

# Introduction of Gaussian Function into Rendering

## 1. Gaussian Splatting

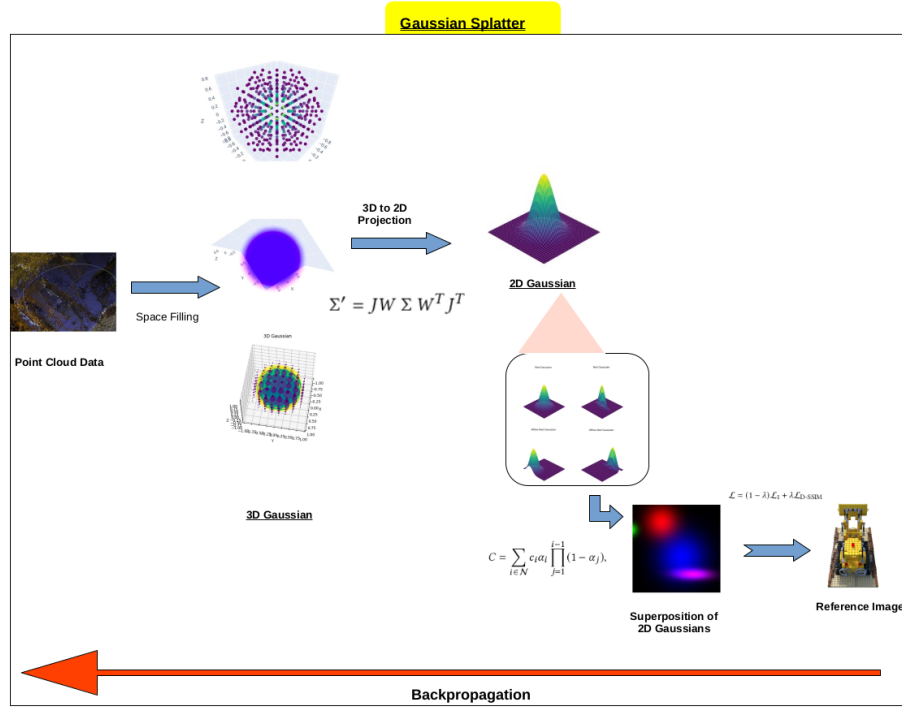


Figure 1: Gaussian Splatting Flow Diagram

### 1.1. Real time training and rendering

Gaussian functions are initialized where the point cloud points exist. They look like expanding point clouds. Gaussian splatting is fast but has its visual defects [Link]

### 1.2. Approximating Image with 2D Gaussian

Gaussians move around on image plane to approximate a target image [Link]

### 1.3. Comparison of Splat Numbering

**1.3.1. 100 Splats** Small number of Gaussians are slow at approximating image [Link]

**1.3.2. 500 Splats** Larger number of Gaussians are faster at approximating image [Link]

#### 1.4. Approximating Image with 3D Gaussian

Gaussians initialized in 3D space, and then projected onto 2D image space can approximate an image [Link]

#### 1.5. Comparison of Output

**1.5.1. Lego Bulldozer: Train vs Test** Gaussian Splatting works great on training (seen) dataset [Link]

Gaussian Splatting works not that great on testing (unseen) dataset [Link]

**1.5.2. Train: Train vs Test** Gaussian Splatting works great but far away objects look fuzzy on training dataset [Link]

Same is the case for testing dataset [Link]

## 2. DreamGaussian (Making Gaussian splatting fast with pretrained diffusion models)

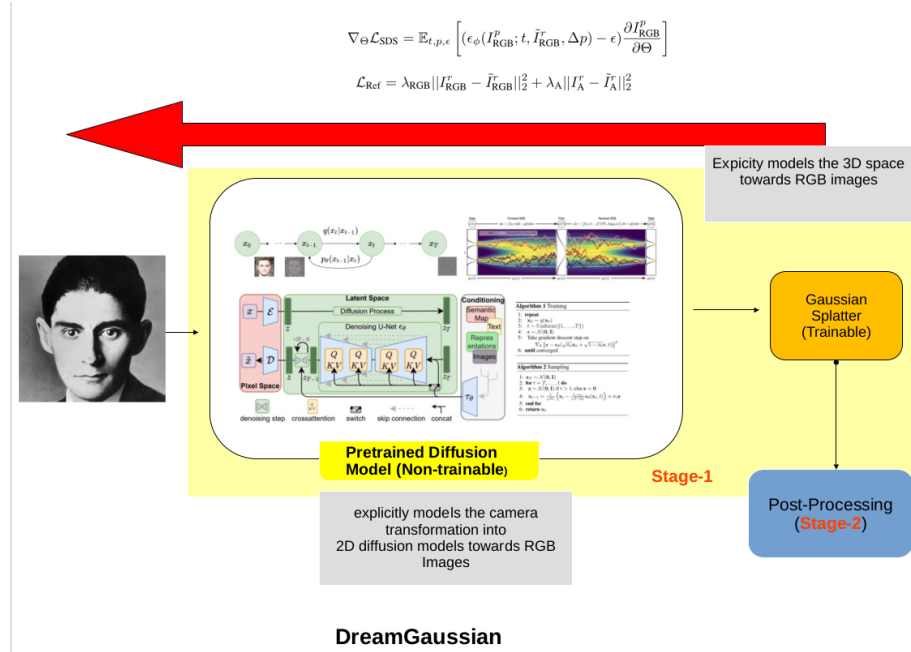


Figure 2: DreamGaussian Flow Diagram

### 2.1. Comparison of Stage-1 and Stage-2 Output

Stage-1 (while being the main pipeline) leads to fuzzy 3D reconstruction, while Stage-2 improves the finer details, but still results are bad [Link]

Improving iterations of Stage-1 and Stage-2 donot lead to significantly better results [Link]

## 3. Future Works

- Nerf without parameters



Figure 3: Bulldozer Reconstructed



Figure 4: Desk Reconstructed

- Neuralangelo (its individual componets have been worked upon)

- Improving point cloud representing with Zero: 1-2-3

### **Code Reference**

- Code [\[Link\]](#)