

Problem 1.

Solution: Note that f is continuous at every point in \mathbb{R}^3 . This implies that Jacobian exists. Let $f_1 : \mathbb{R}^3 \rightarrow \mathbb{R}$, $f_1(x_1, x_2, x_3) = x_1x_2 + \sin(x_3) + x_1^2$ and $f_2 : \mathbb{R}^3 \rightarrow \mathbb{R}^1$, $f_2(x_1, x_2, x_3) = 7 + e^{x_2}$. Therefore

$$\nabla f_1 = [x_2 + 2x_1 \quad x_2 \quad \cos(x_3)] \quad \nabla f_2 = [0 \quad e^{x_2} \quad 0]$$

This implies that

$$J_x = \begin{bmatrix} x_2 + 2x_1 & x_2 & \cos(x_3) \\ 0 & e^{x_2} & 0 \end{bmatrix}$$

We now aim to show what induced one norm on a matrix. For any $x \in \mathbb{R}^n$ and $A \in \mathbb{R}^{m \times n}$, we can see that:

$$\begin{aligned} Ax &= \sum_{j=1}^n a_{ij}x_j \\ \|Ax\|_1 &= \sum_{i=1}^m \left| \sum_{j=1}^n a_{ij}x_j \right| \\ &\leq \sum_{i=1}^m \sum_{j=1}^n |a_{ij}| \cdot |x_j| \\ &\leq \sum_{j=1}^n |x_j| \sum_{i=1}^m |a_{ij}| \\ &\leq \sum_{j=1}^n |x_j| \max_j |c_j| \\ &\leq \max_j |c_j| \end{aligned}$$

where c_j denotes the sum of the j th column. To prove the reverse direction, we can see that if we let $x = e_j$, where it is the maximum column sum, we can see that

$$\|Ax\|_1 = \sup_{\|x\|_1=1} \|Ax\|_1 \geq \max_j |c_j|$$

which implies that $\|A\|_1 = \max_j |c_j|$. Therefore, we see that

$$k_{abs} = \max\{|x_2 + 2x_1|, |x_1 + e^{x_2}|, |\cos(x_3)|\}$$

Therefore, since $k_{rel} = k_{abs} \cdot \frac{\|x\|_1}{\|f(x)\|_1}$, we see that:

$$k_{abs} = \max\{|x_2 + 2x_1|, |x_1 + e^{x_2}|, |\cos(x_3)|\} \cdot \frac{|x_1| + |x_2| + |x_3|}{|x_2 + 2x_1| + |x_1 + e^{x_2}| + |\cos(x_3)|}$$

□

Problem 2.

Solution: Let $x, X, y, Y \in \mathbb{R}$, the following are derived from the statements given.

$$\begin{aligned} x\| \cdot \|_c &\leq \| \cdot \|_a \leq X\| \cdot \|_c \\ y\| \cdot \|_b &\leq \| \cdot \|_c \leq Y\| \cdot \|_b \end{aligned}$$

We can combine these inequalities to find that:

$$xy\| \cdot \|_b \leq x\| \cdot \|_c \leq \| \cdot \|_a \leq X\| \cdot \|_c \leq XY\| \cdot \|_b$$

Thus, showing that $\| \cdot \|_a$ and $\| \cdot \|_b$ are indeed equivalent. \square

Problem 3. WIP

Solution: If $p = q$, the statement is obvious. We aim to prove that the 1 norm is equivalent to the p norm and use transitivity of norms to prove the statement. First, consider $p, q \in \mathbb{R}, p > q \geq 1$. We can consider the following for any $x \in \mathbb{R}^n$ (or \mathbb{C}^n):

$$\|x\|_q^q = \sum_i^n |x_i|^q = \sum_{i=1}^n 1 \cdot |x_i|^q$$

By holder's inequality, we know that:

$$\sum_{i=1}^n 1 \cdot (x_i)^q \leq \left(\sum_{i=1}^n 1^a \right)^{\frac{1}{a}} \left(\sum_{i=1}^n (|x_i|^q)^b \right)^{\frac{1}{b}}$$

such that $\frac{1}{a} + \frac{1}{b} = 1$. Since the choice of a and b are arbitrary, we can let b a value such that $b^{-1} = \frac{q}{p}$. From here, we can perform the following algebra to see that:

$$a = \frac{b}{b-1} = \frac{p}{p-q}$$

and thus:

$$\begin{aligned} \|x\|_q^q &\leq \left(\sum_{i=1}^n 1^a \right)^{\frac{1}{a}} \left(\sum_{i=1}^n (|x_i|^q)^b \right)^{\frac{1}{b}} \\ \|x\|_q^q &\leq \left(\sum_{i=1}^n 1 \right)^{\frac{p-q}{p}} \left(\sum_{i=1}^n |x_i|^p \right)^{\frac{q}{p}} \\ \|x\|_q^q &\leq n^{\frac{p-q}{p}} \|x\|_p^q \\ \|x\|_q &\leq n^{\frac{p-q}{pq}} \|x\|_p \end{aligned}$$

Let $q = 1$ and $p > 1$. we know aim to bound $\|x\|_1$ from below. Let $\{e_1, e_2, \dots, e_n\}$ denote the standard basis vectors of \mathbb{R}^n . Let $x = (x_1, x_2, \dots, x_n)$. and we can see that:

$$x = \sum_{i=1}^n e_i x_i$$

Thus, we can see that:

$$\|x\|_p = \left\| \sum_{i=1}^n x_i e_i \right\|_p$$

By the triangle inequality and the properties of the norm, we know that:

$$\left\| \sum_{i=1}^n x_i e_i \right\|_p \leq \sum_{i=1}^n \|x_i e_i\|_p = \sum_{i=1}^n |x_i| \cdot \|e_i\|_p$$

Let $M = \max_{i \in \{1, 2, \dots, n\}} \|e_i\|_p$. Thus, it follows that:

$$\|x\|_p \leq \sum_{i=1}^n |x_i| \cdot \|e_i\|_p \leq M \sum_{i=1}^n |x_i| = M \|x\|_1$$

Thus, we can see that:

$$\frac{1}{M} \|x\|_p \leq \|x\|_1 \leq n^{\frac{p-1}{p}} \|x\|_p$$

Thus, we have proved that 1 norm and the p norm is equivalent. Thus, by transitive of norms, we can see that 1 and q are equivalent, which implies that p and q are equivalent norms. \square

Problem 4.

Solution: Consider the following: We know that by the definition of the induced norm that:

$$\|Ax\|_a \leq \|A\|_{a \leftarrow c} \cdot \|x\|_c$$

as

$$\|A\|_{a \leftarrow c} := \sup \frac{\|Ax\|_a}{\|x\|_c}, \forall x \in \mathbb{R}^n$$

Let $y = Bx$, we see that:

$$\|Ay\|_a \leq \|A\|_{a \leftarrow c} \cdot \|Bx\|_c$$

But, since we know that:

$$\|B\|_{c \leftarrow b} := \sup \frac{\|Bx\|_c}{\|x\|_b}, \forall x \in \mathbb{R}^n$$

we can see that:

$$\|Bx\|_c \leq \|B\|_{c \leftarrow b} \cdot \|x\|_b$$

Thus, we can see that, if we were to combine these two inequalities, we get that:

$$\|Ay\|_a \leq \|A\|_{a \leftarrow c} \cdot \|B\|_{c \leftarrow b} \cdot \|x\|_b$$

We can see that

$$\begin{aligned} \|ABx\|_a &\leq \|A\|_{a \leftarrow c} \cdot \|B\|_{c \leftarrow b} \cdot \|x\|_b \\ \frac{\|ABx\|_a}{\|x\|_b} &\leq \|A\|_{a \leftarrow c} \cdot \|B\|_{c \leftarrow b} \end{aligned}$$

We can take the supremum of $\frac{\|ABx\|_a}{\|x\|_b}$, and we can see that:

$$\|AB\|_{a \leftarrow b} = \|A\|_{a \leftarrow c} \|B\|_{c \leftarrow b}$$

□

Problem 5. WIP

Problem 6.

Solution: Let $a_1 = 2 \sin(\pi x) + \sin(\pi x)$ and $a_2 = -3 \sin(\pi x) + \sin(2\pi x)$. Let $q_1 = \frac{a_1}{\|a_1\|}$. Thus, we can proceed with the following computation:

$$\begin{aligned} \langle a_1, a_1 \rangle &= \langle 2 \sin(\pi x) + \sin(\pi x), 2 \sin(\pi x) + \sin(\pi x) \rangle \\ &= \int_0^1 (2 \sin(2\pi x) + \sin(\pi x))^2 dx \\ &= \int_0^1 4 \sin^2(2\pi x) + 4 \sin(\pi x) \sin(2\pi x) + \sin^2(\pi x) dx \end{aligned}$$

Note that $\int_0^1 \sin(\pi x) \sin(2\pi x) dx = 0$. Thus, we can see that:

$$\begin{aligned} \langle a_1, a_1 \rangle &= \int_0^1 4 \sin^2(2\pi x) + 4 \sin(\pi x) \sin(2\pi x) + \sin^2(\pi x) dx \\ &= \int_0^1 4 \sin^2(2\pi x) + \sin^2(\pi x) dx \end{aligned}$$

Note $\int_0^1 \sin^2(n\pi x) = 0.5, \forall n \in \mathbb{N}$. Thus, we can see that:

$$\langle a_1, a_1 \rangle = \int_0^1 4 \sin^2(2\pi x) + \sin^2(\pi x) dx = 2 + 0.5 = \frac{5}{2}$$

This implies that:

$$q_1 = \sqrt{\frac{2}{5}} (2 \sin(2\pi x) + \sin(\pi x))$$

How, we must consider solving the following $v_2 = a_2 - \text{proj}_{a_2} q_1 = a_2 - \langle a_2, q_1 \rangle q_1$. We now the following the integral;

$$\begin{aligned} \sqrt{\frac{2}{5}} \int_0^1 (2 \sin(2\pi x) + \sin(\pi x)) (\sin(2\pi x) - 3 \sin(\pi x)) dx &= \sqrt{\frac{2}{5}} \int_0^1 2 \sin^2(2\pi x) - 3 \sin^2(\pi x) dx \\ &= \sqrt{\frac{2}{5}} * \frac{-1}{2} \\ &= -\sqrt{\frac{1}{10}} \end{aligned}$$

Thus, we see that $v_2 = a_2 - \text{proj}_{a_2} q_1 = a_2 - \langle a_2, q_1 \rangle q_1 = a_2 + \left(\sqrt{\frac{1}{10}}\right) \left(\sqrt{\frac{2}{5}}\right) a_1 = a_2 + 0.2a_1$. Simplifying the vectors, we can see that we can simplify to:

$$-3\sin(\pi x) + \sin(2\pi x) + 0.2(2\sin(2\pi x) + \sin(\pi x)) = \frac{-14}{5}\sin(\pi x) + \frac{7}{5}\sin(2\pi x)$$

We now proceed with the following calculation:

$$\begin{aligned} \int_0^1 \left(\frac{7}{5}(-2\sin(\pi x) + \sin(2\pi x)) \right)^2 dx &= \frac{49}{25} \int_0^1 4\sin^2(\pi x) + \sin^2(2\pi x) dx \\ &= \frac{49}{25} \left(2 + \frac{1}{2} \right) \\ &= \frac{49}{10} \end{aligned}$$

We see that $\|v_2\| = \frac{7}{\sqrt{10}}$. Therefore, we can see that

$$q_1 = \sqrt{\frac{2}{5}}(2\sin(2\pi x) + \sin(\pi x)), q_2 = \frac{7}{\sqrt{10}}(\sin(2\pi x) - 2\sin(\pi x))$$

Note that $r_{11} = \sqrt{\frac{5}{2}}$, $r_{12} = \frac{\langle a_2, q_1 \rangle}{\|q_1\|} = -\frac{1}{\sqrt{10}}$, $r_{22} = \frac{7}{\sqrt{10}} = \|v_2\|$. Thus, this implies that:

$$R = \begin{bmatrix} \sqrt{\frac{5}{2}} & -\sqrt{\frac{1}{10}} \\ 0 & \frac{7}{\sqrt{10}} \end{bmatrix}$$

□