Introduction to topology

MATH 429, Spring 2022

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Lecture 1

Metric spaces

In this chapter we discuss *metric spaces* — a motivating example that will guide us toward the definition of *topological spaces* — the main object of topology.

Examples of metric spaces were considered for thousands of years, but the first general definition was given only in 1906 by Maurice Fréchet.

A Definition

In the following definition we grab together the most important properties of intuitive notion of *distance*.

- **1.1. Definition.** Let \mathcal{X} be a nonempty set with a function which returns a real number, denoted as |x y|, for any pair $x, y \in \mathcal{X}$. Assume that the following conditions are satisfied for any $x, y, z \in \mathcal{X}$:
- (a) Positiveness:

$$|x - y| \ge 0.$$

(b) Identity of indiscernibles:

$$x = y$$
 if and only if $|x - y| = 0$.

(c) Symmetry:

$$|x - y| = |y - x|.$$

(d) Triangle inequality:

$$|x - y| + |y - z| \ge |x - z|$$
.

In this case we say that X is a metric space and the function

$$(x,y) \mapsto |x-y|$$

is called a metric.

The elements of \mathcal{X} are called points of the metric space. Given two points $x, y \in \mathcal{X}$, the value |x - y| is called distance from x to y.

Note that for two points in a metric space the difference between points x-y may have no meaning, but |x-y| always has the meaning defined above.

Typically, we consider only one metric on set, but if few metrics are needed, we can distingush them by a index, say $|x-y|_{\bullet}$ or $|x-y|_{239}$. If we need to emphasize that the distace is taken in the metric space \mathcal{X} we write $|x-y|_{\mathcal{X}}$ instead of |x-y|.

B Examples

Let us give few examples of metric spaces.

- Discrete sapee. Let \mathcal{X} be an arbitrary set. For any $x, y \in \mathcal{X}$, set |x y| = 0 if x = y and |x y| = 1 otherwise. This metric is called discrete metric on \mathcal{X} and the obtained metric space is called discrete.
- Real line. Set of all real numbers (\mathbb{R}) with metric defined as |x-y|.
- Metrics on the plane. Let us denote by \mathbb{R}^2 the set of all pairs (x_1, y_2) of real numbers. Consider two points $p_1 = (x_1, y_2)$ and $p_2 = (x_2, y_2)$ in \mathbb{R}^2 . One can equip \mathbb{R}^2 with the following metrics:
 - Euclidean metric, denoted by

$$|p_1 - p_2|_2 = \sqrt{(x_1 - x_2)^2 + (y_2 - y_2)^2}.$$

- Manhattan metric, denoted by $|*-*|_1$ and defined as

$$|p_1 - p_2|_1 = |x_1 - x_2| + |y_2 - y_2|.$$

- Maximum metric, denoted by $|*-*|_{\infty}$ and defined as

$$|p_1 - p_2|_{\infty} = \max\{|x_1 - x_2|, |y_2 - y_2|\}.$$

- **1.2. Exercise.** Prove that (a) $|*-*|_2$; (b) $|*-*|_1$ and (c) $|*-*|_{\infty}$ are metrics on \mathbb{R}^2 .
- 1.3. Exercise. Show that

$$|x - y|_{\natural} = (x - y)^2$$

is not a metric on \mathbb{R} .

1.4. Exercise. Show that if $(x,y) \mapsto |x-y|$ is a metric then so is

$$(x,y) \mapsto |x-y|_{\max} = \max\{1, |x-y|\}.$$

C Continuous maps

Recall that a real-to-real function f is called *continuous* if for any $x \in \mathbb{R}$ and any $\varepsilon > 0$ there exists $\delta > 0$ such that $|f(x) - f(y)| < \varepsilon$, whenever $|x - y| < \delta$.

This definition can be used for the functions defined on Euclidean space if |x - y| denotes the euclidean distance $|x - y|_2$ between the points x and y. It admits the following straightforward generalization to metric spaces:

- **1.5. Definition.** A function $f: \mathcal{X} \to \mathcal{Y}$ between metric spaces is called continuous if for any $x \in \mathcal{X}$ and any $\varepsilon > 0$ there exists $\delta > 0$ such that $|f(x) f(y)|_{\mathcal{Y}} < \varepsilon$, for any $y \in \mathcal{X}$ such that $|x y|_{\mathcal{X}} < \delta$.
- **1.6. Exercise.** Let \mathcal{X} be a metric space and $z \in \mathcal{X}$ be a fixed point. Show that the function

$$f(x) \stackrel{\text{def}}{=} |x - z|$$

is continuous.

1.7. Exercise. Let \mathcal{X} , \mathcal{Y} and \mathcal{Z} be a metric spaces. Assume that the functions $f: \mathcal{X} \to \mathcal{Y}$ and $g: \mathcal{Y} \to \mathcal{Z}$ are continuous, and

$$h = g \circ f \colon \mathcal{X} \to \mathcal{Z}$$

is its composition; that is, h(x) = g(f(x)) for any $x \in \mathcal{X}$. Show that $h: \mathcal{X} \to \mathcal{Z}$ is continuous at any point.

1.8. Exercise. Show that any distance-preserving map is continuous.

More precisely, assume that $f \colon \mathcal{X} \to \mathcal{Y}$ is a map between metric space such that

$$|x - x'|_{\mathcal{X}} = |f(x) - f(x')|_{\mathcal{Y}}$$

for any $x, x' \in \mathcal{X}$ then f is continuous.

1.9. Exercise. Let \mathcal{X} be a discrete metric space (defined on page 6) and \mathcal{Y} be arbitrary metric space. Show that for any function $f: \mathcal{X} \to \mathcal{Y}$ is continuous.

D Balls

Let \mathcal{X} be a metric space, x is a point in \mathcal{X} and r is a positive real number. The set of points in \mathcal{X} which lies on the distance smaller than r is called *ball of radius* r *centered at* x. It is denoted as B(x,r) or $B(x,r)_{\mathcal{X}}$ if we need to emphasize that it is taken in the space \mathcal{X} .

The ball B(x, r) is also called r-neighborhood of x.

- **1.10. Exercise.** Sketch the unit balls for the metrics $|*-*|_1$, $|*-*|_2$ and $|*-*|_{\infty}$ defined right before Exercise 1.2.
- **1.11. Exercise.** Assume B(x,r) and B(y,R) is a pair of balls in a metric space and $B(x,r) \subseteq B(y,R)$. Show that $r < 2 \cdot R$.

Give an example of a metric space and a pair of balls as above such that r > R.

Let us reformulate the definition of continuous map (1.5) using the introduced notion of ball.

1.12. Definition. A function $f: \mathcal{X} \to \mathcal{Y}$ between metric spaces is called continuous if for any $x \in \mathcal{X}$ and any $\varepsilon > 0$ there exists $\delta > 0$ such that

$$f(B(x,\delta)_{\mathcal{X}}) \subset B(f(x),\varepsilon)_{\mathcal{Y}}.$$

1.13. Exercise. Prove the equivalence of definitions 1.5 and 1.12.

E Open sets

1.14. Definition. A subset V in a metric space \mathcal{X} is called open if for any $x \in V$ there is $\varepsilon > 0$ such that $B(x, \varepsilon) \subset V$.

In other words, V is open if, together with each point, V contains its ε -neighborhood for some $\varepsilon > 0$. For example, any set in a descrete

metric space is open since together with any point it contains its 1-neighborhood. Further the set of positive real numbers

$$(0,\infty) = \{ x \in \mathbb{R} \mid x > 0 \}$$

is open since together with each point x > 0 it contains its x-neighborhood. On the other hand, the set of nonnegative reals

$$[0,\infty) = \{ x \in \mathbb{R} \mid x \ge 0 \}$$

is not open since there are negative numbers in any neighborhood of 0.

- 1.15. Exercise. Show that any ball in a metric space is open.
- **1.16.** Exercise. Show that any open set in a metric space is a union of balls.
- 1.17. Exercise. Show that union of arbitrary collection of open sets is open.
- 1.18. Exercise. Show that intersection of two open sets is open.
- **1.19. Exercise.** Give an example of metric space \mathcal{X} and an infinite sequence of open sets $V_1, V_2 \dots$ such that the intesection

$$\bigcap_{n} V_n$$

is not open.

1.20. Exercise. Show that the metrics $|*-*|_1$, $|*-*|_2$ and $|*-*|_{\infty}$ (defined on page 6) give rise to the same open sets in \mathbb{R}^2 . That is, if $V \subset \mathbb{R}^2$ is open for one of these metrics then it is open for the others.

F Gateway to topology

The following result is the main gateway to topology. It says that continuous maps can be defined entirely in terms of open sets.

1.21. Proposition. A function $f: \mathcal{X} \to \mathcal{Y}$ between two metric spaces is continuous if and only if for any open set $W \subset \mathcal{Y}$ its inverse images

$$f^{-1}(W) = \{ x \in \mathcal{X} \mid f(x) \in W \}$$

is open.

Note that proposition says nothing about the images of open sets. In fact, before going into proof it would be useful to solve the following exercise.

1.22. Exercise. Give an example of a continuous $f: \mathbb{R} \to \mathbb{R}$ and an open set $V \subset \mathbb{R}$ such that the image $f(V) \subset \mathbb{R}$ is not open.

The formulation of proposition contains "if and only if" and the proof brakes into two parta "if"-part and "only if"-part.

Proof; "only-if" part. Let $W \subset \mathcal{Y}$ be an open set and $V = f^{-1}(W)$. Choose $x \in V$; note that so $f(x) \in W$.

Since W is open,

$$\mathbf{0} \qquad \qquad \mathbf{B}(f(x), \varepsilon)_{\mathcal{Y}} \subset W$$

for some $\varepsilon > 0$.

Since f is continuous, by Definition 1.12, there is $\delta > 0$ such that

$$f(B(x,\delta)_{\mathcal{X}}) \subset B(f(x),\varepsilon)_{\mathcal{Y}}.$$

It follows that together with any point $x \in V$, the set V contains $B(x, \delta)$; that is, V is open.

"If" part. Fix $x \in \mathcal{X}$ and $\varepsilon > 0$. According to Exercise 1.15,

$$W = B(f(x), \varepsilon)_{\mathcal{Y}}$$

is an open set in \mathcal{Y} . Therefore its inverse image $f^{-1}(W)$ is open. Clearly $x \in f^{-1}(W)$. By the definition of open set (1.14)

$$B(x,\delta)_{\mathcal{X}} \subset f^{-1}(W)$$

for some $\delta > 0$. Or equivalently

$$f(B(x,\delta)_{\mathcal{X}}) \subset W = B(f(x),\varepsilon)_{\mathcal{Y}}.$$

Hence the "if"-part follows.

G Limits

1.23. Definition. Let $(x_n) = x_1, x_2, ...$ be a sequence of points in a metric space \mathcal{X} . We say the the sequence x_n converges to a point $x \in \mathcal{X}$ if

$$|x - x_n|_{\mathcal{X}} \to 0$$
 as $n \to \infty$.

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In this case we say that the sequence (x_n) is a converging sequence and x is its limit; the latter will be written as

$$x = \lim_{n \to \infty} x_n$$

Note that we defined the convergence of points in a metric space using the convergence of real numbers $d_n = |x - x_n|_{\mathcal{X}}$, which we assume to be known.

1.24. Exercise. Let $f: \mathcal{X} \to \mathcal{Y}$ be a function between metric spaces. Show that f is continuous if and only if for any converging sequence (x_n) in \mathcal{X} the sequence $y_n = f(x_n)$ is converging in \mathcal{Y} and

$$f(x_{\infty}) = y_{\infty},$$

if $x_n \to x_\infty$ and $y_n \to y_\infty$ as $n \to \infty$.

H Closed sets

Let A be a set in a metric space \mathcal{X} . A point $x \in \mathcal{X}$ is called *limit point* of A if there is a sequence $x_n \in A$ such that $x_n \to x$ as $n \to \infty$.

The set of all limit points of A is called *closure* of A and denoted as \bar{A} . Note that $\bar{A} \supset A$; indeed, any point $x \in A$ is a limit point of the constant sequence $x_n = x$.

If $\bar{A} = A$ then the set is called *closed*.

- **1.25.** Exercise. Show that closure of any set in metric space is a closed set; that is $\bar{A} = \bar{A}$.
- **1.26.** Exercise. Show that a subset A in a metric space \mathcal{X} is closed if and only if its complement $\mathcal{X} \setminus A$ is open.