LAPORAN PRAKTIKUM KECERDASAN BUATAN "METODE PENCARIAN"



NAMA: AFRIDHO IKHSAN

NPM : **2210631170002**

KELAS : 3A

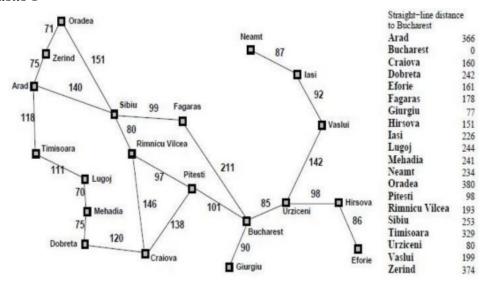
PROGRAM STUDI INFORMATIKA
FAKULTAS ILMU KOMPUTER
UNIVERSITAS SINGAPERBANGSA KARAWANG
2023

DAFTAR ISI

DAFTAR ISI	j
LATIHAN	2
JAWABAN	

LATIHAN

Kasus 1



- a. Bagaimana rute perjalanan dari Arad ke Bucarest
- b. Gunakan teknik pencarian Breadth First Search & Depth First Search

Kasus 2

Sebuah *puzzle* berukuran 3X3

Nilai awal:

Can	1.
Goa	ι.

1	2	3
8		4
7	6	5

2	8	3
1	6	4
7		5

$$f(n) = g(n) + h(n)$$

g(n) = kedalaman pohon

h(n) = jumlah angka yang salah posisi

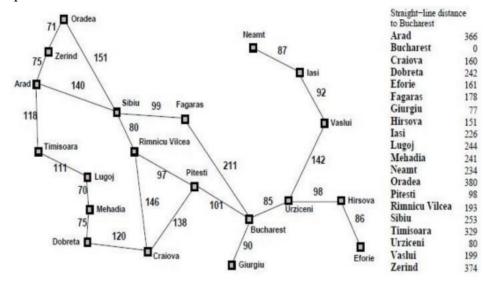
Kerjakan dengan Teknik Best First Search!

JAWABAN

Nomor 1 (a)

```
from IPython.display import Image
Image(filename='kasus1.jpg')
```

Output:



```
graph = {
    'Oradea' : [('Zerind', 71), ('Sibiu', 151)],
    'Arad' : [('Zerind', 75), ('Sibiu', 140), ('Timisoara',
    'Timisoara' : [('Arad', 118), ('Lugoj', 111)],
    'Mehadia' : [('Lugoj', 70), ('Dobreta', 75)],
    'Dobreta': [('Mehadia', 75), ('Craiova', 120)],
    'Sibiu' : [('Oradea', 151), ('Arad', 140), ('Fagaras',
99), ('Rimnicu Vilcea', 80)],
    'Rimnicu Vilcea' : [('Sibiu', 80), ('Craiova', 146),
('Pitesti', 97)],
    'Craiova': [('Dobreta', 120), ('Rimnicu Vilcea', 146),
('Pitesti', 138)],
    'Fagaras' : [('Sibiu', 99), ('Bucharest', 211)],
    'Pitesti' : [('Rimnicu Vilcea', 97), ('Craiova', 138),
('Bucharest', 101)],
    'Bucharest' : [('Fagaras', 211), ('Pitesti', 101),
('Giurgiu', 90), ('Urziceni', 85)],
    'Giurgiu' : [('Bucharest', 90)],
    'Neamt' : [('Lasi', 87)],
    'Lasi' : [('Neamt', 87), ('Vaslui', 92)],
    'Vaslui' : [('Lasi', 92), ('Urziceni', 142)],
```

```
'Urziceni': [('Bucharest', 85), ('Vaslui', 142),
('Hirsova', 98)],
    'Hirsova': [('Urziceni', 98), ('Eforie', 86)],
    'Eforie': [('Hirsova', 86)],

H_table = {
    'Arad': 366,
    'Bucharest': 0,
    'Craiova': 160,
    'Dobreta': 242,
    'Eforie': 161,
    'Fagaras': 178,
    'Giurgiu': 77,
    'Hirsova': 151,
    'Lasi': 226,
    'Lugoj': 244,
    'Mehadia': 241,
    'Neamt': 234,
    'Oradea': 380,
    'Pitesti': 98,
    'Rimnicu Vilcea': 193,
    'Sibiu': 253,
    'Timisoara': 329,
    'Urziceni': 90,
    'Vaslui': 199,
    'Zerind': 374
}
```

```
def path_h_cost(path):
    g_cost = 0
    for (node, cost) in path:
        g_cost += cost
        last_node = path[-1][0]
        h_cost = H_table[last_node]
        f_cost = g_cost + h_cost
        return h_cost, last_node
```

```
def Greedy_best_search(graph, start, goal):
    visited =[]
    queue = [[(start,0)]]

while queue:
    queue.sort(key=path_h_cost)
    path = queue.pop(0)
    node = path[-1][0]
```

```
if node in visited:
    continue
visited.append(node)
if node == goal:
    return path
else:
    adjacent_nodes = graph.get(node, [])
    for (node2, cost) in adjacent_nodes:
        new_path = path.copy()
        new_path.append((node2, cost))
        queue.append(new_path)
```

```
rute = Greedy_best_search(graph, 'Arad', 'Bucharest')
print ('Rute menggunakan teknik Greedy Best First Search
adalah ', rute)
```

Output:

Rute menggunakan teknik Greedy Best First Search adalah [('Arad', 0), ('Sibiu', 140), ('Fagaras', 99), ('Bucharest', 211)]

Nomor 1 (b)

• BFS (Breadth – First Search)

```
from collections import deque
def Breadth First Search(graph, start, goal):
    visited = set()
    queue = deque([(start, [])])
    while queue:
        node, path = queue.popleft()
        if node not in visited:
            visited.add(node)
            path = path + [(node, 0)]
            if node == goal:
                return path
                adjacent nodes = graph.get(node, [])
                queue.extend((neighbor, path + [(neighbor,
cost)]) for neighbor, cost in adjacent nodes)
bfs solution = Breadth First Search(graph, 'Arad',
'Bucharest')
```

```
print('Rute hasil dari penggunaan teknik BFS adalah ',
bfs_solution)
```

Output:

Rute hasil dari penggunaan teknik BFS adalah [('Arad', 0), ('Sibiu', 140), ('Sibiu', 0), ('Fagaras', 99), ('Fagaras', 0), ('Bucharest', 211), ('Bucharest', 0)]

• DFS (Depth – First Search)

```
def Depth_First_Search(graph, start, goal):
    visited = set()
    stack = [(start, [])]

while stack:
    node, path = stack.pop()

if node not in visited:
    visited.add(node)
    path = path + [(node, 0)]

if node == goal:
    return path
    else:
        adjacent_nodes = graph.get(node, [])
        stack.extend((neighbor, path + [(neighbor, cost)]) for neighbor, cost in adjacent_nodes)

return None

dfs_solution = Depth_First_Search(graph, 'Arad', 'Bucharest')
print('Rute hasil dari penggunaan teknik DFS adalah', dfs_solution)
```

Output:

Rute hasil dari penggunaan teknik DFS adalah [('Arad', 0), ('Timisoara', 118), ('Timisoara', 0), ('Lugoj', 111), ('Lugoj', 0), ('Mehadia', 70), ('Mehadia', 0), ('Dobreta', 75), ('Dobreta', 0), ('Craiova', 120), ('Craiova', 0), ('Pitesti', 138), ('Pitesti', 0), ('Bucharest', 101), ('Bucharest', 0)]

Nomor 2

```
from IPython.display import Image
Image(filename='kasus2.jpg')
```

Output:

Nilai awal: Goal:

1	2	3
8		4
7	6	5

2	8	3
1	6	4
7		5

```
class NodePuzzle:
        self.state = state
        self.kedalaman = kedalaman
        self.induk = induk
   def eq (self, other):
       return self.state == other.state
        return "\n".join([" | ".join(map(str, row)) for row in
self.state])
def h cost(state, goal state):
    return sum(1 for i, j in zip(state, goal_state) if i != j)
def posisi_kosong(state):
    for i, baris in enumerate(state):
        for j, nilai in enumerate(baris):
            if nilai is None:
def dapatkan_tetangga(node):
   tetangga = []
    i, j = posisi_kosong(node.state)
   gerakan = [(0, 1), (1, 0), (0, -1), (-1, 0)]
    for geser in gerakan:
        i_baru, j_baru = i + geser[0], j + geser[1]
            state baru = [baris.copy() for baris in
node.state]
            state baru[i][j], state baru[i baru][j baru] =
state baru[i baru][j baru], state baru[i][j]
```

```
tetangga.append(NodePuzzle(state baru,
node.kedalaman + 1, node))
    return tetangga
def pencarian a star(state awal, state goal):
    node awal = NodePuzzle(state awal, 0)
    node goal = NodePuzzle(state goal, float('inf'))
    himpunan terbuka = {node awal}
    himpunan tertutup = set()
    while himpunan terbuka:
        node saat ini = min(himpunan terbuka, key=lambda x:
x.kedalaman + h cost(x.state, state goal))
        himpunan_terbuka.remove(node_saat_ini)
        if node saat ini == node goal:
            path = []
            while node saat ini:
                path.append(node saat ini.state)
            return reversed(path)
        himpunan tertutup.add(node saat ini)
        tetangga_node = dapatkan_tetangga(node_saat_ini)
        for tetangga in tetangga node:
            if tetangga not in himpunan tertutup and tetangga
not in himpunan terbuka:
                himpunan terbuka.add(tetangga)
state awal = [
    [8, None, 4],
state goal = [
   [2, 8, 3],
   [1, 6, 4],
```

```
solusi_pencarian = pencarian_a_star(state_awal, state_goal)
if solusi_pencarian:
    print("Solusi Ditemukan:")
    for langkah, state in enumerate(solusi pencarian):
         print(f"Langkah {langkah + 1}:\n{NodePuzzle(state,
0) }\n")
else:
    print("Tidak ditemukan solusi.")
Output:
Solusi Ditemukan:
Langkah 1:
1 | 2 | 3
8 | None | 4
7 | 6 | 5
Langkah 2:
1 | 2 | 3
None | 8 | 4
7 | 6 | 5
```

Langkah 6:

Langkah 3: None | 2 | 3 1 | 8 | 4 7 | 6 | 5

Langkah 4: 2 | None | 3 1 | 8 | 4 7 | 6 | 5

Langkah 5: 2 | 8 | 3 1 | None | 4 7 | 6 | 5

7 | None | 5