Veronese minimizes normal curvatures

Anton Petrunin

Abstract

Suppose M is a closed submanifold in a Euclidean ball of large dimension. We give an optimal bound on the normal curvatures that guarantee that M is a sphere. The border cases consist of Veronese embeddings of the four projective planes.

1. Introduction. Let $M \subset \mathbb{R}^d$ be a closed smooth n-dimensional submanifold. Assume d is large and M lies in an r-ball. What can we say about the normal curvatures of M?

First note that the curvatures cannot be smaller than $\frac{1}{r}$ at all points. Moreover, the average value of |H| must be at least $n \cdot \frac{1}{r}$; here H denotes the mean curvature vector [2, 28.2.5], [8, 3.1]. This statement is a straightforward generalization of the result of István Fáry about closed curves in a ball [3, 12].

On the other hand, the n-dimensional torus can be embedded into an r-ball with all normal curvatures $\sqrt{3 \cdot n/(n+2)} \cdot \frac{1}{r}$. This embedding was found by Michael Gromov [6, 2.A], [5, 1.1.A]. The bound is optimal; that is, any smooth n-dimensional torus in an r-ball has normal curvature at least $\sqrt{3 \cdot n/(n+2)} \cdot \frac{1}{r}$ at some point [8]. Gromov's examples easily imply the following: any closed smooth manifold M admits a smooth embedding into an r-ball of sufficiently large dimension with normal curvatures less than $\sqrt{3} \cdot \frac{1}{r}$ [6, 1.D], [5, 1.1.C]. But what happens between $\frac{1}{r}$ and $\sqrt{3} \cdot \frac{1}{r}$?

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In this note, we consider embeddings in an r-ball with normal curvatures at most $\frac{2}{\sqrt{3}} \cdot \frac{1}{r}$. We show that if the inequality is strict, then the manifold must be homeomorphic to a sphere (see § 2). For the nonstrict inequality, in addition to spheres, we get real, complex, quaternionic, and octonionic planes mapped by rescaled Veronese embeddings (see § 4).

2. Sphere theorem. Let M be a closed smooth n-dimensional submanifold in a closed r-ball in \mathbb{R}^d . Suppose that the normal curvatures of M are strictly less than $\frac{2}{\sqrt{3}} \cdot \frac{1}{r}$. Then M is homeomorphic to the n-sphere.

Proof. We can assume that $n \ge 2$; otherwise there is nothing to prove.

Denote the r-ball by \mathbb{B}^d . We can assume that $r = \frac{1}{\sqrt{3}}$; that is, r is the circumradius of an equilateral triangle with side 1. Therefore, the normal curvatures of M are smaller than 2.

Choose a unit-speed geodesic $\gamma \colon [0, \frac{\pi}{2}] \to M$; let $x = \gamma(0)$ and $y = \gamma(\frac{\pi}{2})$. By the assumption, the curvature of γ in \mathbb{R}^d is less than 2. Applying Schur's bow lemma, we get |x - y| > 1.

Let Π be the perpendicular bisector to [x,y]. Since the curvature of γ is smaller than 2,

$$\angle(\gamma'(t_0), \gamma'(t)) < 2 \cdot |t - t_0|, \quad \text{and} \quad \langle \gamma'(t_0), \gamma'(t) \rangle > \cos(2 \cdot |t - t_0|)$$

for $t \neq t_0$. Therefore,

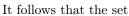
$$\langle y - x, \gamma'(t_0) \rangle > \int_{0}^{\frac{\pi}{2}} \cos(2 \cdot |t - t_0|) \cdot dt \geqslant 0.$$

In particular, the derivative of function $f: t \mapsto \langle y - x, \gamma(t) \rangle$ is positive. Therefore, γ intersects Π transversely at a single point; denote it by s.

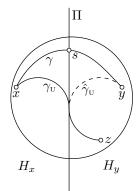
Choose a unit vector $U \in T_x$; let $\gamma_U : [0, \frac{\pi}{2}] \to M$ be the unit-speed geodesic that starts from x in the direction U, and let $z = \gamma_U(\frac{\pi}{2})$. The argument above shows that |x - z| > 1.

Denote by H_x and H_y the closed half-spaces bounded by Π that contain x and y respectively. Assume $z \in H_x$, then we have $|y-z| \ge |x-z| > 1$. Since |x-y| > 1, the triangle [xyz] has all sides larger than 1, which is impossible since $x, y, z \in \mathbb{B}^d$. Therefore, γ_U meets Π before in $\frac{\pi}{2}$; denote by r(U) be the first such time moment.

Let us show that the function $U \mapsto r(U)$ is smooth. In other words, γ_U intersects Π transversely at time r(U). Assume this is not the case, so γ_U is tangent to Π at r(U). Let $\hat{\gamma}_U$ be the concatenation of the reflection of $\gamma_U|_{[0,r(U)]}$ across Π and $\gamma_U|_{[r(U),\frac{\pi}{2}]}$. Note that $\hat{\gamma}_U$ is C^1 -smooth, and it is C^∞ -smooth everywhere except r(U). Therefore, Schur's bow lemma is applicable to $\hat{\gamma}_U$, and hence, |y-z|>1. Again, all sides of triangle [xyz] are larger than 1; hence, it cannot lie in \mathbb{B}^d —a contradiction.



$$V_x = \{ t \cdot U \in T_x : |U| = 1, \quad 0 \le t \le r(U), \}$$



is diffeomorphic to the closed *n*-disc. Denote by W_x the connected component of x in $M \cap H_x$.

From the Gauss formula [9, Lemma 5], the sectional curvatures of M are less than 4. In particular, the exponential map $\exp_x \colon T_x \to M$ is a local diffeomorphism in the $\frac{\pi}{2}$ -ball centered at the origin of T_x .

It follows that $\exp_x: V_x \to W_x$ is a local diffeomorphism; in particular, W_x is a smooth manifold with boundary. Since V_x is simply connected, \exp_x defines a diffeomorphism $V_x \to W_x$. In particular, W_x is a closed topological n-disc and ∂W_x is a smooth hypersurface in M.

Let us swap the roles of x and y, and repeat the construction. We get another closed topological n-disc $W_y \subset M$ bounded by a smooth hypersurface ∂W_y .

Observe that ∂W_x intersects ∂W_y at s. Furthermore, both ∂W_x and ∂W_y are connected components of s in $M \cap \Pi$. Therefore, $\partial W_x = \partial W_y$. That is, M can be obtained by gluing two n-discs by a diffeomorphism between their boundaries. Hence M is homeomorphic to the n-sphere.

3. Veronese embeddings. The real, complex, quaternionic projective spaces of dimension n, and the octonionic projective plane will be denoted by $\mathbb{R}P^n$, $\mathbb{C}P^n$, $\mathbb{H}P^n$, and $\mathbb{O}P^2$ respectively. We assume that each of these spaces is

equipped with the canonical metric; in particular, all the spaces have closed geodesics of length π .

Proposition. There are smooth isometric embeddings

- $\diamond \mathbb{O}\mathrm{P}^2 \hookrightarrow \mathbb{R}^d \text{ for } d \geqslant 26;$

that map each geodesic to a round circle.

Moreover,

- (i) all normal curvatures of the images of these embeddings are equal to 2
- (ii) the images of these embeddings lie in a sphere of radius $r_n = \sqrt{n/(2 \cdot n + 2)}$ (for $\mathbb{O}P^2$, we assume that n=2).

The proposition can be extracted from two theorems in [11, § 2]. The embeddings provided by the proposition will be called Veronese embeddings. Note that r_n is the circumradius of a regular n-simplex with edge length 1. Note that $r_2 = 1/\sqrt{3}$; therefore, the second part of proposition shows that our sphere theorem has the optimal bound.

The Veronese embeddings have a very explicit algebraic description and many nice geometric properties. In particular, these embeddings are equivariant, and their images are minimal submanifolds in the r_n -spheres. All of this is discussed in the cited paper by Kunio Sakamoto.

The following lemma is also closely related to the result of Kunio Sakamoto; it implies that the properties in the proposition uniquely describe Veronese embeddings up to motion of the ambient space.

Lemma. Let M and M' be intrinsically isometric smooth submanifolds in \mathbb{R}^d . Suppose that all geodesics in M and M' are closed and each geodesic forms a round circle in \mathbb{R}^d . Then M is congruent to M'; that is, there is an isometry of \mathbb{R}^d that maps M to M'.

Proof. Recall that the second fundamental form **I** of a submanifold is a bilinear symmetric form on the tangent space with values in the normal space. Assume there is a common point p on M and M' with common tangent space $T_nM =$ $= T_p M'$ and such that the second fundamental forms of M and M' at p coincide. Then M' = M. Indeed, since every geodesic is mapped to a round circle, the image of a geodesic in direction $U \in T_p$ is completely described by $\mathbb{I}(U, U)$. And these circles sweep the whole M and M'.

Recall that the extrinsic curvature tensor Φ of a submanifold is defined as

$$\Phi(x,y,v,w) = \langle I\!I(x,y), I\!I(v,w)\rangle,$$

here X, Y, V, W are tangent vectors to the submanifold at some point; see [7]. Note that the Φ -tensor describes the second fundamental form II up to motion of the ambient space. Therefore, once we show that the Φ -tensors of M and M' coincide at one point, we get that M and M' are congruent.

The tensor Φ can be written as

$$\Phi(X, Y, V, W) = E(X, Y, V, W) + \frac{1}{3} \cdot (Rm(X, V, Y, W) + Rm(X, W, Y, V))$$

where E is the total symmetrization of Φ ; that is,

$$E(X, Y, V, W) = \frac{1}{3} \cdot (\Phi(X, Y, V, W) + \Phi(Y, V, X, W) + \Phi(V, X, Y, W)),$$

and

$$Rm(X,Y,V,W) = \Phi(X,V,Y,W) - \Phi(X,W,Y,V)$$

is the Riemannian curvature tensor of M.

Since M is isometric to M', they have the same Riemannian curvature tensors. It remains to show that the E-tensors are the same. But

$$f(x) = E(x, x, x, x) = |II(x, x)|^2$$

is a homogeneous polynomial of degree 4 on the tangent space and it describes E completely.

The geodesics in M and M' are closed and have the same length. Since each of these geodesic forms a circle in \mathbb{R}^d , all these circles have the same curvature, say κ . Therefore, $\mathbb{I}(\mathbf{x},\mathbf{x}) = \kappa \cdot |\mathbf{x}|^2$ and $\mathbf{E}(\mathbf{x},\mathbf{x},\mathbf{x},\mathbf{x}) = \kappa^2 \cdot |\mathbf{x}|^4$ for both submanifolds and for any tangent vector \mathbf{x} . This finishes the proof.

4. Rigidity theorem. Let M be a closed smooth n-dimensional submanifold in a closed r-ball in \mathbb{R}^d . Suppose that the normal curvatures of M are at most $\frac{2}{\sqrt{3}} \cdot \frac{1}{r}$. If M is not homeomorphic to a sphere, then up to rescaling, it is congruent to an image of the Veronese embedding of a projective plane $\mathbb{R}P^2$, $\mathbb{C}P^2$, $\mathbb{H}P^2$, or $\mathbb{O}P^2$.

This result is an application of the following theorem; its weaker form was proved by Detlef Gromoll and Karsten Grove [4], and the final step was made by Burkhard Wilking [13].

Gromoll–Grove–Wilking theorem. Let M be a compact Riemannian manifold with sectional curvature at least 1 and diameter at least $\frac{\pi}{2}$. If M is not homeomorphic to a sphere, then its Riemannian universal cover is isometric to a compact rank-one symmetric space.

Recall that a compact rank-one symmetric space is isometric to a rescaled copy of one of the following spaces: $\mathbb{R}P^n$, $\mathbb{C}P^n$, $\mathbb{H}P^n$, $\mathbb{O}P^2$, and unit spheres \mathbb{S}^n ; see for example, [14, 8.12.2]. As before we assume that these spaces are equipped with the canonical metrics; in particular, all the projective spaces have closed geodesics of length π .

Proof of the rigidity theorem. Assume M is not homeomorphic to a sphere; in this case, $n \ge 2$. As before, \mathbb{B}^d will denote the r-ball in \mathbb{R}^d , and we assume that $r = \frac{1}{\sqrt{3}}$; therefore, the normal curvatures of M are at most 2.

By the proposition in § 3, the images of Veronese embedding satisfy the assumption of the theorem. It remains to show that there are no other embeddings of that type.

Choose a unit-speed geodesic $\gamma \colon [0, \frac{\pi}{2}] \to M$; let $x = \gamma(0)$ and $y = \gamma(\frac{\pi}{2})$. The argument in our sphere theorem implies that |x - y| = 1. The rigidity case in the bow lemma implies that γ is a half-circle of curvature 2. Since any two points in M can be connected by a geodesic, we get the following.

 \diamond The diameter of M is 1.

- \diamond The intrinsic diameter and injectivity radius of M are equal to $\frac{\pi}{2}$.
- \diamond All geodesics in M are circles of curvature 2 in \mathbb{R}^d .

Furthermore, for x and y as above, there is another point $z \in M$ such that |x-z| = |y-z| = 1. If not, then again, the argument in the sphere theorem would imply that M is a sphere. But since $x, y, z \in \mathbb{B}^d$, the equalities |x-y| = |y-z| = |x-z| = 1 imply that $x \in \partial \mathbb{B}^d$.

The choice of $x \in M$ was arbitrary. Therefore, M lies in the sphere $\partial \mathbb{B}^d$ of radius $r = 1/\sqrt{3}$. This sphere has sectional curvature $1/r^2 = 3$; all normal curvatures of M in the sphere are $\kappa = \sqrt{2^2 - 1/r^2} = 1$. By the Gauss formula [9, Lemma 5], the sectional curvatures of M are at least $3 - 2 \cdot \kappa^2 = 1$.

By the Gromoll–Grove–Wilking theorem, the universal cover \tilde{M} of M is isometric to a rank-one symmetric space. Taking into account the injectivity radius and curvature of M, we get that \tilde{M} must be isometric to one of the following spaces $\frac{1}{2} \cdot \mathbb{S}^n$, \mathbb{S}^n , $\mathbb{C}P^n$, $\mathbb{H}P^n$ for some n, or $\mathbb{O}P^2$. Note that the points $x,y,z \in M$ constructed above lie at an intrinsic distance $\frac{\pi}{2}$ from each other. It forbids $\frac{1}{2} \cdot \mathbb{S}^n$ for every n. Furthermore, if $n \geq 3$, then each space \mathbb{S}^n , $\mathbb{C}P^n$ and $\mathbb{H}P^n$ contain 4 points at a distance $\frac{\pi}{2}$ from each other. Since the injectivity radius of M is $\frac{\pi}{2}$, their projections in M must lie at a distance $\frac{\pi}{2}$ from each other as well. It follows that \mathbb{B}^d must contain 4 points at a distance 1 from each other, which is impossible.

Hence, \tilde{M} must be isometric to one of the following spaces \mathbb{S}^2 , $\mathbb{C}P^2$, $\mathbb{H}P^2$, or $\mathbb{O}P^2$. Since the injectivity radius of M is $\frac{\pi}{2}$, it has to be isometric to $\mathbb{R}P^2$, $\mathbb{C}P^2$, $\mathbb{H}P^2$, or $\mathbb{O}P^2$.

Denote by $M' \subset \mathbb{R}^d$ the image of the corresponding Veronese embedding provided by the proposition in § 3. Without loss of generality, we can assume that d is large, so M' exists. Applying the lemma in § 3, we get that M is congruent M' — hence the result.

5. Final remarks. Recall that the Veronese embeddings map $\mathbb{R}P^n$, $\mathbb{C}P^n$, and $\mathbb{H}P^n$ into balls of radius $r_n = \sqrt{n/(2 \cdot n + 2)}$, which is the circumradius of a regular *n*-simplex with edge length 1. This note is motivated by the following question [10].

Question. Is it true that the Veronese embedding minimizes the maximal normal curvature among all smooth embeddings of $\mathbb{R}P^n$ into the ball of radius r_n in a Euclidean space of large dimension?

The same question can be asked about $\mathbb{C}P^n$ and $\mathbb{H}P^n$. A keen reader might have noticed that the case n=2 is already solved.

Question. Let M be as in our sphere theorem; does it have to be diffeomorphic to the standard n-sphere?

I suspect that the answer is yes. If, in addition, M lies on the boundary of the r-ball, then by the Gauss formula [9, Lemma 5], M has strictly quarter-pinched curvature; so, it has to be diffeomorphic to a standard sphere [1].

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