

# CSE520: Computational Geometry

## Lecture 16

### The Lifting Map

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2 InCircle test

3 New interpretation of the Delaunay triangulation

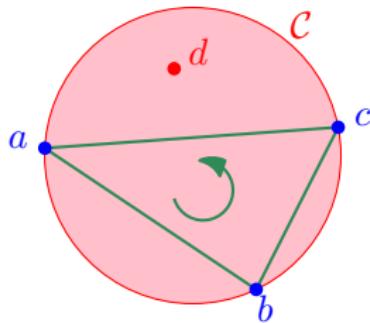
4 Edge flip

5 A first algorithm

# Outline

- Today, I will present a simple  $O(n^2)$  time algorithm for computing the Delaunay triangulation.
  - Before this, I will introduce the *lifting map*, which gives a different view of the Delaunay triangulation. It will be needed to analyze the algorithm.
- 
- References:
  - [Textbook](#) Chapter 9.
  - Dave Mount's [lecture notes](#), Lecture 18.
  - H. Edelsbrunner's book *Geometry and topology of mesh generation*, Chapter 1.

# InCircle Test



$$\text{inCircle}(a, b, c, d) < 0$$

## Definition (InCircle test)

Given a counterclockwise triangle  $abc$ , with circumcircle  $\mathcal{C}$ , the `inCircle` test returns a value such that:

- $\text{inCircle}(a, b, c, d) = 0$  if  $d \in \mathcal{C}$ ,
- $\text{inCircle}(a, b, c, d) > 0$  if  $d$  is outside  $\mathcal{C}$ , and
- $\text{inCircle}(a, b, c, d) < 0$  if  $d$  is inside  $\mathcal{C}$ .

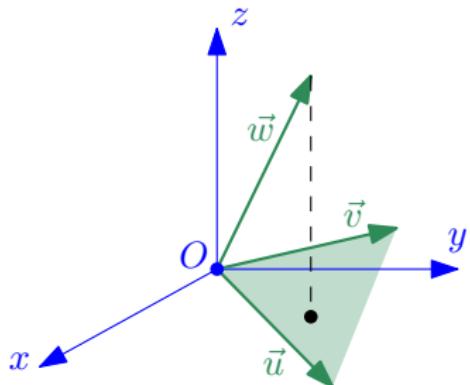
# Expression

- We can use the following expression:

$$\text{inCircle}(a, b, c, d) = \det \begin{pmatrix} 1 & a_x & a_y & a_x^2 + a_y^2 \\ 1 & b_x & b_y & b_x^2 + b_y^2 \\ 1 & c_x & c_y & c_x^2 + c_y^2 \\ 1 & d_x & d_y & d_x^2 + d_y^2 \end{pmatrix}.$$

- Why does it work?
- Next 10 slides: Geometric proof.
- D. Mount's notes 18: Different proof, through algebra.
- I reversed the sign of  $\text{inCircle}(\cdot)$  compared with D. Mount's notes, in order to simplify the presentation.

# Orientation of a Triple of Vectors in $\mathbb{R}^3$



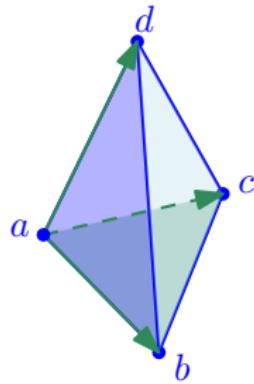
$$\begin{aligned}\text{orientation}(\vec{u}, \vec{v}, \vec{w}) &> 0 \\ \text{orientation}(\vec{v}, \vec{u}, \vec{w}) &< 0\end{aligned}$$

(right thumb rule)

- The orientation of a triple of vectors  $(\vec{u}, \vec{v}, \vec{w})$  is given by the sign of:

$$\det \begin{pmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{pmatrix}$$

# Orientation of a Tetrahedron



$$\text{orientation}(abcd) = \text{orientation}(\vec{ab}, \vec{ac}, \vec{ad}) > 0$$

- The orientation of tetrahedron  $abcd$  is the orientation of  $(\vec{ab}, \vec{ac}, \vec{ad})$ .

# Orientation of a Tetrahedron

- By developing with respect to first column, we obtain

$$\begin{aligned}\text{orientation}(abcd) &= \det \begin{pmatrix} b_x - a_x & b_y - a_y & b_z - a_z \\ c_x - a_x & c_y - a_y & c_z - a_z \\ d_x - a_x & d_y - a_y & d_z - a_z \end{pmatrix} \\ &= \det \begin{pmatrix} 1 & a_x & a_y & a_z \\ 0 & b_x - a_x & b_y - a_y & b_z - a_z \\ 0 & c_x - a_x & c_y - a_y & c_z - a_z \\ 0 & d_x - a_x & d_y - a_y & d_z - a_z \end{pmatrix}.\end{aligned}$$

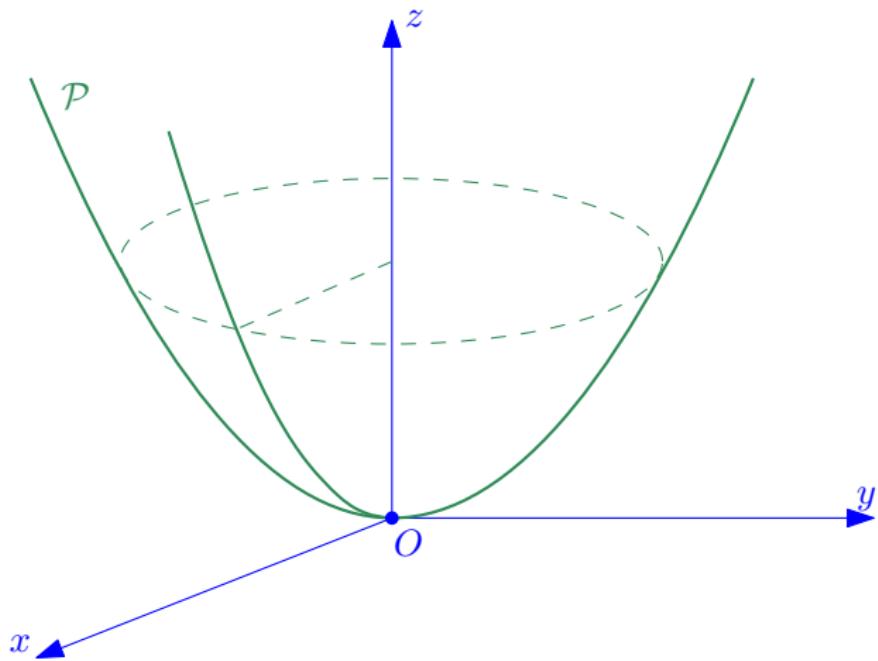
# Orientation of a Tetrahedron

- Now we add the first row to rows 2–4:

$$\text{orientation}(abcd) = \det \begin{pmatrix} 1 & a_x & a_y & a_z \\ 1 & b_x & b_y & b_z \\ 1 & c_x & c_y & c_z \\ 1 & d_x & d_y & d_z \end{pmatrix}.$$

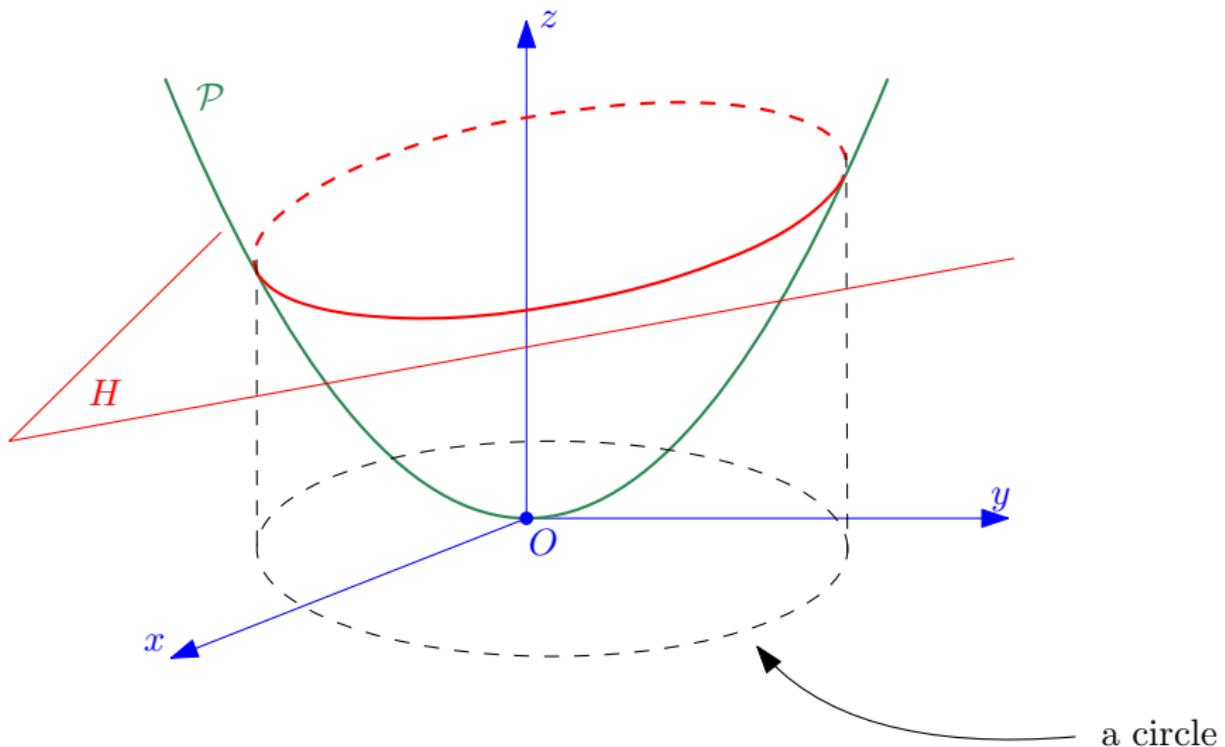
- It generalizes the 2D-counterclockwise (CCW) predicate from Lecture 2.

# Paraboloid $\mathcal{P}$



- Let  $\mathcal{P}$  be the paraboloid with equation  $z = x^2 + y^2$  in  $\mathbb{R}^3$ .

# Paraboloid $\mathcal{P}$



# Paraboloid $\mathcal{P}$

## Property

*When  $H$  is a non-vertical plane, the projection of  $H \cap \mathcal{P}$  onto plane  $Oxy$  is a circle.*

## Proof.

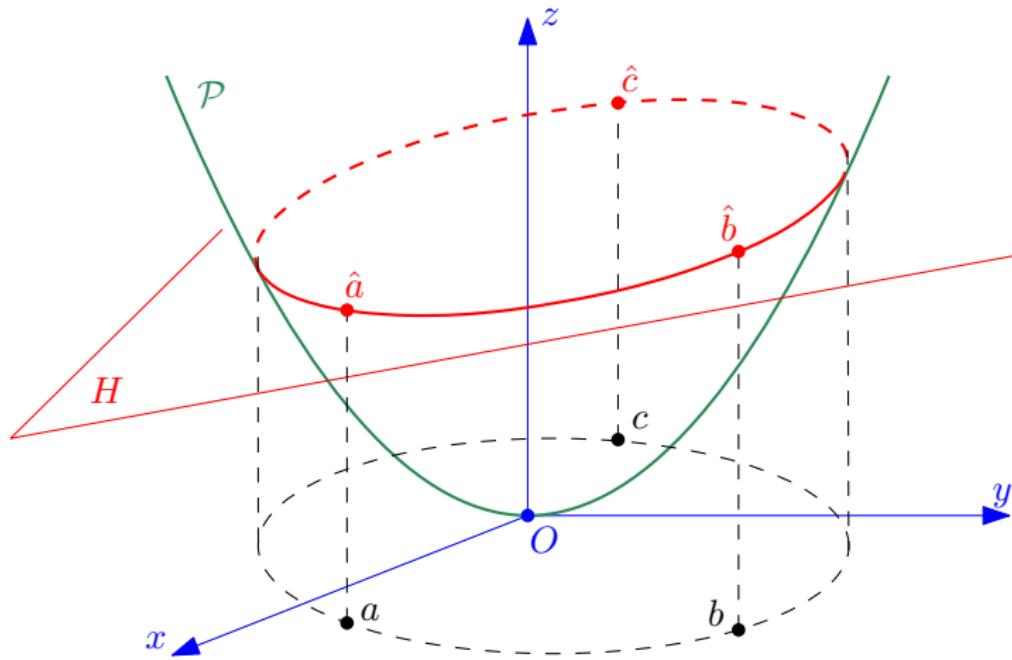
The plane  $H$  has equation  $z = \alpha x + \beta y + \gamma$ , so its projection  $H \cap \mathcal{P}$  onto the horizontal plane  $Oxy$  has equation  $x^2 + y^2 = \alpha x + \beta y + \gamma$ . □

# The Lifting Map

## Definition (Lifting map)

The lifting map is the vertical projection of the horizontal plane onto the paraboloid  $\mathcal{P}$ : Any point  $p = (p_x, p_y)$  is mapped to the point  $\hat{p} = (p_x, p_y, p_x^2 + p_y^2)$ .

# Proof of the InCircle Test Expression



# Proof of the InCircle Test Expression

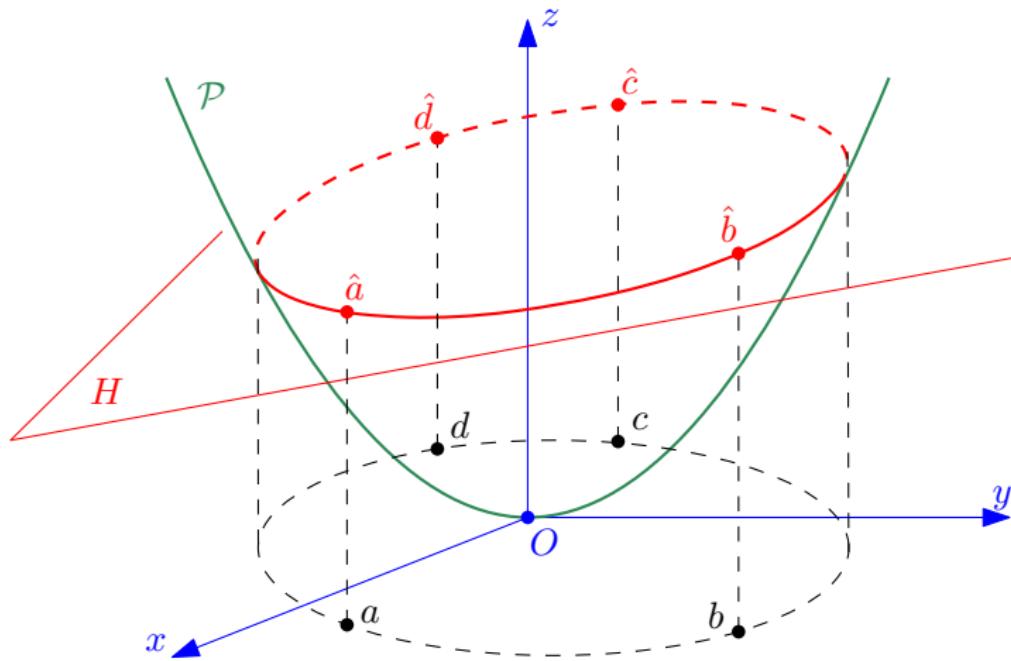
- We lift  $a, b, c$  and  $d$ :

$$\begin{aligned}\hat{a} &= (a_x, a_y, a_x^2 + a_y^2) \\ \hat{b} &= (b_x, b_y, b_x^2 + b_y^2) \\ \hat{c} &= (c_x, c_y, c_x^2 + c_y^2) \\ \hat{d} &= (d_x, d_y, d_x^2 + d_y^2)\end{aligned}$$

- We denote by  $H$  the plane through  $\{\hat{a}, \hat{b}, \hat{c}\}$
- $\text{inCircle}(a, b, c, d) = 0$  means that  $\text{orientation}(\hat{a}, \hat{b}, \hat{c}, \hat{d}) = 0$ .
- So  $\hat{d} \in H$ , and thus  $d \in \mathcal{C}$ .

## Proof: First Case

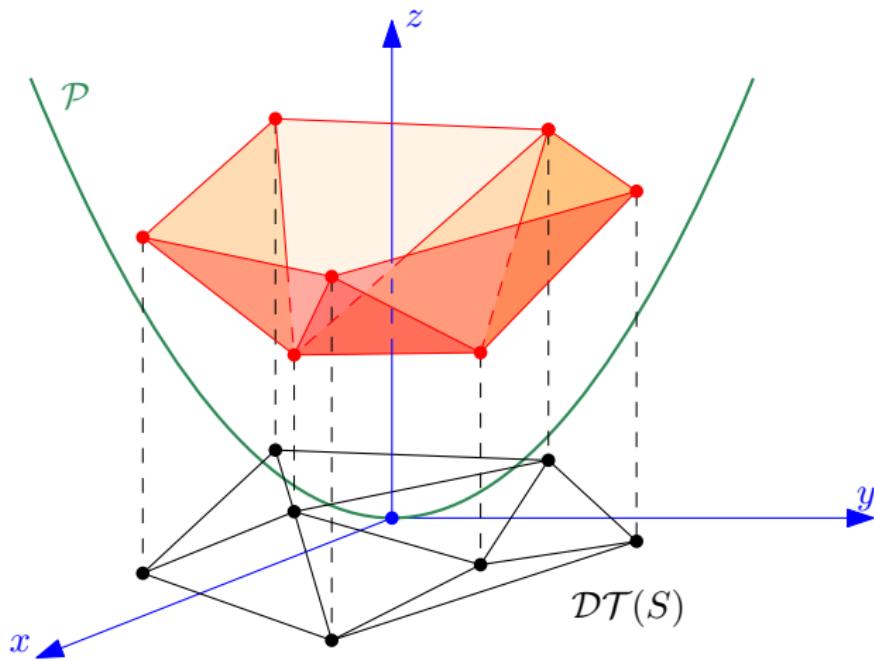
- We just proved that  $a, b, c, d$  are cocircular iff  $\hat{a}, \hat{b}, \hat{c}, \hat{d}$  are coplanar.



## Proof: Remaining Cases

- Assume that  $CCW(a, b, c) > 0$ .
- $\text{inCircle}(a, b, c, d) > 0$  means that  $\text{Orientation}(\hat{a}, \hat{b}, \hat{c}, \hat{d}) > 0$ .
- Then  $\hat{d}$  is above  $H$ .
- So  $d$  is outside the circumcircle of  $abc$ .
- $\text{inCircle}(a, b, c, d) < 0$  means that  $\text{Orientation}(\hat{a}, \hat{b}, \hat{c}, \hat{d}) < 0$ .
- Then  $\hat{d}$  is below  $H$ .
- So  $d$  is inside the circumcircle of  $abc$ .

# New Interpretation of the Delaunay Triangulation



- We lift the Delaunay triangulation onto the paraboloid.

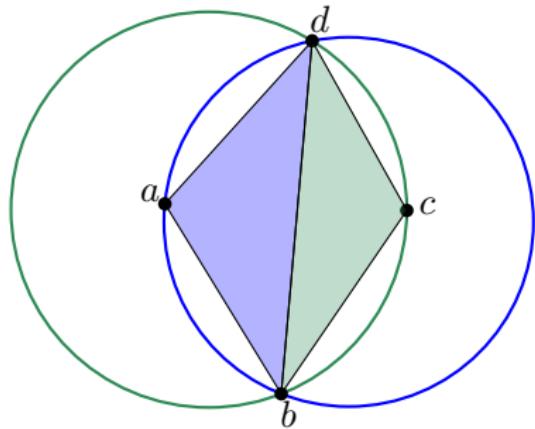
# Circumcircle Property

- $S = \{s_1, s_2, \dots, s_n\}$  is a set of points in the plane in general position.
- We denote  $\hat{S} = \{\hat{s}_1, \hat{s}_2, \dots, \hat{s}_n\}$ .
- Previous lecture: The triangle  $s_i s_j s_k$  is a face of  $\mathcal{DT}(S)$  iff its circumcircle is empty.
- It means that  $\hat{s}$  is above the plane through  $\hat{s}_i \hat{s}_j \hat{s}_k$  for every  $s \in P \setminus \{s_i, s_j, s_k\}$ .
- In other words,  $\hat{s}_i \hat{s}_j \hat{s}_k$  is a facet of the lower hull of  $\hat{P}$ .

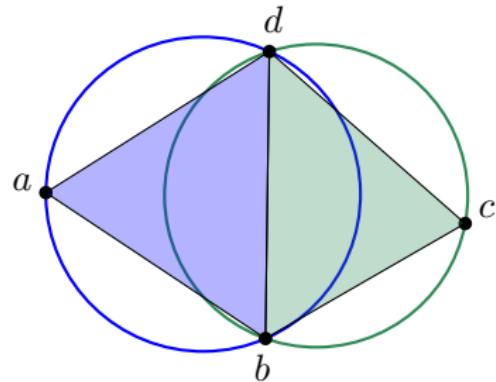
## Theorem

$\mathcal{DT}(S)$  is the projection of the edges of the lower hull of  $\hat{S}$  onto the plane  $z = 0$ .

## Edge Flip



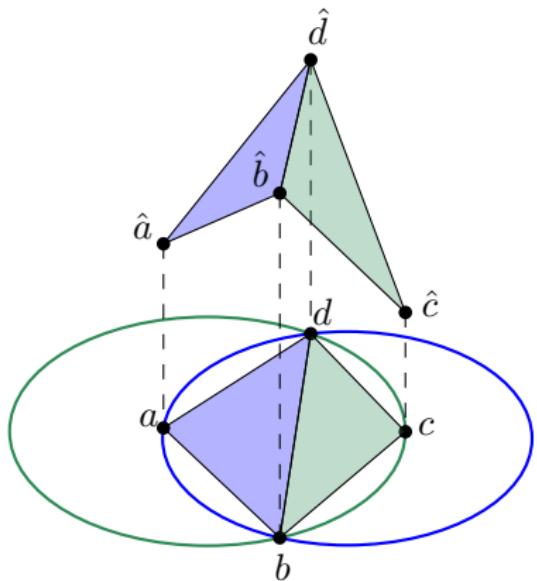
or



### Property

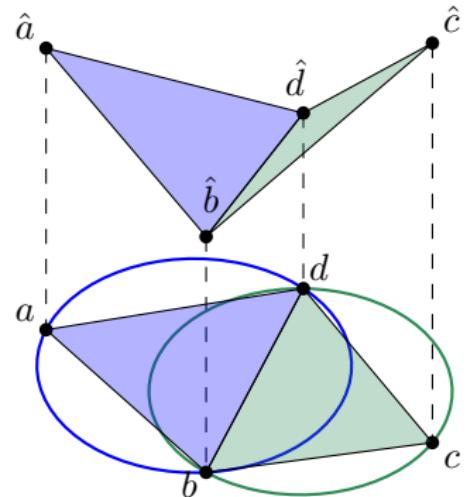
Let  $abcd$  be a convex quadrilateral. Then either  $c$  is inside the circumcircle of  $abd$  and  $a$  is inside the circumcircle of  $bcd$ , or  $c$  is outside circumcircle of  $abd$  and  $a$  is outside the circumcircle of  $bcd$ .

# Proof



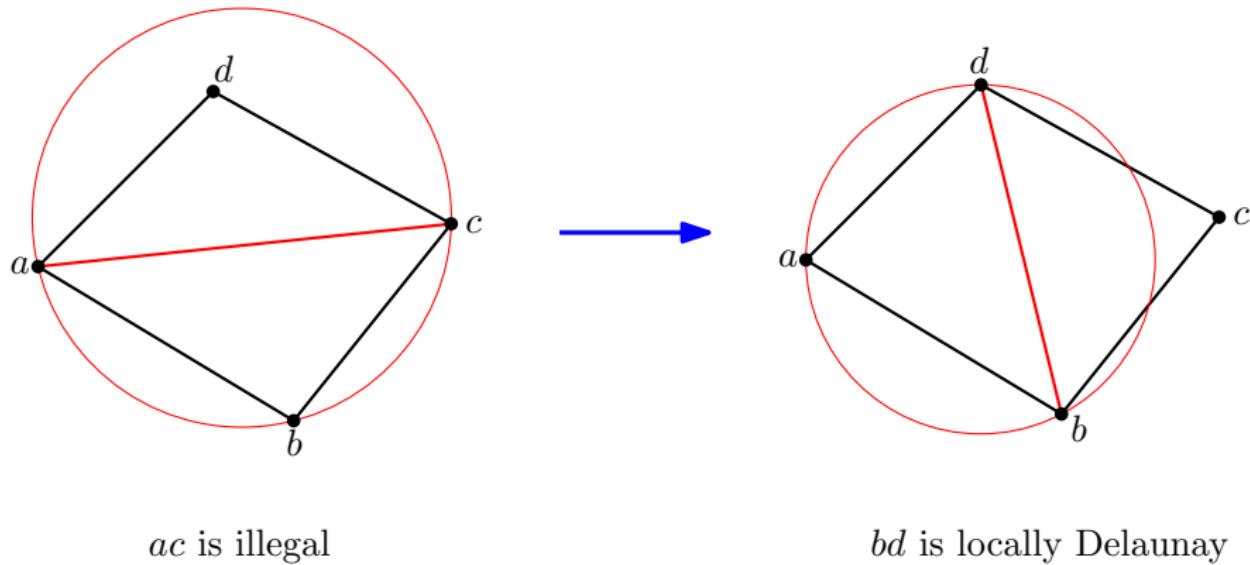
concave

or



convex

## Edge Flip: Definition



$ac$  is illegal

$bd$  is locally Delaunay

# Definitions

- Let  $S$  be a set of  $n$  points in  $\mathbb{R}^2$ . We say that  $S$  is in *general position* if no 4 points in  $S$  are cocircular.
- Let  $\mathcal{T}$  be a triangulation of  $S$ . Suppose that  $abcd$  is a convex quadrilateral, such that  $acb$  and  $acd$  are faces of  $\mathcal{T}$ .

## Definition (Locally Delaunay edge)

The edge  $ac$  is locally Delaunay iff  $d$  is outside the circumcircle of  $abc$ .

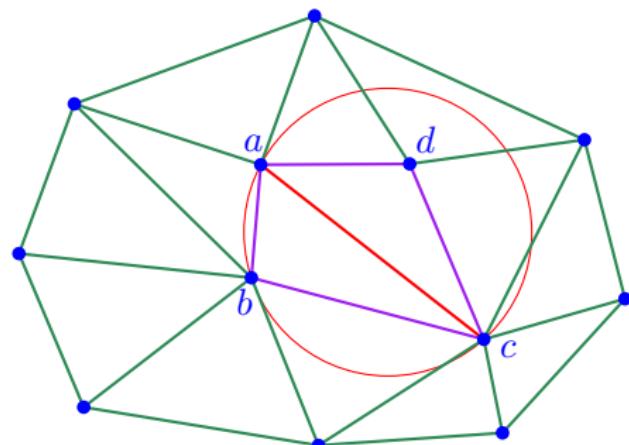
## Definition (Illegal edge)

The edge  $ac$  is illegal iff  $d$  is inside the circumcircle of  $abc$ .

- We can decide whether  $ab$  is locally Delaunay or illegal by computing the sign of  $CCW(a, b, c)$  and the sign of  $inCircle(a, b, c, d)$ .

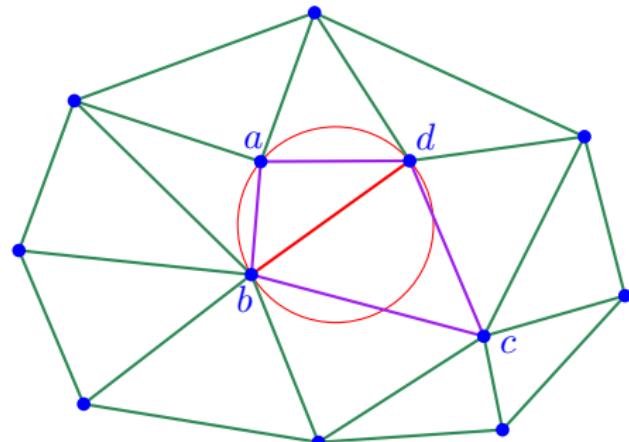
# Edge Flip

If  $ac$  is illegal, we can perform an *edge flip*: Remove  $ac$  from  $\mathcal{T}$  and insert  $bd$ .



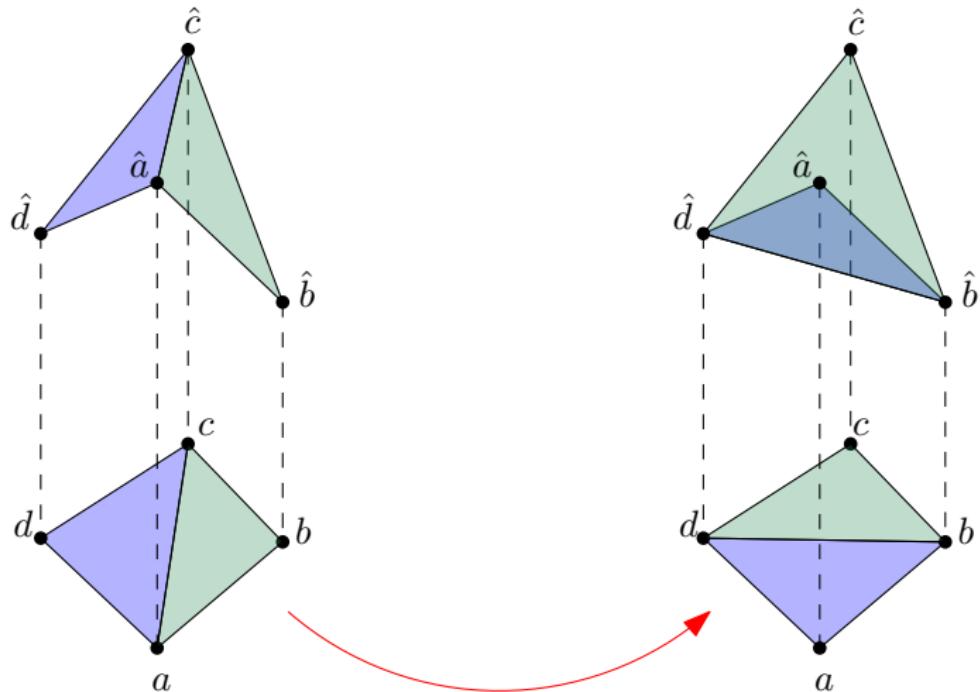
# Edge Flip

If  $ac$  is illegal, we can perform an *edge flip*: Remove  $ac$  from  $\mathcal{T}$  and insert  $bd$ .



Now  $bd$  is locally Delaunay.

# Edge Flip: Interpretation



- The lifted triangulation gets lower, and becomes convex.

# Edge Flip

## Theorem

Let  $\mathcal{T}$  be a triangulation of  $S$ . Then  $\mathcal{T} = \mathcal{DT}(S)$  iff all the edges of  $\mathcal{T}$  are locally Delaunay.

## Proof.

- If  $\mathcal{T}$  is Delaunay, then clearly all edges are locally Delaunay.
- Other direction:
  - The triangulation is locally Delaunay
  - $\Leftrightarrow$  the lifted triangulation is *locally* convex
  - $\Leftrightarrow$  the lifted triangulation is *globally* convex
  - $\Leftrightarrow$  the triangulation is (globally) Delaunay.



# A First Algorithm

Idea:

- Start with an arbitrary triangulation  $\mathcal{T}$  of  $S$ .
- If all the edges of  $\mathcal{T}$  are locally Delaunay, then we are done.
- Otherwise, pick an illegal edge and flip it.
- Repeat this process until each edge is locally Delaunay.

We will use a stack. Invariants:

- All the illegal edges are in the stack.
  - ▶ But some locally Delaunay edges may be in the stack too.
- The edges stored in the stack are *marked*, the others are not.
  - ▶ We use it to avoid having several copies of the same edge in the stack.

# A First Algorithm

## Pseudocode

```
1: procedure SLOWDELAUNAY( $S$ )
2:   compute a triangulation  $\mathcal{T}$  of  $S$ 
3:   mark all the edges of  $\mathcal{T}$ 
4:   initialize a stack containing all the edges of  $\mathcal{T}$ .
5:   while stack is non-empty do
6:     pop  $ac$  from stack and unmark it
7:     if  $ac$  is illegal then
8:       flip  $ac$  to  $bd$ 
9:       for  $xy \in \{ab, bc, cd, da\}$  do
10:        if  $xy$  is not marked then
11:          mark  $xy$  and push it on stack
12:   return  $\mathcal{T}$ 
```

# Analysis

- It is not obvious that this program halts!
- But in fact, it runs in  $\Theta(n^2)$  time.

## Proof.

- Each time we flip an edge, the lifted triangulation gets lower.
- So an edge can be flipped only once: Afterward, it remains above the lifted triangulation.
- There are  $O(n^2)$  possible edges.
- So the algorithm runs in  $O(n^2)$  time.
- Lower bound left as an exercise.

