

Point estimators

Probability theory. Statistics

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① Quiz

② Point estimators. Specific cases

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③ Point estimators. General case

Properties

Mean squared error

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④ Practice

Let Z_1, \dots, Z_7 be a random sample from the standard normal distribution.

Let $W = Z_1^2 + \dots + Z_7^2$.

- 1 Use CLT to estimate $P(1.69 < W < 14.07)$.
- 2 Find exact value of that probability.

Sample variance

- Let sample X_1, \dots, X_n from the same population be i.i.d. random variables with $E(X_i) = \mu$ and $V(X_i) = \sigma^2$. Mean μ is unknown.
- As in the example with sample mean, it would seem that the natural estimator for variance is:

$$\widehat{\sigma^2} = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2.$$

- But it turns out that:

$$E(\widehat{\sigma^2}) = \frac{n-1}{n} \sigma^2.$$

- That's why unbiased sample variance S^2 is used with $E(S^2) = \sigma^2$:

$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2.$$

Degrees of freedom

Definition

Degrees of freedom in statistics – number of independent values, which can be varied without breaking any constraints, while estimating a parameter.

Example

- Let's consider a sample with size 10 and already estimated mean value:

$$\begin{array}{cccccccccc} 2 & -1 & 4 & 9 & -2 & -2 & 3 & -2 & -6 & x \\ \text{Sum} = 10, & & \text{Mean} = 1. \end{array}$$

- The last value has no freedom to vary, since it is tightly connected to known mean value. The only possible outcome is $x = 5$.
- Mean imposes a constraint on a freedom to vary.
- Thus, in this example a number of degrees of freedom is **9**.

Degrees of freedom

- Sample variance has $n - 1$ degrees of freedom.
- Constraint:

$$\sum_{i=1}^n (X_i - \bar{X}) = 0.$$

- Sample variance is calculated from the vector of residuals $X_i - \bar{X}$:

$$(X_1 - \bar{X} \quad X_2 - \bar{X} \quad \dots \quad X_n - \bar{X}).$$

- While there are n independent observations in the sample, there are only $n - 1$ independent residuals, as they sum to 0.
- Overall, number of degrees of freedom is calculated as:

$$\text{DF} = \text{Sample size} - \text{Number of constraints}.$$

What if μ is known?

- If μ is known, we can use it to estimate σ :

$$\varsigma^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \mu)^2.$$

- Such estimator has n degrees of freedom, since residuals have no constraints, and subsequently:

$$\mathbb{E}(\varsigma^2) = \sigma^2.$$

- We can easily derive a distribution for ς^2 :

$$\frac{\varsigma^2}{\sigma^2} = \frac{1}{n} \sum_{i=1}^n \left(\frac{X_i - \mu}{\sigma} \right)^2 = \frac{1}{n} \sum_{i=1}^n Z_i^2,$$

$$\frac{n\varsigma^2}{\sigma^2} \sim \chi_n^2.$$

Fisher's lemma

- Let X_1, \dots, X_n be i.i.d. with $X_i \sim \mathcal{N}(\mu, \sigma^2)$.
- Distribution of $S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$ is given by:

Lemma (Fisher)

$$\frac{(n-1)S^2}{\sigma^2} \sim \chi_{n-1}^2.$$

Problem 1

Suppose X_1, X_2, \dots, X_{10} is a random sample taken from a $\mathcal{N}(12, 25)$ -distributed population.

- 1 Find the probability that the sample variance S^2 is between 20 and 30.
- 2 Find the range for the middle 90% of the distribution of the sample variance.

Problem 1

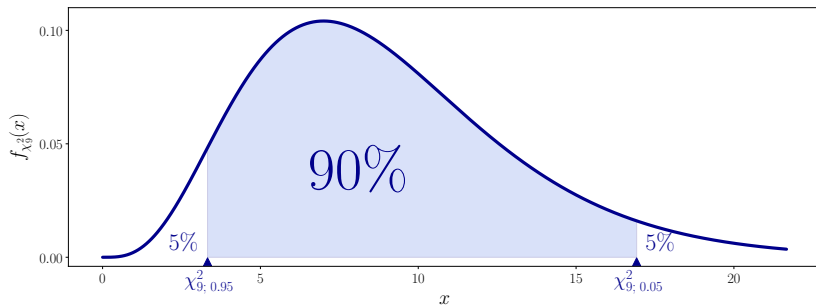


Figure: Middle 90% of χ^2_9 -distribution.

Sample proportion

- Let X be a number of successes in n trials with probability of success p :

$$X \sim \text{Bin}(n, p).$$

- Probability p can be estimated via sample proportion \hat{P} :

$$\hat{P} = \frac{X}{n}.$$

- Expected value and variance of \hat{P} :

$$\mathbb{E}(\hat{P}) = \mathbb{E}\left(\frac{X}{n}\right) = \frac{\mathbb{E}(X)}{n} = \frac{np}{n} = p,$$

$$\mathbb{V}(\hat{P}) = \mathbb{V}\left(\frac{X}{n}\right) = \frac{\mathbb{V}(X)}{n^2} = \frac{np(1-p)}{n^2} = \frac{p(1-p)}{n}.$$

- \hat{P} is **NOT** binomial, since it can take non-integer values.

Sample proportion

- Since explicit form of distribution for \hat{P} is unknown, let's use CLT (or an extension of De Moivre–Laplace theorem, scaled by n):

$$\frac{\hat{P} - \mathbf{E}(\hat{P})}{\sigma(\hat{P})} = \frac{\hat{P} - p}{\sqrt{p(1-p)/n}} \xrightarrow[n \rightarrow \infty]{d} Z \sim \mathcal{N}(0, 1).$$

- Thus:

$$\hat{P} \stackrel{\text{CLT}}{\approx} \mathcal{N}\left(p, \frac{p(1-p)}{n}\right).$$

- Normal approximation of \hat{P} is limited by it's physical meaning – proportion can not exceed bounds $[0, 1]$. Since $\mathbf{E}(\hat{P}) \pm 3 \cdot \sigma(\hat{P})$ contains 99.7% of all possible values of \hat{P} :

$$\left[p - 3\sqrt{\frac{p(1-p)}{n}}, p + 3\sqrt{\frac{p(1-p)}{n}} \right] \subset [0, 1],$$

Problem 2

An ordinary die is “fair” or “balanced” if each face has an equal chance of landing on top when the die is rolled. Thus the proportion of times a three is observed in a large number of tosses is expected to be close to $1/6$. Suppose a die is rolled 240 times and shows three on top 36 times.

- 1 Find the probability that a fair die would produce a proportion of 0.15 or less.
- 2 Give an interpretation of the result in part 1. How strong is the evidence that the die is not fair?
- 3 Suppose the sample proportion 0.15 came from rolling the die 2,400 times instead of only 240 times. Rework part 1 under these circumstances.
- 4 Give an interpretation of the result in part 3. How strong is the evidence that the die is not fair?

Point estimators

- X_1, \dots, X_n – sample from population with size n , assumed to be i.i.d. random variables.
- X_i have common c.d.f. $F_{X_i}(x; \theta)$, where θ is a parameter of distribution.

Definition

Point estimator of parameter θ is an arbitrary function of a sample:

$$\hat{\theta}_n = \hat{\theta}_n(X_1, \dots, X_n).$$

- Point estimators have bias: $\text{Bias}(\hat{\theta}_n) = E(\hat{\theta}_n) - \theta$.

Definition

Point estimator is called unbiased if: $E(\hat{\theta}_n) = \theta$.

Risk functions

- Loss function $u(\hat{\theta}_n - \theta)$ – penalizes the choice of point estimator, based on a “distance” between true parameter and its estimate.
- Properties of loss function:
 - ① $u(0) = 0$,
 - ② $u(-x) = x$,
 - ③ $u(x)$ is monotonous.
- Expected loss is characterized by risk function $R_{\hat{\theta}_n}(\theta)$:

$$R_{\hat{\theta}_n}(\theta) = \mathbb{E} \left(u \left(\hat{\theta}_n - \theta \right) \right).$$

Example

- $\mathbb{E} \left| \hat{\theta}_n - \theta \right|$ – mean absolute error (MAE),
- $\mathbb{E} \left(\hat{\theta}_n - \theta \right)^2$ – mean squared error (MSE),

Mean squared error

- MSE of estimator θ can be represented as

$$\begin{aligned}\text{MSE}(\hat{\theta}_n) &= \mathbb{E}(\hat{\theta}_n - \theta)^2 = \mathbb{V}(\hat{\theta}_n - \theta) + \left(\mathbb{E}(\hat{\theta}_n - \theta)\right)^2 = \\ &= \mathbb{V}(\hat{\theta}_n) + \text{Bias}^2(\hat{\theta}_n).\end{aligned}$$

- Minimizing MSE is a key criterion in selecting estimators.

Problem 3

Random variable X assumes values 0 and 1, each with probability $1/2$.

- ① Find population mean μ and variance σ^2 .
- ② You have 9 independent observations of X : $\{X_1, \dots, X_9\}$.
Consider the following estimators of the population mean μ :

① $\hat{\mu}_1 = 0.45$;

② $\hat{\mu}_2 = X_1$;

③ $\hat{\mu}_3 = \bar{X}$;

④ $\hat{\mu}_4 = X_1 + \frac{1}{3}X_2$;

⑤ $\hat{\mu}_5 = \frac{2}{3}X_1 + \frac{2}{3}X_2 - \frac{1}{3}X_3$.

Which of these estimators are unbiased? Calculate bias for each estimator. Which estimator is the most efficient?

- ③ Which estimators from part 2 are consistent?

Consistent estimators

Definition

Estimator $\hat{\theta}_n$ is called consistent if:

$$\hat{\theta}_n \xrightarrow[n \rightarrow \infty]{P} \theta.$$

or

$$\forall \varepsilon > 0 : \quad P \left(\left| \hat{\theta}_n - \theta \right| > \varepsilon \right) \xrightarrow[n \rightarrow \infty]{} 0.$$

Markov's inequality

If X is a non-negative random variable, then $\forall \varepsilon > 0$

$$P(X \geq \varepsilon) \leq \frac{E(X)}{\varepsilon}.$$

Consistent estimators

- Let's use $|\hat{\theta}_n - \theta|$ in Markov's inequality:

$$\begin{aligned} \mathbf{P} \left(|\hat{\theta}_n - \theta| \geq \varepsilon \right) &= \mathbf{P} \left(\left(\hat{\theta}_n - \theta \right)^2 \geq \varepsilon^2 \right) \leq \\ &\leq \frac{\mathbf{E} \left(\hat{\theta}_n - \theta \right)^2}{\varepsilon^2} = \frac{\text{MSE} \left(\hat{\theta}_n \right)}{\varepsilon^2}. \end{aligned}$$

- Sufficient condition of consistency:

$$\text{MSE} \left(\hat{\theta}_n \right) \xrightarrow{n \rightarrow \infty} 0.$$

Chebyshev's inequality

If X is a variable with $\mathbf{E}|X| < \infty$ and $0 < \mathbf{V}(X) < \infty$, then $\forall \varepsilon > 0$

$$\mathbf{P} \left(|X - \mathbf{E}(X)| > \varepsilon \right) \leq \frac{\mathbf{V}(X)}{\varepsilon^2}.$$

Problem 4

Let X_1, X_2, X_3 be a random sample from a population with mean μ and variance σ^2 . Consider the following two estimators of variance σ^2 :

① $\widehat{\sigma}_1^2 = c_1 (X_1 - X_2)^2$;

② $\widehat{\sigma}_2^2 = c_2 (X_1 - X_2)^2 + c_2 (X_1 - X_3)^2 + c_2 (X_2 - X_3)^2$.

Find constants c_1, c_2 , such that $\widehat{\sigma}_1^2$ and $\widehat{\sigma}_2^2$ are unbiased estimators of σ^2 .

Problem 5

Let $X \sim \mathcal{N}(\mu, \sigma^2)$ and $Y \sim \mathcal{N}(2\mu, 2\sigma^2)$. You have samples of size n and m from the two distributions: $\{X_1, \dots, X_n\}$ and $\{Y_1, \dots, Y_m\}$. Consider the estimator $\hat{\mu} = c_1 \bar{X} + c_2 \bar{Y}$.

- 1 For which c_1, c_2 the estimator is unbiased?
- 2 For which c_1, c_2 the estimator is unbiased and most efficient?

Problem 6

Let $X_1, X_2, X_3, \dots, X_n$ be a random sample from a $\mathcal{U}(0, \theta)$ distribution, where θ is unknown. Define the estimator

$$\hat{\Theta}_n = \max\{X_1, X_2, X_3, \dots, X_n\}.$$

- 1 Find the bias of $\hat{\Theta}_n$.
- 2 Find the MSE of $\hat{\Theta}_n$.
- 3 Is $\hat{\Theta}_n$ a consistent estimator of θ ?

Problem 7

When R successes occur in n trials, the sample proportion $\hat{p} = R/n$ customarily is used as an estimator of the probability of success p . However, there are sometimes good reasons to use the estimator

$p^* \equiv \frac{R+1}{n+2}$. Alternatively, p^* can be written as a linear combination of the familiar estimator \hat{p} :

$$p^* = \frac{n\hat{p} + 1}{n + 2} = \frac{n}{n + 2} \cdot \hat{p} + \frac{1}{n + 2}.$$

- 1 What is the MSE of \hat{p} ? Is it consistent?
- 2 What is the MSE of p^* ? Is it consistent?
- 3 To decide which estimator is better, \hat{p} or p^* , does consistency help? What criterion would help?
- 4 Tabulate the efficiency of p^* relative to \hat{p} , for example when $n = 10$ and $p = 0.0, 0.1, 0.2, \dots, 0.9, 1.0$.
- 5 State some possible circumstances when you might prefer to use p^* instead of \hat{p} to estimate p .

Problem 7

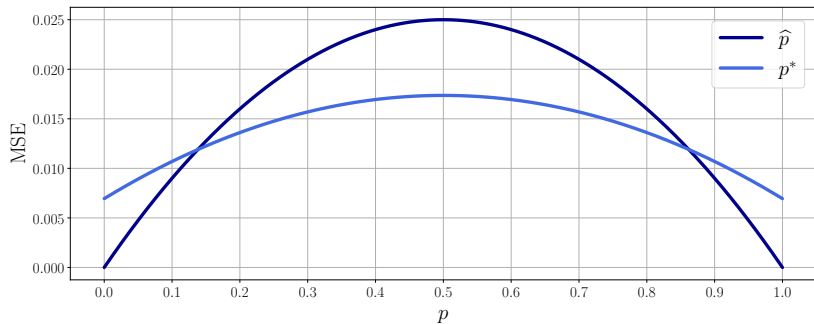


Figure: MSE of estimators \hat{p} and p^* for $n = 10$.



That's all Folks