

# Chapter 2 Problems

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1. The metric of flat, three-dimensional Euclidean space is:

$$ds^2 = dx^2 + dy^2 + dz^2$$

Show that the metric components  $g_{uv}$  in spherical polar coordinates  $r, \theta, \phi$  defined by:

$$\begin{aligned} r &= \sqrt{x^2 + y^2 + z^2} \\ \cos \theta &= \frac{z}{r}, \\ \tan \phi &= \frac{y}{x} \end{aligned}$$

is given by:

$$s^2 = dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2$$

$g_{uv}$  is a tensor of type  $(0, 2)$  and therefore transforms as:

$$g_{\mu', \nu'} = g_{\mu, \nu} \frac{\partial x^\mu}{\partial x^{\mu'}} \frac{\partial x^\nu}{\partial x^{\nu'}}$$

(see page 22 for the general *tensor transformation law*). The above equation uses Einstein index notation indicating that  $\mu$  and  $\nu$  are to be summed from 1 to 3 and the free indices,  $\mu'$  and  $\nu'$ , are enumerated through all possible combinations:

$$\begin{array}{ccc} g_{1'1'} & g_{1'2'} & g_{1'3'} \\ g_{2'1'} & g_{2'2'} & g_{2'3'} \\ g_{3'1'} & g_{3'2'} & g_{3'3'} \end{array}$$

Starting with:

$$\begin{aligned} g_{1', 1'} &= \sum_{\mu=1}^3 \sum_{\nu=1}^3 g_{\mu, \nu} \frac{\partial x^\mu}{\partial x^{1'}} \frac{\partial x^\nu}{\partial x^{1'}} \\ &= \sum_{\mu=1}^3 g_{\mu, 1} \frac{\partial x^\mu}{\partial x^{1'}} \frac{\partial x^1}{\partial x^{1'}} + g_{\mu, 2} \frac{\partial x^\mu}{\partial x^{1'}} \frac{\partial x^2}{\partial x^{1'}} + g_{\mu, 3} \frac{\partial x^\mu}{\partial x^{1'}} \frac{\partial x^3}{\partial x^{1'}} \end{aligned}$$

The off diagonal elements of the Euclidean metric written in matrix form is an identity matrix. This reduces the above summation from a possible 9 components to the following three:

$$g_{1', 1'} = \frac{\partial x^1}{\partial x^{1'}} \frac{\partial x^1}{\partial x^{1'}} + \frac{\partial x^2}{\partial x^{1'}} \frac{\partial x^2}{\partial x^{1'}} + \frac{\partial x^3}{\partial x^{1'}} \frac{\partial x^3}{\partial x^{1'}} = \left( \frac{\partial x^1}{\partial x^{1'}} \right)^2 + \left( \frac{\partial x^2}{\partial x^{1'}} \right)^2 + \left( \frac{\partial x^3}{\partial x^{1'}} \right)^2$$

Converting the notation to reflect the choices of basis:

$$\begin{aligned}g_{r,r} &= \left(\frac{\partial x}{\partial r}\right)^2 + \left(\frac{\partial y}{\partial r}\right)^2 + \left(\frac{\partial z}{\partial r}\right)^2 \\g_{\theta,\theta} &= \left(\frac{\partial x}{\partial \theta}\right)^2 + \left(\frac{\partial y}{\partial \theta}\right)^2 + \left(\frac{\partial z}{\partial \theta}\right)^2 \\g_{\phi,\phi} &= \left(\frac{\partial x}{\partial \phi}\right)^2 + \left(\frac{\partial y}{\partial \phi}\right)^2 + \left(\frac{\partial z}{\partial \phi}\right)^2\end{aligned}$$

First, find an equation for  $x$  in terms of  $r$ . Rearranging:

$$\begin{aligned}r &= \sqrt{x^2 + y^2 + z^2} \rightarrow r^2 = x^2 + z^2 + y^2, \\ \cos \theta &= \frac{z}{r} \rightarrow z = r \cos \theta, \\ \tan \phi &= \frac{y}{x} \rightarrow y = x \tan \phi\end{aligned}$$

Substituting the second and third equation into the first gives:

$$\begin{aligned}r^2 &= x^2 + (r \cos \theta)^2 + (x \tan \phi)^2 \\ r^2 &= x^2 + r^2 \cos^2 \theta + x^2 \tan^2 \phi \\ r^2 - r^2 \cos^2 \theta &= x^2 + x^2 \tan^2 \phi \\ (1 - \cos^2 \theta)r^2 &= (1 + \tan^2 \phi)x^2 \\ r^2 \sin^2 \theta &= (1 + \tan^2 \phi)x^2 \\ x &= r \sqrt{\frac{\sin^2 \theta}{1 + \tan^2 \phi}}\end{aligned}$$

Differentiating:

$$\begin{aligned}\frac{\partial x}{\partial r} &= \sqrt{\frac{\sin^2 \theta}{1 + \tan^2 \phi}}, \\ \frac{\partial x}{\partial \theta} &= -r \frac{\sqrt{1 + \tan^2 \phi}}{\sin} \frac{\sin \theta \cos \theta}{1 + \tan^2 \phi} \\ &= -r \frac{\cos \theta}{\sqrt{1 + \tan^2 \phi}}.\end{aligned}$$

Second, find an equation for  $y$  in terms of  $r$ , and then differentiate:

$$\begin{aligned}y &= x \tan \phi \\ &= r \sqrt{\frac{\sin^2 \theta}{1 + \tan^2 \phi}} \tan \phi \\ \frac{\partial y}{\partial r} &= \sqrt{\frac{\sin^2 \theta}{1 + \tan^2 \phi}} \tan \phi\end{aligned}$$

Lastly,  $z$  in terms of  $r$  simply follows from the definition of them transformation:

$$z = r \cos \theta \rightarrow \frac{\partial z}{\partial r} = \cos \theta$$

Therefore:

$$\begin{aligned}g_{rr} &= \frac{\sin^2 \theta}{1 + \tan^2 \phi} + \frac{\sin^2 \theta}{1 + \tan^2 \phi} \tan^2 \phi + \cos^2 \theta \\g_{rr} &= \frac{\sin^2 \theta + \sin^2 \theta \tan^2 \phi}{1 + \tan^2 \phi} + \frac{(1 + \tan^2 \phi) \cos^2 \theta}{1 + \tan^2 \phi} \\g_{rr} &= \frac{\sin^2 \theta + \sin^2 \theta \tan^2 \phi + (1 + \tan^2 \phi) \cos^2 \theta}{1 + \tan^2 \phi} \\g_{rr} &= \frac{\sin^2 \theta + \cos^2 \theta + \sin^2 \theta \tan^2 \phi + \tan^2 \phi \cos^2 \theta}{1 + \tan^2 \phi} \\g_{rr} &= \frac{1 + \tan^2 \phi}{1 + \tan^2 \phi} \\g_{rr} &= 1\end{aligned}$$