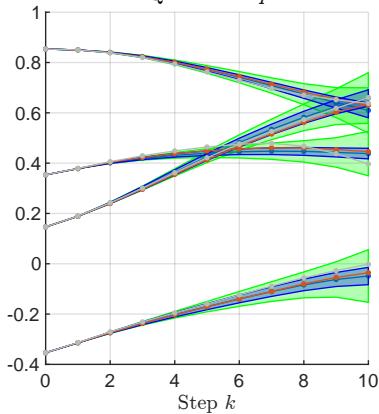
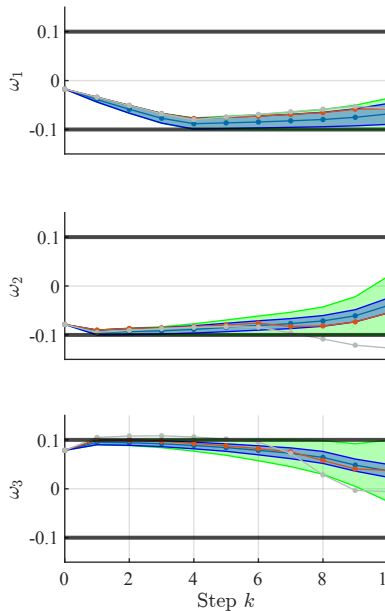


Quaternion q Angular speed ω Control input u 