

SEARCHING ALGORITHM



Image source: https://www.dreamstime.com/illustration/play-blindman.html

BLIND SEARCH/ UNINFORMED SEARCH

Blind Searching/ Uninformed Searching

A **blind search** (also known as an **uninformed search**) is one that has no knowledge of the domain. A blind search can only distinguish between non-goal and goal states.

Why would you use a blind search?

- 1. In some cases, there is **no usable initial information**.
- 2. We will **only know the answer** when **we find it** or **arrive at our destination**.

Blind Searching (Uninformed Searching)

Breadth-First Search (BFS)

Depth-First Search (DFS)

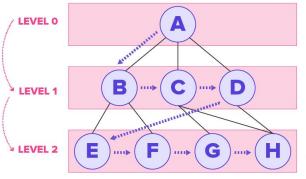
Uniform Cost Search (UCS)

Depth Limited Search (DLS)

Iterative Deeping Depth First Search (IDDFS)

Bidirectional Search (BS)

ARCHITECTURE OF BFS



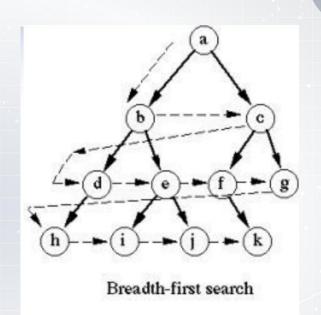
1. Mark any node as starter

2. Explore and traverse unvisited nodes adjacant to starting node

3. Mark node as complete and move to next adjacant and unvisited nodes



- Starting at level 0, the root node,
 A, then proceeds to the destination node (goal), K.
- Using the First In, First Out principle (FIFO).
- Using the **Queuing Principle**.



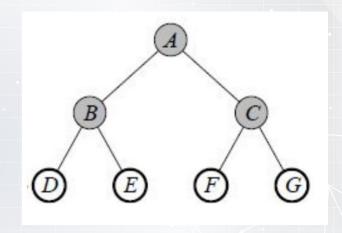


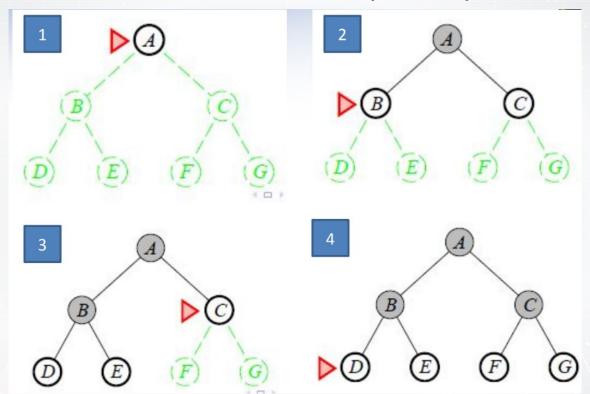
The search is carried out sequentially from left to right on all nodes at the same level.

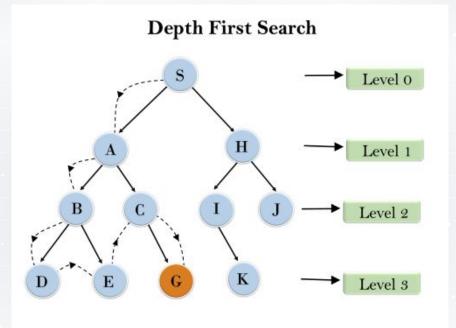
If no solution is found at one level, the search is continued at the next level (n+1).

Example:

Root: A Goal: D

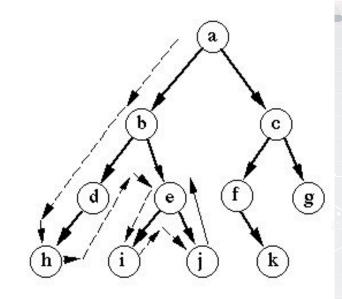








- The search is performed on a node at each level, beginning at the far left.
- If the solution is not found at the deepest level, the search moves to the right end, while the left end is erased from memory.
- If a solution is not found at the deepest level, the search proceeds to the previous level.

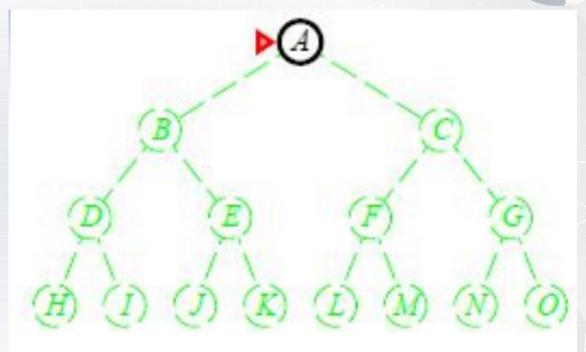


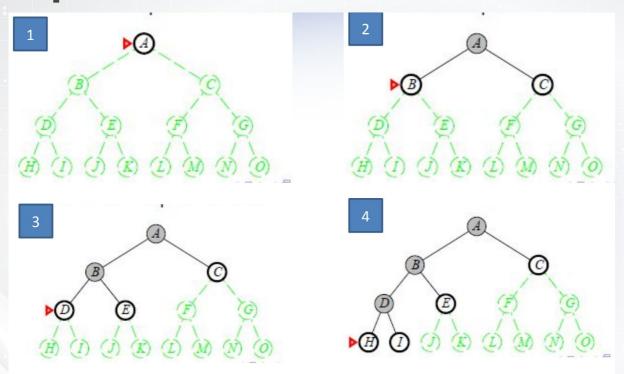
Depth-first search

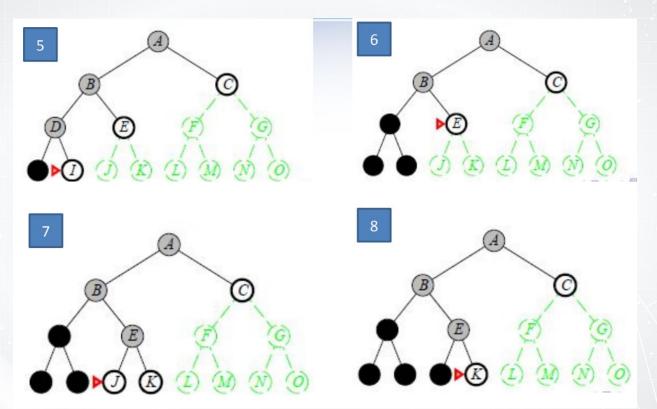
Example:

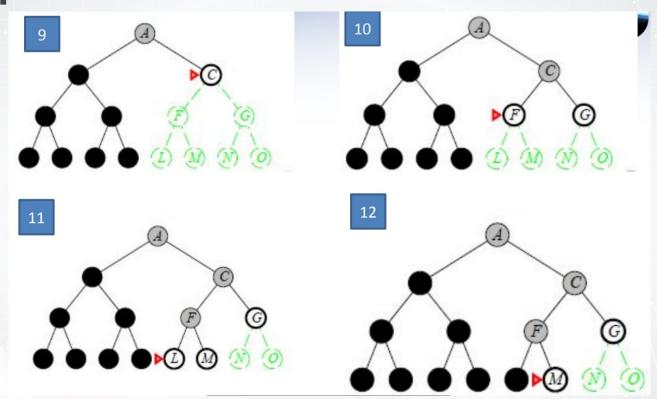
Root: A

Goal: M











HEURISTIC SEARCH

Heuristic Search

Blind searches have these **drawbacks**:

- Long access time
- A lot of memory is required.
- Because the problem space is large, it is not suitable for computers with limited speed and memory.



Heuristic Search

The **heuristic function** is used to assess the circumstances of individual problems and determine how far they can be used to achieve the desired result.

This method employs a heuristic function, which computes the estimated cost from one node to the next.

Heuristic Search

Generate and Test

Hill Climbing

Best First Search

Alpha Beta Prunning

Simulated Annealing

Min-Max

Local Search Algorithms

Local Beam Search

Best First Search

- Combination of DFS and BFS methods
- If the node on a higher level has a lower heuristic value, **the best-first search** allows it to visit a lower node.
- Algorithms are classified into two types:
 - Greedy's Best-First Search

estimated cost
$$f(n) = h(n)$$

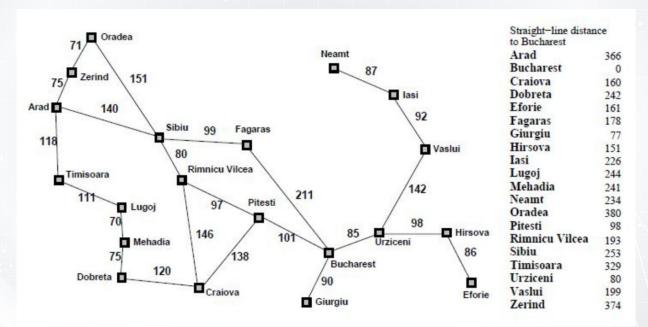
○ A*

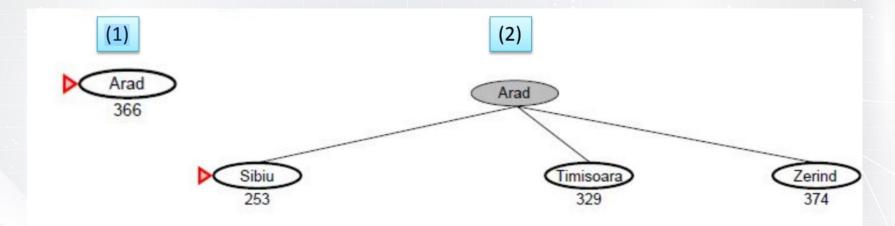
$$f(n) = g(n) + h(n)$$

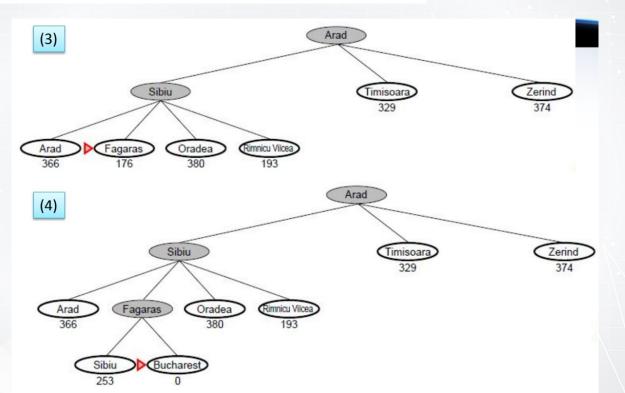
Greedy best-first search algorithm always selects the path which appears best at that moment.

estimated cost f(n) = h(n)

h(n) =estimated cost from node n to the goal

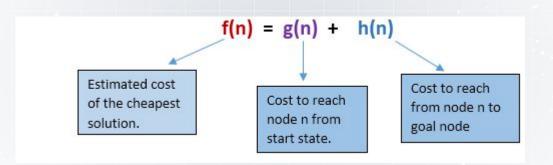


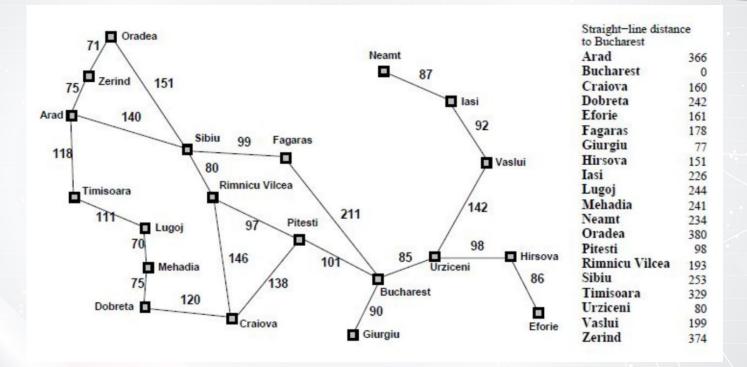


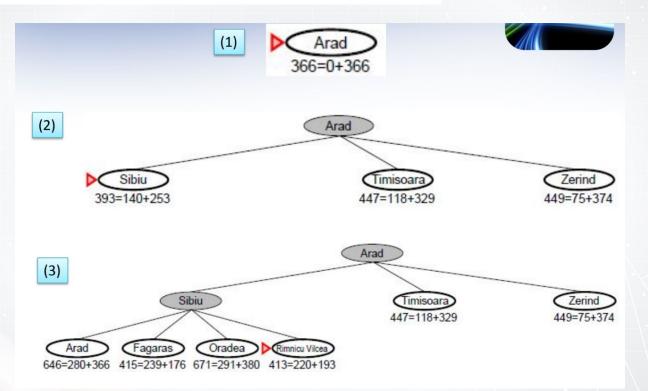


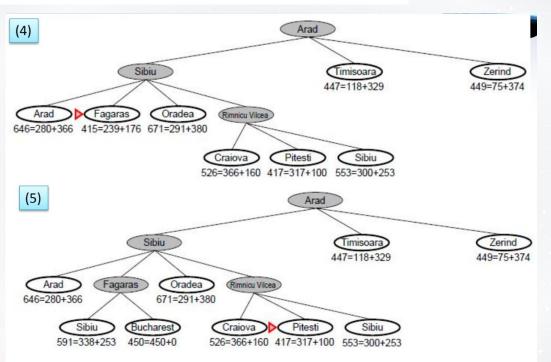
A* Best-First Search

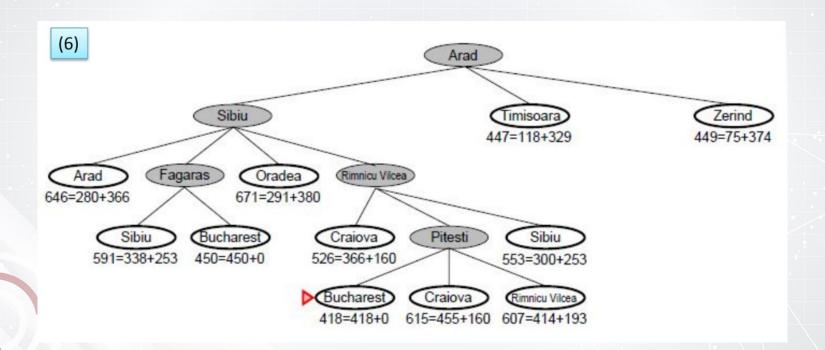
A* search is the most commonly known form of best-first search. It uses heuristic function h(n), and cost to reach the node n from the start state g(n).











THANKS!

See You

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