Planar data classification with one hidden layer

Welcome to your week 3 programming assignment. It's time to build your first neural network, which will have a hidden layer. You will see a big difference between this model and the one you implemented using logistic regression.

You will learn how to:

- Implement a 2-class classification neural network with a single hidden layer
- Use units with a non-linear activation function, such as tanh
- Compute the cross entropy loss
- Implement forward and backward propagation

1 - Packages

Let's first import all the packages that you will need during this assignment.

- numpy (www.numpy.org) is the fundamental package for scientific computing with Python.
- sklearn (http://scikit-learn.org/stable/) provides simple and efficient tools for data mining and data analysis.
- matplotlib (http://matplotlib.org) is a library for plotting graphs in Python.
- testCases provides some test examples to assess the correctness of your functions
- planar utils provide various useful functions used in this assignment

```
In [1]: # Package imports
        import numpy as np
        import matplotlib.pyplot as plt
        from testCases import *
        import sklearn
        import sklearn.datasets
        import sklearn.linear model
        from planar utils import plot decision boundary, sigmoid, load planar dataset, load extra datasets
        %matplotlib inline
        np.random.seed(1) # set a seed so that the results are consistent
```

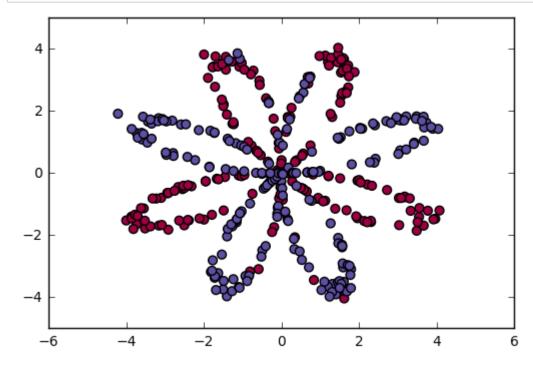
2 - Dataset

First, let's get the dataset you will work on. The following code will load a "flower" 2-class dataset into variables X and Y.

```
In [2]: X, Y = load_planar_dataset()
```

Visualize the dataset using matplotlib. The data looks like a "flower" with some red (label y=0) and some blue (y=1) points. Your goal is to build a model to fit this data.

```
In [3]: # Visualize the data:
        plt.scatter(X[0, :], X[1, :], c=Y, s=40, cmap=plt.cm.Spectral);
```



You have:

- a numpy-array (matrix) X that contains your features (x1, x2)
- a numpy-array (vector) Y that contains your labels (red:0, blue:1).

Lets first get a better sense of what our data is like.

Exercise: How many training examples do you have? In addition, what is the shape of the variables X and Y?

Hint: How do you get the shape of a numpy array? (help) (https://docs.scipy.org/doc/numpy/reference/generated/numpy.ndarray.shape.html)

```
In [6]: ### START CODE HERE ### (≈ 3 lines of code)
        shape X = X.shape
        shape Y = Y.shape
        m = shape X[1] # training set size
        ### END CODE HERE ###
        print ('The shape of X is: ' + str(shape_X))
        print ('The shape of Y is: ' + str(shape Y))
        print ('I have m = %d training examples!' % (m))
        The shape of X is: (2, 400)
        The shape of Y is: (1, 400)
        I have m = 400 training examples!
```

Expected Output:

shape of X	(2, 400)
shape of Y	(1, 400)
m	400

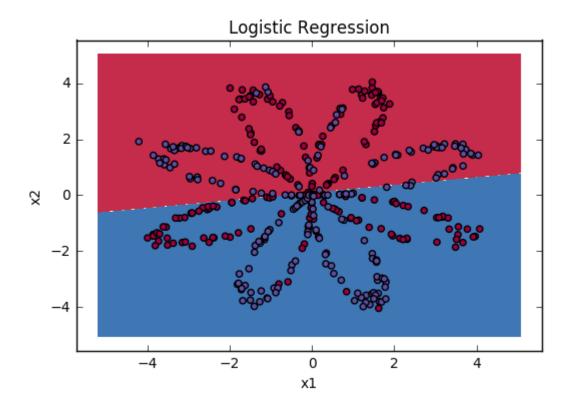
3 - Simple Logistic Regression

Before building a full neural network, lets first see how logistic regression performs on this problem. You can use sklearn's built-in functions to do that. Run the code below to train a logistic regression classifier on the dataset.

```
In [7]: # Train the logistic regression classifier
        clf = sklearn.linear model.LogisticRegressionCV();
        clf.fit(X.T, Y.T);
```

You can now plot the decision boundary of these models. Run the code below.

Accuracy of logistic regression: 47 % (percentage of correctly labelled datapoints)



Expected Output:

Accuracy	47%
Accuracy	77 /0

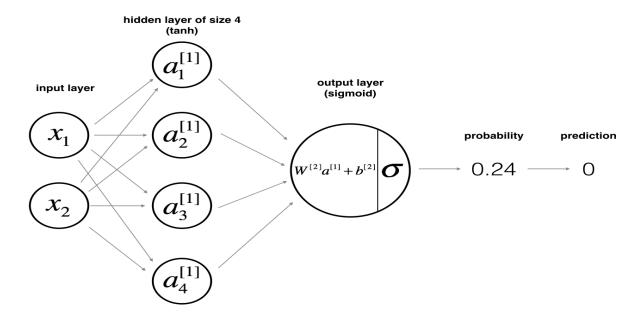
Interpretation: The dataset is not linearly separable, so logistic regression doesn't perform well. Hopefully a neural network will do

better. Let's try this now!

4 - Neural Network model

Logistic regression did not work well on the "flower dataset". You are going to train a Neural Network with a single hidden layer.

Here is our model:



Mathematically:

For one example $x^{(i)}$:

$$z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1](i)}$$
(1)

$$a^{[1](i)} = \tanh(z^{[1](i)}) \tag{2}$$

$$a^{[1](i)} = \tanh(z^{[1](i)})$$

$$z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2](i)}$$
(3)

$$\hat{y}^{(i)} = a^{[2](i)} = \sigma(z^{[2](i)}) \tag{4}$$

$$\hat{y}^{(i)} = a^{[2](i)} = \sigma(z^{[2](i)})$$

$$y_{prediction}^{(i)} = \begin{cases} 1 & \text{if } a^{[2](i)} > 0.5 \\ 0 & \text{otherwise} \end{cases}$$
(5)

Given the predictions on all the examples, you can also compute the cost J as follows:

$$J = -\frac{1}{m} \sum_{i=0}^{m} \left(y^{(i)} \log(a^{[2](i)}) + (1 - y^{(i)}) \log(1 - a^{[2](i)}) \right)$$
 (6)

Reminder: The general methodology to build a Neural Network is to:

- 1. Define the neural network structure (# of input units, # of hidden units, etc).
- 2. Initialize the model's parameters
- 3. Loop:
 - Implement forward propagation
 - Compute loss
 - Implement backward propagation to get the gradients
 - Update parameters (gradient descent)

You often build helper functions to compute steps 1-3 and then merge them into one function we call nn model (). Once you've built nn model () and learnt the right parameters, you can make predictions on new data.

4.1 - Defining the neural network structure

Exercise: Define three variables:

- n_x: the size of the input layer
- n h: the size of the hidden layer (set this to 4)
- n y: the size of the output layer

Hint: Use shapes of X and Y to find n_x and n_y. Also, hard code the hidden layer size to be 4.

```
In [9]: # GRADED FUNCTION: layer sizes
        def layer_sizes(X, Y):
            Arguments:
            X -- input dataset of shape (input size, number of examples)
            Y -- labels of shape (output size, number of examples)
            Returns:
            n x -- the size of the input layer
            n h -- the size of the hidden layer
            n y -- the size of the output layer
            ### START CODE HERE ### (≈ 3 lines of code)
            n_x = X.shape[0] # size of input layer
            n h = 4
            n_y = Y.shape[0] # size of output layer
            ### END CODE HERE ###
            return (n x, n h, n y)
```

```
In [10]: X assess, Y assess = layer sizes test case()
         (n \times n + n \times n) = layer sizes(X assess, Y assess)
         print("The size of the input layer is: n_x = " + str(n_x))
         print("The size of the hidden layer is: n h = " + str(n h))
         print("The size of the output layer is: n y = " + str(n y))
         The size of the input layer is: n_x = 5
         The size of the hidden layer is: n h = 4
```

Expected Output (these are not the sizes you will use for your network, they are just used to assess the function you've just coded).

n_x	5
n_h	4
n_y	2

4.2 - Initialize the model's parameters

The size of the output layer is: n y = 2

Exercise: Implement the function initialize_parameters().

Instructions:

- Make sure your parameters' sizes are right. Refer to the neural network figure above if needed.
- You will initialize the weights matrices with random values.
 - Use: np. random. randn(a,b) * 0.01 to randomly initialize a matrix of shape (a,b).
- You will initialize the bias vectors as zeros.
 - Use: np.zeros((a,b)) to initialize a matrix of shape (a,b) with zeros.

```
In [11]: # GRADED FUNCTION: initialize parameters
         def initialize_parameters(n_x, n_h, n_y):
             Argument:
             n x -- size of the input layer
             n h -- size of the hidden layer
             n y -- size of the output layer
             Returns:
             params -- python dictionary containing your parameters:
                              W1 -- weight matrix of shape (n h, n x)
                              b1 -- bias vector of shape (n h, 1)
                              W2 -- weight matrix of shape (n y, n h)
                              b2 -- bias vector of shape (n v, 1)
              0.00
             np.random.seed(2) # we set up a seed so that your output matches ours although the initialization
             ### START CODE HERE ### (≈ 4 lines of code)
             W1 = np.random.randn(n h, n x) * 0.01
             b1 = np.zeros((n h,1))
             W2 = np.random.randn(n_y,n_h) * 0.01
             b2 = np.zeros((n y,1))
             ### END CODE HERE ###
             assert (W1.shape == (n h, n x))
             assert (b1.shape == (n h, 1))
             assert (W2.shape == (n y, n h))
             assert (b2.shape == (n y, 1))
             parameters = {"W1": W1,
                            "b1": b1,
                            "W2": W2,
                            "b2": b2}
             return parameters
```

```
In [12]: | n_x, n_h, n_y = initialize_parameters_test case()
         parameters = initialize_parameters(n_x, n_h, n y)
         print("W1 = " + str(parameters["W1"]))
         print("b1 = " + str(parameters["b1"]))
         print("W2 = " + str(parameters["W2"]))
         print("b2 = " + str(parameters["b2"]))
         W1 = [[-0.00416758 - 0.00056267]]
          [-0.02136196 0.01640271]
          [-0.01793436 -0.00841747]
          [ 0.00502881 -0.01245288]]
         b1 = [[0.]]
          [ 0.]
          [ 0.]
          [ 0.11
         W2 = [[-0.01057952 - 0.00909008 0.00551454 0.02292208]]
         b2 = [[0.1]]
```

Expected Output:

W1	[[-0.00416758 -0.00056267] [-0.02136196 0.01640271] [-0.01793436 -0.00841747] [0.00502881 -0.01245288]]
b1	[[0.] [0.] [0.] [0.]]
W2	[[-0.01057952 -0.00909008 0.00551454 0.02292208]]
b2	[[0.]]

4.3 - The Loop

Question: Implement forward propagation().

Instructions:

- Look above at the mathematical representation of your classifier.
- You can use the function sigmoid(). It is built-in (imported) in the notebook.
- You can use the function np.tanh(). It is part of the numpy library.
- The steps you have to implement are:

- 1. Retrieve each parameter from the dictionary "parameters" (which is the output of initialize_parameters()) by using parameters [".."].
- 2. Implement Forward Propagation. Compute $Z^{[1]}, A^{[1]}, Z^{[2]}$ and $A^{[2]}$ (the vector of all your predictions on all the examples in the training set).
- Values needed in the backpropagation are stored in "cache". The cache will be given as an input to the backpropagation function.

```
In [13]: # GRADED FUNCTION: forward propagation
         def forward propagation(X, parameters):
             Argument:
             X -- input data of size (n x, m)
             parameters -- python dictionary containing your parameters (output of initialization function)
             Returns:
             A2 -- The sigmoid output of the second activation
             cache -- a dictionary containing "Z1", "A1", "Z2" and "A2"
             # Retrieve each parameter from the dictionary "parameters"
             ### START CODE HERE ### (≈ 4 lines of code)
             W1 = parameters['W1']
             b1 = parameters['b1']
             W2 = parameters['W2']
             b2 = parameters['b2']
             ### END CODE HERE ###
             # Implement Forward Propagation to calculate A2 (probabilities)
             ### START CODE HERE ### (≈ 4 lines of code)
             Z1 = np.dot(W1, X) + b1
             A1 = np.tanh(Z1)
             Z2 = np.dot(W2, A1) + b2
             A2 = sigmoid(Z2)
             ### END CODE HERE ###
             assert(A2.shape == (1, X.shape[1]))
             cache = {"Z1": Z1,}
                       "A1": A1,
                       "Z2": Z2,
                       "A2": A2}
             return A2, cache
```

```
In [14]: X assess, parameters = forward propagation test case()
         A2, cache = forward propagation(X assess, parameters)
         # Note: we use the mean here just to make sure that your output matches ours.
         print(np.mean(cache['Z1']) ,np.mean(cache['A1']),np.mean(cache['Z2']),np.mean(cache['A2']))
```

-0.000499755777742 -0.000496963353232 0.000438187450959 0.500109546852

Expected Output:

-0.000499755777742 -0.000496963353232 0.000438187450959 0.500109546852

Now that you have computed $A^{[2]}$ (in the Python variable "A2"), which contains $a^{[2](i)}$ for every example, you can compute the cost function as follows:

$$J = -\frac{1}{m} \sum_{i=0}^{m} \left(y^{(i)} \log(a^{[2](i)}) + (1 - y^{(i)}) \log(1 - a^{[2](i)}) \right)$$
 (13)

Exercise: Implement compute cost() to compute the value of the cost J.

Instructions:

• There are many ways to implement the cross-entropy loss. To help you, we give you how we would have implemented

$$-\sum_{i=0}^{m} y^{(i)} \log(a^{[2](i)}):$$

logprobs = np.multiply(np.log(A2),Y) cost = - np.sum(logprobs) # no need to use a for loop!

(you can use either np.multiply() and then np.sum() or directly np.dot()).

```
In [15]: # GRADED FUNCTION: compute cost
         def compute cost(A2, Y, parameters):
             Computes the cross-entropy cost given in equation (13)
             Arguments:
             A2 -- The sigmoid output of the second activation, of shape (1, number of examples)
             Y -- "true" labels vector of shape (1, number of examples)
             parameters -- python dictionary containing your parameters W1, b1, W2 and b2
             Returns:
             cost -- cross-entropy cost given equation (13)
             m = Y.shape[1] # number of example
             # Compute the cross-entropy cost
             ### START CODE HERE ### (≈ 2 lines of code)
             logprobs = np.multiply(np.log(A2), Y) + np.multiply((1 - Y), np.log(1 - A2))
             cost = - np.sum(logprobs) / m
             ### END CODE HERE ###
                                         # makes sure cost is the dimension we expect.
             cost = np.squeeze(cost)
                                          # E.g., turns [[17]] into 17
             assert(isinstance(cost, float))
             return cost
```

```
In [16]: A2, Y assess, parameters = compute cost test case()
         print("cost = " + str(compute cost(A2, Y assess, parameters)))
         cost = 0.692919893776
```

Expected Output:

cost | 0.692919893776

Using the cache computed during forward propagation, you can now implement backward propagation.

Question: Implement the function backward_propagation().

 $db^{[1]} = dz^{[1]}$

Instructions: Backpropagation is usually the hardest (most mathematical) part in deep learning. To help you, here again is the slide from the lecture on backpropagation. You'll want to use the six equations on the right of this slide, since you are building a vectorized implementation.

Summary of gradient descent
$$dz^{[2]} = a^{[2]} - y \qquad dZ^{[2]} = A^{[2]} - Y$$

$$dW^{[2]} = dz^{[2]}a^{[1]^T} \qquad dW^{[2]} = \frac{1}{m}dZ^{[2]}A^{[1]^T}$$

$$db^{[2]} = dz^{[2]} \qquad db^{[2]} = \frac{1}{m}np.sum(dZ^{[2]},axis = 1,keepdims = True)$$

$$dz^{[1]} = W^{[2]T}dz^{[2]} * g^{[1]'}(z^{[1]}) \qquad dZ^{[1]} = W^{[2]T}dZ^{[2]} * g^{[1]'}(Z^{[1]})$$

$$dW^{[1]} = dz^{[1]}x^T \qquad dW^{[1]} = \frac{1}{m}dZ^{[1]}X^T$$

 $db^{[1]} = \frac{1}{m} np. sum(dZ^{[1]}, axis = 1, keepdims = True)$

Andrew Ng

- Tips:
 - To compute dZ1 you'll need to compute $g^{[1]'}(Z^{[1]})$. Since $g^{[1]}(.)$ is the tanh activation function, if $a=g^{[1]}(z)$ then $g^{[1]'}(z)=1-a^2$. So you can compute $g^{[1]'}(Z^{[1]})$ using (1 np.power(A1, 2)).

```
In [17]: # GRADED FUNCTION: backward propagation
         def backward propagation(parameters, cache, X, Y):
             Implement the backward propagation using the instructions above.
             Arguments:
             parameters -- python dictionary containing our parameters
             cache -- a dictionary containing "Z1", "A1", "Z2" and "A2".
             X -- input data of shape (2, number of examples)
             Y -- "true" labels vector of shape (1, number of examples)
             Returns:
             grads -- python dictionary containing your gradients with respect to different parameters
             m = X.shape[1]
             # First, retrieve W1 and W2 from the dictionary "parameters".
             ### START CODE HERE ### (≈ 2 lines of code)
             W1 = parameters['W1']
             W2 = parameters['W2']
             ### END CODE HERE ###
             # Retrieve also A1 and A2 from dictionary "cache".
             ### START CODE HERE ### (≈ 2 lines of code)
             A1 = cache['A1']
             A2 = cache['A2']
             ### END CODE HERE ###
             # Backward propagation: calculate dW1, db1, dW2, db2.
             ### START CODE HERE ### (\approx 6 lines of code, corresponding to 6 equations on slide above)
             dZ2 = A2 - Y
             dW2 = (1 / m) * np.dot(dZ2, A1.T)
             db2 = (1 / m) * np.sum(dZ2, axis=1, keepdims=True)
             dZ1 = np.multiply(np.dot(W2.T, dZ2), 1 - np.power(A1, 2))
             dW1 = (1 / m) * np.dot(dZ1, X.T)
             db1 = (1 / m) * np.sum(dZ1, axis=1, keepdims=True)
             ### END CODE HERE ###
             grads = {"dW1": dW1,}
                       "db1": db1,
                       "dW2": dW2,
```

```
"db2": db2}
return grads
```

```
In [18]: parameters, cache, X assess, Y assess = backward propagation test case()
         grads = backward propagation(parameters, cache, X assess, Y assess)
         print ("dW1 = "+ str(grads["dW1"]))
         print ("db1 = "+ str(grads["db1"]))
         print ("dW2 = "+ str(grads["dW2"]))
         print ("db2 = "+ str(grads["db2"]))
         dW1 = [[0.01018708 - 0.00708701]]
          [ 0.00873447 -0.0060768 ]
          [-0.00530847 0.00369379]
          [-0.02206365 0.01535126]]
         db1 = [[-0.00069728]]
          [-0.00060606]
          [ 0.000364 ]
          [ 0.00151207]]
         dW2 = [[0.00363613 \ 0.03153604 \ 0.01162914 \ -0.01318316]]
         db2 = [[0.06589489]]
```

Expected output:

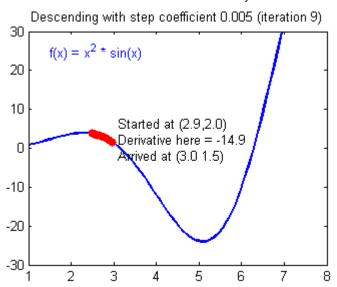
dW1	[[0.01018708 -0.00708701] [0.00873447 -0.0060768] [-0.00530847 0.00369379] [-0.02206365 0.01535126]]
db1	[[-0.00069728] [-0.00060606] [0.000364] [0.00151207]]
dW2	[[0.00363613 0.03153604 0.01162914 -0.01318316]]
db2	[[0.06589489]]

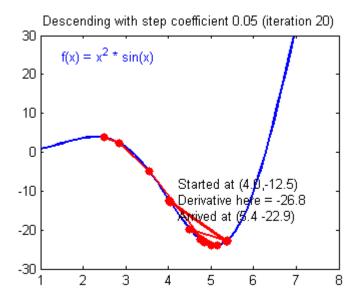
Question: Implement the update rule. Use gradient descent. You have to use (dW1, db1, dW2, db2) in order to update (W1, b1, W2, b2).

General gradient descent rule: $\theta = \theta - \alpha \frac{\partial J}{\partial \theta}$ where α is the learning rate and θ represents a parameter.

Illustration: The gradient descent algorithm with a good learning rate (converging) and a bad learning rate (diverging). Images courtesy of Adam Harley.

Planar data classification with one hidden layer v3





```
In [19]: # GRADED FUNCTION: update parameters
         def update parameters(parameters, grads, learning rate = 1.2):
             Updates parameters using the gradient descent update rule given above
             Arguments:
             parameters -- python dictionary containing your parameters
             grads -- python dictionary containing your gradients
             Returns:
             parameters -- python dictionary containing your updated parameters
             # Retrieve each parameter from the dictionary "parameters"
             ### START CODE HERE ### (≈ 4 lines of code)
             W1 = parameters['W1']
             b1 = parameters['b1']
             W2 = parameters['W2']
             b2 = parameters['b2']
             ### END CODE HERE ###
             # Retrieve each gradient from the dictionary "grads"
             ### START CODE HERE ### (≈ 4 lines of code)
             dW1 = grads['dW1']
             db1 = grads['db1']
             dW2 = qrads['dW2']
             db2 = qrads['db2']
             ## END CODE HERE ###
             # Update rule for each parameter
             ### START CODE HERE ### (≈ 4 lines of code)
             W1 = W1 - learning rate * dW1
             b1 = b1 - learning rate * db1
             W2 = W2 - learning rate * dW2
             b2 = b2 - learning rate * db2
             ### END CODE HERE ###
             parameters = {"W1": W1,
                            "b1": b1,
                            "W2": W2,
                            "b2": b2}
```

return parameters

```
parameters, grads = update_parameters_test_case()
In [20]:
         parameters = update parameters(parameters, qrads)
         print("W1 = " + str(parameters["W1"]))
         print("b1 = " + str(parameters["b1"]))
         print("W2 = " + str(parameters["W2"]))
         print("b2 = " + str(parameters["b2"]))
         W1 = [[-0.00643025 \quad 0.01936718]]
          [-0.02410458 0.03978052]
          [-0.01653973 -0.02096177]
          [ 0.01046864 -0.05990141]]
         b1 = [[-1.02420756e-06]]
          [ 1.27373948e-05]
          [ 8.32996807e-07]
          [ -3.20136836e-06]]
         W2 = [[-0.01041081 - 0.04463285 0.01758031 0.04747113]]
         b2 = [[0.00010457]]
```

Expected Output:

W1	[[-0.00643025 0.01936718] [-0.02410458 0.03978052] [-0.01653973 -0.02096177] [0.01046864 -0.05990141]]
b1	[[-1.02420756e-06] [1.27373948e-05] [8.32996807e-07] [-3.20136836e-06]]
W2	[[-0.01041081 -0.04463285 0.01758031 0.04747113]]
b2	[[0.00010457]]

4.4 - Integrate parts 4.1, 4.2 and 4.3 in nn_model()

Question: Build your neural network model in nn_model().

Instructions: The neural network model has to use the previous functions in the right order.

```
In [21]: # GRADED FUNCTION: nn model
         def nn_model(X, Y, n_h, num_iterations = 10000, print_cost=False):
             Arguments:
             X -- dataset of shape (2, number of examples)
             Y -- labels of shape (1, number of examples)
             n h -- size of the hidden layer
             num iterations -- Number of iterations in gradient descent loop
             print cost -- if True, print the cost every 1000 iterations
             Returns:
             parameters -- parameters learnt by the model. They can then be used to predict.
             np.random.seed(3)
             n x = layer sizes(X, Y)[0]
             n y = layer sizes(X, Y)[2]
             # Initialize parameters, then retrieve W1, b1, W2, b2. Inputs: "n x, n h, n y". Outputs = "W1, b1
             ### START CODE HERE ### (≈ 5 lines of code)
             parameters = initialize parameters(n x, n h, n y)
             W1 = parameters['W1']
             b1 = parameters['b1']
             W2 = parameters['W2']
             b2 = parameters['b2']
             ### END CODE HERE ###
             # Loop (gradient descent)
             for i in range(0, num iterations):
                 ### START CODE HERE ### (≈ 4 lines of code)
                 # Forward propagation. Inputs: "X, parameters". Outputs: "A2, cache".
                 A2, cache = forward propagation(X, parameters)
                 # Cost function. Inputs: "A2, Y, parameters". Outputs: "cost".
                 cost = compute cost(A2, Y, parameters)
                 # Backpropagation. Inputs: "parameters, cache, X, Y". Outputs: "grads".
                 grads = backward propagation(parameters, cache, X, Y)
```

```
# Gradient descent parameter update. Inputs: "parameters, grads". Outputs: "parameters".
   parameters = update parameters(parameters, grads)
   ### END CODE HERE ###
   # Print the cost every 1000 iterations
   if print cost and i % 1000 == 0:
       print ("Cost after iteration %i: %f" %(i, cost))
return parameters
```

```
In [22]: X assess, Y assess = nn model test case()
         parameters = nn model(X assess, Y assess, 4, num iterations=10000, print cost=False)
         print("W1 = " + str(parameters["W1"]))
         print("b1 = " + str(parameters["b1"]))
         print("W2 = " + str(parameters["W2"]))
         print("b2 = " + str(parameters["b2"]))
         W1 = [[-4.18494056 5.33220609]]
          [-7.52989382 1.24306181]
          [-4.1929459 5.32632331]
          [ 7.52983719 -1.24309422]]
         b1 = [[2.32926819]]
          [ 3.794589981
          [ 2.33002577]
          [-3.79468846]]
         W2 = [[-6033.83672146 -6008.12980822 -6033.10095287 6008.06637269]]
         b2 = [[-52.666077241]]
```

Expected Output:

W1	[[-4.18494056 5.33220609] [-7.52989382 1.24306181] [-4.1929459 5.32632331] [7.52983719 -1.24309422]]
b1	[[2.32926819] [3.79458998] [2.33002577] [-3.79468846]]
W2	[[-6033.83672146 -6008.12980822 -6033.10095287 6008.06637269]]
b2	[[-52.66607724]]

4.5 Predictions

Question: Use your model to predict by building predict(). Use forward propagation to predict results.

```
Reminder: predictions = y_{prediction} = 1\{\text{activation} > 0.5\} = \begin{cases} 1 & \text{if } activation > 0.5 \\ 0 & \text{otherwise} \end{cases}
```

As an example, if you would like to set the entries of a matrix X to 0 and 1 based on a threshold you would do: X new = (X > threshold)

```
In [23]: # GRADED FUNCTION: predict
         def predict(parameters, X):
             Using the learned parameters, predicts a class for each example in X
             Arguments:
             parameters -- python dictionary containing your parameters
             X -- input data of size (n x, m)
             Returns
             predictions -- vector of predictions of our model (red: 0 / blue: 1)
             \# Computes probabilities using forward propagation, and classifies to 0/1 using 0.5 as the thresh
             ### START CODE HERE ### (≈ 2 lines of code)
             A2, cache = forward propagation(X, parameters)
             predictions = np.round(A2)
             ### END CODE HERE ###
             return predictions
```

```
In [25]: parameters, X_assess = predict_test_case()
         predictions = predict(parameters, X_assess)
         print("predictions mean = " + str(np.mean(predictions)))
```

Expected Output:

predictions mean = 0.6666666666667

predictions mean	0.666666666667
------------------	----------------

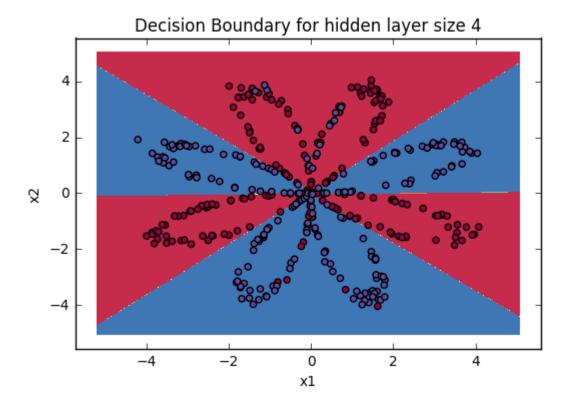
It is time to run the model and see how it performs on a planar dataset. Run the following code to test your model with a single hidden layer of n_h hidden units.

In [26]: # Build a model with a n_h-dimensional hidden layer
 parameters = nn_model(X, Y, n_h = 4, num_iterations = 10000, print_cost=True)

Plot the decision boundary
 plot_decision_boundary(lambda x: predict(parameters, x.T), X, Y)
 plt.title("Decision Boundary for hidden layer size " + str(4))

Cost after iteration 0: 0.693048
Cost after iteration 1000: 0.288083
Cost after iteration 2000: 0.254385
Cost after iteration 3000: 0.233864
Cost after iteration 4000: 0.226792
Cost after iteration 5000: 0.222644
Cost after iteration 6000: 0.219731
Cost after iteration 7000: 0.217504
Cost after iteration 8000: 0.219454
Cost after iteration 9000: 0.218607

Out[26]: <matplotlib.text.Text at 0x7fce64055940>



Expected Output:

Cost after iteration 9000	0.218607
---------------------------	----------

```
In [27]: # Print accuracy
```

predictions = predict(parameters, X)

print ('Accuracy: %d' % float((np.dot(Y,predictions.T) + np.dot(1-Y,1-predictions.T))/float(Y.size)*1

Accuracy: 90%

Expected Output:

Accuracy 90%

Accuracy is really high compared to Logistic Regression. The model has learnt the leaf patterns of the flower! Neural networks are able to learn even highly non-linear decision boundaries, unlike logistic regression.

Now, let's try out several hidden layer sizes.

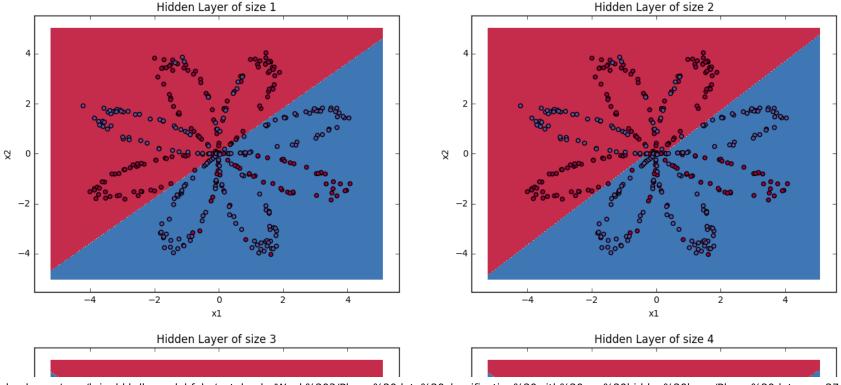
4.6 - Tuning hidden layer size (optional/ungraded exercise)

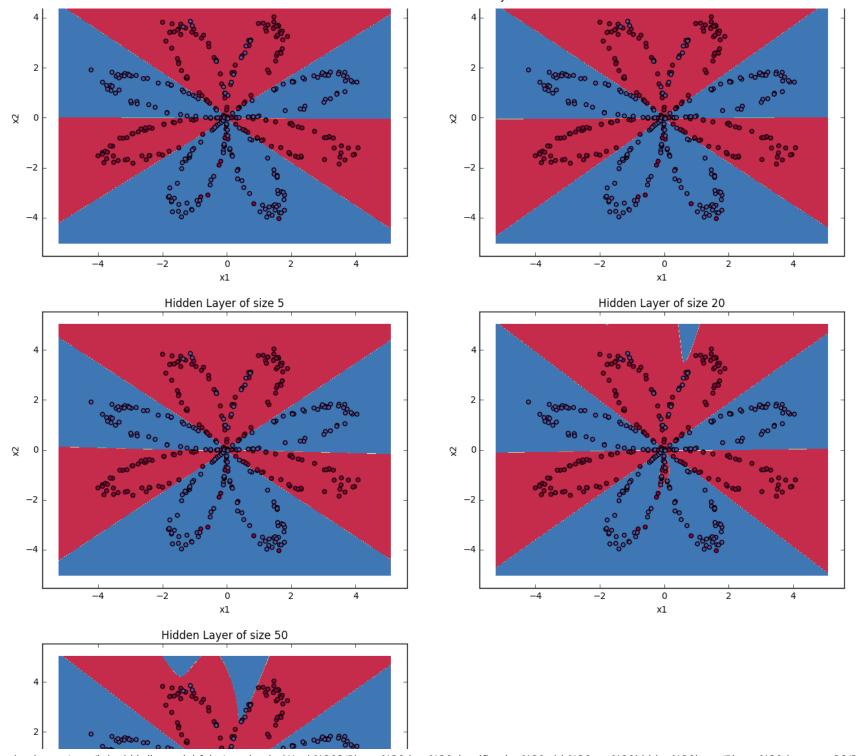
Run the following code. It may take 1-2 minutes. You will observe different behaviors of the model for various hidden layer sizes.

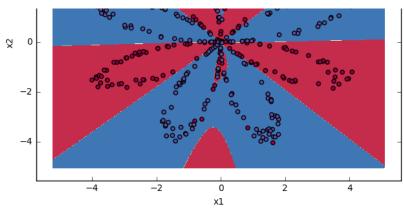
```
In [28]: # This may take about 2 minutes to run

plt.figure(figsize=(16, 32))
hidden_layer_sizes = [1, 2, 3, 4, 5, 20, 50]
for i, n_h in enumerate(hidden_layer_sizes):
    plt.subplot(5, 2, i+1)
    plt.title('Hidden Layer of size %d' % n_h)
    parameters = nn_model(X, Y, n_h, num_iterations = 5000)
    plot_decision_boundary(lambda x: predict(parameters, x.T), X, Y)
    predictions = predict(parameters, X)
    accuracy = float((np.dot(Y,predictions.T) + np.dot(1-Y,1-predictions.T))/float(Y.size)*100)
    print ("Accuracy for {} hidden units: {} %".format(n_h, accuracy))
```

Accuracy for 1 hidden units: 67.5 %
Accuracy for 2 hidden units: 67.25 %
Accuracy for 3 hidden units: 90.75 %
Accuracy for 4 hidden units: 90.5 %
Accuracy for 5 hidden units: 91.25 %
Accuracy for 20 hidden units: 90.0 %
Accuracy for 50 hidden units: 90.25 %







Interpretation:

- The larger models (with more hidden units) are able to fit the training set better, until eventually the largest models overfit the data.
- The best hidden layer size seems to be around n_h = 5. Indeed, a value around here seems to fits the data well without also incurring noticable overfitting.
- You will also learn later about regularization, which lets you use very large models (such as n_h = 50) without much overfitting.

Optional questions:

Note: Remember to submit the assignment but clicking the blue "Submit Assignment" button at the upper-right.

Some optional/ungraded questions that you can explore if you wish:

- What happens when you change the tanh activation for a sigmoid activation or a ReLU activation?
- Play with the learning rate. What happens?
- What if we change the dataset? (See part 5 below!)

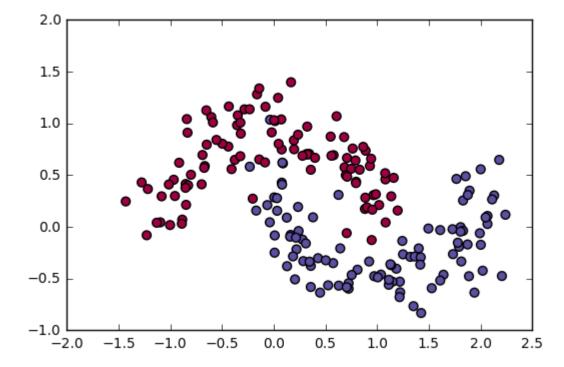
You've learnt to:

- Build a complete neural network with a hidden layer
- · Make a good use of a non-linear unit
- Implemented forward propagation and backpropagation, and trained a neural network
- · See the impact of varying the hidden layer size, including overfitting.

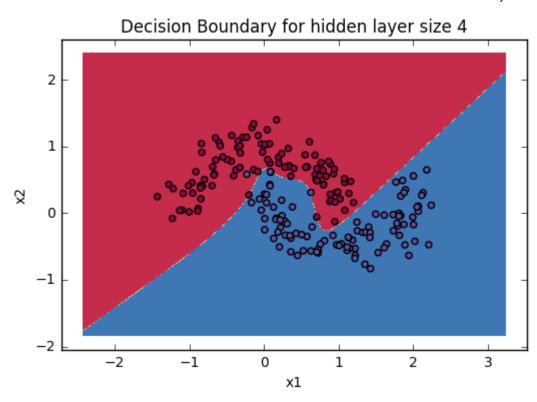
Nice work!

5) Performance on other datasets

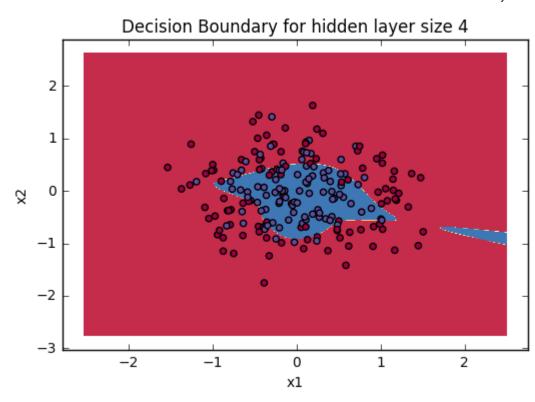
If you want, you can rerun the whole notebook (minus the dataset part) for each of the following datasets.



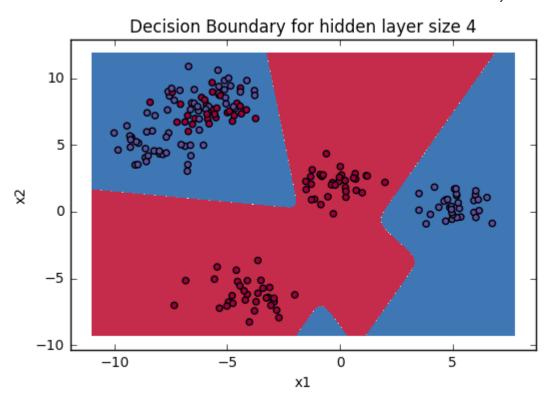
```
In [33]: ### START CODE HERE ### (choose your dataset)
         dataset = "noisy_moons"
         ### END CODE HERE ###
         X, Y = datasets[dataset]
         X, Y = X.T, Y.reshape(1, Y.shape[0])
         # make blobs binary
         if dataset == "blobs":
             Y = Y%2
         # Visualize the data
         plt.scatter(X[0, :], X[1, :], c=Y, s=40, cmap=plt.cm.Spectral);
         # Build a model with a n h-dimensional hidden layer
         parameters = nn_model(X, Y, n_h = 4, num_iterations=10000, print cost=True)
         # Plot the decision boundary
         plot decision boundary(lambda x: predict(parameters, x.T), X, Y)
         plt.title("Decision Boundary for hidden layer size " + str(4))
         # Print accuracy
         predictions = predict(parameters, X)
         print ('Accuracy: %d' % float((np.dot(Y,predictions.T) + np.dot(1-Y,1-predictions.T))/float(Y.size)*1
         Cost after iteration 0: 0.692992
         Cost after iteration 1000: 0.167137
         Cost after iteration 2000: 0.069092
         Cost after iteration 3000: 0.063716
         Cost after iteration 4000: 0.061312
         Cost after iteration 5000: 0.059669
         Cost after iteration 6000: 0.058364
         Cost after iteration 7000: 0.057279
         Cost after iteration 8000: 0.056359
         Cost after iteration 9000: 0.055569
         Accuracy: 98%
```



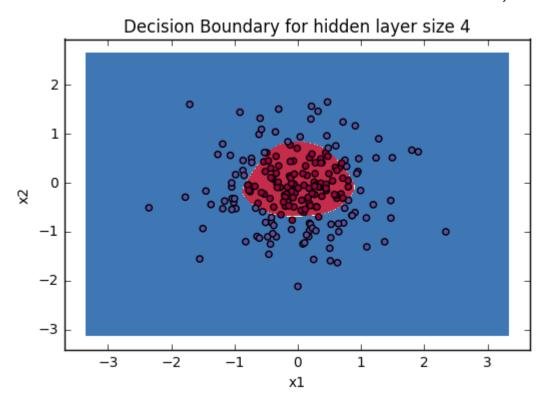
```
In [34]: | ### START CODE HERE ### (choose your dataset)
         dataset = "noisy circles"
         ### END CODE HERE ###
         X, Y = datasets[dataset]
         X, Y = X.T, Y.reshape(1, Y.shape[0])
         # make blobs binary
         if dataset == "blobs":
             Y = Y%2
         # Visualize the data
         plt.scatter(X[0, :], X[1, :], c=Y, s=40, cmap=plt.cm.Spectral);
         # Build a model with a n h-dimensional hidden layer
         parameters = nn_model(X, Y, n_h = 4, num_iterations=10000, print cost=True)
         # Plot the decision boundary
         plot decision boundary(lambda x: predict(parameters, x.T), X, Y)
         plt.title("Decision Boundary for hidden layer size " + str(4))
         # Print accuracy
         predictions = predict(parameters, X)
         print ('Accuracy: %d' % float((np.dot(Y,predictions.T) + np.dot(1-Y,1-predictions.T))/float(Y.size)*1
         Cost after iteration 0: 0.693155
         Cost after iteration 1000: 0.450026
         Cost after iteration 2000: 0.425231
         Cost after iteration 3000: 0.431254
         Cost after iteration 4000: 0.431356
         Cost after iteration 5000: 0.431040
         Cost after iteration 6000: 0.430653
         Cost after iteration 7000: 0.430309
         Cost after iteration 8000: 0.430031
         Cost after iteration 9000: 0.429812
         Accuracy: 76%
```



```
In [36]: | ### START CODE HERE ### (choose your dataset)
         dataset = "blobs"
         ### END CODE HERE ###
         X, Y = datasets[dataset]
         X, Y = X.T, Y.reshape(1, Y.shape[0])
         # make blobs binary
         if dataset == "blobs":
             Y = Y%2
         # Visualize the data
         plt.scatter(X[0, :], X[1, :], c=Y, s=40, cmap=plt.cm.Spectral);
         # Build a model with a n h-dimensional hidden layer
         parameters = nn model(X, Y, n h = 4, num iterations=10000, print <math>cost=True)
         # Plot the decision boundary
         plot decision boundary(lambda x: predict(parameters, x.T), X, Y)
         plt.title("Decision Boundary for hidden layer size " + str(4))
         # Print accuracy
         predictions = predict(parameters, X)
         print ('Accuracy: %d' % float((np.dot(Y,predictions.T) + np.dot(1-Y,1-predictions.T))/float(Y.size)*1
         Cost after iteration 0: 0.693527
         Cost after iteration 1000: 0.370642
         Cost after iteration 2000: 0.323369
         Cost after iteration 3000: 0.323051
         Cost after iteration 4000: 0.322919
         Cost after iteration 5000: 0.322846
         Cost after iteration 6000: 0.322799
         Cost after iteration 7000: 0.322767
         Cost after iteration 8000: 0.322743
         Cost after iteration 9000: 0.322724
         Accuracy: 83%
```



```
In [35]: ### START CODE HERE ### (choose your dataset)
         dataset = "gaussian quantiles"
         ### END CODE HERE ###
         X, Y = datasets[dataset]
         X, Y = X.T, Y.reshape(1, Y.shape[0])
         # make blobs binary
         if dataset == "blobs":
             Y = Y%2
         # Visualize the data
         plt.scatter(X[0, :], X[1, :], c=Y, s=40, cmap=plt.cm.Spectral);
         # Build a model with a n h-dimensional hidden layer
         parameters = nn_model(X, Y, n_h = 4, num_iterations=10000, print cost=True)
         # Plot the decision boundary
         plot decision boundary(lambda x: predict(parameters, x.T), X, Y)
         plt.title("Decision Boundary for hidden layer size " + str(4))
         # Print accuracy
         predictions = predict(parameters, X)
         print ('Accuracy: %d' % float((np.dot(Y,predictions.T) + np.dot(1-Y,1-predictions.T))/float(Y.size)*1
         Cost after iteration 0: 0.693130
         Cost after iteration 1000: 0.102746
         Cost after iteration 2000: 0.081035
         Cost after iteration 3000: 0.075216
         Cost after iteration 4000: 0.090696
         Cost after iteration 5000: 0.082406
         Cost after iteration 6000: 0.070028
         Cost after iteration 7000: 0.067212
         Cost after iteration 8000: 0.075135
         Cost after iteration 9000: 0.075134
         Accuracy: 97%
```



Congrats on finishing this Programming Assignment!

Reference:

- http://scs.ryerson.ca/~aharley/neural-networks/ (http://scs.ryerson.ca/~aharley/neural-networks/)
- http://cs231n.github.io/neural-networks-case-study/ (http://cs231n.github.io/neural-networks-case-study/ (http://cs231n.github.io/neural-networks-case-study/ (http://cs231n.github.io/neural-networks-case-study/)