

**ACM/IDS 104 APPLIED LINEAR ALGEBRA
PRACTICE PROBLEMS FOR LECTURE 4: SOLUTIONS**

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Problem 4A. FUNDAMENTAL SUBSPACES

Consider the following matrix:

$$A = \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{bmatrix} \quad (1)$$

- (a) Find the four fundamental subspaces, $\ker A$, $\operatorname{im} A$, $\operatorname{coker} A$, and $\operatorname{coim} A$, using their definitions. Here, to “find” means to describe the subspaces explicitly by constructing their bases.
- (b) Check that the dimensions of the four fundamental subspaces satisfy the relationships predicted by the Fundamental Theorem of Linear Algebra.

Solution:

(a) By definition, the kernel of A is a subspace of \mathbb{R}^4 consisting of all vectors $x \in \mathbb{R}^4$ such that $Ax = 0$. The most systematic way to find $\ker A$ is first to reduce A to its row echelon form U , and then find $\ker U$, which coincides with $\ker A$. Indeed, since $PA = LU$, we have that $A = NU$, where $N = P^{-1}L$ is a nonsingular matrix, and, therefore,

$$x \in \ker A \Leftrightarrow Ax = 0 \Leftrightarrow NUx = 0 \Leftrightarrow Ux = 0 \Leftrightarrow x \in \ker U. \quad (2)$$

Finding U is straightforward:

$$A = \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{bmatrix} \xrightarrow{a^3 \rightarrow a^3 - a^1} \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \end{bmatrix} \xrightarrow{a^3 \rightarrow a^3 - a^2} \begin{bmatrix} \textcircled{1} & 0 & 1 & 2 \\ 0 & \textcircled{1} & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} = U \quad (3)$$

The circled entries are pivots. Therefore, $\operatorname{rank} A = 2$ (we will need this number for part (b) anyway), x_1 and x_2 are basic variables, and x_3 and x_4 are free variables. The general solution of $Ux = 0$ looks, therefore, as follows:

$$\begin{aligned} x_2 &= -x_3 - x_4, \\ x_1 &= -x_3 - 2x_4, \end{aligned} \quad (4)$$

where x_3 and x_4 are arbitrary. As we discussed in Lecture 4, the basis of $\ker U (= \ker A)$ can be constructed by setting the free variables to $x_3 = 1, x_4 = 0$ and then to $x_3 = 0, x_4 = 1$, and computing the corresponding values of the basic variables x_1 and x_2 from the above relationships. Therefore,

$$\ker A = \operatorname{span}\{v_1, v_2\}, \quad \text{where } v_1 = \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} \quad \text{and } v_2 = \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \end{bmatrix} \quad (5)$$

By definition, the image of A is the column space of A , that is, the span of all columns of A . The four columns a_1, a_2, a_3, a_4 of A are linearly dependent, since any four vectors in \mathbb{R}^3 are linearly dependent. In fact, $a_3 = a_1 + a_2$ and $a_4 = 2a_1 + a_2$. But a_1 and a_2 are linearly independent. Therefore,

$$\operatorname{im} A = \operatorname{span}\{a_1, a_2\}, \quad \text{where } a_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \quad \text{and } a_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad (6)$$

We can find $\operatorname{coker} A = \ker A^T$ by analogy with how we found $\ker A$. The row echelon form of A^T is

$$A^T = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 2 \\ 2 & 1 & 3 \end{bmatrix} \xrightarrow{a^3 \rightarrow a^3 - a^1} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \\ 2 & 1 & 3 \end{bmatrix} \xrightarrow{a^4 \rightarrow a^4 - 2a^1} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{a^3 \rightarrow a^3 - a^2, a^4 \rightarrow a^4 - a^2} \begin{bmatrix} \textcircled{1} & 0 & 1 \\ 0 & \textcircled{1} & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = W \quad (7)$$

The general solution of $Wx = 0$, where $x \in \mathbb{R}^3$, looks as follows:

$$\begin{aligned} x_2 &= -x_3, \\ x_1 &= -x_3, \end{aligned} \tag{8}$$

where x_3 is arbitrary. Therefore,

$$\text{coker } A = \text{span}\{w_1\}, \quad \text{where } w_1 = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \tag{9}$$

By definition, the coimage of A is the row space of A , that is, the span of all rows of A . Note that a^1, a^2, a^3 are linearly dependent, since $a^3 = a^1 + a^2$. But a^1 and a^2 are linearly independent. Therefore,

$$\text{coim } A = \text{span}\{a^1, a^2\}, \quad \text{where } a^1 = [1 \ 0 \ 1 \ 2] \text{ and } a^2 = [0 \ 1 \ 1 \ 1] \tag{10}$$

(b) In this problem, $m = 3$, $n = 4$, $r = \text{rank } A = 2$, $\dim \ker A = 2$, $\dim \text{im } A = 2$, $\dim \text{coker } A = 1$, and $\dim \text{coim } A = 2$. The relationships between these numbers predicted by the Fundamental Theorem of Linear Algebra hold:

$$\begin{aligned} \dim \ker A &= n - r = 4 - 2 = 2, \\ \dim \text{im } A &= r = 2, \\ \dim \text{coim } A &= r = 2, \\ \dim \text{coker } A &= m - r = 3 - 2 = 1. \end{aligned} \tag{11}$$

Problem 4B. FROBENIUS INNER PRODUCT AND FROBENIUS NORM

The vector space $\mathbb{M}_{m \times n}$ of all $m \times n$ matrices admits many inner products. One of the most useful ones, which appears in theorems and applications, is the Frobenius inner product¹.

(a) Prove that the function $\langle \cdot, \cdot \rangle_F : \mathbb{M}_{m \times n} \times \mathbb{M}_{m \times n} \rightarrow \mathbb{R}$ defined by

$$\langle A, B \rangle_F = \text{tr}(A^T B), \quad \text{for all } A, B \in \mathbb{M}_{m \times n} \tag{12}$$

is an inner product (called the Frobenius inner product) on the vector space $\mathbb{M}_{m \times n}$.

(b) Let $\|\cdot\|_F$ be the Frobenius norm induced by the Frobenius inner product. Prove that this norm is invariant under transposition, that is $\|A^T\|_F = \|A\|_F$.

Solution:

(a) Let's check that $\langle \cdot, \cdot \rangle_F$ satisfies all three properties of inner products. First, it is bilinear:

$$\begin{aligned} \langle \alpha_1 A_1 + \alpha_2 A_2, B \rangle_F &= \text{tr}((\alpha_1 A_1 + \alpha_2 A_2)^T B) = \text{tr}(\alpha_1 A_1^T B + \alpha_2 A_2^T B) = \alpha_1 \text{tr}(A_1^T B) + \alpha_2 \text{tr}(A_2^T B) \\ &= \alpha_1 \langle A_1, B \rangle_F + \alpha_2 \langle A_2, B \rangle_F, \\ \langle A, \beta_1 B_1 + \beta_2 B_2 \rangle_F &= \text{tr}(A^T (\beta_1 B_1 + \beta_2 B_2)) = \text{tr}(\beta_1 A^T B_1 + \beta_2 A^T B_2) = \beta_1 \text{tr}(A^T B_1) + \beta_2 \text{tr}(A^T B_2) \\ &= \beta_1 \langle A, B_1 \rangle_F + \beta_2 \langle A, B_2 \rangle_F. \end{aligned} \tag{13}$$

To prove that $\langle \cdot, \cdot \rangle_F$ is symmetric, we first establish the invariance of the trace under transposition: if C is an $n \times n$ square matrix, then $\text{tr}(C^T) = \text{tr}(C)$. This is obvious, but here is a formal justification:

$$\text{tr}(C^T) = \sum_{i=1}^n (C^T)_{ii} = \sum_{i=1}^n (C)_{ii} = \text{tr}(C). \tag{14}$$

Now, the symmetry of $\langle \cdot, \cdot \rangle_F$ follows directly:

$$\langle B, A \rangle_F = \text{tr}(B^T A) = \text{tr}((B^T A)^T) = \text{tr}(A^T (B^T)^T) = \text{tr}(A^T B) = \langle A, B \rangle_F. \tag{15}$$

Finally, positive-definiteness:

$$\langle A, A \rangle_F = \text{tr}(A^T A) = \sum_{i=1}^n (A^T A)_{ii} = \sum_{i=1}^n \sum_{j=1}^m (A^T)_{ij} A_{ji} = \sum_{i=1}^n \sum_{j=1}^m A_{ji}^2 \geq 0 \tag{16}$$

Moreover, $\langle A, A \rangle_F = 0$ if and only if $A_{ji} = 0$ for all $i = 1, \dots, n$ and $j = 1, \dots, m$, that is, if and only if $A = 0$.

It is illuminating to write the expression for the Frobenius inner product in terms of the entries of matrices:

$$\langle A, B \rangle_F = \text{tr}(A^T B) = \sum_{i=1}^n (A^T B)_{ii} = \sum_{i=1}^n \sum_{j=1}^m (A^T)_{ij} B_{ji} = \sum_{i=1}^n \sum_{j=1}^m A_{ji} B_{ji}. \tag{17}$$

¹Also known as the Hilbert–Schmidt inner product.

In other words, this inner product multiplies all of the entries of A by the corresponding entries of B and adds them up, just like the dot product on $\mathbb{R}^{m \times n}$. The Frobenius inner product is simply what we get if we forget about the shape of A and B and just take their dot product as if they were vectors in $\mathbb{R}^{m \times n}$.

(b) By definition, the Frobenius norm is the norm on $\mathbb{M}_{m \times n}$ induced by the Frobenius inner product:

$$\|A\|_F = \sqrt{\langle A, A \rangle_F} = \sqrt{\text{tr}(A^T A)} = \sqrt{\sum_{i=1}^n \sum_{j=1}^m A_{ji}^2}. \quad (18)$$

It is straightforward to see that it is invariant under transposition:

$$\|A^T\|_F = \sqrt{\sum_{s=1}^m \sum_{k=1}^n ((A^T)_{ks})^2} = \sqrt{\sum_{s=1}^m \sum_{k=1}^n A_{sk}^2} = \sqrt{\sum_{k=1}^n \sum_{s=1}^m A_{sk}^2} = \|A\|_F. \quad (19)$$