## Helper Functions

```
# helper to update D, J using equations 48, 49 on page 10
    def updateDJ(self, R):
2
        # equation 48
3
        self.D = np.dot(R, self.D)
4
        for b in range(self.k):
6
            for c in range(b):
7
               self.D += self.J[b, c]*R[b]*R[:, c]
        self.D = self.D \% 8
8
10
        # equation 49
        self.J = np.dot(np.dot(R, self.J), R.T) % 8
11
```

```
# helper to update Q, D using equations 51, 52 on page 10
    def updateQD(self, y):
        # equation 51
3
        self.Q += np.dot(self.D, y)
        for a in range(self.k):
5
            for b in range(a):
                self.Q += self.J[a, b]*y[a]*y[b]
7
        self.Q = self.Q \% 8
8
10
        # equation 52
        self.D += np.dot(self.J, y)
11
        self.D = self.D \% 8
```