient-type algorithm

Initialize  $u^0 = 0$  and construct a sequence  $\{u^k\}_{k \ge 1}$  such that

$$y^k = \Lambda^{\delta}(R_W^{-1}(Au^k - b))$$

with

•  $y^k = \Lambda^{\delta}(z^k)$  with

$$\left\langle R_W z^k, \delta y \right\rangle_{W',W} = \left\langle A u^k - b, \delta y \right\rangle_{W',W} \quad \forall \delta y \in W$$

solved with a tensor approximation method (with precision  $\delta$ ).

• Quasi-best approximations in  $\mathcal{M}$ :

$$\Pi_{\mathcal{M}}^{\epsilon}(u) = \left\{ w \in \mathcal{M} : \|u - w\|_{V} \leq (1 + \epsilon) \min_{v \in \mathcal{M}} \|u - v\|_{V} \right\}$$

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## Properties of the gradient-type algorithm

• If  $\delta(2+\epsilon) < 1$ , then

$$\limsup_{k \to \infty} \|u^k - u\|_V \le \frac{1 + \epsilon}{1 - \delta(2 + \epsilon)} \inf_{v \in \mathcal{M}} \|u - v\|_V$$

- For  $\delta = 0$ , convergence in one iteration  $(u^1 \in \Pi^{\epsilon}_{\mathcal{M}}(u))$ .
- For  $\delta \neq 0$ , quite fast convergence.

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- For  $\delta \neq 0$ , quite fast convergence.

#### Error estimation

$$(1-\delta)\|u^k-u\|_V < \|v^k\|_W < (1+\delta)\|u^k-u\|_V$$

Furthermore, if  $\Lambda^{\delta}$  is an W-orthogonal projection onto some subspace of W, then

$$\sqrt{1-\delta^2}\|u^k - u\|_V \le \|y^k\|_W \le \|u^k - u\|_V$$

# Progressive (greedy-type) algorithm for solving Au = b

### Greedy-type algorithm

Let  $u_0 = 0$  and  $U_0 = 0$ . For m > 1,

- **1** Set  $b_m = b Au_{m-1}$ .
- **2** Compute a correction  $w_m \in \mathcal{M}$  of  $u u_{m-1}$  such that

$$||Aw_m - b_m||_W \le (1 + \lambda_m) \min_{w \in \mathcal{M}} ||Aw - b_m||_W$$

with  $||Aw - b_m||_W = ||u - u_{m-1} - w_m||_V$ . Use a gradient type algorithm with precision  $\delta_m$  ( $\lambda_m > \delta_m$ ).

ullet Define a subspace  $U_m$  such that  $U_m\supset U_{m-1}$  and  $w_m\in U_m$ , and compute  $u_m\in U_m$  such that

$$||u - u_m||_V \le (1 + \delta'_m) \min_{v \in U_m} ||u - v||_V$$

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# Progressive (greedy-type) algorithm for solving Au = b

Define

$$\kappa_{\it m} = 1 - \beta_{\it m} \alpha_{\it m}^2$$

with

$$eta_m = (1 - \delta_m')^{-2} (1 + \lambda_m)^2 - 1$$
 and  $lpha_m = rac{\|u - u_{m-1} - w_m\|_V}{\|w_m\|_V}$ 

#### Convergence result

Assume

$$\delta_m' o 0$$

and

$$\kappa_m \ge 0, \quad \sum_m \kappa_m = +\infty$$

Then, the sequence  $\{u_m\}_{m\geq 1}$  converges towards the solution u.

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## Illustration: advection-diffusion-reaction equation

$$A(u) = -a_1 \Delta u + a_2 u + a_3 c \cdot \nabla u = I_{\Omega_1} \quad \text{on} \quad \Omega$$

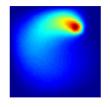
$$u = 0 \quad \text{on} \quad \partial \Omega$$

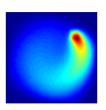


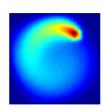
#### Uncertain parameters

$$a_1 = \mu_1(1 + 0.2\xi_1), \quad a_2 = \mu_2(1 + 0.2\xi_2), \quad a_3 = \xi_3$$
  
 $\xi_i \in U(-1, 1), \ \Xi = (-1, 1)^3$ 

Samples of the solution  $u(x, \xi)$ 







## Description of the solution method

$$A(u) = b$$
,  $A: V \to W'$ ,  $V = W = \mathcal{V}_N \otimes \mathcal{S}_P$ 

with  $\mathcal{V}_N$  a finite element space and  $\mathcal{S}_P = \mathbb{P}_4(-1,1) \otimes \mathbb{P}_4((-1,0),(0,1)) \otimes \mathbb{P}_4(-1,1)$ .

#### Progressive construction of tensor approximation

We choose the canonical norm

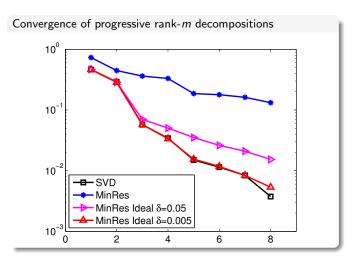
$$||u||_{V}^{2} = \int_{\Xi} ||u(\xi)||_{\mathcal{V}_{N}}^{2} d\mu(\xi)$$

- We choose  $\mathcal{M} = \mathcal{R}_1 = \{ v \otimes \phi; v \in \mathcal{V}_N, \phi \in \mathcal{S}_P \}$ , the set of rank-one elements
- Progressive construction of  $u_m = u_{m-1} + w_m$  with  $w_m \in \mathcal{M}$  an approximate solution of

$$\min_{w\in\mathcal{M}}\left\|A(u_{m-1}+w)-b\right\|_*$$

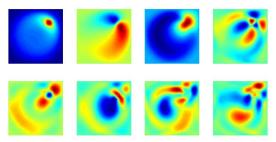
For  $||A(\cdot)||_* = ||\cdot||_V$ ,  $u_m$  is the ideal rank-m approximation (SVD).

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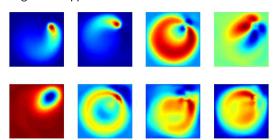


- For  $||A(\cdot)||_* = ||A(\cdot)||_V$ , classical Minimal Residual formulation
- As  $\delta \rightarrow$  0, convergence to the SVD
- For a fixed  $\delta$ , it coincides with SVD up to precision  $\delta$ .

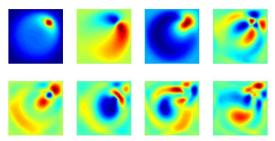
- 8 first spatial modes  $v_i$  of the decomposition  $u_m = \sum_{i=1}^m v_i \otimes \phi_i$ 
  - Singular Value Decomposition of u



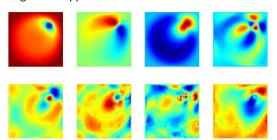
• Progressive approximation based on Minimal residual (canonical norm)



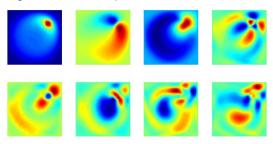
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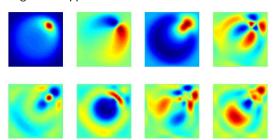
• Progressive approximation based on Ideal Minimal residual ( $\delta=0.05$ )



- 8 first spatial modes  $v_i$  of the decomposition  $u_m = \sum_{i=1}^m v_i \otimes \phi_i$ 
  - Singular Value Decomposition of u



ullet Progressive approximation based on Ideal Minimal residual ( $\delta=0.005$ )



### Illustration on a benchmark

# Cooling of electronic components (benchmark OPUS : http://www.opus-project.fr)

$$-\nabla \cdot \kappa \nabla u + \mathbf{D} \mathbf{v} \cdot \nabla u = \mathbf{f}$$

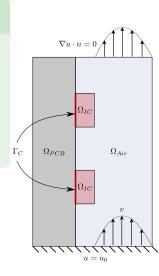
- $\kappa_{\text{IC}} \sim \log \mathcal{U} \Big( 0.2, 2 \Big) \leadsto \text{diffusion coefficient}$
- $\bullet$   $\textbf{\textit{r}} \sim \log \mathcal{U} \Big(0.1, 100\Big) \leadsto$  thermal contact conductance
- ullet  $D\sim \log \mathcal{U}\Big(5.10^{-4},10^{-2}\Big) \leadsto$  advection intensity

#### Variable of interest:

$$\ell(u(\xi);\xi) = \int_{\Omega_{IC}} u(x,\xi) dx$$

#### Quantity of interest:

$$Lu = \mathbb{E}_{u} \left( \ell(u(\xi); \xi) | \kappa_{IC} \right)$$



## Numerical results : $\delta = 0.5$ , $\varepsilon = 10^{-3}$

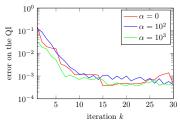


Figure: Evolution of the error on the quantity of interest during iteration process

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## Numerical results : $\delta = 0.5$ , $\varepsilon = 10^{-3}$

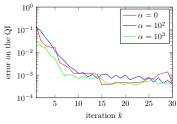


Figure: Evolution of the error on the quantity of interest during iteration process

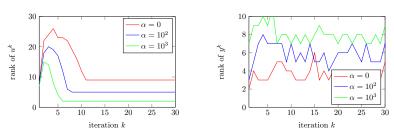


Figure: Evolution of the rank of  $u^k$  and  $y^k$  during iteration process

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## Numerical results: rank of the approximation

$\alpha \setminus \varepsilon$	$10^{-1}$	$10^{-2}$	$10^{-3}$	$10^{-4}$	$10^{-5}$
0	3	5	9	15	21
10 <sup>2</sup> 10 <sup>3</sup>	2	4	5	10	17
10 <sup>3</sup>	1	1	2	8	14
10 <sup>4</sup> 10 <sup>5</sup>	1	1	1	3	7
10 <sup>5</sup>	1	1	1	1	4
CMR	5	9	14	20	36

Figure: Final rank of the approximation  $u^k$ 

Comparison with the canonical minimal residual method (CMR) :

$$\min_{v \in \mathcal{M}_r} \|Av - b\|_X \quad \leadsto \quad ext{ error on the QI evaluated } a \ posteriori$$

## On-going works and open questions

- A priori results for greedy constructions of subspaces: optimal vs nested subspaces
- Strategy for general tree-based formats ?
- Optimal approximation with respect to quantities of interest (not norms)

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