

Problem 1a. (*T/F*) In order to generate persistence in business cycle fluctuations, we need to model a persistent process for productivity shock

Solution: **False.** While we can model a persistent shock to productivity to show that there are such in business cycle fluctuations, this does not guarantee that we can do so for all shocks. This only depends if we know that the shock itself is autoregressive in nature. If the shock is autoregressive, then we know that the shock will die sufficiently fast enough such that it follows growth facts. If not, it could have some unexpected behavior. \square

Problem 1b. (*T/F*) The value function iteration algorithm for a stochastic model involves discretizing both the endogenous and exogenous state space and iterating on the value function for each grid on the state space.

Solution: **True.** This is a standard formulation of the value function iteration algorithm. \square

Problem 1c. (*T/F*) Calculating correlation between raw data (e.g., real GDP vs consumption) would still give us a good sense of how the variables co-move along business cycle

Solution: **False.** This is because there is some noise within the data that must be removed before any proper analysis can be conducted. The noise being the cyclical part of the data, which means that we have to use a filter like the HP filter to ensure that we conduct analysis only on the residual cyclical data rather than entire data. \square

Problem 3. Consider the same model environment as in lecture. Suppose that the wage distribution follows a uniform distribution $w \sim u(\underline{w}, \bar{w})$. For parameters, use $\beta = 0.9$, $b = 0.3$, $\underline{w} = 0$, and $\bar{w} = 1$

Problem 3.1. Describe the value function iteration algorithm verbally. Describe each step.

Solution: We first

- Choose an error ϵ
- discretize the space of wage $w_i \in \{w_1, w_2, \dots, w_n\}$
- Initialize the probabilities of each wage, a tuple of length n , where $\{\frac{1}{n}, \frac{1}{n}, \dots, \frac{1}{n}\}$
- Pick a guess $V \in \mathbb{R}^n$
- Calculate $V = \text{some equation}$
- Calculate $|V' - V|$, and if this is less than ϵ , end and return values.
- If else, continue to next iteration.

□

Problem 3.2.

Solution:

```
1      % McCall Model - Baseline Solution + Parameter Analysis +  
      Plot Saving  
2      clear; clc; close all;  
3  
4      %% ==== BASELINE PARAMETERS  
      =====  
5      beta = 0.90;  
6      b    = 0.30;  
7      wMin = 0.0; wMax = 1.0;  
8      N    = 10000;  
9  
10     wGrid = linspace(wMin, wMax, N)';  
11     Ve    = wGrid ./ (1 - beta);  
12  
13     %% ==== VALUE FUNCTION ITERATION  
      =====  
14     Vu    = 0; tol = 1e-10; diff = Inf;  
15  
16     while diff > tol  
17         EV    = mean( max(Ve, Vu) );  
18         Vu_new = b + beta * EV;  
19         diff   = abs(Vu_new - Vu);
```

```
20     Vu      = Vu_new;
21 end
22
23 wStar = (1 - beta) * Vu;
24 Vw     = max(Vu, Ve);
25
26 fprintf('\nBaseline Results:\n');
27 fprintf('  Vu    = %.8f\n', Vu);
28 fprintf('  w*    = %.8f\n\n', wStar);
29
30 %% ==== FIGURE 1: Accept/Reject
31     =====
32 decisionRule = Ve >= Vu;
33
34 figure(1); clf;
35 plot(wGrid, decisionRule, '.', 'MarkerSize', 4); hold on;
36 xline(wStar, 'r--', 'w*', 'LineWidth', 1.5, ...
37       'LabelHorizontalAlignment', 'left', '
38       LabelVerticalAlignment', 'middle');
39 xlabel('wage offer w'); ylabel('Accept? (1 = Yes, 0 = No)');
40 title('Figure 1: Accept-Reject Decision Rule');
41 ylim([-0.05, 1.05]); grid on;
42 saveas(gcf, 'figure1_accept_rule.pdf');
43
44 %% ==== FIGURE 2: Value Function
45     =====
46 figure(2); clf;
47 plot(wGrid, Vw, 'b', 'LineWidth', 1.4); hold on;
48 xline(wStar, 'r--', 'w*', 'LineWidth', 1.5, ...
49       'LabelHorizontalAlignment', 'left', '
50       LabelVerticalAlignment', 'middle');
51 yline(Vu, 'k--', 'V_u', 'LineWidth', 1.2);
52 xlabel('wage'); ylabel('value');
53 title('Figure 2: Value Function  $V(w) = \max\{V_u, V_e(w)\}$ ');
54 grid on;
55 ylim([0.95*Vu, max(Vw)*1.05]);
56 saveas(gcf, 'figure2_value_function.pdf');
57
58 %% ==== COMPARATIVE STATICS
59     =====
60 betaVec = linspace(0.5, 0.99, 60);
61 bVec     = linspace(0.0, 0.5, 60);
62 wStar_beta = zeros(size(betaVec));
63 wStar_b     = zeros(size(bVec));
64
65 for i = 1:length(betaVec)
66     wStar_beta(i) = reserv_wage(betaVec(i), b, N, wMin, wMax
```

```
        );
62     end
63
64     for j = 1:length(bVec)
65         wStar_b(j) = reserv_wage(beta, bVec(j), N, wMin, wMax);
66     end
67
68     %% ==== FIGURE 3: w* vs beta
69     %=====
70     figure(3); clf;
71     plot(betaVec, wStar_beta, 'LineWidth', 1.6);
72     xlabel('beta'); ylabel('reservation wage w*');
73     title('Figure 3: w* vs beta (b fixed)');
74     grid on;
75     saveas(gcf, 'figure3_wstar_vs_beta.pdf');
76
77     %% ==== FIGURE 4: w* vs b
78     %=====
79     figure(4); clf;
80     plot(bVec, wStar_b, 'LineWidth', 1.6);
81     xlabel('b (unemployment benefit)'); ylabel('reservation wage w*');
82     title('Figure 4: w* vs b (beta fixed)');
83     grid on;
84     saveas(gcf, 'figure4_wstar_vs_b.pdf');
85
86     %% ==== FUNCTION: reservation wage
87     %=====
88     function wStar = reserv_wage(beta, b, N, wMin, wMax)
89         if nargin < 3, N = 10000; end
90         if nargin < 4, wMin = 0.0; end
91         if nargin < 5, wMax = 1.0; end
92
93         w = linspace(wMin, wMax, N)';
94         Ve = w ./ (1 - beta);
95         Vu = 0; tol = 1e-10; diff = Inf;
96
97         while diff > tol
98             EV = mean( max(Ve, Vu) );
99             Vu_n = b + beta * EV;
100             diff = abs(Vu_n - Vu);
101             Vu = Vu_n;
102         end
103
104         wStar = (1 - beta) * Vu;
105     end
```

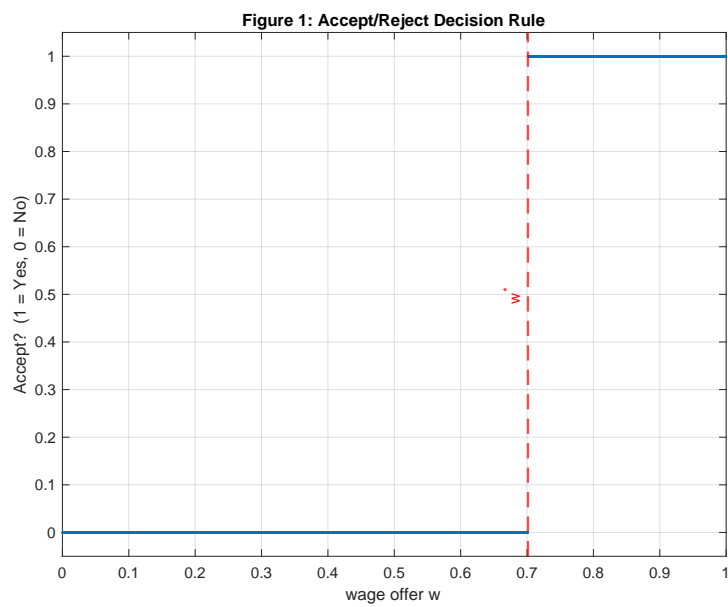


Figure 1: Figure 1

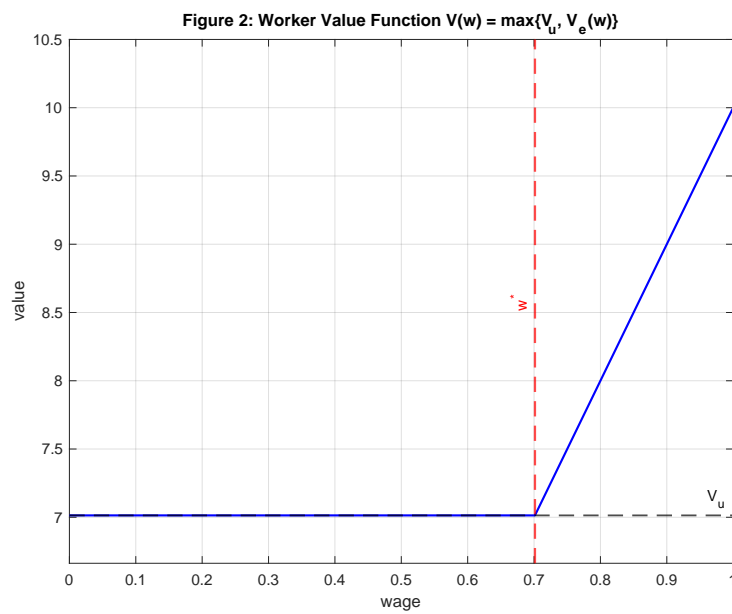


Figure 2: Figure 2

$$W_R \approx 0.7$$

Problem 3.3.*Solution:*

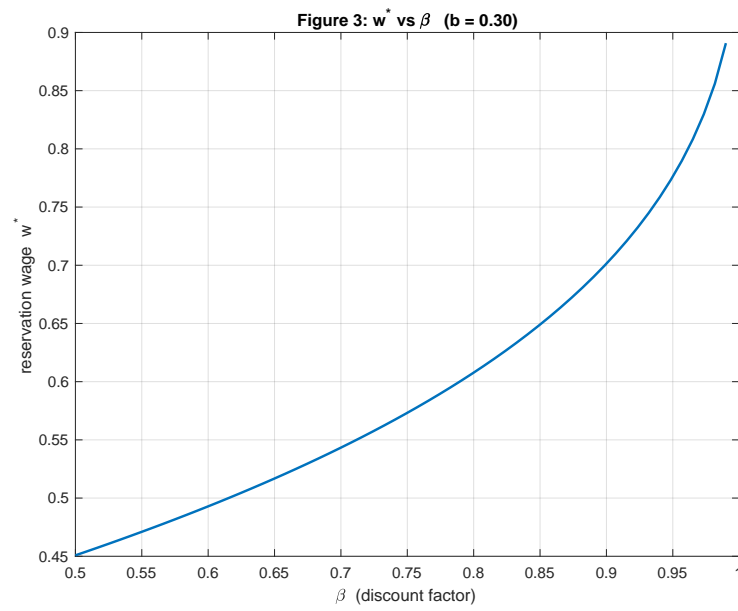


Figure 3: Figure 3

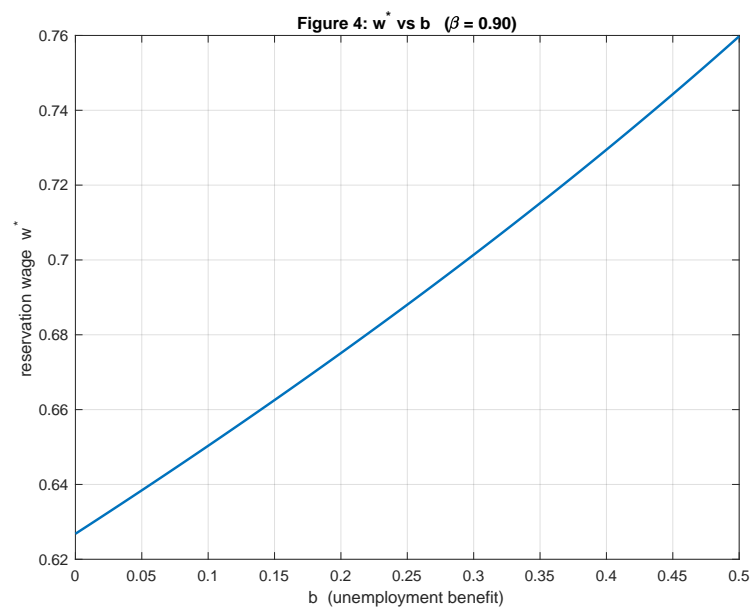


Figure 4: Figure 4

□

Problem 4.

Solution: Note:

$$\begin{aligned} V(w) &= \max \{V_E(w), c + \beta E[(V(w'))]\} \\ &= \max \left\{ \frac{w}{1-\beta}, c + \beta(\phi E(V(w')|\phi) + (1-\phi)E(V(w')|(1-\phi))) \right\} \\ &= \max \left\{ \frac{w}{1-\beta}, c + \beta(\phi V(0) + (1-\phi)E(V(w')|(1-\phi))) \right\} \\ &= \max \left\{ \frac{w}{1-\beta}, c + \beta(\phi V(0) + (1-\phi) \int V(w')dF(w')) \right\} \end{aligned}$$

□