DJITelloPy

This documentation is the API reference of the DJITelloPy Library.

For more information on the project please see the readme on github.

API

Currently the library contains the following classes:

- [Tello][tello] for controlling a single tello drone.
- [Swarm][swarm] for controlling multiple Tello EDUs in parallel.

Example Code

Please see the example directory on github.

Installation

```
pip install djitellopy
```

For Linux distributions with both python2 and python3 (e.g. Debian, Ubuntu, ...) you need to run

```
pip3 install djitellopy
```

v: latest ▾

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