

# Wei DAI

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## Education

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**City University of Hong Kong**, Hong Kong, China

*Sep. 2021 - Oct. 2025*

*Ph.D. in Robotics and Automation*

*Thesis: Efficient Deep Learning Techniques for Automated Biomedical Image Analysis with Applications in Medical Robotics*

Supervisor: Prof. Jun Liu & Prof. Steven Wang

**South China University of Technology**, Guangzhou, China

*Sep. 2017 - Jun. 2021*

*B.Eng. in Mechanical Engineering*

Supervisor: Prof. Zhenping Wan

## Selected Awards

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| • <b>Research Tuition Grant</b> , CityU  | 2021-2025 |
| • <b>Postgraduate Studentship</b> , CityU                                      | 2021-2025 |
| • <b>Research Activities Fund</b> , CityU                                      | 2024-2025 |
| • <b>Outstanding Academic Performance Award</b> , CityU                        | 2024      |
| • <b>Institutional Research Tuition Scholarship</b> , CityU                    | 2024      |
| • <b>ISBI Student Travel Grant</b> (3 recipients in Hong Kong), ISBI           | 2024      |
| • <b>Conference Grant</b> , CityU  | 2024      |
| • <b>Outstanding Undergraduate Thesis Award</b> (Top 1%), SCUT                 | 2021      |
| • <b>The First Prize Scholarship</b> (Top 2%), SCUT                            | 2019-2020 |
| • <b>National Stellar Volunteer Award</b> (121 volunteer hours), CVSF          | 2020      |
| • <b>Honorable Mention</b> , National University Student Mechanics Competition | 2019      |
| • <b>Honorable Mention</b> , Mathematical Contest in Modeling (MCM)            | 2019      |
| • <b>Zhangtao-Lifen Dengyun Scholarship</b> (Top 1%), SCUT                     | 2018      |

## Professional Experience

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**Department of Data and Systems Engineering, The University of Hong Kong**

*Sep. 2024 - Now*

*Research Assistant, Adviser: Prof. Jun Liu*

- Developing a vision foundation model to enhance robotic systems for in vitro fertilisation, specifically for selecting viable reproductive cells.

**Centre for Robotics and Automation, City University of Hong Kong**

*Sep. 2021 - Aug. 2024*

*Research Assistant, Adviser: Prof. Jun Liu & Prof. Steven Wang*

- Analysed small-scale medical objects using proposed multi-scale attention mechanisms.
- Constructed lightweight neural networks based on vision transformer and vision mamba.

- Enriched data by identifying salient areas using the minimum barrier distance algorithm.

**School of Science and Engineering, The Chinese University of Hong Kong** Jul. 2024 - Feb. 2025  
Visiting Student, Adviser: Prof. Zhuoran Zhang

- Assessed sperm health to support micromanipulation robotics in selecting target sperms.

**Prince of Wales Hospital, The Chinese University of Hong Kong** May 2022 - Jun. 2022  
Clinical Intern, Adviser: Prof. David YL Chan

- Acquired knowledge of CASA systems and criteria for sperm selection.

**Key Laboratory of Surface Functional Structure Manufacturing Technology of Guangdong**  
Research Assistant, Adviser: Prof. Zhenping Wan Nov. 2019 - Jun. 2021

- Simulated grinding processes with precisely distributed geometrical grains on the grinding wheel.

**School of Automation Science and Engineering, South China University of Technology**  
Smart car team member, Adviser: Prof. An Chen Oct. 2020 - Mar. 2021

- Used STM32 microcontrollers and a grayscale camera to manage and steer an intelligent vehicle.

**Robot Innovation Base, South China University of Technology** Sep. 2019 - Oct. 2019  
Computer Vision Intern, Adviser: Prof. Dong Zhang

- Implemented U-Net architecture for traffic lane extraction to aid mobile robot navigation.
- Developed systems for detecting ArUco markers and distinguished traffic light colours.

**School of Science and Engineering, University of Dundee** Jul. 2019 - Aug. 2019  
Visiting student, Adviser: Dr. Bill Lewinger

- Programmed a PID controller using LabView for navigation control of an EV3 robot.

**School of Mechanical and Automotive Engineering, South China University of Technology**  
Robotics Intern, Adviser: Prof. Feng Ye Oct. 2018 - Apr. 2019

- Developed an acoustic model for voice command control of TurtleBot locomotion.
- Applied OpenSLAM for trajectory planning using LiDAR and stereo vision.

## **Publications** (Google Scholar)

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### **Journal Papers**

1. **W. Dai**, R. Liu, T. Wu, M. Wang, J. Yin and J. Liu, "Deeply Supervised Skin Lesions Diagnosis with Stage and Branch Attention," in *IEEE Journal of Biomedical and Health Informatics*, vol. 28, no. 2, pp. 719-729, Feb. 2024. (**JBHI**, **IF: 7.7**)
2. **W. Dai**, T. Wu, R. Liu, M. Wang, J. Yin, and J. Liu, "Any Region Can Be Perceived Equally and Effectively on Rotation Pretext Task Using Full Rotation and Weighted-region Mixture," in *Neural Networks*, 2024. (**NN**, **IF: 7.8**)
3. **W. Dai**, Z. Wu, R. Liu, T. Wu, M. Wang, J. Zhou, Z. Zhang, and J. Liu, "Automated Non-invasive Analysis of Motile Sperms Using Sperm Feature-correlated Network," in *IEEE Transactions on Automation Science and Engineering*, pp. 1-11, 2024. (**TASE**, **IF: 5.9**)
4. R. Liu, **W. Dai**, C. Wu, T. Wu, M. Wang, J. Zhou, X. Zhang, W. Li, and J. Liu, "Deep Learning-based Microscopic Cell Detection Using Inverse Distance Transform and Auxiliary Counting," in *IEEE Journal of Biomedical and Health Informatics*, pp. 1-13, 2024. (**JBHI**, **IF: 7.7**)

5. R. Liu, **W. Dai**, T. Wu, M. Wang, S. Wan, and J. Liu, “AIMIC: Deep Learning for Microscopic Image Classification,” *Computer Methods and Programs in Biomedicine*, vol. 226, p. 107162, 2022. (**CMPB, IF: 6.1**)
6. T. Wu, K. Shang, **W. Dai**, M. Wang, R. Liu, J. Zhou, and J. Liu, “High-resolution Cross-scale Transformer: A Deep Learning Model for Bolt Loosening Detection Based on Monocular Vision Measurement”, in *Engineering Applications of Artificial Intelligence*, vol. 133, pp. 108574, Feb. 2024. (**EAAI, IF: 8.0**)
7. R. Liu, Y. Zhu, C. Wu, H. Guo, **W. Dai**, T. Wu, M. Wang, W. J. Li, and J. Liu, “Interactive Dual Network with Adaptive Density Map for Automatic Cell Counting,” *IEEE Transactions on Automation Science and Engineering*, 2023. (**TASE, IF: 5.6**)
8. K. Shang, T. Wu, X. Jin, Z. Zhang, C. Li, R. Liu, M. Wang, **W. Dai**, and J. Liu, “Coaxiality Prediction for Aeroengines Precision Assembly Based on Geometric Distribution Error Model and Point Cloud Deep Learning,” *Journal of Manufacturing Systems*, vol. 71, pp. 681–694, 2023. (**JMS, IF: 12.1**)
9. M. Wang, J. Zhang, R. Liu, T. Wu, **W. Dai**, R. Liu, J. Zhang, and J. Liu, “Liquid Metal-based Flexible Sensor for Perception of Force Magnitude, Location, and Contacting Orientation,” *IEEE Transactions on Instrumentation and Measurement*, 2023. (**TIM, IF: 5.6**)

### Conference Papers

1. **W. Dai**, Z. Wu, J. Wang, R. Liu, M. Wang, T. Wu, J. Zhou, Z. Zhang, and J. Liu, “Automated Non-invasive Analysis of Motile Sperms Using Cross-scale Guidance Network,” in *IEEE International Conference on Robotics and Automation*. pp. 17708-17714, IEEE, 2024. (**ICRA 2024**)
2. **W. Dai**, Z. Wu, R. Liu, J. Zhou, M. Wang, T. Wu, and J. Liu, “SoSegFormer: A Cross-scale Feature Correlated Network for Small Medical Object Segmentation,” in *IEEE International Symposium on Biomedical Imaging*. pp. 1-4, IEEE, 2024. (**ISBI 2024**)
3. J. Zhou, R. Liu, M. Wang, T. Wu, **W. Dai**, X. Zhang, and J. Liu, “Sonicplex: Simultaneous Arrangement of Massive Particles Through a Simple Acoustic Micromanipulation Platform,” in *International Conference on Manipulation, Automation and Robotics at Small Scales*. IEEE, 2023, pp. 1–6. (**MARSS 2023**)
4. M. Wang, Z. Li, **W. Dai**, R. Liu, S. Yuan, and J. Liu, “On-chip Transportation and Mixing of Microsample Using Electrohydrodynamic Flow,” in *International Conference on Manipulation, Automation and Robotics at Small Scales*. IEEE, 2022, pp. 1–6. (**MARSS 2022**)

### Preprints

1. **W. Dai**, R. Liu, Z. Wu, T. Wu, M. Wang, J. Zhou, Y. Yuan, and J. Liu, “Exploiting Scale-Variant Attention for Segmenting Small Medical Objects ,” in *arXiv*. 2024. *IEEE Transactions on Neural Networks and Learning Systems*. First revision.
2. **W. Dai** and J. Liu, “MobileViM: A Light-weight and Dimension-independent Vision Mamba for 3D Medical Image Analysis,” in *arXiv*. 2025. *International Journal of Computer Vision*. Under review.

### Professional Activities

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#### Journal Reviewers

- IEEE Transactions on Circuits and Systems for Video Technology (IEEE TCSVT)

- IEEE Journal of Biomedical and Health Informatics (IEEE JBHI)
- IEEE Transactions on Biomedical Engineering (IEEE TBME)
- Computer Methods and Programs in Biomedicine (CMPB)
- IEEE Transactions on Robotics (IEEE TRO)
- IEEE Transactions on Automation Science and Engineering (IEEE TASE)
- IEEE Robotics and Automation Letters (IEEE RAL)
- Engineering Applications of Artificial Intelligence (EAAI)
- Lab on a Chip
- Advanced Intelligent Systems
- International Journal of Computing and Digital Systems

### Conference Reviewers

- IEEE International Symposium on Biomedical Imaging
- IEEE International Conference on Robotics and Automation
- IEEE International Conference on Intelligent Robots and Systems
- IEEE International Conference on Advanced Robotics and Its Social Impacts
- IEEE International Conference on Nano/Micro Engineered and Molecular Systems
- IEEE International Conference on Manipulation, Automation and Robotics at Small Scales

### Conference Presentations

- ISBI 2024, Athens, Greece *May 2024*
- ICRA 2024, Yokohama, Japan *May 2024*

### Teaching Assistant

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- MNE6126/MNE8110 Sensors for Robotics, AI, and Control Systems *Spring 2025*
- MNE4032 Robotics and Machine Vision *Spring 2024*
- MNE8116 Computer Controlled Systems *Spring 2023*
- MNE6005/MNE8113 Micro Systems Technology *Fall 2022-2024*

### Extracurricular Activities

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- 25th & 26th Standard Chartered Hong Kong Marathon (10 km), Hong Kong *2023 - 2024*
- 7th & 8th Nike Relay Race, Guangzhou *2018 - 2019*