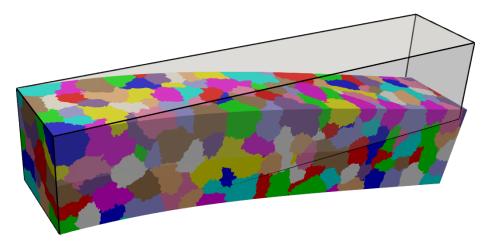
PSD: a Parallel Structural Dynamics solver



PSD is a finite elements-based solid mechanics solver with capabilities of performing High Performance Computing (HPC) simulations with billions of unknowns. The kernel of PSD is wrapped around FreeFEM for finite element discretization, and PETSc for linear algebra/Preconditioning. PSD solver contains straightforward supports for static or dynamic simulations with linear and nonlinear solid mechanics problems. Besides these hybrid-phase field fracture mechanics models have also been incorporated within PSD. For dynamics the genralized- α model for time discretization is used, this models enable straightforward use of Newmark- β , central difference, or HHT as time discretization. PSD uses sate-of-the art domain-decomposition paradigm via vectorial finite elements for parallel computing and all solvers are proven to scale quasi-optimally. PSD has proven scalabilty uptill 13,000 cores with largest problem solved containing over 5 Billion unknowns.

Besides the parallel suite, PSD also includes a sequential solver which does not require PETSc.

PSD works for two and three dimensional problems only. Unstructured meshes (triangular for 2D and tetrahedral for 3D) are supported in MEDIT's .mesh format or Gmsh's .msh format. PSD post processing is done via .vtk and .vtu files of the ParaView platform.

Installation procedure

PSD is built to work with Linux platforms. (Windows comping up soon)

Dependencies

- automake
- FreeFEM
- PETSc (optional)

- Gmsh
- gnuplot (optional)
- C++
- git

Now that I have all the dependencies what next

• Go ahead and grab the latest copy of PSD. The code is hosted on CEA's internal git repository.

git clone https://codev-tuleap.intra.cea.fr/plugins/git/hpcseism/freefem.git PSD-Sources

• Autoconf PSD within the cloned folder

autoreconf -i

• Configure PSD within the cloned folder

./configure

Note: ./configure will install PSD in \$HOME/PSD to change this directory use --prefix=Your/Own/Path with ./configure. Note: ./configure will try to look for installation of FreeFEM and Gmsh in usr/bin/ or usr/local/bin/directories. If you have these packages installed in some other directory this should be specified during ./configure by using flags --with-FreeFEM= and --with-Gmsh=. For example, if FreeFEM is installed at home/FreeFem/bin and Gmsh in home/Gmsh/bin then one should use

./configure --with-FreeFEM=home/FreeFem/bin --with-Gmsh=home/Gmsh/bin

• Make PSD directives

make

• Install PSD

make install

Now you should have the solver at \$HOME/PSD. To use the solver please go to \$HOME/PSD.

Additional FreeFEM tweak for brittle fracture mechanics

Note that this procedure is only recommended if you are interested in using PSD for brittle fracture problems. In your FreeFEM source files (installation) go to src/femlib/fem.cpp , in this file replace the lines of code

R seuil=hm/splitmax/4.0;

by the following

R seuil=hm/splitmax/4.0/1000.0;

Using procedure

The parallel/sequential solvers can be run on Linux platforms and can be used with command line options to control the solver. In order to make your choice of physics, command line options need to be typed right into the bash.

To perform a simulation three steps are involved

Step 1: Providing the mesh

A valid finite element mesh needs to be provided to the solver. PSD accepts only unstructured meshes: triangular for 2D and tetrahedral for 3D. These meshes need to be in MEDIT's .mesh format or Gmsh's .msh format. Once you have your mesh please copy the mesh to Meshes folder of your installed PSD directory. The 2D meshes need to be separated by the 2D ones.

Note: There is a native mesher bmag within FreeFEM which could also be used. However, it can only be used to generate simple geometries. In this case no need to copy the mesh to the Meshes folder.

Step 2: Setting up the solver

Now that the mesh has been loaded. Its time to set up the solver. Open the terminal window at the location of the solver, i.e., \$HOME/PSD/Solver. Then run the following command in the terminal.

```
./PSD_PreProcess [Options-PSD]
```

Via the command line options you will embed the physics within the solver. This step generates a bunch of .edp files which are native to FreeFEM and additionally prints out instructions on what to do next. You then need to open and edit couple of these files via your favorite text editor, which could be vim, gedit ,Notepad++, etc. To facilitate the edit process for your will have to go through the instructions printed on the terminal.

For example to generate a sequential 2D elasticity solver for a problem with body force and one Dirichlet border use

/PSD_PreProcess -dimension 2 -bodyforceconditions 1 -dirichletconditions 1

Step 3: Launching the solver

Now you are all set to run your simulation. To do so you will need to do the run the following in the terminal:

if you complied a parallel PSD version

PSD Solve -np \$N Main.edp -v 0 -nw

if you complied a sequential PSD version

PSD_Solve Main.edp -v 0 -nw

- In the parallel command \$N is an int value, i.e., number of processes that you want to use for performing the simulation in parallel.
- Additional flag -wg may be required while launching the solver, this is in case debug mode is on.

Sit back and be amazed at the speed of the solver.

[Options-PSD] explained

These are a set of commandline flags/options that control your simulation. You can think of it as a way to talk to the solver. Here is a table that lists out some of the options that are available (for full list see documentation).

Option	Type	Comment
-help	[bool]	To activate helping message on the terminal.
-debug	[bool]	To activate debug mode with a wait plot.
		Development flag.
-useGFP	[bool]	To activate use of GoFastPlugins. A suite of C++ plugins.
-useRCM	[bool]	To activate mesh level renumbering via Reverse Cuthill Mckee.
-timepvd	[bool]	To activate time pvd plotting for ParaView
-pipegnu	[bool]	Use to activate realtime pipe plotting using gnuplot.
-timelog	[bool]	To activate time logging the different phases of the solver.
-supercomp	[bool]	Use when using a super computer without Xterm. support .
-bodyforce	[bool]	To activate volumetric source term (body force).
-vectorial	[bool]	To use vectorial finite element method.
-sequential	[bool]	To solve via a sequential solver.
-energydecom		To activate energy decomposition, only for
chergydeco	mkroor1	phase-field.
-doublecoup	l∉bool]	To activate double couple source for soildynamics.
-dirichletconditions		Number of Dirchlet boundaries.
-bodyforcecomditions		Number of regions acted upon by bodyforce.
-tractioncon (int) ns		Number of Neumann/traction bounders.
-parmetis_wor[kient]		Number of parallel workers used by ParMetis for partiotining.
-lagrange	[int]	Lagrange order used for FE spaces. 1 for P1 or 2 for P2.
-dimension	[int]	Accepts values 2 or 3. Use 3 for 3D. and 2 for 2D problem.
-nonlinearmet[scdng]		Nonlinear method type. Use "Picard" or "Newton-Raphsons".

Option	Type	Comment
-postprocess[sting]		To communicate what to postprocess "u", "v", "a", "uv", "ud", "ua", "d", "ud", or "uav".
-problem	[sting]	Interested problem. Use "linear-elasticity", "damage", "elastodynamics", or "soildynamics".
-partitioner[sting]		Mesh partitioner could be "metis" "parmetis" or "scotch".

 $To\ report\ bugs,\ issues,\ feature-requests\ contact:$

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