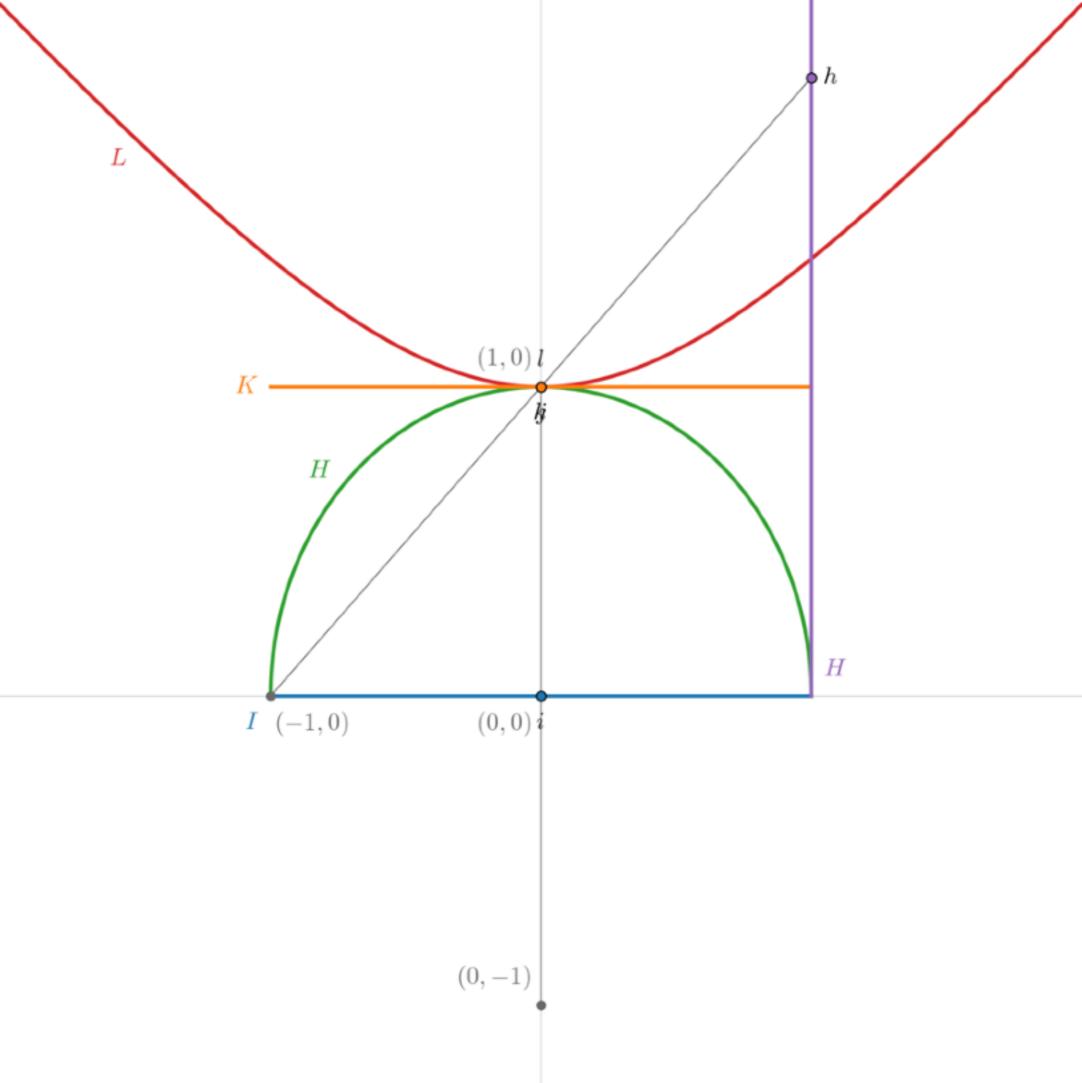
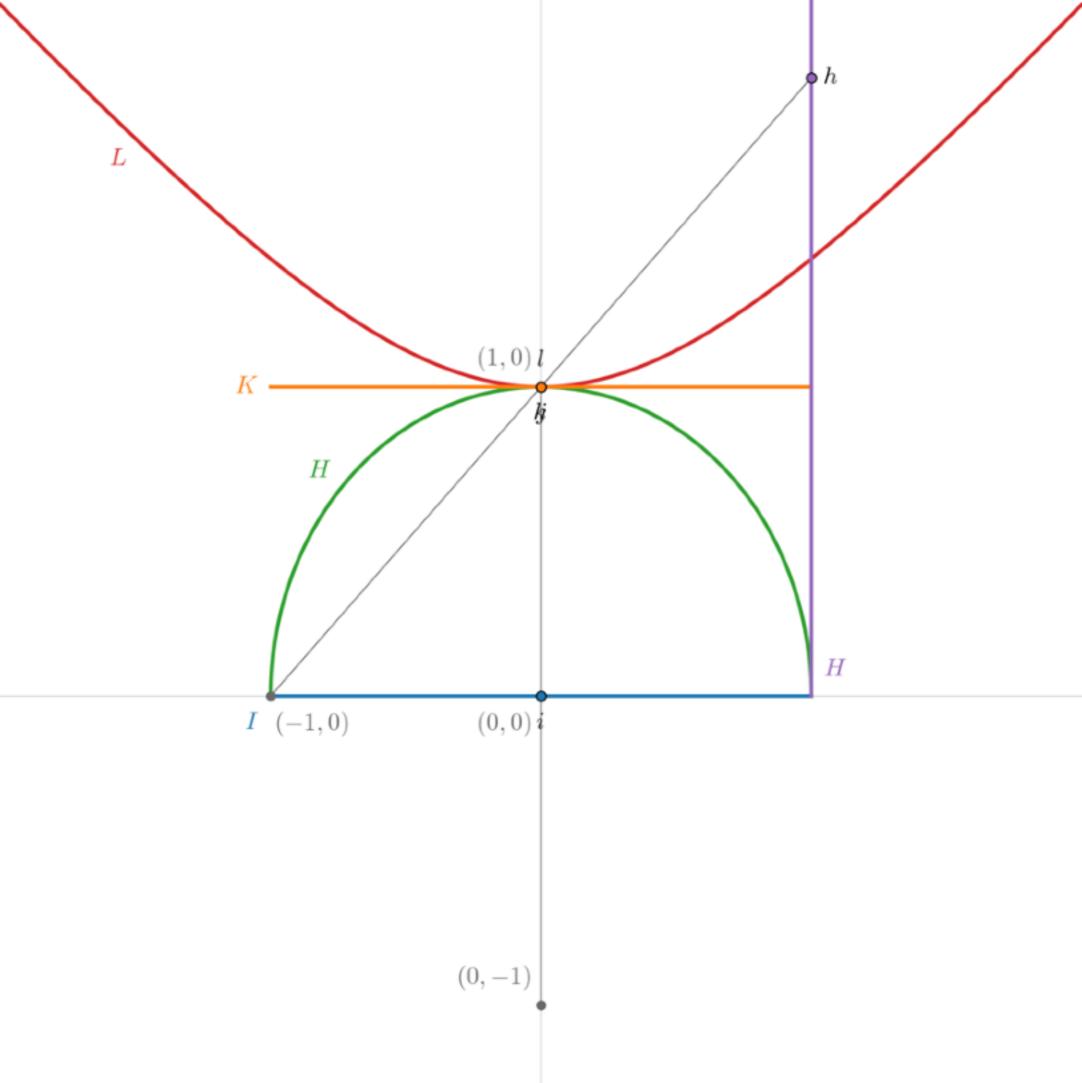
H: the half-space model; *I*: the interior of the disk model; J: the hemisphere model; K: the Klein model; L: the hyperboloid model. → They are isometrically equivalent. ▶ They have their own metric, geodesics, isometries, and so on. Each model supplies its own natural intuitions.

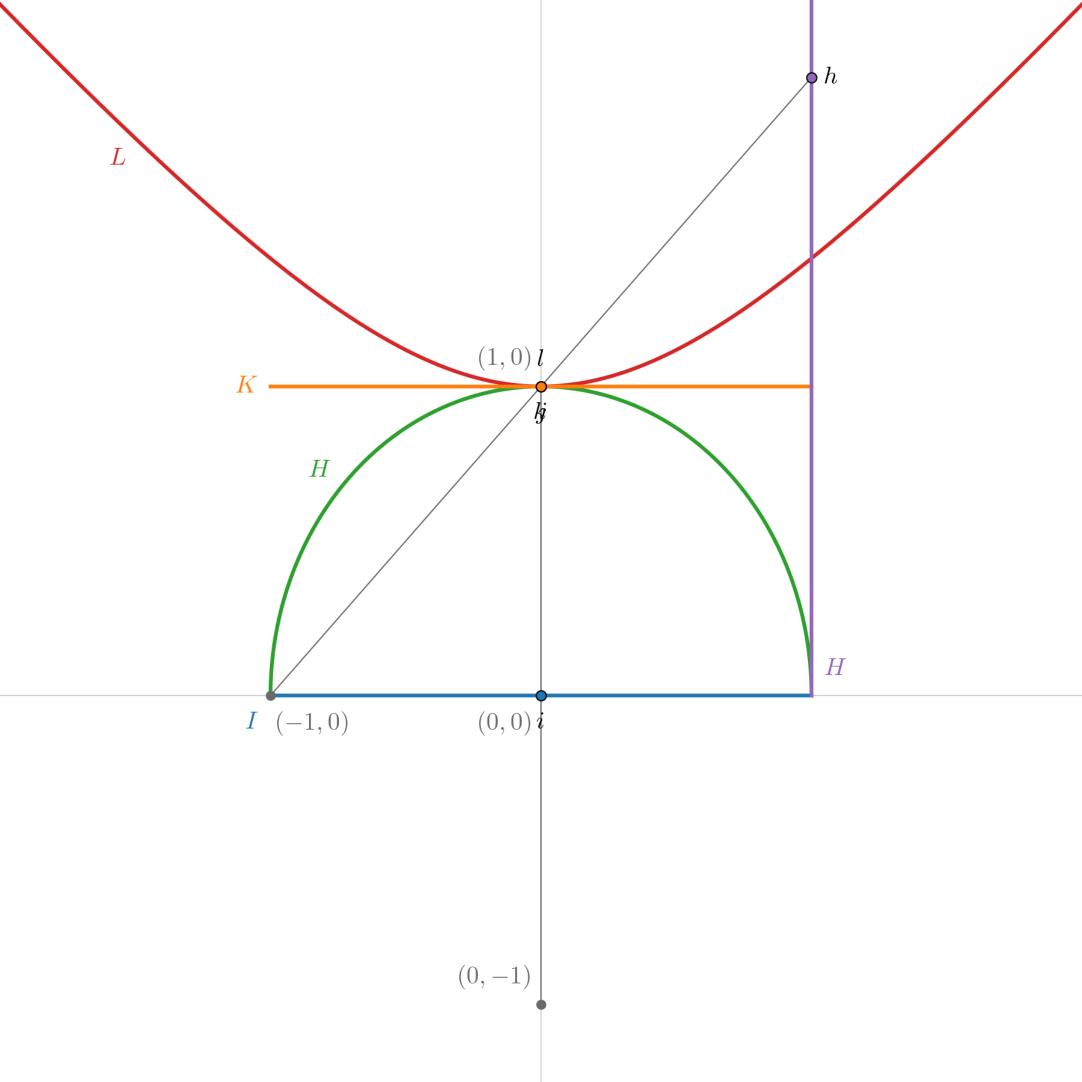
 \triangleright There are 5 models of hyperbolic geometry in $\mathbb{R}^{D,1}$:

Hyperbolic geometry



The five analytic models and their connecting isometries in D=1.

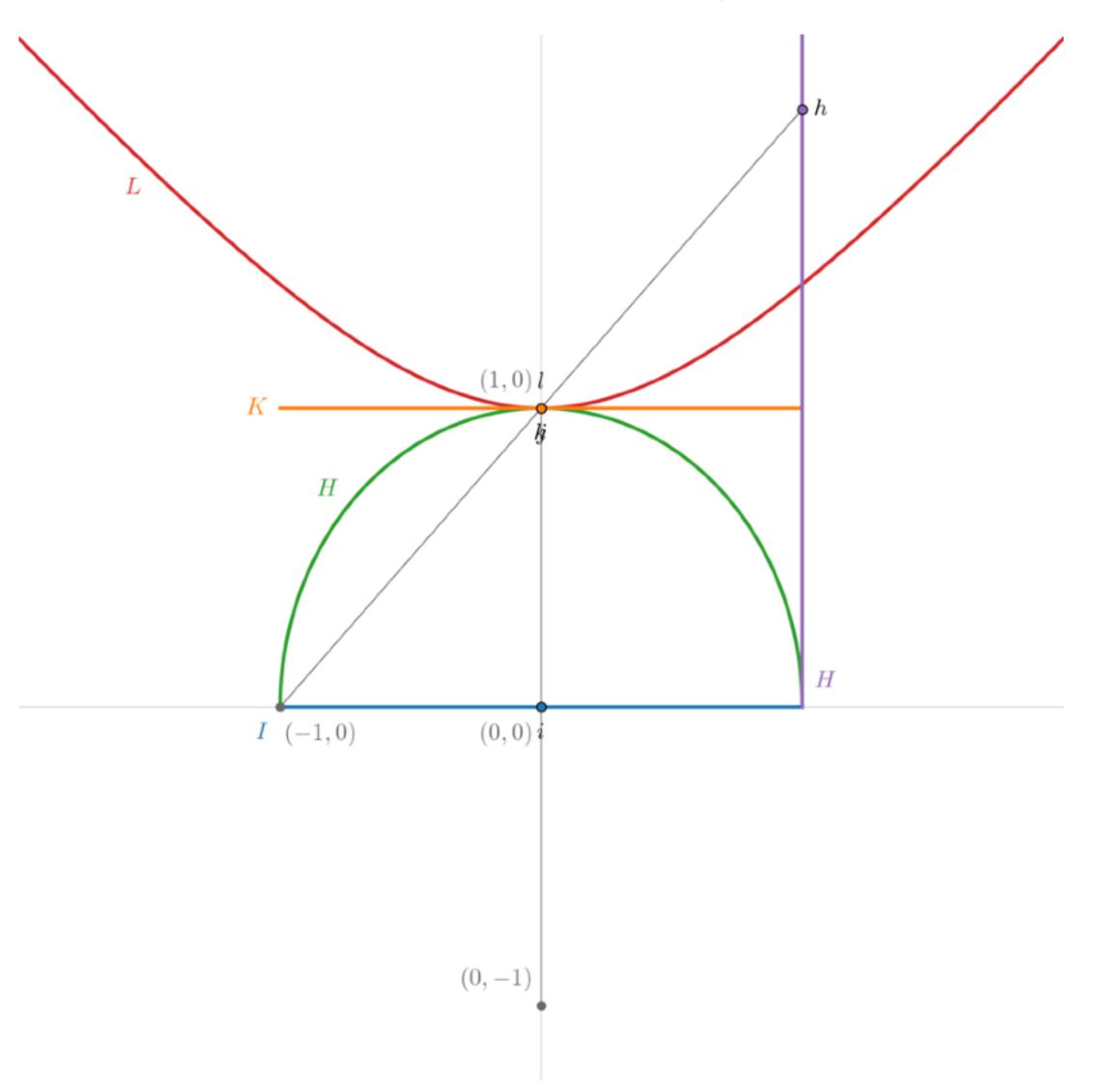




Hyperbolic geometry

- \triangleright There are 5 models of hyperbolic geometry in $\mathbb{R}^{D,1}$:
 - H: the half-space model;
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- ▶ They are isometrically equivalent.
- ▶ They have their own metric, geodesics, isometries, and so on.
- ▶ Each model supplies its own natural intuitions.

The five analytic models and their connecting isometries in D=1.



Hyperbolic geometry

- Space of constant negative curvature (as opposed to flat or Euclidean space, or spherical space)
- ightharpoonup Model for the D=2 hyperbolic space : positive sheet of the hyperboloid defined by

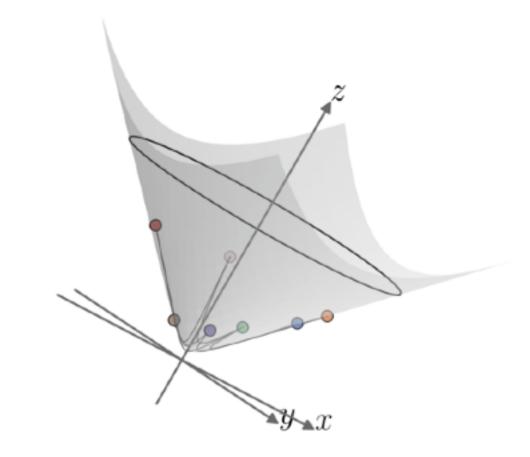
$$x^2 + y^2 - z^2 = -1$$

 \triangleright Distance between points (x_1,y_1,z_1) and (x_2,y_2,z_2) is

$$d(1,2) = \operatorname{arccosh}(z_1 z_2 - x_1 x_2 - y_1 y_2)$$

> Polar coordinates

$$x = \sinh(r)\cos(\theta)$$
$$y = \sinh(r)\sin(\theta)$$
$$z = \cosh(r)$$



hyperboloid in $\mathbb{R}^{2,1}$

